

32-Segment CMOS LCD Driver

FEATURES

- Drives up to 32 LCD segments of arbitrary configuration
- CMOS process for: wide supply voltage range, low- power operation, high-noise immunity, wide temperature range
- CMOS and TTL-compatible inputs
- · Electrostatic discharge protection on all pins
- Cascadable
- · On-chip oscillator
- · Requires only three control lines

APPLICATIONS

- · Industrial displays
- Consumer product displays
- · Telecom product displays
- · Automotive dashboard displays

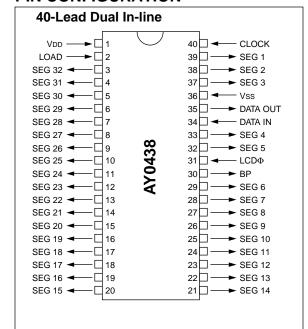
DESCRIPTION

The AY0438 is a CMOS integrated device that drives a liquid crystal display, usually under microprocessor control. The part acts as a smart peripheral that drives up to 32 LCD segments. It needs only three control lines due to its serial input construction. It latches the data to be displayed and relieves the microprocessor from the task of generating the required waveforms.

The AY0438 can drive any standard or custom parallel drive LCD display, whether it be field effect or dynamic scattering; 7-, 9-, 14- or 16-segment characters; decimals; leading + or -; or special symbols. Several AY0438 devices can be cascaded. The AC frequency of the LCD waveforms can either be supplied by the user or generated by attaching a capacitor to the LCD input, which controls the frequency of an internal oscillator.

The AY0438 is available in 40-lead dual in-line plastic and 44-lead PLCC packages. Unpackaged dice are also available.

PIN CONFIGURATION



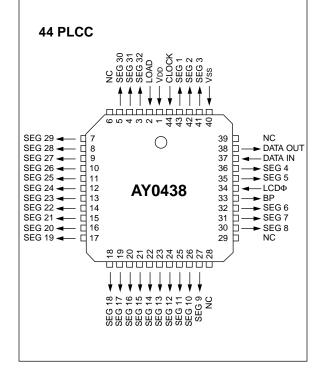


FIGURE 1: PIN DESCRIPTIONS

Pin # (PDIP Only)	Name	Direction	Description
1	VDD	-	Supply voltage
2	Load	Input	Latch data from registers
3-29, 32, 33, 37-39	Seg 1-32	Output	Direct drive outputs
30	BP	Output	Backplane drive output
31	LCDΦ	Input	Backplane drive input
34	Data In	Input	Data input to shift register
35	Data Out	Output	Data output from shift register
36	Vss	Ground	Ground
40	Clock	Input	System clock input

FIGURE 2: BLOCK DIAGRAM

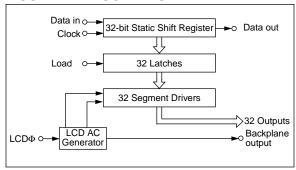


FIGURE 3: BACKPLANE AND SEGMENT OUTPUT

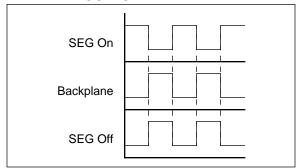
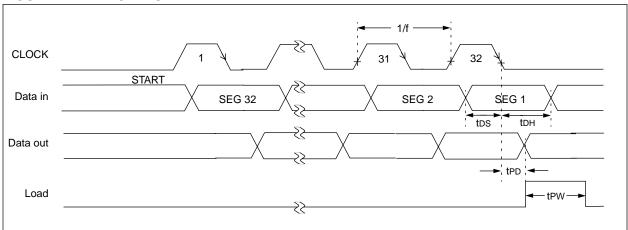


FIGURE 4: TIMING DIAGRAM



1.0 OPERATION:

1.1 Data In and Clock

The shift register shifts and outputs on the falling edge of the clock. Every clock falling edge does a logical left shift. As an example, if 32 clock pulses are supplied as in Figure 4, then the data input at the first clock will output at SEG 32, and the last data input (# 32) will output at SEG 1 when a LOAD signal is enabled (Figure 2). It is recommended that a complete 32 bit transfer be done every time the outputs are updated. A logic 1 at the Data In causes the corresponding segment to be

enabled or visible, i.e. the output at Segment Output is 180° out-of-phase with the Backplane output (Figure 3).

1.2 <u>Load</u>

A logic 1 at the Load input (Figure 2) causes the parallel load of the data in the shift register into the latches that control the segment drivers. If the Load signal is tied high, then the latches become transparent and the segment drivers are always connected to the shift registers.

1.3 <u>LCD</u>₀

LCD ϕ can be driven by an external signal or by connecting a capacitor between LCD ϕ and ground (GND), which will enable the on-chip oscillator required to generate the backplane output voltage. Figure 5 shows the relationship between capacitance value and output frequency. Leaving the LCD ϕ input unconnected is not recommended. When driven by an external clock, the backplane output is in phase with the input clock. When cascading two AY0438 devices (Figure 6 and Figure 7), the backplane output can be generated using a capacitor to GND on the first AY0438. This backplane output can then be connected to the LCD ϕ input of the second AY0438. The backplane output of the second device is then used to drive the backplane of the LCD module.

FIGURE 5: OSCILLATOR FREQUENCY GRAPH (TYPICAL @ 25°C)

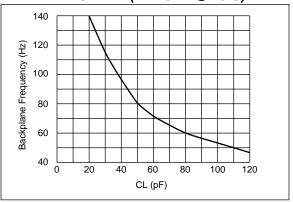


FIGURE 6: CASCADING TWO AY0438 DEVICES

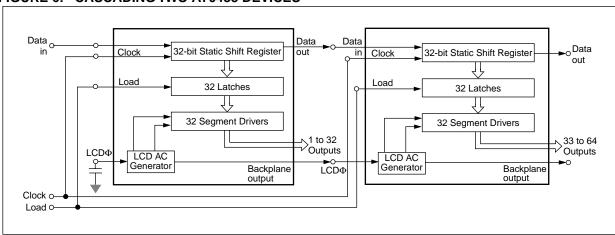
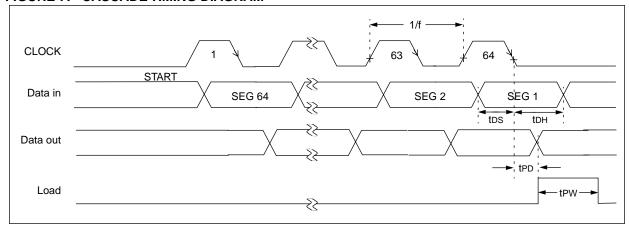


FIGURE 7: CASCADE TIMING DIAGRAM



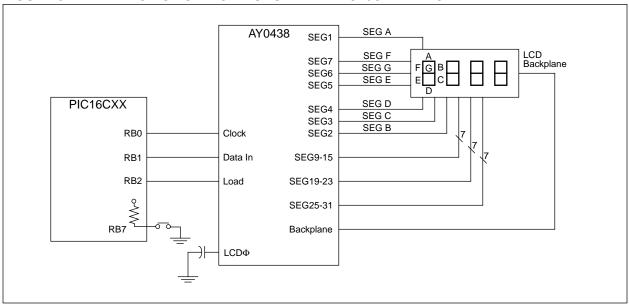
1.4 General

In order to avoid any race conditions, the Data In and Load signals should not be changed during a falling edge of the Clock. Figure 4 and Figure 7 show a typical timing diagram for a 32 segment and 64 segment LCD module.

1.5 <u>Interfacing to a LCD Module and</u> PIC16CXX Device

Figure 8 shows a typical layout of an AY0438 connected to a LCD module and interfaced to a PIC16CXX family device. Example 1 lists code used to program the PIC16CXX device. This code was complied using MPASM.

FIGURE 8: INTERFACING TO A LCD MODULE AND PIC16CXX DEVICE



EXAMPLE 1: EXAMPLE CODE

```
;The DP are not connected, but can be connected to seg8, 16, 24 & 32.
; For each digit, the segments are connected as:
        Seg A --> seg(8*n + 1)
        Seq B --> seq(8*n + 2)
        Seg C --> seg(8*n + 3)
        Seg D --> seg(8*n + 4)
        Seq E \longrightarrow seq(8*n + 5)
        Seq F \longrightarrow seq(8*n + 6)
        Seg G --> seg(8*n + 7)
; where n = 0, 1, 2 and 3 for MSD, 3rdSD, 2ndSD and LSD respectively.
;The firmware uses the values in registers:
        MSD, THRDSD, SCNDSD and LSD
                                        to determine the values to be
; pulsed to the AY0438.
; In this example, a pushbutton connected to PORTB bit 7
is checked periodically to see if it has been pressed. If so,
; the LCD values in locations MSD to LSD are updated.
        list p=16c71,f=inhx8m
;
MSD
        equ
                 0x20
THRDSD
        equ
                 0x21
                 0x22
SCNDSD equ
LSD
                 0x23
        equ
count
        equ
                 0x24
temp
        equ
                 0x25
PORTB
                 0x06
        equ
#define CLK
                 PORTB, 0
#define DATAIN PORTB,1
#define LOAD
                 PORTB, 2
#define UPDATELCD PORTB,7
                 0
        equ
STATUS
        equ
                 0x03
С
                 0
        equ
RP0
        equ
                 5
OPTION
                 0x81
        equ
RBPU
        equ
                 7
PCL
                 0x02
        equ
PCLATH equ
                 0x0A
;
;
        org
                 0
                 start
        goto
                 0x10
        org
;This DecodeValue table must reside in page 0 for this program to work
DecodeValue
                 PCL
        addwf
                B'00111111'
                                  ;decode for 0
        retlw
        retlw
                B'00000110'
                                  ;decode for 1
        retlw
                B'01011011'
                                  ;decode for 2
                                  ;decode for 3
        retlw
                B'01001111'
        retlw
                 B'01100110'
                                  ;decode for 4
        retlw
                 B'01101101'
                                  ;decode for 5
```

```
;decode for 6
        retlw
                B'01111101'
                B'00000111'
                                 ;decode for 7
        retlw
                B'01111111'
                                 ;decode for 8
        retlw
                B'01101111'
        retlw
                                 ;decode for 9
start
        clrf
                PORTB
        bsf
                STATUS, RPO
                                 ;set portb 0,1&2 as outputs
        movlw
                B'11111000'
                                 ;
                                          /
        movwf
                PORTB
        bcf
                OPTION, RBPU
                                 ;enable pull-up for switch
        bcf
                STATUS, RPO
wait
                                 ;see if update switch is low
        btfsc
                UPDATELCD
                                 ;no then wait
        goto
                wait
        bcf
                LOAD
                                 ; make sure load is disabled
        movf
                LSD, w
                                 ; get least significant value
        clrf
                PCLATH
                                 ;PCH = 0
                                 ;decode the value
        call
                DecodeValue
        call
                Send8
                                 ; serially output the seg values
        movf
                SCNDSD, w
                                 ;get 2nd significant digit
        call
               DecodeValue
                                 ;decode it
        call
                                 ; serially output it
                Send8
        movf
                THRDSD, w
                                 ;get 3rd significant digit
        call
               DecodeValue
                                 ;decode it
        call
                Send8
        movf
                MSD, w
                                 ; get Most significant value
        call
               DecodeValue
                                 ;decode it
        call
                Send8
                                 ; serially send it
        bsf
                LOAD
                                 ;toggle the LOAD line
        bcf
                LOAD
                                 ; to enable the latches
KeyReleased
                                 ;wait for key to be released
        btfss
                UPDATELCD
        goto
                KeyReleased
        goto
                wait
                                 ;repeat loop.
;Send8, sends the 8 bits in the W register
Send8
                                 ; save in temp
        movwf
                temp
        movlw
                . 8
                                 ;init count
        movwf
                count
                                 ;to 8
sendloop
                DATAIN
                                 ; make sure DATAIN is low
        bcf
        rrf
                                 ;rotate value through carry
                temp
        btfsc
                STATUS, C
                                 ; if bit clear then skip
        bsf
                DATAIN
                                 ;else set data bit
        bsf
                CLK
                                 ;toggle clock
        bcf
                CLK
        decfsz count
                                 ;see if 8 done
        goto
                sendloop
                                 ;no then do all
                                 ;else return
        return
        end
```

2.0 ELECTRICAL CHARACTERISTICS

Maximum Ratings*

Data labeled "typical" is presented for design guidance only and is not guaranteed.

TABLE 2: DC CHARACTERISTICS

VDD = +5V unless otherwise noted, TA = 40° C to +85°C							
Characteristic	s	Sym	Min	Тур	Max	Units	Conditions
Supply Voltage		VDD	+3.0	_	+8.5	V	
Supply Current		IDD	_	25	60	μΑ	LCD⊕ OSC < 15 kHz
			_	13	30	μΑ	LCD⊕ OSC < 100 Hz
Input High Level		ViH	0.5 VDD	_	VDD	V	
Input Low Level	Clock	VIL1	0	_	0.1 VDD	V	$3.0V \le VDD \le 8.5V$
	Data,	VIL2	0	_	0.1 VDD	V	$3.0V \le VDD \le 8.5V$
Input Leakage Current	Load	IL	_	0.01	±10	μΑ	VIN = 0V and +5.0V
Input Capacitance		Cı	_	_	5.0	pF	VDD = +5.0V
Segment Output Voltage		Voн	0.8 VDD	_	VDD	V	ΙΟΗ = -100 μΑ
		Vol	0	_	0.1 VDD	V	IOL = 100 μA
LCD⊕ Input High Level		VIN	0.9 VDD	—	VDD	V	
LCD⊕ Input Low Level		VIL	0	_	0.1 VDD	V	
LCD		IL	_	_	10	μΑ	VIN = 0V and +5.0V
							VDD = +5.0V

TABLE 3: AC CHARACTERISTICS

Characteristics	Sym	Min	Тур	Max	Units	Conditions
Clock Rate	f	DC	_	1.5	MHz	50% duty cycle
Data Set-up Time	tDS	150	_	_	nsec	Data change to Clk falling edge
Data Hold Time	tDH	50	_	_	nsec	
Load Pulse Width	tpw	175	_	_	nsec	
Data Out Prop. Delay	tPD	_	_	500	nsec	CL = 55 pF

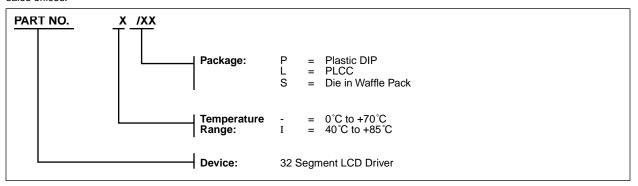
^{*} Exceeding these ratings could cause permanent damage to the device. This is a stress rating only and functional operation of this device at these conditions is not implied. Operating ranges are specified in Standard Conditions. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.



NOTES:

AY0438 Product Identification System

To order or to obtain information, e.g., on pricing or delivery, please use the listed part numbers, and refer to the factory or the listed sales offices.



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