# 80C196EA/83C196EA CHMOS 16-BIT MICROCONTROLLER

Automotive

- 40 MHz operation
- Optional clock doubler
- 2 Mbytes of linear address space
- 1 Kbyte of register RAM
- 3 Kbytes of code RAM
- 8 Kbytes of ROM
- Register-to-register architecture
- Stack overflow/underflow monitor with user-defined upper and lower stack pointer boundary limits
- 2 peripheral interrupt handlers (PIH) provide direct hardware handling of up to 16 peripheral interrupts
- Peripheral transaction server (PTS) with high-speed, microcoded interrupt service routines
- Up to 83 I/O port pins
- 2 full-duplex serial ports with dedicated baud-rate generators
- Enhanced synchronous serial unit
- 8 pulse-width modulator (PWM) outputs with 8-bit resolution
- 16-bit watchdog timer
- Sixteen 10-bit A/D channels with autoscan mode and dedicated results registers

- Serial debug unit provides read and write access to code RAM with no CPU overhead
- Chip-select unit (CSU)
- 3 chip-select pins
- Dynamic demultiplexed/multiplexed address/data bus for each chip-select
- Programmable wait states (0, 1, 2, or 3) for each chip-select
- Programmable bus width (8- or 16-bit) for each chip-select
- Programmable address range for each chip-select
- Event processor array (EPA)
- 4 flexible 16-bit timer/counters
- 17 high-speed capture/compare channels
- 8 output-only channels capture value of any other timer upon compare, providing easy conversion between angle and time domains
- Programmable clock output signal
- 160-pin QFP package
- Complete system development support
- High-speed CHMOS technology

The 8xC196EA is the first member of a new family of microcontrollers with features that are useful in automotive applications, such as powertrain control. Two Mbytes of linear address space provide more space for high-level language compilation. A demultiplexed address/data bus and three chip-select signals make it easier to design low-cost memory solutions. The external bus can dynamically switch between multiplexed and demultiplexed operation.

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### 80C196EA/83C196EA

### **CHMOS 16-bit Microcontroller**

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## 1.0 PRODUCT OVERVIEW

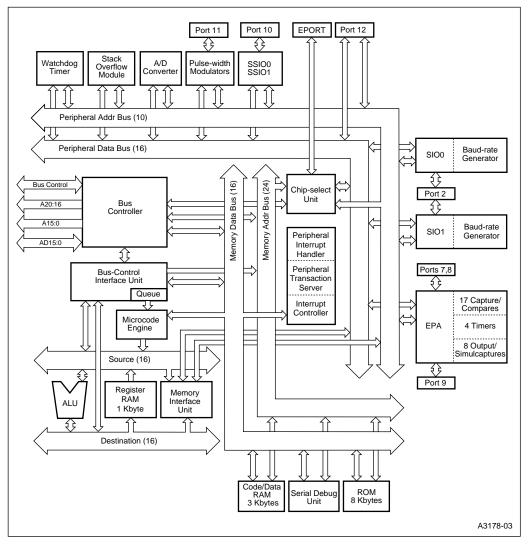


Figure 1. 8xC196EA Block Diagram

The 8xC196EA is highly integrated with an enhanced peripheral set. The serial debug unit (SDU) provides system debug and development capabilities. The SDU can set a single hardware breakpoint and provides read and write access to code RAM through a high-speed, dedicated serial link. A stack overflow/underflow monitor assists in code development by causing an unmaskable interrupt if the stack pointer crosses a user-defined boundary. The 16-channel A/D converter supports an auto-scan mode that operates with no

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CPU overhead. Each A/D channel has a dedicated result register. The EPA supports high-speed input captures and output compares with 17 programmable, high-speed capture/compare channels. Eight output-only channels provide support for time-base conversions by capturing the value of one of four timers when a compare occurs.

### 2.0 NOMENCLATURE OVERVIEW

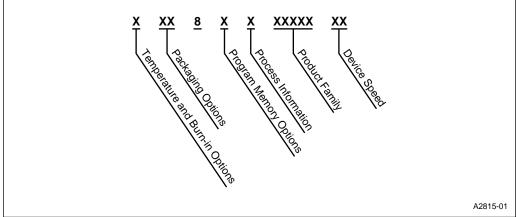
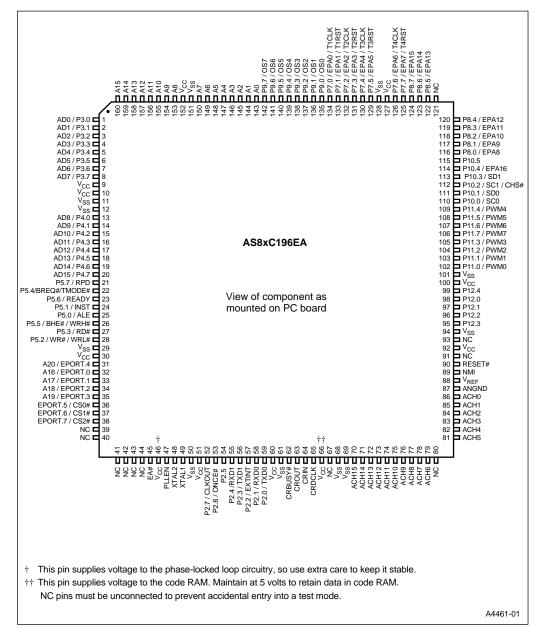


Figure 2. Product Nomenclature

Parameter	Options	Description
Temperature and Burn-in Options	A	Automotive operating temperature range (–40° C to 125° C case) with Intel standard burn-in.
Packaging Options	S	QFP
Program Memory Options	3	Internal ROM
	0	CPU only - no internal ROM
Process Information	С	CHMOS
Product Family	196EA	
Device Speed	no mark	40 MHz



### 3.0 PINOUT



#### Figure 3. 8xC196EA 160-pin QFP Package

	Table 2. 8xC196EA 160-pin QFP Package Pin Assignments (Sheet 1 of 2)								
Pin	Name	Pin	Name	Pin	Name	Pin	Name		
1	AD0 / P3.0	41	NC	81	ACH5	121	NC		
2	AD1 / P3.1	42	NC	82	ACH4	122	P8.5 / EPA13		
3	AD2 / P3.2	43	NC	83	ACH3	123	P8.6 / EPA14		
4	AD3 / P3.3	44	NC	84	ACH2	124	P8.7 / EPA15		
5	AD4 / P3.4	45	EA#	85	ACH1	125	P7.7 / EPA7 / T4RST		
6	AD5 / P3.5	46	V <sub>CC</sub>	86	ACH0	126	P7.6 / EPA6 / T4CLK		
7	AD6 / P3.6	47	PLLEN	87	ANGND	127	V <sub>CC</sub>		
8	AD7 / P3.7	48	XTAL2	88	V <sub>REF</sub>	128	V <sub>SS</sub>		
9	V <sub>CC</sub>	49	XTAL1	89	NMI	129	P7.5 / EPA5 / T3RST		
10	V <sub>CC</sub>	50	V <sub>SS</sub>	90	RESET#	130	P7.4 / EPA4 / T3CLK		
11	V <sub>SS</sub>	51	V <sub>CC</sub>	91	NC	131	P7.3 / EPA3 / T2RST		
12	V <sub>SS</sub>	52	P2.7 / CLKOUT	92	V <sub>CC</sub>	132	P7.2 / EPA2 / T2CLK		
13	AD8 / P4.0	53	P2.6 / ONCE#	93	NC	133	P7.1 / EPA1 / T1RST		
14	AD9 / P4.1	54	P2.5	94	V <sub>SS</sub>	134	P7.0 / EPA0 / T1CLK		
15	AD10 / P4.2	55	P2.4 / RXD1	95	P12.3	135	P9.0 / OS0		
16	AD11 / P4.3	56	P2.3 / TXD1	96	P12.2	136	P9.1 / OS1		
17	AD12 / P4.4	57	P2.2 / EXTINT	97	P12.1	137	P9.2 / OS2		
18	AD13 / P4.5	58	P2.1 / RXD0	98	P12.0	138	P9.3 / OS3		
19	AD14 / P4.6	59	P2.0 / TXD0	99	P12.4	139	P9.4 / OS4		
20	AD15 / P4.7	60	V <sub>CC</sub>	100	V <sub>CC</sub>	140	P9.5 / OS5		
21	P5.7 / RPD	61	V <sub>SS</sub>	101	V <sub>SS</sub>	141	P9.6 / OS6		
22	P5.4/BREQ#/TMODE#	62	CRBUSY#	102	P11.0 / PWM0	142	P9.7 / OS7		
23	P5.6 / READY	63	CROUT	103	P11.1 / PWM1	143	A0		
24	P5.1 / INST	64	CRIN	104	P11.2 / PWM2	144	A1		
25	P5.0 / ALE	65	CRDCLK	105	P11.3 / PWM3	145	A2		
26	P5.5 / BHE# / WRH#	66	V <sub>CC</sub>	106	P11.7 / PWM7	146	A3		
27	P5.3 / RD#	67	NC	107	P11.6 / PWM6	147	A4		
28	P5.2 / WR# / WRL#	68	V <sub>SS</sub>	108	P11.5 / PWM5	148	A5		

#### Table 2. 8xC196EA 160-pin QFP Package Pin Assignments (Sheet 1 of 2)

	Table 2. 8xC196EA 160-pin QFP Package Pin Assignments (Sneet 2 of 2)							
Pin	Name	Pin	Name	Pin	Name	Pin	Name	
29	V <sub>SS</sub>	69	V <sub>SS</sub>	109	P11.4 / PWM4	149	A6	
30	V <sub>CC</sub>	70	ACH15	110	P10.0 / SC0	150	A7	
31	A20 / EPORT.4	71	ACH14	111	P10.1 / SD0	151	V <sub>SS</sub>	
32	A16 / EPORT.0	72	ACH13	112	P10.2 / SC1	152	V <sub>CC</sub>	
33	A17 / EPORT.1	73	ACH12	113	P10.3 / SD1	153	A8	
34	A18 / EPORT.2	74	ACH11	114	P10.4 / EPA16	154	A9	
35	A19 / EPORT.3	75	ACH10	115	P10.5	155	A10	
36	EPORT.5 / CS0#	76	ACH9	116	P8.0 / EPA8	156	A11	
37	EPORT.6 / CS1#	77	ACH8	117	P8.1 / EPA9	157	A12	
38	EPORT.7 / CS2#	78	ACH7	118	P8.2 / EPA10	158	A13	
39	NC	79	ACH6	119	P8.3 / EPA11	159	A14	
40	NC	80	NC	120	P8.4 /EPA12	160	A15	

#### Table 2. 8xC196EA 160-pin QFP Package Pin Assignments (Sheet 2 of 2)

#### Table 3. Pin Assignment Arranged by Functional Categories (Sheet 1 of 2)

Addr & Data		Input/Outp	ut	Input/Output (Cont	'd)	Input/Output (Co	nt'd)
Name	Pin	Name	Pin	Name	Pin	Name	Pin
A0	143	P2.0 / TXD0	59	EPORT.7	38	P12.0	98
A1	144	P2.1 / RXD0	58	P7.0 / EPA0 / T1CLK	134	P12.1	97
A2	145	P2.2	57	P7.1 / EPA1 / T1RST	133	P12.2	96
A3	146	P2.3 / TXD1	56	P7.2 / EPA2 / T2CLK	132	P12.3	95
A4	147	P2.4 / RXD1	55	P7.3 / EPA3 / T2RST	131	P12.4	99
A5	148	P2.5	54	P7.4 / EPA4 / T3CLK	130		
A6	149	P2.6	53	P7.5 / EPA5 / T3RST	129	Analog Input	S
A7	150	P2.7	52	P7.6 / EPA6 / T4CLK	126	Name	Pin
A8	153	P3.0	1	P7.7 / EPA7 / T4RST	125	ACH0	86
A9	154	P3.1	2	P8.0 / EPA8	116	ACH1	85
A10	155	R3.2	3	P8.1 / EPA9	117	ACH2	84
A11	156	P3.3	4	P8.2 / EPA10	118	ACH3	83
A12	157	P3.4	5	P8.3 / EPA11	119	ACH4	82
A13	158	P3.5	6	P8.4 / EPA12	120	ACH5	81
A14	159	P3.6	7	P8.5 / EPA13	122	ACH6	79
A15	160	P3.7	8	P8.6 / EPA14	123	ACH7	78
A16	32	P4.0	13	P8.7 / EPA15	124	ACH8	77
A17	33	P4.1	14	P9.0 / OS0	135	ACH9	76
A18	34	P4.2	15	P9.1 / OS1	136	ACH10	75
A19	35	P4.3	16	P9.2 / OS2	137	ACH11	74
A20	31	P4.4	17	P9.3 / OS3	138	ACH12	73

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	Tabl	e 3. Pin Assignr	ment Arra	anged by Functional C	ategories	(Sheet 2 of 2)	
AD0	1	P4.5	18	P9.4 / OS4	139	ACH13	72
AD1	2	P4.6	19	P9.5 / OS5	140	ACH14	71
AD2	3	P4.7	20	P9.6 / OS6	141	ACH15	70
AD3	4	P5.0	25	P9.7 / OS7	142		
AD4	5	P5.1	24	P10.0 / SC0	110	Bus Control &	Status
AD5	6	P5.2	28	P10.1 / SD0	111	Name	Pin
AD6	7	P5.3	27	P10.2 / SC1	112	ALE	25
AD7	8	P5.4	22	P10.3 / SD1	113	BHE#/WRH#	26
AD8	13	P5.5	26	P10.4 / EPA16	114	BREQ#	22
AD9	14	P5.6	23	P10.5	115	CS0#	36
AD10	15	P5.7	21	P11.0 / PWM0	102	CS1#	37
AD11	16	EPORT.0	32	P11.1 / PWM1	103	CS2#	38
AD12	17	EPORT.1	33	P11.2 / PWM2	104	INST	24
AD13	18	EPORT.2	34	P11.3 / PWM3	105	RD#	27
AD14	19	EPORT.3	35	P11.4 / PWM4	109	READY	23
AD15	20	EPORT.4	31	P11.5 / PWM5	108		
		EPORT.5	36	P11.6 / PWM6	107		
		EPORT.6	37	P11.7 / PWM7	106	WR#/WRL#	28

### Table 3. Pin Assignment Arranged by Functional Categories (Sheet 2 of 2)

	Powe	er & Ground	
Name		Pins	
ANGND	87		CL
V <sub>CC</sub>	9, 10, 30, 46 <sup>†</sup> , 5	1, 60, 66 <sup>††</sup> , 92, 100, 127, 152	EA
V <sub>SS</sub>	11, 12, 29, 50, 6	1, 68, 69, 94, 101, 128, 151	EX
V <sub>REF</sub>	88		NM

No Connection						
Name Pins						
NC <sup>†††</sup>	39–44, 67, 69, 80, 91, 93, 121					

WR#/WRL#	28					
Processor Control						
Name	Pin					
CLKOUT	52					
EA#	45					
EXTINT	57					
NMI	89					
ONCE#	53					
PLLEN	47					
RESET#	90					
RPD	21					
TMODE#	22					
XTAL1	49					
XTAL2	48					

- <sup>†</sup> This pin supplies voltage to the phase-locked loop circuitry, so use extra care to keep it stable.
- <sup>††</sup> This pin supplies voltage to code RAM. To retain data, maintain 5 volts.
- \*\*\*\* Always leave NC (no connect) pins unconnected to prevent accidental entry into test modes.

Code Debug	
Name	Pin
CRBUSY#	62
CRDCLK	65
CRIN	64
CROUT	63

## 4.0 SIGNALS

Name	Туре	Description
A15:0	0	System Address Bus
		These address lines provide address bits 0–15 during the entire external mem- ory cycle during both multiplexed and demultiplexed bus modes.
A20:16	I/O	Address Lines 16–20
		These address lines provide address bits 16–20 during the entire external memory cycle, supporting extended addressing of the 2 Mbyte address space.
		<b>NOTE:</b> Internally, there are 24 address bits; however, only 21 external address pins (A20:0) are implemented. The internal address space is 16 Mbytes (000000 FFFFFH) and the external address space is 2 Mbytes (00000 1FFFFFH). The device resets to FF2080H in internal memory or 1F2080H in external memory.
		A20:16 are multiplexed with EPORT.4:0.
ACH15:0	I	Analog Channels
		These pins are analog inputs to the A/D converter.
		The ANGND and $V_{REF}$ pins must be connected for the A/D converter to function.
AD15:0	I/O	Address/Data Lines
		The function of these pins depend on the bus size and mode. When a bus access is not occurring, these pins revert to their I/O port function.
		<b>16-bit Multiplexed Bus Mode</b> : AD15:0 drive address bits 0–15 during the first half of the bus cycle and drive or receive data during the second half of the bus cycle.
		<b>8-bit Multiplexed Bus Mode</b> : AD15:8 drive address bits 8–15 during the entire bus cycle. AD7:0 drive address bits 0–7 during the first half of the bus cycle and drive or receive data during the second half of the bus cycle.
		16-bit Demultiplexed Mode:
		AD15:0 drive or receive data during the entire bus cycle.
		<b>8-bit Demultiplexed Mode</b> : AD7:0 drive or receive data during the entire bus cycle. AD15:8 drive the data that is currently on the high byte of the internal bus.
		AD7:0 share package pins P3.7:0. AD15:8 share package pins P4.7:0.
ALE	0	Address Latch Enable
		This active-high output signal is asserted only during external memory cycles. ALE signals the start of an external bus cycle and indicates that valid address information is available on the system address/data bus (A20:16 and AD15:0 for a multiplexed bus; A20:0 for a demultiplexed bus).
		An external latch can use this signal to demultiplex address bits 0–15 from the address/data bus in multiplexed mode.
		ALE shares a package pin with P5.0.
ANGND	GND	Analog Ground
		ANGND must be connected for A/D converter operation. ANGND and $\rm V_{SS}$ should be nominally at the same potential.

Table 4. Signal Descriptions (Sheet 1 of 8)

Name	Туре	Description
BHE#	0	Byte High Enable <sup>†</sup> During 16-bit bus cycles, this active-low output signal is asserted for word and high-byte reads and writes to external memory. BHE# indicates that valid data is being transferred over the upper half of the system data bus. Use BHE#, in conjunction with AD0, to determine which memory byte is being transferred over the system bus:
		BHE# AD0 Byte(s) Accessed
		00both bytes01high byte only10low byte only
		BHE# shares a package pin with P5.5 and WRH#.
		<sup>†</sup> The chip configuration register 0 (CCR0) determines whether this pin func- tions as BHE# or WRH#. CCR0.2 = 1 selects BHE#; CCR0.2 = 0 selects WRH#.
BREQ#	0	Bus Request This active-low output signal is asserted during a hold cycle when the bus con- troller has a pending external memory cycle. You must enable the bus-hold protocol before using this signal. BREQ# shares a package pin with P5.4.
CLKOUT	0	Clock Output
		Output of the internal clock generator. The CLKOUT frequency can be pro- grammed to one of five frequencies: the internal operating frequency (f) divided by a factor of two, four, eight, or sixteen, or the same frequency as the oscillator input ( $F_{XTAL1}$ ). CLKOUT has a 50% duty cycle. CLKOUT shares a package pin with P2.7
CRBUSY#	0	Code RAM Busy
		This signal indicates that the serial debug unit (SDU) is not ready to conduct a transaction.
CRDCLK	I	Code RAM Clock Provides the clock signal for the serial debug unit (SDU). The maximum clock frequency equals the operating frequency (f) divided by two.
CRIN	1	Code RAM Data Input
		Serial input for test instructions and data into the serial debug unit (SDU). Data is transferred in 8-bit bytes with the most-significant bit (MSB) first. Each bit is sampled on the rising edge of CRDCLK.
CROUT	0	Code RAM Data Output
		Serial output for data from the serial debug unit (SDU). Data is transferred in 8-bit bytes with the most-significant bit (MSB) first. Each bit is valid on the rising edge of CRDCLK.

#### Table 4. Signal Descriptions (Sheet 2 of 8)

Name	Type	Table 4. Signal Descriptions (Sheet 3 of 8) Description
	Туре	
CS2:0#	0	Chip-select Lines 0–2 The active-low output CS <i>x</i> # is asserted during an external memory cycle when the address to be accessed is in the range programmed for chip select <i>x</i> . If the external memory address is outside the range assigned to the three chip selects, no chip-select output is asserted and the bus configuration defaults to the CS2# values.
		Immediately following reset, CS0# is automatically assigned to the range FF2000 FF20FFH (1F2000 1F20FFH if external).
		CS2:0# share package pins with EPORT.7:5.
EA#	I	External Access
		This input determines whether memory accesses to special-purpose and pro- gram memory partitions (FF2000 FF3FFFH) are directed to internal or external memory. These accesses are directed to internal memory if EA# is held high and to external memory if EA# is held low. For an access to any other memory location, the value of EA# is irrelevant.
		EA# is sampled and latched only on the rising edge of RESET#. Changing the level of EA# after reset has no effect.
		On devices with no internal nonvolatile memory, always connect EA# to $V_{SS}.$
EPA16:0	I/O	Event Processor Array (EPA) Capture/Compare Channels
		High-speed input/output signals for the EPA capture/compare channels.
		EPA16:0 share package pins with the following signals: EPA0/P7.0/T1CLK, EPA1/P7.1/T1RST, EPA2/P7.2/T2CLK, EPA3/P7.3/T2RST, EPA4/P7.4/T3CLK, EPA5/P7.5/T3RST, EPA6/P7.6/T4CLK, EPA7/P7.7/T4RST, EPA8/P8.0, EPA9/P8.1, EPA10/P8.2, EPA11/P8.3, EPA12/P8.4, EPA13/P8.5, EPA14/P8.6, EPA15/P8.7, and EPA16/P10.4.
EPORT.7:0	I/O	Extended Addressing Port
		This is a standard 8-bit, bidirectional port.
		EPORT.4:0 share package pins with A20:16. EPORT7:5 share package pins with CS2:0#.
EXTINT	I	External Interrupt
		In normal operating mode, a rising edge on EXTINT sets the EXTINT interrupt pending bit. EXTINT is sampled during phase 2 (CLKOUT high). The minimum high time is one state time.
		In powerdown mode, asserting the EXTINT signal for at least 50 ns causes the device to resume normal operation. The interrupt need not be enabled, but the pin must be configured as a special-function input. If the EXTINT interrupt is enabled, the CPU executes the interrupt service routine. Otherwise, the CPU executes the instruction that immediately follows the command that invoked the power-saving mode.
		In idle mode, asserting any enabled interrupt causes the device to resume nor- mal operation.
		EXTINT shares a package pin with P2.2.

#### Table 4. Signal Descriptions (Sheet 3 of 8)

Name	Туре	Description
INST	0	Instruction Fetch
		This active-high output signal is valid only during external memory bus cycles. When high, INST indicates that an instruction is being fetched from external memory. The signal remains high during the entire bus cycle of an external instruction fetch. INST is low for data accesses, including interrupt vector fetches and chip configuration byte reads. INST is low during internal memory fetches. INST shares a package pin with P5.1.
NMI		Nonmaskable Interrupt In normal operating mode, a rising edge on NMI generates a nonmaskable interrupt. NMI has the highest priority of all prioritized interrupts. Assert NMI for greater than one state time to guarantee that it is recognized.
ONCE#	I	On-circuit Emulation
		Holding ONCE# low during the rising edge of RESET# places the device into on-circuit emulation (ONCE) mode. PLLEN must also be held low. This mode puts all pins into a high-impedance state, thereby isolating the device from other components in the system. The value of ONCE# is latched when the RESET# pin goes inactive. While the device is in ONCE mode, you can debug the system using a clip-on emulator.
		To exit ONCE mode, reset the device by pulling the RESET# signal low. To prevent inadvertent entry into ONCE mode, either configure this pin as an output or hold it high during reset and ensure that your system meets the $V_{\rm IH}$ specification.
		ONCE# shares a package pin with P2.6.
OS7:0	0	Event Processor Array (EPA) Compare-only Channels with Simulcapture Outputs of the EPA's compare-only channels. These pins are multiplexed with port 9 and may be configured as standard I/O. OS7:0 share package pins with P9.7:0.
P2.7:0	I/O	Port 2
		This is a standard, 8-bit, bidirectional port that is multiplexed with individually selectable special-function signals. P2.6 is multiplexed with ONCE#. To prevent inadvertent entry into ONCE mode, either configure this pin as an output or hold it high during reset and ensure that your system meets the V <sub>IH</sub> specification. Port 2 shares package pins with the following signals: P2.0/TXD0, P2.1/RXD0, P2.2/EXTINT, P2.3/TXD1, P2.4/RXD1, P2.6/ONCE#, and P2.7/CLKOUT.
P3.7:0	I/O	Port 3 This is a memory-mapped, 8-bit, bidirectional port with programmable open-drain or complementary output modes. The pins are shared with the mul- tiplexed address/data bus, which has complementary drivers. P3.7:0 share package pins with AD7:0.
P4.7:0	I/O	Port 4 This is a memory-mapped, 8-bit, bidirectional port with programmable open-drain or complementary output modes. The pins are shared with the mul- tiplexed address/data bus, which has complementary drivers. P4.7:0 share package pins with AD15:8.

Table 4. Signal Descriptions (Sheet 4 of 8)

Name	Туре	Description
P5.7:0	I/O	Port 5
		This is a memory-mapped, 8-bit, bidirectional port that is multiplexed with individually selectable control signals. P5.4 is multiplexed with TMODE#. If this pin is held low during reset, the device will enter a test mode. To prevent inadvertent entry into a reserved test mode, either configure this pin as an output or hold it high during reset and ensure that your system meets the $V_{\rm IH}$ specification.
		Port 5 shares package pins with the following signals: P5.0/ALE, P5.1/INST, P5.2/WR#/WRL#, P5.3/RD#, P5.4/BREQ#/TMODE#, P5.5/BHE#/WRH#, P5.6/READY, and P5.7/RPD.
P7.7:0	I/O	Port 7
		This is a standard, 8-bit, bidirectional port that is multiplexed with individually selectable special-function signals.
		Port 7 shares package pins with the following signals: P7.0/EPA0/T1CLK, P7.1/EPA1/T1RST, P7.2/EPA2/T2CLK, P7.3/EPA3/T2RST, P7.4/EPA4/T3CLK, P7.5/EPA5/T3RST, P7.6/EPA6/T4CLK, and P7.7/EPA7/T4RST.
P8.7:0	I/O	Port 8
		This is a standard, 8-bit, bidirectional port that is multiplexed with individually selectable special-function signals.
		P8.7:0 share package pins with EPA15:8.
P9.7:0	I/O	Port 9
		This is a standard, 8-bit, bidirectional port that is multiplexed with individually selectable special-function signals.
		P9.7:0 share package pins with OS7:0.
P10.5:0	I/O	Port 10
		This is a standard, 6-bit, bidirectional port that is multiplexed with individually selectable special-function signals.
		Port 10 shares package pins with the following signals: P10.0/SC0, P10.1/SD0, P10.2/SC1, P10.3/SD1, P10.4/EPA16, and P10.5.
P11.7:0	I/O	Port 11
		This is a standard, 8-bit, bidirectional port that is multiplexed with individually selectable special-function signals.
		P11.7:0 share package pins with PWM7:0.
P12.4:0	I/O	Port 12
1 12.1.0	1,0	This is a memory-mapped, 5-bit, bidirectional port. P12.2:0 select the test-ROM execution mode.
PLLEN	I	Phase-locked Loop Enable
		This active-high input pin enables the on-chip clock doubler.
		This pin must be held low when entering on-circuit emulation (ONCE) mode.
PWM7:0	0	Pulse Width Modulator Outputs
		These are PWM output pins with high-current drive capability.
		PWM7:0 share package pins with P11.7:0.

#### Table 4. Signal Descriptions (Sheet 5 of 8)

#### Name Type Description RD# 0 Read Read-signal output to external memory. RD# is asserted only during external memory reads. RD# shares a package pin with P5.3. READY L Ready Input This active-high input signal is used to lengthen external memory cycles for slow memory by generating wait states in addition to the wait states that are generated internally. When READY is high, CPU operation continues in a normal manner with wait states inserted as programmed in the chip configuration registers or the chip-select x bus control register. READY is ignored for all internal memory accesses. READY shares a package pin with P5.6. I/O RESET# Reset A level-sensitive reset input to and open-drain system reset output from the microcontroller. Either a falling edge on RESET# or an internal reset turns on a pull-down transistor connected to the RESET# pin for 16 state times. In the powerdown and idle modes, asserting RESET# causes the chip to reset and return to normal operating mode. After a device reset, the first instruction fetch is from FF2080H (or 1F2080H in external memory). RPD I Return from Powerdown Timing pin for the return-from-powerdown circuit. If your application uses powerdown mode, connect a capacitor between RPD and $V_{ss}$ if **either** of the following conditions are true. the internal oscillator is the clock source the phase-locked loop (PLL) circuitry is enabled (see PLLEN signal description) The capacitor causes a delay that enables the oscillator and PLL circuitry to stabilize before the internal CPU and peripheral clocks are enabled. The capacitor is not required if your application uses powerdown mode and if both of the following conditions are true. an external clock input is the clock source the phase-locked loop circuitry is disabled If your application does not use powerdown mode, leave this pin unconnected. RPD shares a package pin with P5.7. **RXD1:0** I/O Receive Serial Data 0 and 1 In modes 1, 2, and 3, RXD0 and 1 receive serial port input data. In mode 0, they functions as either inputs or open-drain outputs for data. RXD0 shares a package pin with P2.1 and RXD1 shares a package pin with P2.4 SC1:0 I/O Clock Pins for SSIO0 and 1 For handshaking mode, configure SC1:0 as open-drain outputs. This pin carries a signal only during receptions and transmissions. When the SSIO port is idle, the pin remains either high (with handshaking) or low (without handshaking). SC0 shares a package pin with P10.0, and SC1 shares a package pin with P10.2.

#### Table 4. Signal Descriptions (Sheet 6 of 8)

Table 4. Signal Descriptions (Sneet 7 or 6)			
Name	Туре	Description	
SD1:0	I/O	Data Pins for SSIO0 and 1	
		These pins are the data I/O pins for SSIO0 and 1.	
		SD0 shares a package pin with P10.1, and SD1 shares a package pin with P10.1.	
T1CLK	I	Timer 1 External Clock	
		External clock for Timer 1.Timer 1 is programmable to increment or decement on the rising edge, the falling edge, or both rising and falling edges of T1CLK. T1CLK shares a package pin with P7.0 and EPA0.	
T2CLK	I	Timer 2 External Clock	
		External clock for timer 2. Timer 2 is programmable to increment or decement on the rising edge, the falling edge, or both rising and falling edges of T2CLK.	
		External clock for the serial I/O baud-rate generator input (program selectable).	
		T2CLK shares a package pin with P7.2 and EPA2.	
T3CLK	I	Timer 3 External Clock	
		External clock for timer 3. Timer 3 is programmable to increment or decement on the rising edge, the falling edge, or both rising and falling edges of T3CLK.	
		T3CLK shares a package pin with P7.4 and EPA4.	
T4CLK	I	Timer 4 External Clock	
		External clock for timer 4. Timer 2 is programmable to increment or decement on the rising edge, the falling edge, or both rising and falling edges of T4CLK. T4CLK shares a package pin with P7.6 and EPA6.	
T1RST	I	Timer 1 External Reset	
		External reset for timer 1. Timer 1 is programmable to reset on the rising edge, the falling edge, or both rising and falling edges of T1RST.	
		T1RST shares a package pin with P7.1 and EPA1.	
T2RST	I	Timer 2 External Reset	
		External reset for timer 2. Timer 2 is programmable to reset on the rising edge, the falling edge, or both rising and falling edges of T2RST.	
		T2RST shares a package pin with P7.3 and EPA3.	
T3RST	I	Timer 3 External Reset	

#### Table 4. Signal Descriptions (Sheet 7 of 8)

		External reset for timer 2. Timer 2 is programmable to reset on the rising edge, the falling edge, or both rising and falling edges of T2RST. T2RST shares a package pin with P7.3 and EPA3.
T3RST	I	Timer 3 External Reset
		External reset for timer 3. Timer 3 is programmable to reset on the rising edge, the falling edge, or both rising and falling edges of T3RST.
		T3RST shares a package pin with P7.5 and EPA5.
T4RST	I	Timer 4 External Reset
		External reset for timer 4. Timer 4 is programmable to reset on the rising edge, the falling edge, or both rising and falling edges of T4RST.
		T4RST shares a package pin with P7.6 and EPA6.
TMODE#	I	Test-Mode Entry
		If this pin is held low during reset, the device will enter a test mode. The value of several other pins defines the actual test mode. All test modes, except test-ROM execution, are reserved for Intel factory use. If you choose to configure this signal as an input, always hold it high during reset and ensure that your system meets the $V_{IH}$ specification to prevent inadvertent entry into test mode.
		TMODE# shares a package pin with P5.4 and BREQ#.

# **ADVANCE INFORMATION**

Name	Туре	Description
TXD1:0	0	Transmit Serial Data 0 and 1
		In serial I/O modes 1, 2, and 3, TXD0 and 1 transmit serial port output data. In mode 0, they are the serial clock output.
		TXD0 shares a package pin with P2.0 and TXD1 shares a package pin with P2.3.
V <sub>cc</sub>	PWR	Digital Supply Voltage
		Connect each V <sub>CC</sub> pin to the digital supply voltage.
V <sub>REF</sub>	PWR	Reference Voltage for the A/D Converter
		This pin also supplies operating voltage to the analog portion of the A/D con- verter.
V <sub>SS</sub>	GND	Digital Circuit Ground
		These pins supply ground for the digital circuitry. Connect each $V_{\rm SS}$ pin to ground through the lowest possible impedance path.
WR#	0	Write <sup>†</sup>
		This active-low output indicates that an external write is occurring. This signal is asserted only during external memory writes.
		WR# is multiplexed with P5.2 and WRL#.
		<sup>†</sup> The chip configuration register 0 (CCR0) determines whether this pin func- tions as WR# or WRL#. CCR0.2 = 1 selects WR#; CCR0.2 = 0 selects WRL#.
WRH#	0	Write High <sup>†</sup>
		During 16-bit bus cycles, this active-low output signal is asserted for high-byte writes and word writes to external memory. During 8-bit bus cycles, WRH# is asserted for all write operations.
		WRH# shares a package pin with P5.5 and BHE#.
		<sup>†</sup> The chip configuration register 0 (CCR0) determines whether this pin func- tions as BHE# or WRH#. CCR0.2 = 1 selects BHE#; CCR0.2 = 0 selects WRH#.
WRL#	0	Write Low <sup>†</sup>
		During 16-bit bus cycles, this active-low output signal is asserted for low-byte writes and word writes to external memory. During 8-bit bus cycles, WRL# is asserted for all write operations.
		WRL# shares a package pin with P5.2 and WR#.
		<sup>†</sup> The chip configuration register 0 (CCR0) determines whether this pin func- tions as WR# or WRL#. CCR0.2 = 1 selects WR#; CCR0.2 = 0 selects WRL#.
XTAL1	I	Input Crystal/Resonator or External Clock Input
		Input to the on-chip oscillator and the internal clock generators. The internal clock generators provide the peripheral clocks, CPU clock, and CLKOUT signal. When using an external clock source instead of the on-chip oscillator, connect the clock input to XTAL1. The external clock signal must meet the $V_{\rm IH}$ specification for XTAL1.
XTAL2	0	Inverted Output for the Crystal/Resonator
		Output of the on-chip oscillator inverter. Leave XTAL2 floating when the design uses an external clock source instead of the on-chip oscillator.

#### Table 4. Signal Descriptions (Sheet 8 of 8)

# ADVANCE INFORMATION

intel

### 5.0 ADDRESS MAP

#### Table 5. 8xC196EA Address Map (Sheet 1 of 2)

Hex Address	Description (Note 1, Note 2)	Addressing Modes
FFFFFF FF4000	External device (memory or I/O) connected to address/data bus	Indirect, indexed, extended
FF3FFF FF2400	Program memory (Note 3)	Indirect, indexed, extended
FF23FF FF2200	Program memory (Note 3)	Indirect, indexed, extended
FF21FF FF20C0	Special-purpose memory (PIH vectors; Note 3)	Indirect, indexed, extended
FF20BF FF2080	Program memory (Note 3); (After reset, the first instruction is fetched from FF2080H.)	Indirect, indexed, extended
FF207F FF2000	Special-purpose memory (CCBs, interrupt vectors, PTS vectors; Note 3)	Indirect, indexed, extended
FF1FFF FF1000	External device (memory or I/O) connected to address/data bus	Indirect, indexed, extended
FF0FFF FF0400	Internal code/data RAM (identically mapped from page 00H)	Indirect, indexed, extended
FF03FF FF0000	Reserved for in-circuit emulators	_
FEFFFF 1F0000	Overlaid memory (reserved for future devices); locations <i>x</i> F0000– <i>x</i> F03FFH are reserved for in-circuit emulators	Indirect, indexed, extended
1EFFFF 004000	External device (memory or I/O) connected to address/data bus	Indirect, indexed, extended
003FFF 002400	A copy of internal ROM (FF2400–FF3FFFH) if CCB1.2=0 External memory if CCB1.2=1	Indirect, indexed, extended
0023FF 002000	External device (memory or I/O) connected to address/data bus	Indirect, indexed, extended
001FFF 001FE0	Memory-mapped special-function registers (SFRs)	Indirect, indexed, extended
001FDF 001C00	Peripheral special-function registers (SFRs)	Indirect, indexed, extended, windowed direct
001BFF 001000	External device (memory or I/O) connected to address/data bus	Indirect, indexed, extended
000FFF 000400	Internal code/data RAM (identically mapped into page FFH)	Indirect, indexed, extended

#### NOTES:

1. Unless otherwise noted, write 0FFH to reserved memory locations and write 0 to reserved SFR bits.

2. The contents or functions of reserved locations may change in future device revisions, in which case a program that relies on one or more of these locations might not function properly.

3. External memory if EA# is low; internal ROM if EA# is high.

Table 5. 8xC196EA Address Map (Sheet 2 of 2)	

Hex Address	Description (Note 1, Note 2)	Addressing Modes
0003FF 000100	Upper register file (general-purpose register RAM)	Indirect, indexed, windowed direct
0000FF 00001A	Lower register file (general-purpose register RAM)	Direct, indirect, indexed
000019 000000	Lower register file (stack pointer and CPU SFRs)	Direct, indirect, indexed

#### NOTES:

- 1. Unless otherwise noted, write 0FFH to reserved memory locations and write 0 to reserved SFR bits.
- 2. The contents or functions of reserved locations may change in future device revisions, in which case a program that relies on one or more of these locations might not function properly.
- 3. External memory if EA# is low; internal ROM if EA# is high.



### 6.0 ELECTRICAL CHARACTERISTICS

#### ABSOLUTE MAXIMUM RATINGS<sup>†</sup>

Storage Temperature	-60°C to +150°C	
Supply Voltage with Respect to V <sub>ss</sub> Power Dissipation	0.5 V to +7.0 V	ľ
Power Dissipation	1.5 W	Ľ

#### **OPERATING CONDITIONS<sup>†</sup>**

T <sub>c</sub> (Case Temperature Under Bias)	40°C to +125°C
V <sub>CC</sub> (Digital Supply Voltage)	
V <sub>REF</sub> (Analog Supply Voltage)	4.5 V to 5.5 V
$F_{XTAL 1}$ (Input frequency for $V_{CC} = 4.5 \text{ V} - 1000 \text{ V}$	5.5 V)
(Note 1)	20 MHz to 40 MHz

NOTE:

1. This device is static and should operate below 1 Hz, but has been tested only down to 20 MHz.

**NOTICE**: This document contains information on products in the design phase of development. The specifications are subject to change without notice. Verify with your local Intel sales office that you have the latest datasheet before finalizing a design.

<sup>†</sup>**WARNING**: Stressing the device beyond the "Absolute Maximum Ratings" may cause permanent damage. These are stress ratings only. Operation beyond the "Operating Conditions" is not recommended and extended exposure beyond the "Operating Conditions" may affect device reliability.

### 6.1 DC Characteristics

Symbol	Parameter	Min	Typical (Note 1)	Max	Units	Test Conditions	
I <sub>CC</sub>	V <sub>cc</sub> supply current		120	135	mA	XTAL1 = 40 MHz V <sub>CC</sub> = 5.5 V Device in Reset	
I <sub>IDLE</sub>	Idle mode current		60	95	mA	XTAL1 = 40 MHz V <sub>CC</sub> = 5.5 V	
I <sub>PD</sub>	Powerdown mode current		50		μA	$V_{CC} = 5.5 V$	
I <sub>REF</sub>	A/D reference supply cur- rent			5	mA	$\begin{array}{l} \text{XTAL1} = 40 \text{ MHz} \\ \text{V}_{\text{CC}} = \text{V}_{\text{REF}} = 5.5 \text{ V} \\ \text{Device in Reset} \end{array}$	
ICRVCC	Code RAM V <sub>CC</sub> Supply Current			110	μA	V <sub>CC</sub> =5.5 V	
I <sub>INJD</sub>	Maximum injection current per port on bidirectional pins (Note 4)	-10		10	mA		

#### Table 6. DC Characteristics at $V_{CC}$ = 4.5 V – 5.5 V (Sheet 1 of 2)

#### NOTES:

- 1. Typical values are based on a limited number of samples and are not guaranteed. The values listed are at room temperature with  $V_{CC} = 5.0 \text{ V}$ .
- For P2.7:0, P3.7:0, P4.7:0, P5.7:0, P6.7:0, P10.3:0, P11.7:0, P12.4:0, AD15:0, EA#, RESET#, PLLEN, NMI, TDI, TCLK, ONCE#, and XTAL1.
- 3. For P7.7:0, P8.7:0, P9.7:0, and P10.5:4.
- 4. The maximum injection current is not tested. The device is designed to meet this specification.
- 5. Pin capacitance is not tested. This value is based on design simulations.

Table 6.	DC Characteristics at V <sub>CC</sub> = 4.5 V – 5.5 V	(Sheet 2 of 2)
1 4010 01		(011001 - 01 -)

Symbol	Parameter	Min	Typical (Note 1)	Max	Units	Test Conditions
ILI	Input leakage current (Standard inputs except analog inputs)	-10		10	μA	$V_{SS} < V_{IN} < V_{CC}$
I <sub>LI1</sub>	Input leakage current (analog inputs)	-300		300	nA	$V_{SS}$ + 100 mV < $V_{IN}$ < $V_{REF}$ – 100 mV
I <sub>IH</sub>	Input high current (NMI only)			175	μA	$NMI = V_{CC} = 5.5 V$
V <sub>IL1</sub>	Input low voltage (Note 2)	-0.5		0.3 V <sub>CC</sub>	V	
V <sub>IH1</sub>	Input high voltage (Note 2)	0.7 V <sub>CC</sub>		V <sub>CC</sub> + 0.5	V	
V <sub>IL2</sub>	Input low voltage (Note 3)	-0.5		0.4 V <sub>CC</sub>	V	
V <sub>IH2</sub>	Input high voltage (Note 3)	0.7 V <sub>CC</sub>		V <sub>CC</sub> + 0.5	V	
V <sub>OL1</sub>	Output low voltage (output configured as complemen- tary)			0.3 0.45 1.5	>>>	I <sub>OL</sub> = 200 μA I <sub>OL</sub> = 3.2 mA I <sub>OL</sub> = 7.0 mA
V <sub>OH1</sub>	Output high voltage (output configured as complemen- tary)	$V_{CC} - 0.3$ $V_{CC} - 0.7$ $V_{CC} - 1.5$			> > >	I <sub>OH</sub> = -200 μA I <sub>OH</sub> = -3.2 mA I <sub>OH</sub> = -7.0 mA
V <sub>OL2</sub>	Output low voltage in reset			0.5	V	I <sub>OL</sub> = 15 μΑ
I <sub>OH2</sub>	Output high current in reset	-30 -65 -75		-120 -240 -280	μΑ μΑ μΑ	$V_{OH2} = V_{CC} - 1.0V$ $V_{OH2} = V_{CC} - 2.5V$ $V_{OH2} = V_{CC} - 4.0V$
I <sub>OH3</sub>	Output high current in reset on Port 11	-5 -8 -10		-50 -110 -130	μΑ μΑ μΑ	$V_{OH3} = V_{CC} - 1.0V$ $V_{OH3} = V_{CC} - 2.5V$ $V_{OH3} = V_{CC} - 4.0V$
V <sub>OH2</sub>	Output high voltage in reset	$V_{CC} - 1$			V	I <sub>OH</sub> = -15 μA
V <sub>HYS</sub>	Hysteresis voltage on all inputs except XTAL1	700			mV	
C <sub>S</sub>	Pin Capacitance (any pin to V <sub>SS</sub> ) (Note 5)			10	pF	
R <sub>RST</sub>	Pull-up resistor on RESET# pin	9		95	kΩ	V <sub>CC</sub> = 5.5 V, V <sub>IN</sub> = 4.0 V

#### NOTES:

1. Typical values are based on a limited number of samples and are not guaranteed. The values listed are at room temperature with  $V_{CC}$  = 5.0 V.

2. For P2.7:0, P3.7:0, P4.7:0, P5.7:0, P6.7:0, P10.3:0, P11.7:0, P12.4:0, AD15:0, EA#, RESET#, PLLEN, NMI, TDI, TCLK, ONCE#, and XTAL1.

3. For P7.7:0, P8.7:0, P9.7:0, and P10.5:4.

4. The maximum injection current is not tested. The device is designed to meet this specification.

5. Pin capacitance is not tested. This value is based on design simulations.

## 6.2 AC Characteristics — Multiplexed Bus Mode

Test Conditions: Capacitive load on all pins = 50 pF, Rise and Fall Times = 3 ns.

Symbol	Parameter	Min	Max	Units
F <sub>XTAL1</sub>	Frequency on XTAL1, PLL in 1x mode	20	40	MHz (1, 8)
	Frequency on XTAL1, PLL in 2x mode	10	20	MHz ( <mark>8</mark> )
f	Operating frequency, f = F <sub>XTAL1</sub> ; PLL in 1x mode		10	
	Operating frequency, f = 2F <sub>XTAL1</sub> ; PLL in 2x mode	20	40	MHz (8)
t	Period, t = 1/f	25	50	ns
T <sub>AVDV</sub>	Address Valid to Input Data Valid		3t – 40	ns (2)
T <sub>RLDV</sub>	RD# Low to Input Data Valid		t – 18	ns (2)
T <sub>CHDV</sub>	CLKOUT High to Input Data valid		2t – 35	ns ( <mark>9</mark> )
T <sub>RHDZ</sub>	RD# High to Input Data Float		t + 5	ns
T <sub>RXDX</sub>	Data Hold after RD# Inactive	0		ns
T <sub>XHCH</sub>	XTAL1 Rising Edge to CLKOUT High or Low	3	50	ns ( <mark>9</mark> )
T <sub>CLCL</sub>	CLKOUT Cycle Time	2	2t	
T <sub>CHCL</sub>	CLKOUT High Period	t – 10	t + 10	ns ( <mark>9</mark> )
T <sub>CLLH</sub>	CLKOUT Falling to ALE Rising	- 10	10	ns ( <mark>9</mark> )
T <sub>LLCH</sub>	ALE Falling to CLKOUT Rising	- 10	10	ns ( <mark>9</mark> )
T <sub>LHLH</sub>	ALE Cycle Time	4	t	ns (2)
T <sub>LHLL</sub>	ALE High Period	t – 10	t + 10	ns
T <sub>AVLL</sub>	Address Setup to ALE Low	t – 15		ns
T <sub>LLAX</sub>	Address Hold after ALE Low	t – 15		ns
T <sub>LLRL</sub>	ALE Low to RD# Low	t – 15		ns
T <sub>RLCL</sub>	RD# Low to CLKOUT Low	- 10	10	ns ( <mark>9</mark> )
T <sub>RLRH</sub>	RD# Low to RD# High	t – 12		ns (2)
T <sub>RHLH</sub>	RD# High to ALE Rising	t – 5	t + 15	ns (3)

#### NOTES:

- 1. 20 MHz is the maximum input frequency when using an external crystal oscillator; however, 40 MHz can be applied with an external clock source.
- 2. If wait states are used, add  $2t \times n$ , where n = number of wait states.
- 3. Assuming back-to-back bus cycles.
- 4. When forcing wait states using the BUSCON register, add  $2t \times n$ .
- 5. Exceeding the maximum specification causes additional wait states.
- 6. 8-bit bus only.
- 7. The first falling edge of READY is not synchronized to a CLKOUT edge; therefore, one programmed wait state is required.
- 8. Device is static by design but has been tested only down to 20 MHz.
- 9. Assumes CLKOUT is operating in divide-by-two mode (f/2).

Symbol	Parameter	Min	Max	Units
T <sub>RLAZ</sub>	RD# Low to Address Float		5	ns
T <sub>LLWL</sub>	ALE Low to WR# Low	t – 12		ns
T <sub>QVWH</sub>	Data Stable to WR# Rising Edge	t – 14		ns (2)
T <sub>CHWH</sub>	CLKOUT High to WR# Rising Edge	- 10	10	ns (9)
T <sub>WLWH</sub>	WR# Low to WR# High	t – 10		ns (2)
T <sub>WHQX</sub>	Data Hold after WR# High	t – 20		ns
T <sub>WHLH</sub>	WR# High to ALE High	t – 15	t + 10	ns
T <sub>WHBX</sub>	BHE#, INST Hold after WR# High	t – 4		ns
T <sub>WHAX</sub>	AD15:8, CS <i>x</i> # Hold after WR# High	t – 4		ns ( <mark>6</mark> )
T <sub>RHBX</sub>	BHE#, INST Hold after RD# High	t – 5		ns
T <sub>RHAX</sub>	AD15:8, CSx# Hold after RD# High	t – 5		ns ( <mark>6</mark> )
T <sub>WHSH</sub>	A20:0, CS <i>x</i> # Hold after WR# High	0		ns
T <sub>RHSH</sub>	A20:0, CS <i>x</i> # Hold after RD# High	0		ns
T <sub>AVYV</sub>	AD15:0 Valid to READY Setup		2t - 40	ns (4)
T <sub>CLYX</sub>	READY Hold after CLKOUT Low	0	2t - 40	ns (5, 7, 9)
T <sub>YLYH</sub>	Non-READY Time	No Upp	er Limit	ns

Table 7. AC Characteristics, Multiplexed Bus Mode (Sheet 2 of 2)

#### NOTES:

- 1. 20 MHz is the maximum input frequency when using an external crystal oscillator; however, 40 MHz can be applied with an external clock source.
- 2. If wait states are used, add  $2t \times n$ , where n = number of wait states.
- 3. Assuming back-to-back bus cycles.
- 4. When forcing wait states using the BUSCON register, add  $2t \times n$ .
- 5. Exceeding the maximum specification causes additional wait states.
- 6. 8-bit bus only.
- 7. The first falling edge of READY is not synchronized to a CLKOUT edge; therefore, one programmed wait state is required.
- 8. Device is static by design but has been tested only down to 20 MHz.
- 9. Assumes CLKOUT is operating in divide-by-two mode (f/2).

			Signals				Conditions
Α†	Address	L	ALE	W	WR#, WRH#, WRL#	Н	High
В	BHE#	Q	Output Data	Х	XTAL1	L	Low
С	CLKOUT	R	RD#	Y	READY	V	Valid
D	Input Data	S	CS <i>x</i> #			Х	No Longer Valid
				•		Ζ	Floating

#### Table 8. AC Timing Symbol Definitions

<sup>†</sup> Address bus (demultiplexed mode) or address/data bus (multiplexed mode)

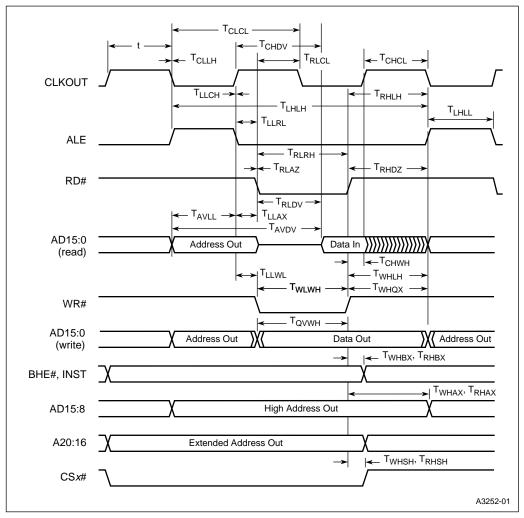


Figure 4. System Bus Timing Diagram (Multiplexed Bus Mode)

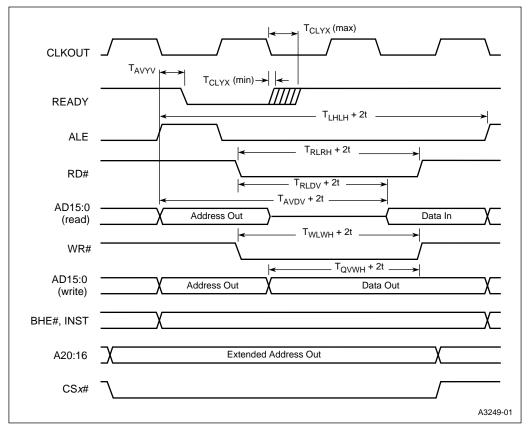


Figure 5. READY Timing Diagram (Multiplexed Bus Mode)

## 6.3 AC Characteristics — Demultiplexed Bus Mode

Test Conditions: Capacitive load on all pins = 50 pF, Rise and Fall Times = 3 ns.

Symbol	Parameter	Min	Max	Units
F <sub>XTAL1</sub>	Frequency on XTAL1, PLL in 1x mode	20	40	MHz (1,8)
	Frequency on XTAL1, PLL in 2x mode	10	20	MHz (8)
f	Operating frequency, f = F <sub>XTAL1</sub> ; PLL in 1x mode		40	N41-
	Operating frequency, f = 2F <sub>XTAL1</sub> ; PLL in 2x mode	20	40	Mhz
t	Period, t = 1/f	25	50	ns
T <sub>AVDV</sub>	Address Valid to Input Data Valid		4t - 23	ns (2)
T <sub>RLDV</sub>	RD# Low to Input Data Valid		3t – 25	ns (2)
T <sub>AVWL</sub>	Address Valid to WR# Low	t		ns
T <sub>AVRL</sub>	Address Valid to RD# Low	t – 8		ns
T <sub>SLDV</sub>	Chip Select Low to Data Valid		4t – 27	ns (2)
T <sub>CHDV</sub>	CLKOUT Rising Edge to Input Data Valid		2t – 25	ns ( <mark>9</mark> )
T <sub>RHDZ</sub>	RD# High to Input Data Float		t - 5	ns
T <sub>RHRL</sub>	Read High to Next Read Low	t – 5		ns
T <sub>RXDX</sub>	Data Hold after RD# Inactive	0		ns
T <sub>XHCH</sub>	XTAL1 High to CLKOUT High or Low	10	35	ns ( <mark>9</mark> )
T <sub>CLCL</sub>	CLKOUT Cycle Time	2t		ns ( <mark>9</mark> )
T <sub>CHCL</sub>	CLKOUT High Period	t – 10	t + 10	ns ( <del>9</del> )
T <sub>CLLH</sub>	CLKOUT Falling ALE Rising	- 10	10	ns ( <mark>9</mark> )
T <sub>RLCL</sub>	RD# Low to CLKOUT Low	- 5	5	ns ( <del>9</del> )
T <sub>RLRH</sub>	RD# Low to RD# High	3t – 12		ns (2)
T <sub>RHLH</sub>	RD# Rising to ALE Rising	t - 4	t + 12	ns ( <mark>3</mark> )
T <sub>WLCL</sub>	WR# Low to CLKOUT Falling	- 12	5	ns (9)
T <sub>QVWH</sub>	Data Stable to WR# Rising Edge	3t – 18		ns (3)

Table 9. AC Characteristics, Demultiplexed Bus Mode (Sheet 1 of 2	2)
---	----

#### NOTES:

1. 20 MHz is the maximum input frequency when using an external crystal oscillator; however, 40 MHz can be applied with an external clock source.

- 2. If wait states are used, add  $2t \times n$ , where n = number of wait states.
- 3. Assuming back-to-back bus cycles.
- 4. When forcing wait states using the BUSCON register, add  $2t \times n$ .
- 5. Exceeding the maximum specification causes additional wait states.
- 6. 8-bit bus only.
- 7. The first falling edge of READY is not synchronized to a CLKOUT edge; therefore, one programmed wait state is required.
- 8. Device is static by design but has been tested only down to 20 MHz.
- 9. Assumes CLKOUT is operating in divide-by-two mode (f/2).

Symbol	Parameter	Min	Max	Units
T <sub>CHWH</sub>	CLKOUT High to WR# Rising Edge	- 5	10	ns ( <mark>9</mark> )
T <sub>WLWH</sub>	WR# Low to WR# High	3t – 15		ns (2)
T <sub>WHQX</sub>	Data Hold after WR# Rising Edge	t	t + 15	ns
T <sub>WHBX</sub>	BHE#, INST Hold after WR# High	t		ns
T <sub>WHAX</sub>	A20:0, CS <i>x</i> # Hold after WR# High	0		ns
T <sub>RHBX</sub>	BHE#, INST Hold after RD# High	t		ns
T <sub>RHAX</sub>	A20:0, CSx# Hold after RD# High	0		ns
T <sub>AVYV</sub>	A20:0 Valid to READY Setup		3t – 25	ns (4)
T <sub>CLYX</sub>	READY Hold after CLKOUT Low	0	2t – 28	ns (5, 7,9)
$T_{YLYH}$	Non READY Time	No Upper Limit		ns

Table 9. AC Characteristics, Demultiplexed Bus Mode (Sheet 2 of 2)

NOTES:

- 1. 20 MHz is the maximum input frequency when using an external crystal oscillator; however, 40 MHz can be applied with an external clock source.
- 2. If wait states are used, add  $2t \times n$ , where n = number of wait states.
- 3. Assuming back-to-back bus cycles.
- 4. When forcing wait states using the BUSCON register, add  $2t \times n$ .
- 5. Exceeding the maximum specification causes additional wait states.
- 6. 8-bit bus only.
- 7. The first falling edge of READY is not synchronized to a CLKOUT edge; therefore, one programmed wait state is required.
- 8. Device is static by design but has been tested only down to 20 MHz.
- 9. Assumes CLKOUT is operating in divide-by-two mode (f/2).

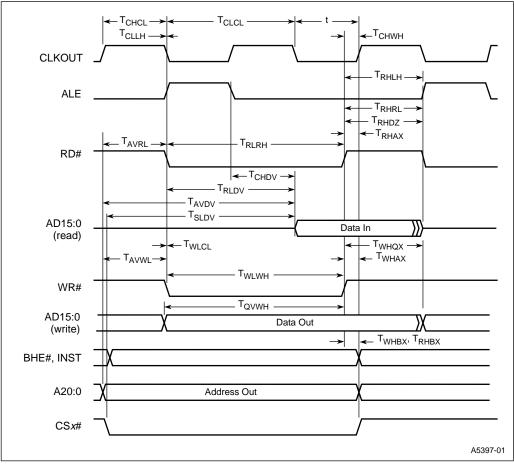


Figure 6. System Bus Timing Diagram (Demultiplexed Bus Mode)

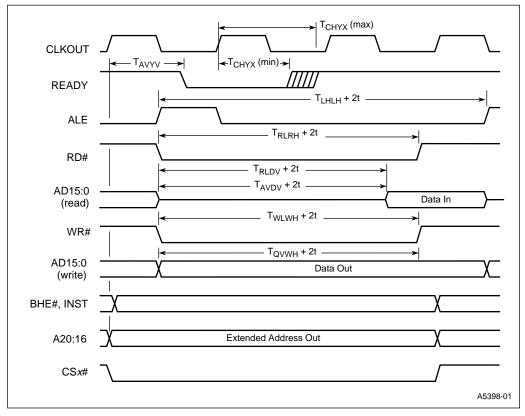


Figure 7. READY Timing Diagram (Demultiplexed Bus Mode)



### 6.4 Deferred Bus Timing Mode

Deferred Bus Cycle Mode: This bus mode (enabled by setting CCB1.5) reduces bus contention when using the 8xC196EA in demultiplexed mode with

slow memories. As shown in Figure 8, a delay of 2t occurs in the first bus cycle following a chip-select output change and the first write cycle following a read cycle.

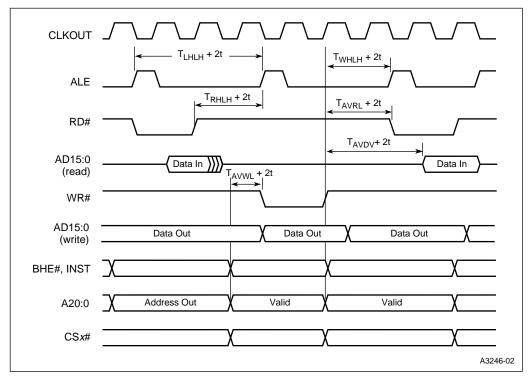


Figure 8. Deferred Bus Mode Timing Diagram

### 8xC196EA — AUTOMOTIVE

### 6.5 AC Characteristics — Serial Port, Shift Register Mode

Symbol	Parameter	Min	Max	Units
T <sub>XLXL</sub>	Serial Port Clock period SP_BAUD $\ge x002H$ SP_BAUD $= x001H^{\dagger}$	6t 4t		ns ns
T <sub>XLXH</sub>	Serial Port Clock falling edge to rising edge SP_BAUD $\ge x002H$ SP_BAUD $= x001H^{\dagger}$	4t – 27 2t – 27	4t + 27 2t + 27	ns ns
T <sub>QVXH</sub>	Output data setup to clock high	4t - 30		ns
T <sub>XHQX</sub>	Output data hold after clock high	2t - 30		ns
T <sub>XHQV</sub>	Next output data valid after clock high		2t + 30	ns
T <sub>DVXH</sub>	Input data setup to clock high	2t + 30		ns
T <sub>XHDX</sub>	Input data hold after clock high	0		ns
T <sub>XHQZ</sub>	Last clock high to output float		t + 30	ns

Table 10.	Serial Port	Timing — Shift	Register Mode
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<sup>†</sup> The minimum baud-rate (SP\_BAUD) register value for receive is *x*002H and the minimum baud-rate (SP\_BAUD) register value for transmit is *x*001H.

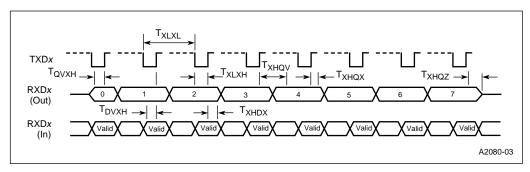


Figure 9. Serial Port Waveform — Shift Register Mode

## 6.6 AC Characteristics — Synchronous Serial Port

Symbol	Parameter	Min	Max	Units
T <sub>CLCL</sub>	Synchronous Serial Port Clock period	8t		ns
T <sub>CLCH</sub>	Synchronous Serial Port Clock falling edge to rising edge	4t		ns
T <sub>D1DV</sub>	Setup time for MSB output	2t		ns
T <sub>CXDV</sub>	Setup time for D6:0 output		3t + 20	ns
T <sub>CXDX</sub>	Output data hold after clock low	t	3t + 20	ns
T <sub>DVCX</sub>	Setup time for input data	10		ns
T <sub>DXCX</sub>	Input data hold after clock high	t + 5		ns

#### Table 11. Synchronous Serial Port Timing

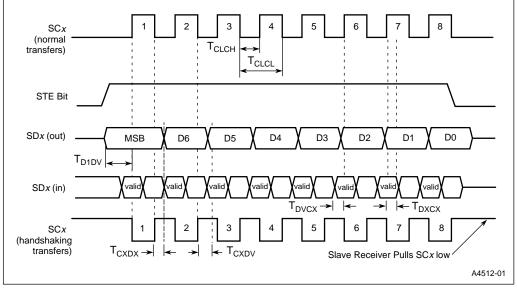


Figure 10. Synchronous Serial Port

#### 8xC196EA — AUTOMOTIVE



### 6.7 A/D Sample and Conversion Times

Two parameters, sample time and conversion time, control the time required for an A/D conversion. The sample time is the length of time that the analog input voltage is actually connected to the sample capacitor. If this time is too short, the sample capacitor will not charge completely. If the sample time is too long, the input voltage may change and cause conversion errors. The conversion time is the length of time required to convert the analog input voltage stored on the sample capacitor to a digital value. The conversion time must be long enough for the comparator and circuitry to settle and resolve the voltage. Excessively long conversion times allow the sample capacitor to discharge, degrading accuracy.

The AD\_TIME register programs the A/D sample and conversion times. Use the  $T_{SAM}$  and  $T_{CONV}$  specifications in Table 12 and Table 14 to determine appropriate values for SAM and CONV; otherwise, erroneous conversion results may occur.

When the SAM and CONV values are known, write them to the AD\_TIME register. Do not write to this register while a conversion is in progress; the results are unpredictable.

Use the following formulas to determine the SAM and CONV values.

SAM = 
$$\frac{T_{SAM} \times f - 2}{8}$$
 CONV =  $\left[\frac{T_{CONV} \times f - 3}{2 \times B}\right] - 1$ 

where:

SAM	equals a number, 1 to 7
CONV	equals a number, 2 to 31
$T_{SAM}$	is the sample time, in μsec (Table 12 and Table 14)
$T_{CONV}$	is the conversion time, in μsec (Table 12 and Table 14)
f	is the operating frequency, in MHz
В	is the number of bits to be converted (8 or 10)

At 40 Mhz, to meet T<sub>SAM</sub> and T<sub>CONV</sub> minimum specifications:

10-bit mode:	SAM= $[5, 6, 7] \Rightarrow T_{SAM} \ge 1 \mu s$
	$CONV = [18, 19, 20,, 31] \Rightarrow T_{CONV} \ge 10 \mu$

8-bit mode: SAM=  $[5, 6, 7] \Rightarrow T_{SAM} \ge 1 \mu s$ CONV=  $[23, 24, ..., 31] \Rightarrow T_{CONV} \ge 10 \mu s$ 



#### 6.7.1 AC CHARACTERISTICS - A/D CONVERTER, 10-BIT MODE

Symbol	Description	Min	Max	Units	Notes
Т <sub>С</sub>	Case Temperature	- 40	+ 125	°C	
V <sub>CC</sub>	Digital Supply Voltage	4.50	5.50	V	
V <sub>REF</sub>	Analog Supply Voltage	4.50	5.50	V	2
T <sub>SAM</sub>	Sample Time	1.0		μs	3
T <sub>CONV</sub>	Conversion Time	10.0	15.0	μs	3

#### Table 12. 10-bit A/D Operating Conditions (1)

#### NOTES:

1. ANGND and  $V_{SS}$  should nominally be at the same potential.

- V<sub>REF</sub> must not exceed V<sub>CC</sub> by more than + 0.5 V because V<sub>REF</sub> supplies both the resistor ladder and the analog portion of the converter and input port pins.
- Program the AD\_TIME register to meet the T<sub>SAM</sub> and T<sub>CONV</sub> specifications.

Parameter	Typical (2)	Min	Max	Units (1)	Notes
Resolution		1024 10	1024 10	Levels Bits	
Absolute Error		0	± 3.0	LSBs	
Full-scale Error	$0.25\pm0.5$			LSBs	
Zero Offset Error	$0.25\pm0.5$			LSBs	
Nonlinearity	$1.0\pm2.0$		± 3.0	LSBs	
Differential Nonlinearity		- 0.75	+ 0.75	LSBs	
Channel-to-channel Matching	± 0.1	0	± 1.0	LSBs	
Repeatability	± 0.25	0		LSBs	
Temperature Coefficients: Offset Full-scale Differential Nonlinearity	0.009 0.009 0.009			LSB/C LSB/C LSB/C	
Off-isolation		- 60		dB	2, 3, 4

#### Table 13. 10-bit Mode A/D Characteristics Over Specified Operating Conditions (7) (Sheet 1 of 2)

#### NOTES:

- 1. An *LSB*, as used here, has a value of approximately 5 mV.
- 2. Most parts will meet these values at 25°C, but they are not tested or guaranteed.
- 3. DC to 100 KHz.
- 4. Multiplexer break-before-make guaranteed.
- 5. Resistance from device pin, through internal multiplexer, to sample capacitor.
- Applying voltage beyond these specifications will degrade the accuracy of other channels being converted.
- 7. All conversions were performed with processor in idle mode.
- 8.  $100 \text{ mV} < \text{V}_{\text{IN}} < \text{V}_{\text{REF}} 100 \text{ mV}.$



#### Table 13. 10-bit Mode A/D Characteristics Over Specified Operating Conditions (7) (Sheet 2 of 2)

Parameter	Typical (2)	Min	Max	Units (1)	Notes
Feedthrough	- 60			dB	2, 3
V <sub>CC</sub> Power Supply Rejection	- 60			dB	2, 3
Input Series Resistance		750	1.2K	Ω	5
Voltage on Analog Input Pin		ANGND	V <sub>REF</sub>	V	6
Sampling Capacitor	3.0			pF	
DC Input Leakage	± 100	- 300	300	nA	8

#### NOTES:

- 1. An *LSB*, as used here, has a value of approximately 5 mV.
- 2. Most parts will meet these values at 25°C, but they are not tested or guaranteed.
- 3. DC to 100 KHz.
- 4. Multiplexer break-before-make guaranteed.
- 5. Resistance from device pin, through internal multiplexer, to sample capacitor.
- 6. Applying voltage beyond these specifications will degrade the accuracy of other channels being converted.
- 7. All conversions were performed with processor in idle mode.
- 8.  $100 \text{ mV} < \text{V}_{\text{IN}} < \text{V}_{\text{REF}} 100 \text{ mV}.$

#### 6.7.2 AC CHARACTERISTICS — A/D CONVERTER, 8-BIT MODE

#### Table 14. 8-bit A/D Operating Conditions (1)

Symbol	Description	Min	Max	Units	Note s
Т <sub>С</sub>	Case Temperature	- 40	+ 125	°C	
v <sub>CC</sub>	Digital Supply Voltage	4.50	5.50	V	
V <sub>REF</sub>	Analog Supply Voltage	4.50	5.50	V	2
T <sub>SAM</sub>	Sample Time	1.0		μs	3
T <sub>CONV</sub>	Conversion Time	8.0	15.0	μs	3

#### NOTES:

- 1. ANGND and V<sub>SS</sub> should nominally be at the same potential.
- V<sub>REF</sub> must not exceed V<sub>CC</sub> by more than + 0.5 V because V<sub>REF</sub> supplies both the resistor ladder and the analog portion of the converter and input port pins.
- 3. Program the AD\_TIME register to meet the T<sub>SAM</sub> and T<sub>CONV</sub> specifications.



Typical (2)	Min	Max	Units (1)	Notes
	256 8	256 8	Levels Bits	
	0	± 1.0	LSBs	
± 0.5			LSBs	
± 0.5			LSBs	
	0	± 1.0	LSBs	
	- 0.5	+ 0.5	LSBs	
	0	± 1.0	LSBs	
± 0.25	0		LSBs	
0.003 0.003 0.003			LSB/°C LSB/°C LSB/°C	
	- 60		dB	2, 3, 4
- 60			dB	2, 3
- 60			dB	2, 3
	750	1.2K	Ω	5
	ANGND	V <sub>REF</sub>	V	6
3.0			pF	
±100	- 300	300	nA	8
	± 0.5 ± 0.5 ± 0.5 ± 0.25 0.003	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{ c c c c c c c } & 256 & 8 & 8 \\ \hline & 0 & \pm 1.0 \\ \hline \pm 0.5 & & & \\ \hline \pm 0.5 & & & \\ \hline \pm 0.5 & & & \\ \hline & 0 & \pm 1.0 \\ \hline & -0.5 & \pm 0.5 \\ \hline & 0 & \pm 1.0 \\ \hline & -0.5 & \pm 0.5 \\ \hline & 0 & \pm 1.0 \\ \hline & -0.5 & & 0 \\ \hline & 0.003 & & & \\ \hline & 0.003 & & \\ \hline & $	$\begin{array}{c c c c c c c c c c c c c c c c c c c $

Table 15.	8-bit Mode	A/D Characteristics	Sover Specified	Operating	g Conditions (7	7)

#### NOTES:

1. An LSB, as used here, has a value of approximately 20 mV.

2. Most parts will need these values at 25°C, but they are not tested or guaranteed.

- 3. DC to 100 KHz.
- 4. Multiplexer break-before-make guaranteed.
- 5. Resistance from device pin, through internal multiplexer, to sample capacitor.
- 6. Applying voltage beyond these specifications will degrade the accuracy of other channels being converted.
- 7. All conversions were performed with processor in idle mode.
- 8.  $100 \text{ mV} < \text{V}_{\text{IN}} < \text{V}_{\text{REF}} 100 \text{ mV}.$

### 6.8 External Clock Drive

Table 16. External Clock Drive

Symbol	Parameter	Min	Max	Units
1/T <sub>XLXL</sub>	Oscillator Frequency (F <sub>XTAL1</sub> )	10	40 (1)	MHz (2)
T <sub>XLXL</sub>	Oscillator Period (T <sub>XTAL1</sub> )	25	100	ns
T <sub>XHXX</sub>	High Time	0.35T <sub>XTAL1</sub>	0.65T <sub>XTAL1</sub>	ns
T <sub>XLXX</sub>	Low Time	0.35T <sub>XTAL1</sub>	0.65T <sub>XTAL1</sub>	ns
T <sub>XLXH</sub>	Rise Time		10	ns
T <sub>XHXL</sub>	Fall Time		10	ns

#### NOTES:

1. 20 MHz is the maximum input frequency when using an external crystal oscillator; however, 40 MHz can be applied with an external clock source.

2. These values represent PLL-bypass mode.

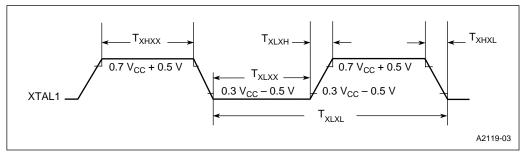
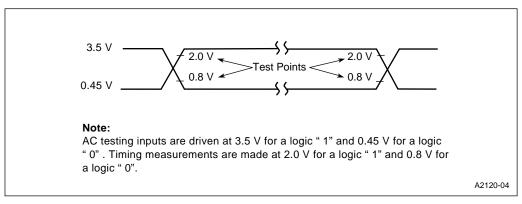
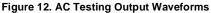


Figure 11. External Clock Drive Waveforms

### 6.9 Test Output Waveforms





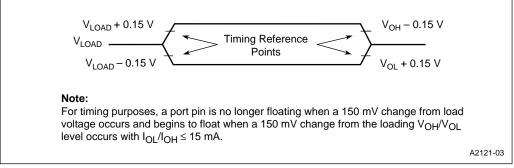


Figure 13. Float Waveforms During 5.0 Volt Testing

### 7.0 THERMAL CHARACTERISTICS

All thermal impedance data is approximate for static air conditions at 1 W of power dissipation. Values change depending on operating conditions and the application. The Intel *Packaging Handbook* (order number 240800) describes Intel's thermal impedance test methodology. The *Components Quality and Reliability Handbook* (order number 210997) provides quality and reliability information.

Package Type	$\theta_{JA}$	θ <sub>JC</sub>
160-pin QFP	34°C/W	5°C/W

#### Table 17. Thermal Characteristics

### 7.1 8xC196EA Errata

The 8xC196EA may contain design defects or errors known as errata. Characterized errata that may cause the 8xC196EA's behavior to deviate from published specifications are documented in a specification update. Specification updates can be obtained from your local Intel sales office or from the World Wide Web (*www.intel.com*).

### 8.0 DATASHEET REVISION HISTORY

This datasheet is valid for devices with an "C" at the end of the topside field process order (FPO) number. Datasheets are changed as new device information becomes available. Verify with your local Intel sales office that you have the latest version before finalizing a design or ordering devices.

This is the -003 version of the datasheet. The following changes were made in this version:

ltem	Description
Data Sheet	Added 80C196EA device to heading. All device references changed to 8xC196EA.
Figure 1 on page -1	Revised drawing to reflect "8xC196EA".
Table 4 on page -7	A15:0 - Type - Changed "I/O" to "O" only.
	AD15:0 - Description - 8-bit Demultiplexed Mode: Added last para- graph "AD7:0 share package pins P3.7:0. AD15:8 share package pins P4.7:0."
	CRIN - Description: Changed "byte" to "bit".
	CROUT - Description: Changed "byte" to "bit".
	ONCE# - Description - 1st paragraph: Added second sentence "PLLEN must also be held low."
	PLLEN - Description: Added last paragraph "This pin must be held low when entering on-circuit emulation (ONCE) mode."
	T1CLK - Description: Removed sentence "External clock for the serial I/O baud-rate generator input (program selectable)."
	T2CLK - Description: Added sentence "External clock for the serial I/O baud-rate generator input (program selectable)."
	XTAL1 - Description: Corrected spelling "sourcel" to "source".
Table 6 on page -17	$I_{PD}:$ • Typical: Changed "20" to "50" • Max: Changed "50" to "blank" $I_{REF} - Max: Changed TBD to "5".$ $I_{CRVCC} - Added row.$ $I_{HO2:}$ • Min: Changed V <sub>OH2</sub> =V <sub>CC</sub> -2.5 V to "-65", V <sub>OH2</sub> =V <sub>CC</sub> -4.0 V to "-75" • Units: Changed all from "mA" to "µA" $I_{HO3}:$ • Parameter: Changed "Port 12" to "Port 11" • Min: Changed V <sub>OH3</sub> =V <sub>CC</sub> -1.0 V to "-5", V <sub>OH3</sub> =V <sub>CC</sub> -2.5 V to "-8", V <sub>OH3</sub> =V <sub>CC</sub> -4.0 V to "-10" • Units: Changed all from "mA" to "µA".

Table 18.	Revision	History	(rev.	002 -	003) (	Sheet 1	of 2)
14010 101						0	v,

Item	Description
Table 7 on page -19	F <sub>XTAL1</sub> - Min:
1 0	<ul> <li>1x mode changed from "15" to "20"</li> </ul>
	<ul> <li>2x mode changed from "8" to "10"</li> </ul>
	f - Min: Changed from "15" to "20".
	t - Max: Changed from "62.5" to "50".
	T <sub>RLRH</sub> - Min: Changed from "t-10" to "t-12".
	T <sub>CHWH</sub> - Max: Changed from "5" to "10".
	T <sub>WHQX</sub> - Min: Changed from "t-15" to "t-20".
	Note 1: "16 MHz" changed to "20 MHz".
Table 9 on page -23	F <sub>XTAL1</sub> - Min:
	<ul> <li>1x mode changed from "15" to "20"</li> </ul>
	<ul> <li>2x mode changed from "8" to "10"</li> </ul>
	f - Min: Changed from "15" to "20".
	t - Max: Changed from "62.5" to "50".
	T <sub>CHCL</sub> - Min: Changed from "t-5" to "t-10"; Max: Changed from "t+5" to "t+10".
	T <sub>CLLH</sub> - Min: Changed from "-5" to "-10"; Max: Changed from "5" to "10".
	T <sub>RLRH</sub> - Min: Changed from "3t-10" to "3t-12".
	T <sub>WLWH</sub> - Min: Changed from "3t-12" to "3t-15".
	T <sub>AVYV</sub> - Max: Changed from "3t-23" to "3t-25".
	Note 1: "16 MHz" changed to "20 MHz".
Table 11 on page -29	T <sub>D1DV</sub> - Symbol: Changed T <sub>D1VD</sub> " to "T <sub>D1DV</sub> ".
	T <sub>D1DV</sub> - Min: Changed TBD to "2t".
Figure 10 on page -29	Revised figure.
Table 13 on page -31	DC Input Leakage
	<ul> <li>Min - Changed "0" to "-300"</li> </ul>
	<ul> <li>Max - Removed "±" from "300"</li> </ul>
	Note 2: Changed "need" to "meet".
Table 15 on page -33	DC Input Leakage:
	<ul> <li>Typical: Added "±" to "100"</li> <li>Min: Changed "0" to "-300"</li> </ul>
Table 16 on page -34	1/T <sub>XLXL</sub> - Min: Changed "8" to "10".
	T <sub>XLXL</sub> :
	• Min: Changed "50" to "25"
	<ul> <li>Max: Changed "125" to "100"</li> </ul>
	Note 1:
	Changed "16 MHz" to "20 MHz"
	Changed "32 MHz" to "40 MHz"

#### Table 18. Revision History (rev. 002 - 003) (Sheet 2 of 2)

ltem	Description	
Data Sheet	Status changed from "Product Preview" to "Advance Information".	
Cover	The frequency designation was changed from 32 MHz to 40 MHz.	
"DC Characteristics" on page -17	The following DC characteristics specifications were either changed or added:	
	• I <sub>CC</sub> (max) • I <sub>OH2</sub> • I <sub>OH3</sub> • I <sub>IDLE</sub> (max)	
"AC Characteristics — Multiplexed Bus Mode" on page -19	The following AC characteristics <b>multiplexed</b> bus mode specifica- tions were changed:	
	$\begin{array}{cccc} \bullet & T_{CHCL}\left(max\right) & \bullet & T_{WHLH}\left(max\right) & \bullet & T_{LLAX}\left(min\right) \\ \bullet & T_{LLCH} & \bullet & T_{AVYV}\left(max\right) & \bullet & T_{RLDV}\left(max\right) \\ & (min/max) & \bullet & T_{CLYX}\left(max\right) \\ \bullet & T_{RLCL}\left(max\right) & \bullet & T_{WHQX}\left(min\right) \\ \bullet & T_{CHWH}\left(min\right) \end{array}$	
"AC Characteristics — Demultiplexed Bus Mode" on page -23	The following AC characteristics <b>demultiplexed</b> bus mode speci- fications were changed:	
	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	
"AC Characteristics — Demultiplexed Bus Mode" on page -23	The following AC characteristics <b>demultiplexed</b> bus mode specifications were removed:	
	• T <sub>LLCH</sub> • T <sub>LHLL</sub> • T <sub>WHLH</sub> • T <sub>LHLH</sub>	
Figure 6 on page -25	Address out line in the System Bus Timing Diagram (Demulti- plexed Bus Mode) was corrected from A20:16 to A20:0.	
Figure 5 on page -22	$\rm T_{CHYX}$ (max) timing was corrected in the Ready Timing Diagram to show the rising edge of READY after the falling edge of CLKOUT.	
HOLD#/HLDA# Timings	Section was removed, and all references to either HOLD# or HLDA# were removed.	
Table 11 on page -29	Synchronous Serial timing specifications changed in table.	
"A/D Sample and Conversion Times" on page -30	A/D sample and conversion times example added.	
Table 15 on page -33	Note 1 of the 8-bit mode A/D characteristics table changed to state 20 mV, instead of 5 mV.	

### Table 19. Revision History (rev. 001 - 002)

### 8xC196EA — AUTOMOTIVE

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#### Table 20. Revision History (rev. 001)

Item	Description
Table 17	Package thermal characteristics changed.