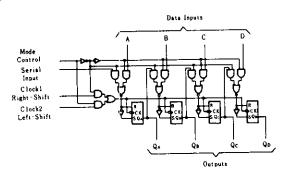
This 4-bit register features parallel and serial inputs, parallel outputs, mode control, and two clock inputs. The register has three mode operation:

- Parallel (broadside) load
- Shift right (the direction Cl<sub>A</sub> toward Q<sub>D</sub>)
- Shift left (the direction Q<sub>D</sub> toward Q<sub>A</sub>)

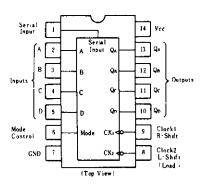
Parallel loading is accomplished by applying the four bits of data and taking the mode control input high. The data is loaded into the associated flip-flops and appears at the outputs after the high-to-low transition of the clock-2 input. During loading, the entry of serial data is inhibited. Shift right is accomplished on the high-to-low transition of clock-1 when the

mode control is low; shift left is accomplished on the high-to-low transition of clock-2 when the mode control is high by connecting the output of each flip-flop to the parallel input of the previous flip-flop ( $\Omega_D$  to input C, etc.) and serial data is entered at input D. The clock input may be applied commonly to clock-1 and clock-2 if both modes can be clocked from the same source. Changes at the mode control input should normally be made while both clock inputs are low: however, conditions described in the last three lines of the function table will also ensure that register contents are protected.

#### **■BLOCK DIAGRAM**



#### **■PIN ARRANGEMENT**



# **INTERPOLE TABLE**

				Out	puts						
Mode	Clocks				Par	allel		Q <sub>A</sub>	Qв	$\mathbf{Q}_{\mathrm{C}}$	Qυ
Control	2(L)	100	Serial	A	В	С	D	₩A	W D	40	<b>4</b> (1)
Н	Н	×	×	×	×	×	×	Qao	Qво	<b>Q</b> co	Qpo
Н	1	×	×	a	ь	c	d	a	b	c	d
н	1	×	×	Q <sub>B</sub> †	Qc†	Qn†	d.	QBn	Q <sub>Cn</sub>	Q <sub>Dn</sub>	d
L	L	Н	×	×	×	×	×	Qao	Qво	Qco	Quo
L	×	<b>1</b>	Н	×	×	×	×	Н	Q <sub>An</sub>	Q <sub>Bn</sub>	Qcn
L	×	ı	L	×	×	×	×	L	QAn	Q <sub>Bn</sub>	Qca
1	L	L	×	×	×	×	×	Qao	Qво	Qco	Qυo
1	L	L	×	×	×	×	×	Qao	Qво	Qcσ	QDO
	L	H	×	×	×	×	×	QAO	Qво	Qco	Qno
<u>†</u>	Н	L.	×	×	×	×	×	QAO	Qво	Qco	Qpo
<u>†</u>	Н	Н	×	×	×	×	×	QAO	Qво	Qco	QDO

Notes) 1. H; high level, L; low level, X; irrelevant

- 2. †; transition from low to high level
- 3. 4; transition from high to low level
- 4. a~d; the level of steady-state input at inputs A,B,C, or D,
- 5. QA0~QD0; the level of QA, QB, QC, or QD, respectively,

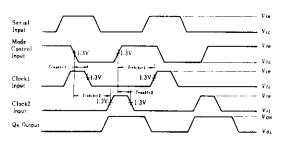
before the indicated steady-state input conditions were established.

- Q<sub>An</sub>~Q<sub>Dn</sub>; the level of Q<sub>A</sub>, Q<sub>B</sub>, Q<sub>C</sub>, or Q<sub>D</sub>, respectively, before the most-recent (1) transition of the clock.
- †; Shifting left requires external connection of Q<sub>B</sub> to A, Q<sub>C</sub> to B, and Q<sub>D</sub> to C. Serial data is entered at input D.

# HD74LS95B

# **TRECOMMENDED OPERATING CONDITIONS**

Item	Symbol	min	typ	max	Unit MHz	
Clock frequency	felock	0	-	25		
Clock pulse width	łw(CK)	25		-	ns	
Setup time	tre	20		_	ית	
Hold time	th	10	_	_	n	
Enable time 1	tenable 1	20	_		n:	
Enable time 2	tenable 2	20	_		n:	
Inhibit time 1	Linkibit 1	20	_	_	יח	
Inhibit time 2	Inhibit 2	20	_		ns	



Clock Enable/Inhibit Times

# **ELECTRICAL CHARACTERISTICS** ( $Ta = -20 \sim +75^{\circ}C$ )

Item	Symbol	Test Condition	min	typ*	max	Unit	
	$V_{IH}$			2.0	_		
Input voltage	VIL	4		-		0.8	V
	Voн	$V_{CC} = 4.75 \text{V}, V_{IH} = 2 \text{V}, V_{IL} = 0.8 \text{V}$	2.7		_	V	
Output voltage		$V_{CC} = 4.75 \text{V},  V_{IH} = 2 \text{V},$	$I_{OL} = 4 \text{mA}$			0.4	ν
	Vol	$V_{IL}=0.8V$	Io L = 8mA	-		0.5	٧
	Iтн	$V_{CC} = 5.25 \text{V},  V_I = 2.7 \text{V}$				20	μA
Input current	Iπ	$V_{CC} = 5.25 \text{V},  V_I = 0.4 \text{V}$		-	_	-0.4	mА
	Iı	$V_{CC} = 5.25 \text{ V},  V_i = 7 \text{ V}$				0.1	mА
Short-circuit output current los		$V_{CC}=5.25V$	•	- 20		-100	mΑ
Supply current * * Icc		$V_{CC} = 5.25 \text{V}$			13	21	mА
Input clamp voltage Vik		$V_{CC} = 4.75 \text{V}, I_{IN} = -18 \text{m}_{I}$	4			-1.5	V

<sup>\*</sup> V<sub>CC</sub>=5V, Ta=25°C

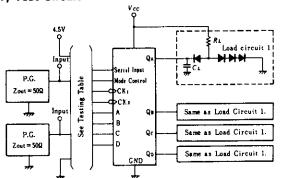
# **ESWITCHING CHARACTERISTICS** ( $V_{cc} = 5V$ , $T_a = 25^{\circ}C$ )

Item	Symbol	Test Conditions	min	typ	max	Unit
Maximum clock frequency	fmoz		25	36	••	MHz
	tplh	$C_L = 15 \text{pF},  R_L = 2 \text{k}\Omega$	-	18	27	ns
Propagation delay time	tPHL		_	21	32	ns

<sup>\*\*</sup>I<sub>CC</sub> is measured with all outputs and serial input open; A,B,C, and D inputs grounded; mode control at 4.5V; and momentary 3V, then ground, applied both clock inputs.

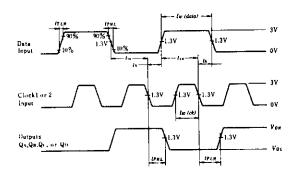
# **TESTING METHOD**

# 1) Test Circuit



Notes) 1.  $C_L$  includes probe and jig capacitance. 2. All diodes are 1S2074 P.

#### Waveform

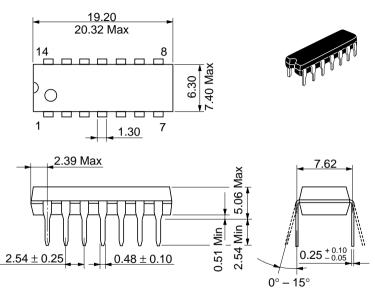


Note) 1. Input pulse:  $t_{TLH}$ ,  $t_{THL} \le 10$ ns, Data PRR = 500kHz Clock PRR=1MHz

#### 2) Testing Table

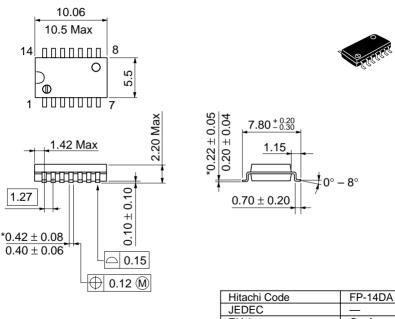
	From input	Inputs							Outputs				
ltem		CK-1	CK-2	Mode Control	Secial Inputs	A	В	С	D	Q۸	Qв	Qc	Qυ
	CK-1→Q	IN	4.5V	0V	IN	4.5V	4.5V	1.5V	4.5V	OUT	OUT	OUT	OUT
fmax	CK-2→Q	4.5V	IN	4.5V	4.5V	IN	IN	IN	IN	OUT	OUT	OUT	OUT
tPLH	CK-1→Q	IN	1.5V	0V	IN	4.5V	4.5V	4.5V	4.5V	OUT	OUT	OUT	OUT
tPHL	CK-2→Q	4.5V	IN	4.5V	4.5V	IN	IN	IN	IN	OUT	OUT	OUT	OUT

Unit: mm



Hitachi Code	DP-14
JEDEC	Conforms
EIAJ	Conforms
Weight (reference value)	0.97 g

Unit: mm



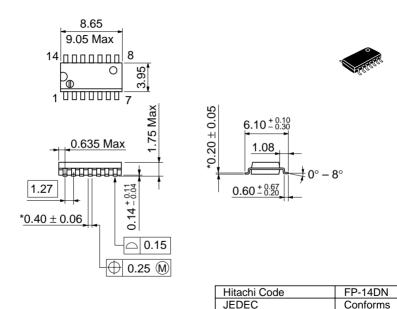
\*Dimension including the plating thickness
Base material dimension

\*Dimension including the plating thickness

Base material dimension

\*United States of The 14-57 of The 14

Unit: mm



EIAJ

Weight (reference value)

Conforms

0.13 g

\*Pd plating

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