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| STRUCTURE | Silicon monolithic integrated circuits |
| PRODUCT SERIES | 2ch DC brush motor driver |
| TYPE | BD63823EFV |
| FUNCTION | <ul style="list-style-type: none"> • PWM constant current controllable two H bridge driver • Forward, reverse, brake and stop function • Direct PWM control |

○Absolute maximum ratings(Ta=25°C)

| Item | Symbol | Ratings | Unit |
|------------------------------------|----------------------|--------------------|------|
| Supply voltage | V _{CC1,2} | -0.3~+36.0 | V |
| Power dissipation | Pd | 1.45 ^{※1} | W |
| | | 4.70 ^{※2} | W |
| Input voltage for control pin | V _{IN} | -0.3~+7.0 | V |
| RNF voltage | V _{RNF} | 0.7 | V |
| Output current | I _{OUT} | 2.0 ^{※3} | A/ch |
| Output current(peak) ^{※4} | I _{OUTPEAK} | 2.8 ^{※3} | A/ch |
| FAULT, LOCK voltage | V _{FAULT} | -0.3~+7.0 | V |
| FAULT, LOCK current | I _{FAULT} | 5 | mA |
| Operating temperature range | T _{opr} | -25~+85 | °C |
| Storage temperature range | T _{stg} | -55~+150 | °C |
| Junction temperature | T _{jmax} | +150 | °C |

※1 70mm × 70mm × 1.6mm glass epoxy board. Derating in done at 11.6mW/°C for operating above Ta=25°C.

※2 4-layer recommended board. Derating in done at 37.6mW/°C for operating above Ta=25°C.

※3 Do not, however exceed Pd, ASO and Tjmax=150°C.

※4 Pulse width tw ≤ 20ms.

○Operating conditions (Ta=-25~+85°C)

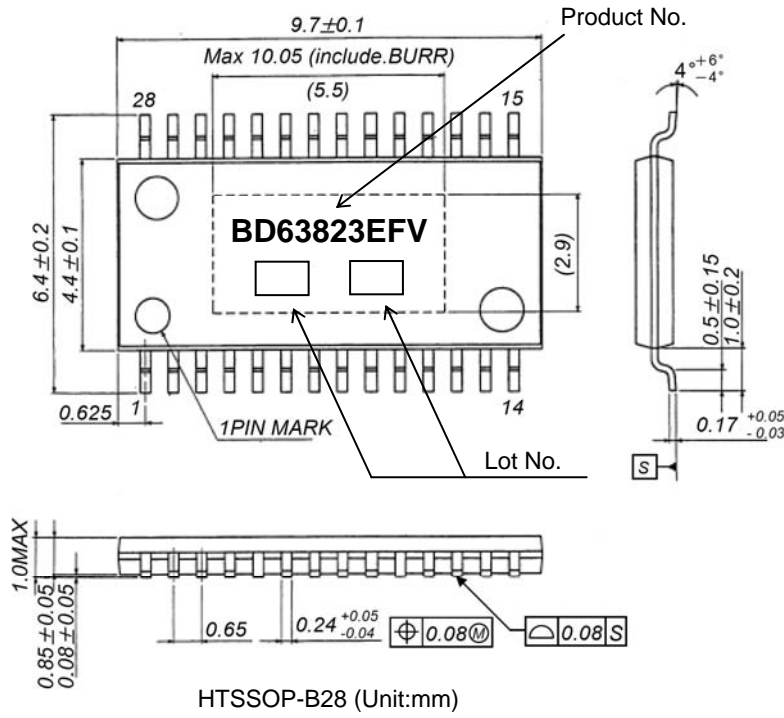
| Item | Symbol | Min. | Typ. | Max. | Unit |
|-------------------------------|--------------------|------|------|------|------|
| Supply voltage | V _{CC1,2} | 19 | 24 | 28 | V |
| Input voltage for control pin | V _{IN} | 0 | - | 5.5 | V |
| PWM input frequency | F _{IN} | - | - | 100 | kHz |

This product isn't designed for protection against radioactive rays.

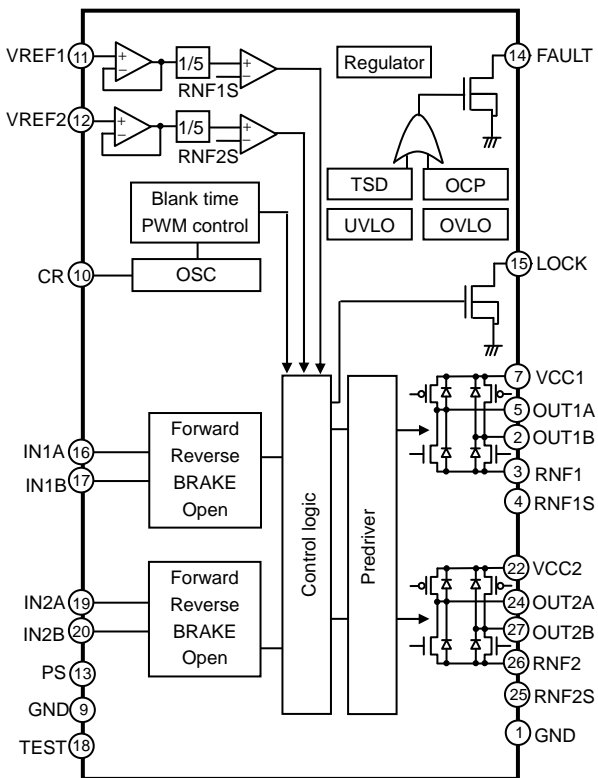
○Electrical characteristics (Unless otherwise specified Ta=25°C, V_{CC1,2}=24V)

| Item | Symbol | Limit | | | Unit | Conditions |
|---|-------------------------|-------|------|------|------|---|
| | | Min. | Typ. | Max. | | |
| Whole | | | | | | |
| Circuit current at standby | I _{CCST} | - | 1.0 | 2.5 | mA | PS=0V |
| Circuit current | I _{CC} | - | 2.5 | 5.0 | mA | PS=IN1A=IN2A=5V |
| Control input (IN1A, IN1B, IN2A, IN2B, PS) | | | | | | |
| H level input voltage | V _{INH} | 2.0 | - | - | V | |
| L level input voltage | V _{INL} | - | - | 0.8 | V | |
| H level input current | I _{INH} | 35 | 50 | 100 | μA | V _{IN} =5V |
| L level input current | I _{INL} | -10 | 0 | - | μA | V _{IN} =0V |
| FAULT LOCK output (FAULT, LOCK) | | | | | | |
| Output low voltage | V _{FAULT} | - | 50 | 100 | mV | I _{FAULT} =1mA |
| Output leak current | I _{FAULT_LEAK} | - | - | 10 | μA | V _{FAULT} =5V |
| Output (OUT1A, OUT1B, OUT2A, OUT2B) | | | | | | |
| Output on resistance | R _{ON} | - | 0.65 | 0.90 | Ω | I _{OUT} =1.5A, Sum of upper and lower |
| Output leak current | I _{LEAK} | - | - | 10 | μA | |
| Current control | | | | | | |
| RNFXS input current | I _{RNFS} | -2.0 | -0.1 | - | μA | RNFXS=0V |
| RNFX input current | I _{RNF} | -40 | -20 | - | μA | RNFX=0V |
| VREFX input current | I _{VREF} | -2.0 | -0.1 | - | μA | VREFX=0V |
| VREFX input voltage range | V _{REF} | 0 | - | 3.0 | V | |
| Minimum on time (Blank time) | t _{ONMIN} | 0.7 | 1.5 | 3.0 | μs | |
| Current limit Comparator threshold | V _{CTH} | 0.57 | 0.60 | 0.63 | V | VREFX=3V |

○ Package outline



○ Block diagram



○ Pin No. / Pin name

| Pin No. | Pin name | Pin No. | Pin name |
|---------|----------|---------|----------|
| 1 | GND | 15 | LOCK |
| 2 | OUT1B | 16 | IN1A |
| 3 | RNF1 | 17 | IN1B |
| 4 | RNF1S | 18 | TEST |
| 5 | OUT1A | 19 | IN2A |
| 6 | NC | 20 | IN2B |
| 7 | VCC1 | 21 | NC |
| 8 | NC | 22 | VCC2 |
| 9 | GND | 23 | NC |
| 10 | CR | 24 | OUT2A |
| 11 | VREF1 | 25 | RNF2S |
| 12 | VREF2 | 26 | RNF2 |
| 13 | PS | 27 | OUT2B |
| 14 | FAULT | 28 | NC |

NC : Non Connection

OOperation Notes

- (1) Absolute maximum ratings
An excess in the absolute maximum ratings, such as supply voltage, temperature range of operating conditions, etc., can break down the devices, thus making impossible to identify breaking mode, such as a short circuit or an open circuit. If any over rated values will expect to exceed the absolute maximum ratings, consider adding circuit protection devices, such as fuses.
- (2) Power supply lines
As return of current regenerated by back EMF of motor happens, take steps such as putting capacitor between power supply and GND as an electric pathway for the regenerated current. Be sure that there is no problem with each property such as emptied capacity at lower temperature regarding electrolytic capacitor to decide capacity value. If the connected power supply does not have sufficient current absorption capacity, regenerative current will cause the voltage on the power supply line to rise, which combined with the product and its peripheral circuitry may exceed the absolute maximum ratings. It is recommended to implement a physical safety measure such as the insertion of a voltage clamp diode between the power supply and GND pins.
- (3) GND potential
The potential of GND pin must be minimum potential in all operating conditions.
- (4) Metal on the backside (Define the side where product markings are printed as front)
The metal on the backside is shorted with the backside of IC chip therefore it should be connected to GND. Be aware that there is a possibility of malfunction or destruction if it is shorted with any potential other than GND.
- (5) Thermal design
Use a thermal design that allows for a sufficient margin in light of the power dissipation (Pd) in actual operating conditions. This IC exposes the metal on the backside of package. Note that this part is assumed to use after providing heat dissipation treatment to improve heat dissipation efficiency. Try to occupy as wide as possible with heat dissipation pattern not only on the board surface but also the backside.
- (6) Operation in strong electromagnetic field
Use caution when using the IC in the presence of a strong electromagnetic field as doing so may cause the IC to malfunction.
- (7) ASO
When using the IC, set the output transistor so that it does not exceed absolute maximum ratings or ASO.
- (8) Thermal shutdown circuit
The IC has a built-in thermal shutdown circuit (TSD circuit). If the chip temperature becomes $T_{jmax}=150^{\circ}\text{C}$, and higher, coil output to the motor will be open. The TSD circuit is designed only to shut the IC off to prevent runaway thermal operation. It is not designed to protect or indemnify peripheral equipment. Do not use the TSD function to protect peripheral equipment.
- (9) Over current protection circuit
The IC has a built-in over current protection circuit (OCP circuit). The OCP circuit is designed only to shut the IC off to prevent abnormal situations, when absolute maximum output current is exceeded. It is not designed to protect or indemnify peripheral equipment. Do not use the OCP function to protect peripheral equipment.
- (10) Ground Wiring Pattern
When using both large current and small signal GND patterns, it is recommended to isolate the two ground patterns, placing a single ground point at the ground potential of application so that the pattern wiring resistance and voltage variations caused by large currents do not cause variations in the small signal ground voltage. Be careful not to change the GND wiring pattern of any external components, either.
- (11) TEST pin
Be sure to connect TEST pin to GND.

Notes

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