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Serially Interfaced, 4-Digit LED Driver AS1105

Key Features

- Cost effective version of AS1100 functionality for
- applications up to 4-Digits
- 10MHz Serial Interface
- Individual LED Segment Control
- Decode/No-Decode Digit Selection
- 20µA Low-Power Shutdown (Data Retained)
- Extremely low Operating Current 0.5mA in open loop
- Digital and Analog Brightness Control
- Display Blanked on Power-Up
- Drive Common-Cathode LED Display
- Software Reset¹
- **Optional External clock**
- 20 pin SO Packages

General Description

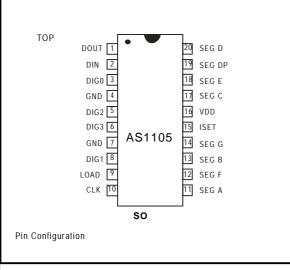
The AS1105 is an LED driver for 7 segment numeric displays of up to 4 digits. The AS1105 can be programmed via a conventional 4 wire serial interface. It includes a BCD code-B decoder, a multiplex scan circuitry, segment and display drivers and a 32 Bit memory. The memory is used to store the LED settings, so that continuous reprogramming is not necessary.

TOP SEG D DOUT 20 DIN 2 19 SEG DP DIG0 3 18 SEG E GND 4 17 SEG C

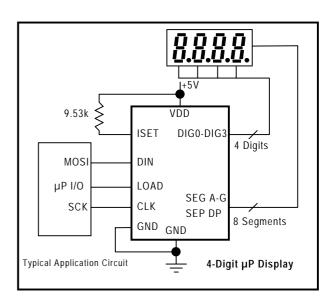
Every individual segment can be addressed and updated separately. Only one external resistor is required to set the current through the LED display. Brightness can be controlled either in an analog or digital way. The user can choose the internal code-B decoder to display numeric digits or to address each segment directly. The AS1105 features an extremely low shutdown current of only 20µA. and an operational current of less than 500µA. The number of visible digits can be programmed as well. The AS1105 can be reset by software and an external clock can be used. Several test modes support easy debugging. AS1105 is offered in a 20 SOIC package.

Applications

- Bar-Graph Displays
- Industrial Controllers
- Panel Meters
- LED Matrix Displays
- White Goods



¹ Software Reset and external clock are not supported by MAX7219



DATA SHEET

Absolute Maximum Ratings

Voltage (with respect to GND)	
VDD	-0.3V to 6V
DIN, CLK, LOAD	-0.3V to 6V
All Other Pins	-0.3V to (VDD +0.3V)
Current	
DIG0-DIG3 Sink Current	500mA
SEGA-G, DP Source Current	100mA
Continuous Power Dissipation (TA = +85°C)	
Wide SO (derate 11.8mW/°C above +70°C)	941mW
Operating Temperature Ranges (T _{MIN} to T _{MAX})	
AS1105xL	0°C to +70°C
AS1105xE	-40°C to +85°C
Storage Temperature Range	-65°C to +150°C
Package body temperature ²	+240°C

Electrical Characteristics

(VDD = 5V, R_{SET} = 9.53k Ω ±1%, T_A = T_{MIN} to T_{MAX} , unless otherwise noted.)

Parameter	Symbol	Conditions	Min	Тур	Max	Units
Operating Supply Voltage	VDD		4.0	5.0	5.5	V
Shutdown Supply Current	IDDsd	All digital inputs at VDD or GND, T _A = +25°C		20	50	μA
		R _{SET} = open circuit			500	μA
Operating Supply Current	IDD	All segments and decimal point on, $I_{SEG} = -40$ mA		330		mA
Display Scan Rate	fosc		500	800	1300	Hz
Digit Drive Sink Current	DIGIT	V _{OUT} = 0.65V	320			mA
Segment Drive Source Current	ISEG	$T_{A} = +25^{\circ}C, V_{OUT} = (VDD - 1V)$	-30	-40	-45	mA
Segment Drive Current Matching	ΔI_{SEG}			3.0		%
Digit Drive Source Current	DIGIT	Digit off, V _{DIGIT} = (VDD -0.3V)	-2			mA
Segment Drive Sink Current	SEG	Segment off, V _{SEG} = 0.3V	5			mA
Logic Inputs		· · · · · · · · · · · · · · · · · · ·				
Input Current DIN, CLK, LOAD	I _{IH} , I _{IL}	$V_{IN} = 0V \text{ or } VDD$	-1		1	μA
Logic High Input Voltage	VIH		3.5			V

² The reflow peak soldering temperature (body temperature) is specified according IPC/JEDEC J-STD-020B "Moisture/Reflow Sensitivity Classification for non-hermetic Solid State Surface Mount Devices".

Parameter	Symbol	Conditions	Min	Тур	Max	Units
Logic Low Input Voltage	VIL				0.8	V
Output High Voltage	Vон	DOUT, Isource = -1mA	VDD - 1			V
Output Low Voltage	Vol	DOUT, Isink = 1.6mA			0.4	V
Hysteresis Voltage	VI	DIN, CLK, LOAD		1		V
Timing Characteristics						
CLK Clock Period	tcp		100			ns
CLK Pulse Width High	tсн		50			ns
CLK Pulse Width Low	tc∟		50			ns
CLK Rise to LOAD Rise Hold	tсsн		0			ns
Time	ICSH		0			115
DIN Setup Time	tos		25			ns
DIN Hold Time	tdн		0			ns
Output Data Propagation Delay	tdo	$C_{LOAD} = 50 pF$			25	ns
LOAD Rising Edge to Next	t. s. s.v.		50			ns
Clock Rising Edge	tldck		50			115
Minimum LOAD Pulse High	tcsw		50			ns
Data-to-Segment Delay	tdspd				2.25	ms

Pin Description

Pin	Name	Function
1	DOUT	Serial data output for cascading drivers. The output is valid after 16.5 clock cycles. The output is never set to high impedance.
2	DIN	Data input. Data is programmed into the 16Bit shift register on the rising CLK edge
3,8,5,6	DIG0-DIG3	4 digit driver lines that sink the current from the common cathode of the display. In shutdown mode the AS1105 switches the outputs to VDD
4, 7	GND	both GND pins must be connected
9	LOAD	Strobe input. With the rising edge of the LOAD signal the 16 bit of serial data is latched into the register.
10	CLK	Clock input. The interface is capable to support clock frequencies up to 10MHz. The serial data is clocked into the internal shift register with the rising edge of the CLK signal. On the DOUT pin the data is applied with the falling edge of CLK.
11–14, 17–20	SEG A-G, DP	Seven segment driver lines including the decimal point. When a segment is turned off the output is connected to GND.
15	ISET	The current into I_{SET} determines the peak current through the segments and therefore the brightness.
16	VDD	Positive Supply Voltage (+5V)

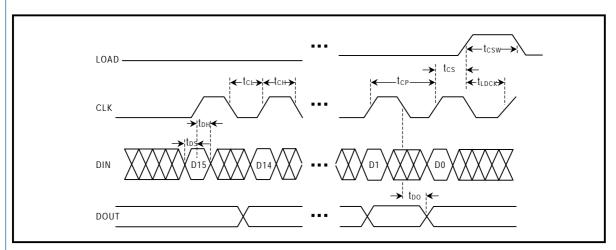


Figure 1: Timing diagram

D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
Х	Х	Х	Х		Addı	ress		MSB			D	ata			LSB

Table 1: Serial data format (16 bits)

Detailed Description

Serial-Addressing Modes

Programming of the AS1105 is done via the 4 wire serial interface. A programming sequence consists of 16-bit packages. The data is shifted into the internal 16 Bit register with the rising edge of the CLK signal. With the rising edge of the LOAD signal the data is latched into a digital or control register depending on the address. The LOAD signal must go to high after the 16th rising clock edge. The LOAD signal can also come later but just before the next rising edge of CLK, otherwise data would be lost. The content of the internal shift register is applied 16.5 clock cycles later to the DOUT pin. The data is clocked out at the falling edge of CLK. The Bits of the 16Bitprogramming package are described in table 1. The first 4 Bits D15-D12 are "don't care, D11-D8 contain the address and D7-D0 contain the data. The first bit is D15, the most significant bit (MSB). The exact timing is given in figure 1.

Digit and Control Registers

The AS1105 incorporates 12 registers, which are listed in Table 2. The digit and control registers are selected via the 4Bit address word. The 4 digit registers are realized with a

32bit memory. Each digit can be controlled directly without rewriting the whole contents. The control registers consist of decode mode, display intensity, number of scanned digits, shutdown, display test and reset/external clock register.

Shutdown Mode

The AS1105 features a shutdown mode, where it consumes only 20 μ A current. The shutdown mode is entered via a write to register 0Ch. Then all segment current sources are pulled to ground and all digit drivers are connected to VDD, so that nothing is displayed. All internal digit registers keep the programmed values. The shutdown mode can either be used for power saving or for generating a flashing display by repeatedly entering and leaving the shutdown mode. The AS1105 needs typically 250 μ s to exit the shutdown mode. During shutdown the AS1105 is fully programmable. Only the display test function overrides the shutdown mode.

Initial Power-Up

After powering up the system all register are reset, so that the display is blank. The AS1105 starts the shutdown mode. All registers should be programmed for normal operation. The default settings enable only scan of one digit, the internal decoder is disabled, data register and intensity register are set to the minimum value.

Decode-Mode Register

In the AS1105 a BCD decoder is included. Every digit can be selected via register 09h to be decoded. The BCD code consists of the numbers 0-9, E,H, L,P and -. In register 09h a logic high enables the decoder for the appropriate digit. In case that the decoder is bypassed (logic low) the data Bits D7-D0 correspond to the segment lines of the AS1105. In table 4 some possible settings for register 09h are shown. Bit D7, which corresponds to the decimal point, is not affected by the settings of the decoder. Logic high means that the decimal point is displayed. In table 5 the font of the Code B decoder is shown. In table 6 the correspondence of the register to the appropriate segments of a 7 segment display is shown (see figure 2)

Intensity Control and Interdigit Blanking

Brightness of the display can be controlled in an analog way by changing the external resistor (R_{SET}). The current, which flows between VDD and I_{SET} , defines the current that flows through the LEDs. The LED current is 100 times the I_{SET} current. The minimum value of R_{SET} should be 9.53k Ω , which corresponds to 40mA segment current. The brightness of the display can also be controlled digitally via register 0Ah. The brightness can be programmed in 16 steps and is shown in table 7. An internal pulse width modulator controls the intensity of the display.

Scan-Limit Register

The scan limit register 0Bh selects the number of digits displayed. When all 4 digits are displayed the update frequency is typically 800Hz. If the number of digits displayed is reduced, the update frequency is reduced as well. The frequency can be calculated using 8fOSC/N, where N is the number of digits. Since the number of displayed digits influences the brightness, the resistor R_{SET}

should be adjusted accordingly. Table 9 shows the maximum allowed current, when fewer than 4 digits are used. To avoid differences in brightness the scan limit register should not be used to blank portions of the display (leading zeros).

Register		Addr	ess			Hex
Register	D15-D12	D11	D10	D9	D8	Code
No-Op	Х	0	0	0	0	0xX0
Digit 0	Х	0	0	0	1	0xX1
Digit 1	Х	0	0	1	0	0xX2
Digit 2	Х	0	0	1	1	0xX3
Digit 3	Х	0	1	0	0	0xX4
Decode	х	1	0	0	1	0xX9
Mode	Χ	i	U	0		0,,,,,
Intensity	Х	1	0	1	0	0xXA
Scan Limit	Х	1	0	1	1	0xXB
Shutdown	Х	1	1	0	0	0xXC
Not used	Х	1	1	0	1	0xXD
Reset and	х	1	1	1	0	0xXE
ext. Clock	^	I	1		0	UNAL
Display	х	1	1	1	1	0xXF
Test	Λ	1				5771

Table 2: Register address map

	Address Code		Register Data						
Mode	(Hex)	D7	D6	D5	D4	D3	D2	D1	D0
Shutdown	0xXC	v	v	х	v	v	х	v	0
Mode	UXAC	^	^	^	^	^	^	^	0
Normal	0xXC	v	v	х	v	v	v	v	1
Operation	UNAC	^	^	^	^	^	^	^	1

Table 3: Shutdown register format (address (hex) = 0xXC)

Decode Mode			R	egist	er Dat	ta			Hex Code
Decode Mode	D7	D6	D5	D4	D3	D2	D1	D0	
No decode for digits 4-0	0	0	0	0	0	0	0	0	0x00
Code B decode for digit 0	0	0	0	0	0	0	0	1	0x01
No decode for digits 4–1	0	0	0	0	0	0	0	1	0.01
Code B decode for digits	0	0	0	0	1	1	1	1	0x0F
3–0	0	0	0	0			1	1	UXUF
Code B decode for digits	1	1	1	1	1	1	1	1	0xFF
4-0	'	'	1	1			1	1	UXEE

Table 4: Decode-mode register examples (address (hex) = 0xX9)

7-Segment		Reç	gister	Data					On	Segn	nents	= 1		
Character	D7*	D6-D4	D3	D2	D1	D0	DP*	Α	В	С	D	E	F	G
0		Х	0	0	0	0		1	1	1	1	1	1	0
1		Х	0	0	0	1		0	1	1	0	0	0	0
2		Х	0	0	1	0		1	1	0	1	1	0	1
3		Х	0	0	1	1		1	1	1	1	0	0	1
4		Х	0	1	0	0		0	1	1	0	0	1	1
5		Х	0	1	0	1		1	0	1	1	0	1	1
6		Х	0	1	1	0		1	0	1	1	1	1	1
7		Х	0	1	1	1		1	1	1	0	0	0	0
8		Х	1	0	0	0		1	1	1	1	1	1	1
9		Х	1	0	0	1		1	1	1	1	0	1	1
—		Х	1	0	1	0		0	0	0	0	0	0	1
E		Х	1	0	1	1		1	0	0	1	1	1	1
Н		Х	1	1	0	0		0	1	1	0	1	1	1
L		Х	1	1	0	1		0	0	0	1	1	1	0
Р		Х	1	1	1	0		1	1	0	0	1	1	1
blank		Х	1	1	1	1		0	0	0	0	0	0	0

Table 5: Code B font

*The decimal point is set by bit D7 = 1

		Register Data										
	D7	D6	D5	D4	D3	D2	D1	D0				
Corresponding Segment Line	DP	A	В	С	D	E	F	G				

Table 6: No-decode mode data bits and corresponding segment lines

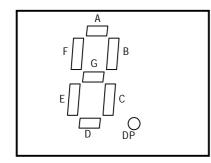


Figure 2: Standard 7-segment LED

Duty Cycle	D7	D6	D5	D4	D3	D2	D1	D0	Hex Code
1/32 (min on)	Х	Х	Х	Х	0	0	0	0	0xX0
3/32	Х	Х	Х	Х	0	0	0	1	0xX1
5/32	Х	Х	Х	Х	0	0	1	0	0xX2
7/32	Х	Х	Х	Х	0	0	1	1	0xX3
9/32	Х	Х	Х	Х	0	1	0	0	0xX4
11/32	Х	Х	Х	Х	0	1	0	1	0xX5
13/32	Х	Х	Х	Х	0	1	1	0	0xX6
15/32	Х	Х	Х	Х	0	1	1	1	0xX7
17/32	Х	Х	Х	Х	1	0	0	0	0xX8
19/32	Х	Х	Х	Х	1	0	0	1	0xX9
21/32	Х	Х	Х	Х	1	0	1	0	0xXA
23/32	Х	Х	Х	Х	1	0	1	1	0xXB
25/32	Х	Х	Х	Х	1	1	0	0	0xXC
27/32	Х	Х	Х	Х	1	1	0	1	0xXD
29/32	Х	Х	Х	Х	1	1	1	0	0xXE
31/32 (max on)	Х	Х	Х	Х	1	1	1	1	0xXF

Table 7: Intensity register format (address (hex) = 0xXA)

Coon Limit			R	egist	er Dai	a			Hex Code
Scan Limit	D7	D6	D5	D4	D3	D2	D1	D0	
Display digit 0 only	Х	Х	Х	Х	Х	0	0	0	0xX0
Display digits 0 & 1	Х	Х	Х	Х	Х	0	0	1	0xX1
Display digits 0 1 2	Х	Х	Х	Х	Х	0	1	0	0xX2
Display digits 0 1 2 3	Х	Х	Х	Х	Х	0	1	1	0xX3

Table 8: Scan-limit register format (address (hex) = 0xXB)

Display Test Register

With the display test register 0Fh all LED can be tested. In the test mode all LEDs are switched on at maximum brightness (duty cycle 31/32). All programming of digit and control registers is maintained. The format of the register is given in table 10.

Number of Digits Displayed	Maximum Segment Current (mA)
1	10
2	20
3	30

Table 9: Maximum segment current for 1-, 2-, or 3-digit displays

Mada	Register Data								
Mode	D7	D6	D5	D4	D3	D2	D1	D0	
Normal Operation	Х	Х	Х	Х	Х	Х	Х	0	
Display Test Mode	Х	Х	Х	Х	Х	Х	Х	1	

Table 10: Display-test register format (address (hex) = 0xXF)

Note: The AS1105 remains in display-test mode until the display-test register is reconfigured for normal operation.

No-Op Register (Cascading of AS1105)

The no-operation register 00h is used when AS1105s are cascaded in order to support more than 4 digit displays. The cascading must be done in a way that all DOUT are connected to DIN of the following AS1105. The LOAD and CLK signals are connected to all devices. For a write operation for example to the fifth device the command must be followed by four no-operation commands.

When the LOAD signal finally goes to high all shift registers are latched. The first four devices have got no-operation commands and only the fifth device sees the intended command and updates its register.

Reset and external Clock Register³

This register is addressed via the serial interface. It allows to switch the device to external clock mode (If D0=1 the CLK pin of the serial interface operates as system clock input.) and to apply an external reset (D1). This brings all registers (except reg. E) to default state. For standard operation the register contents should be "00h".

	Address	Register Data							
Mode	code (hex)	D7	D6	D5	D4	D3	D2	D1	D0
Normal Operation, internal clock	0xXE	Х	Х	Х	Х	Х	Х	0	0
Normal Operation, external clock	0xXE	Х	Х	Х	Х	Х	Х	0	1
Reset state, internal clock	0xXE	Х	Х	Х	Х	Х	Х	1	0
Reset state, external clock	0xXE	Х	Х	Х	Х	Х	Х	1	1

Table 11: Reset and external Clock register (address (hex) = 0xXE)

Iseg (mA)	VLED (V)						
	1.5	2.0	2.5	3.0	3.5		
40	12.2	11.8	11.0	10.6	9.69		
30	17.8	17.1	15.8	15.0	14.0		
20	29.8	28.0	25.9	24.5	22.6		
10	66.7	63.7	59.3	55.4	51.2		

Table 12: RSET vs. segment current and LED forward voltage

Applications Information

Supply Bypassing and Wiring

In order to achieve optimal performance the AS1105 shall be placed very close to the LED display to minimize effects of electromagnetic interference and wiring inductance. Furthermore it is recommended to connect a 10μ F electrolytic and a 0.1μ F ceramic capacitor between VDD and GND to avoid power supply ripple. Also, both GNDs must be connected to ground.

Selecting R_{SET} Resistor and Using External Drivers

The current through the segments is controlled via the external resistor R_{SET} . Segment current is about 100 times the current in I_{SET} . The right values for I_{SET} are given in table 12. The maximum current the AS1105 can drive is 40mA. If higher currents are needed, external drivers must be used. In that case it is no longer necessary that the AS1105 drives high currents. A recommended value for R_{SET} is $47k\Omega$. In cases that the AS1105 only drives few digits table 9 specifies the maximum currents and R_{SET} must be set accordingly. Refer to absolute maximum ratings to calculate acceptable limits for ambient temperature, segment current, and the LED forward-voltage drop.

³ This register is not used by MAX7219, since it does not support software reset and external clocks

4x8 LED Dot Matrix Driver

The example in Figure 3 uses the AS1105 to drive an 4x8 LED dot matrix. The LED columns have common cathode and are connected to the DIGO-3 outputs. The rows are connected to the segment drivers. Each of the 32 LEDs can be addressed separately. The columns are selected via the digits as shown in Table 2. The decode mode register (0xX9) has to be programmed to '00000000' as stated in Table 4. The single LEDs in a column can be addressed as stated in Table 6, where D0 corresponds to segment G and d/ to segment DP. For a multiple digit dot matrix several AS1105 have to be cascaded.

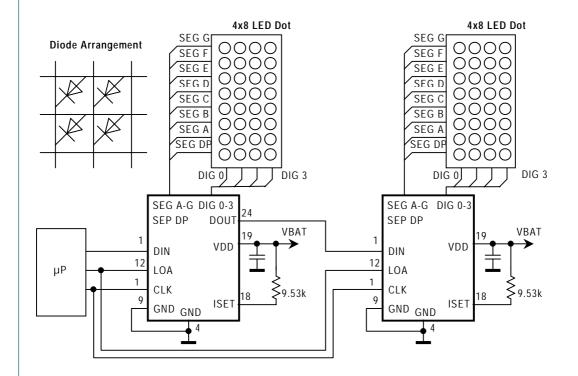


Figure 3: Application example as LED dot matrix driver

Cascading Drivers

The AS1105 can be cascaded as well. The DOUT pin must be connected to the DIN pin of the following AS1105.

Package	Thermal Resistance ($oldsymbol{ heta}_{JA}$)				
20 Wide SO	+85°C/W				
Maximum Junction Temperature (TJ) = +150°C					
Maximum Ambient Temperature (T _A) = +85°C					

Table 13: Package thermal resistance data

Data Sheet AS1105

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Computing Power Dissipation

The upper limit for power dissipation (PD) for the AS1105 is determined from the following equation:

 $PD = (VDD \times 0.5mA) + (VDD - V_{LED})(DUTY \times I_{SEG} \times N)$

where:

VDD = supply voltage DUTY = duty cycle set by intensity register N = number of segments driven (worst case is 4) V_{LED} = LED forward voltage Iseg = segment current set by RSET

Dissipation Example:

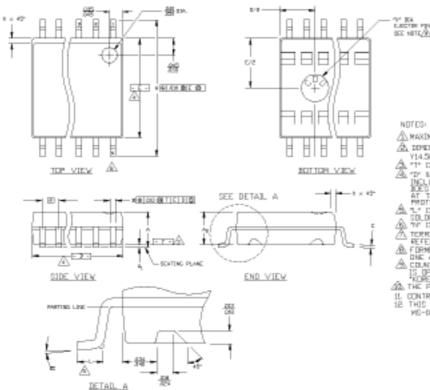
Iseg = 40mA, N = 4, DUTY = 31/32, VLED = 1.8V at 40mA, VDD = 5.25V $PD = 5.25V(0.5mA) + (5.25V - 1.8V)(31/32 \times 40mA \times 4) = 0.54W$

Thus, for a SO package $\theta_{JA} = +85^{\circ}$ C/W (from Table 13), the maximum allowed ambient temperature T_A is given by:

 $T_{J,MAX} = T_A + PD \ x \ \theta_{JA} = 150^{\circ}C = T_A + 0.54W \ x \ 85^{\circ}C/W.$

where $T_A = +104^{\circ}C$.

Package Information



NUTES

- ⚠ MAXIMUM IDE THICKNESS ALLOVARLE IS #PS.
- A DMENSIONING & TOLERANDES PER ANSI.
- 54 1982. IS A REPERENCE DATUM. Y14.5P
- REFERENCE DATUM. AGE REFERENCE DATUMS AND DO NOT MOLD FLASH DR PROTRUSIONS, BUT UDE MOLD NISMATCH AND ARE MEASURED DIJ PARTING LOW. MOLD FLASH DR DAS SHALL NOT EXCRED DOOS INCHES MER E LENGTH OF TERMINAL FOR 5 TO A SUBSTRATE. E NUMBER OF TERMINAL POSITIONS.
- H DR INCHES PER SIDE. A
- SITIONS ARE SHOWN FOR
- H RESPECT TO SEATING PLANE
- BE PLANAR WIT .000 INCHES AT .00ATION ON PAO ENDS ON ASSEMB LOCATION A 30
- ŵ.
- "KOMEA" FOR ADD. AND "PHILIPPING" FOM AMEL THE POCKETS DN THE BOTTOM ARE OPTIONAL. CONTROLING DORDNSIDA INCHES. THIS PART IS COMPLIANT WITH JEDEC STANDARD MS-003, VARIATIONS AA, AB, AC, AD & AE.

Z Z	COMMON			NOTE	3			5
]	DIMENSIO	NS	Nn	VARI-		D		N
IIM 🖉		L MAX.	N _O TE	ATIONS	MIN.	N⊡M.	MAX.	
A 2.4	6 2.56	2.64		AA	10.21	10.34	10.46	16
A. 0.16	27 0.22	0.29		l ab	11,46	11.58	11.71	18
A. 2.2	9 2.34	2.39		AC	12.70	12,83	12,95	20
B 0.3	5 0.41	0.48		L AD	15.29	15.42	15.54	24
C 0.23	0.25	0.32		AE	17,81	17,93	18.06	28
			3					
E 7.42	2 7.52	7.59						
e	1.27 BSC	-						
H 10.1	6 10.31	10.41						
[h] 0.2	5 0.33	0.41						
L 0.61	. 0.81	1.02						
	SEE VARIATI	[DNS	5					
∞ 0°	5°	8°						
X 2.3	16 2.36	2.54						

THIS TABLE IN MILLIMETERS

Figure 4: SOIC-20 package dimensions

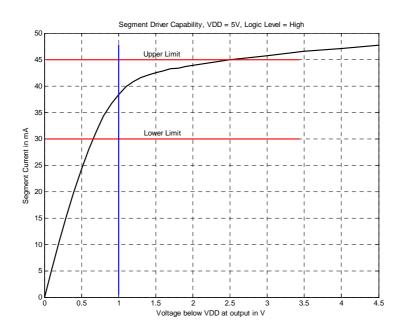


Figure 5: Segment driver capability

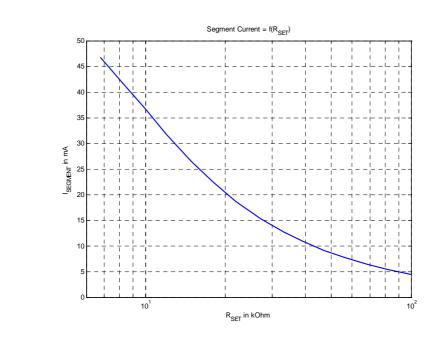


Figure 6: Segment Current versa R_{SET}

Ordering Information

Part	Temp Range	Pin Package	Delivery Form
AS1105WL	0°C to +70°C	24 Wide SO	Tubes
AS1105WE ⁴	-40°C to +85°	24 Wide SO	
AS1105WL-T	0°C to +70°C	24 Wide SO	T&R

Contact

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⁴ Contact factory for availability