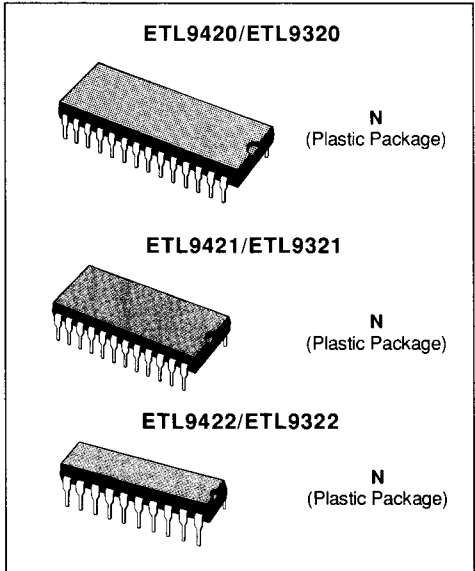


## NMOS MICROCONTROLLERS

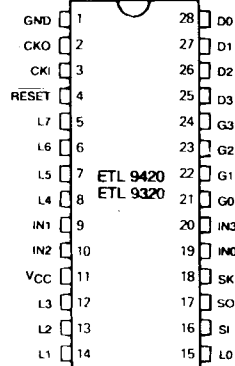
- LOW COST
- POWERFUL INSTRUCTION SET
- 1K x 8 ROM, 64 x 4 RAM
- 23 I/O LINES (ETL9420)
- TRUE VECTORED INTERRUPT, PLUS RESTART
- THREE-LEVEL SUBROUTINE STACK
- 16 $\mu$ s INSTRUCTION TIME
- SINGLE SUPPLY OPERATION (4.5-6.3V)
- LOW CURRENT DRAIN (9mA max.)
- INTERNAL TIME-BASE COUNTER FOR REAL-TIME PROCESSING
- INTERNAL BINARY COUNTER REGISTER WITH MICROWIRE® COMPATIBLE SERIAL I/O
- GENERAL PURPOSE AND TRI-STATE® OUTPUTS
- LSTTL/CMOS COMPATIBLE IN AND OUT
- DIRECT DRIVE OF LED DIGIT AND SEGMENT LINES
- SOFTWARE/HARDWARE COMPATIBLE WITH OTHER MEMBERS OF ET9400 FAMILY
- EXTENDED TEMPERATURE RANGE DEVICE
- ETL9320/L9321/L9322 (- 40°C to + 85°C)
- WIDER SUPPLY RANGE (4.5V - 9.5V) OPTIONALLY AVAILABLE
- SOIC 20/24/28 AND PLCC 28 PACKAGES AVAILABLE

### DESCRIPTION

The ETL9420, ETL9421, ETL9422, ETL9320, ETL9321, and ETL9322 Single-Chip N-Channel Microcontrollers are fully compatible with the COPS® family, fabricated using N-channel, silicon gate XMOS technology. These controller oriented processors are complete microcomputers containing all system timing, internal logic, ROM, RAM, and I/O necessary to implement dedicated control functions in a variety of applications. Features include single supply operation, a variety of output configuration options, with an instruction set, internal architecture, and I/O scheme designed to facilitate keyboard input, display output, and BCD data manipulation. The ETL9421 and ETL9422 are identical to the ETL9420, but with 19 and 15 I/O lines, respectively, instead of 23. They are an appropriate choice for use in numerous human interface control environments. Standard test procedures and relia-



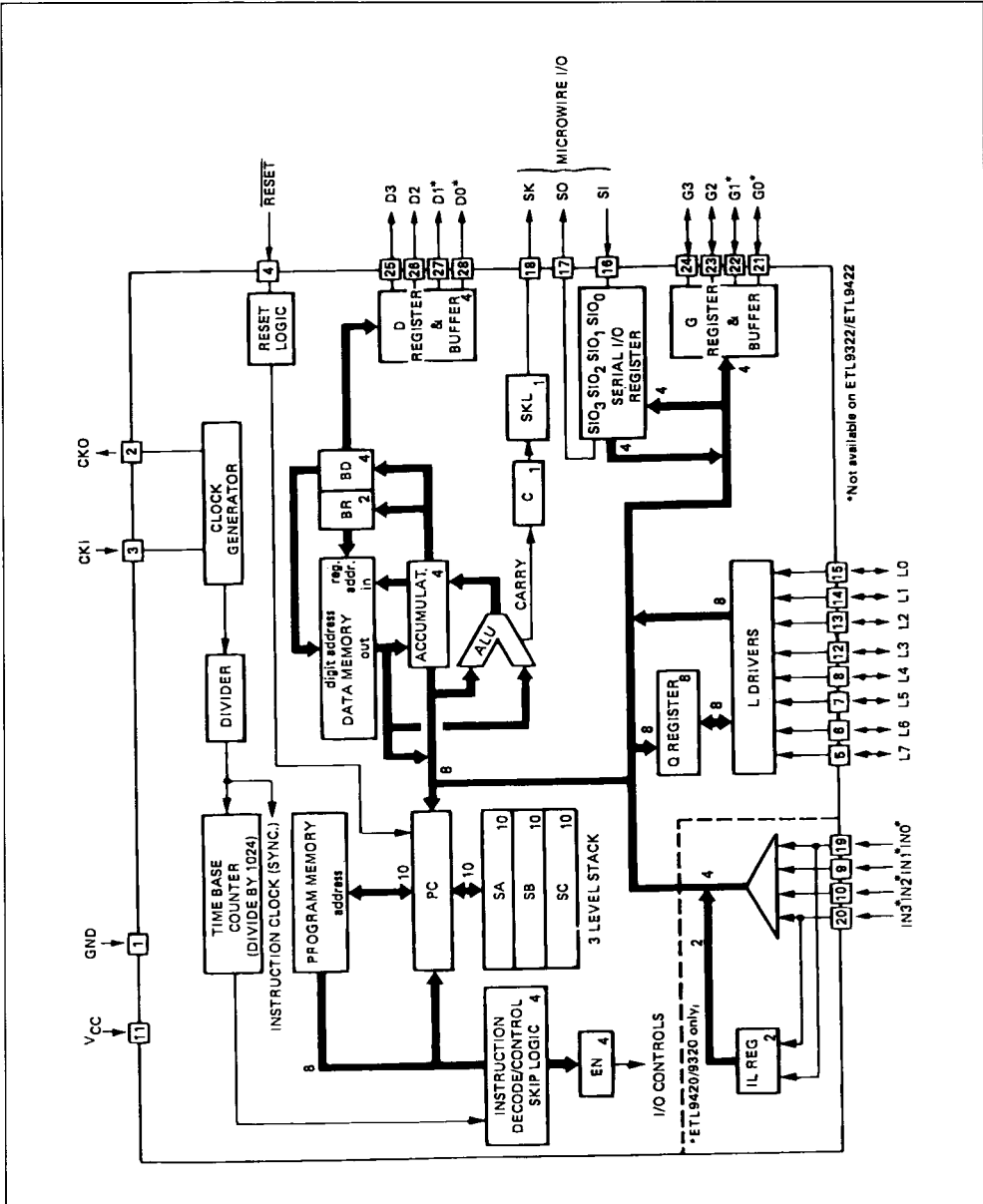
### PIN CONNECTIONS



ble high-density fabrication techniques provide the medium to large volume customers with a customized controller oriented processor at a low end-product cost.

The ETL9320/L9321/L9322 are exact functional equivalents, but extended temperature range versions, of the ETL9420, ETL9421 and ETL9422 respectively.

Figure 1 : Block Diagram (28-pin version).



ETL9420/L9421/L9422

**ABSOLUTE MAXIMUM RATINGS**

Parameter	Value	Unit
Voltage at Any Pin Relative to GND	- 0.5 to + 10	V
Ambient Operating Temperature	0 to + 70	°C
Ambient Storage Temperature	- 65 to + 150	°C
Lead Temperature (soldering , 10seconds)	300	°C
Power Dissipation ETL9420/L9421 ETL9422	0.75W at 25°C 0.4W at 70°C 0.65W at 25°C 0.3W at 70°C	
Total Source Current	120	mA
Total Sink Current	120	mA

Absolute maximum ratings indicate limits beyond which damage to the device may occur. DC and AC electrical specifications are not ensured when operating the device at absolute maximum ratings.

**DC ELECTRICAL CHARACTERISTICS** 0°C ≤ T<sub>A</sub> ≤ + 70°C, 4.5V ≤ V<sub>CC</sub> ≤ 9.5V

(unless otherwise specified).

Parameter	Test Conditions	Min.	Max.	Unit
Standard Operating Voltage (V <sub>CC</sub> )	Note 1	4.5	6.3	V
Optional Operating Voltage (V <sub>CC</sub> )		4.5	9.5	V
Power Supply Ripple	Peak to Peak		0.5	V
Operating Supply Current	All Input and Outputs Open		9	mA
Input Voltage Levels				
CKI Input Levels				
Crystal Input (+ 32, + 16, + 8)				
Logic High (V <sub>IH</sub> )		2.0		V
Logic Low (V <sub>IL</sub> )		- 0.3	0.4	V
Schmitt Trigger Input (+ 4)				
Logic High (V <sub>IH</sub> )		0.7 V <sub>CC</sub>		V
Logic Low (V <sub>IL</sub> )		- 0.3	0.6	V
RESET Input Levels	Schmitt Trigger Input			
Logic High		0.7 V <sub>CC</sub>		V
Logic Low		- 0.3	0.6	V
SO Input Level (test mode)		2.0	2.5	V
All Other Inputs				
Logic High	V <sub>CC</sub> = Max.	3.0		V
Logic High	With TTL trip level options selected, V <sub>CC</sub> = 5V ± 5%	2.0		V
Logic Low	with high trip level options selected.	- 0.3	0.8	V
Logic High		3.6		V
Logic Low		- 0.3	1.2	V
Input Capacitance			7	pF
Hi-Z Input Leakage		- 1	+ 1	µA
Output Voltage Levels				
LSTTL Operation	V <sub>CC</sub> = 5V ± 5%			
Logic High (V <sub>OH</sub> )	I <sub>OH</sub> = - 25µA	2.7		V
Logic Low (V <sub>OL</sub> )	I <sub>OL</sub> = 0.36mA		0.4	V
CMOS Operation				
Logic High	I <sub>OH</sub> = - 10µA	V <sub>CC</sub> - 1		V
Logic Low	I <sub>OL</sub> = + 10µA		0.2	V

**Note** : 1. V<sub>CC</sub> voltage change must be less than 0.5V in a 1ms period to maintain proper operation.

ETL9420/L9421/L9422

DC ELECTRICAL CHARACTERISTICS (continued)

Parameter	Test Conditions	Min.	Max.	Unit
<b>Output Current Levels</b>				
<b>Output Sink Current</b>				
SO and SK Outputs ( $I_{OL}$ )	$V_{CC} = 9.5V, V_{OL} = 0.4V$	1.8		mA
	$V_{CC} = 6.3V, V_{OL} = 0.4V$	1.2		mA
	$V_{CC} = 4.5V, V_{OL} = 0.4V$	0.9		mA
L <sub>0</sub> -L <sub>7</sub> Outputs and Standard	$V_{CC} = 9.5V, V_{OL} = 0.4V$	0.8		mA
G <sub>0</sub> -G <sub>3</sub> , D <sub>0</sub> -D <sub>3</sub> Outputs ( $I_{OL}$ )	$V_{CC} = 6.3V, V_{OL} = 0.4V$	0.5		mA
	$V_{CC} = 4.5V, V_{OL} = 0.4V$	0.4		mA
G <sub>0</sub> -G <sub>3</sub> and D <sub>0</sub> -D <sub>3</sub> Outputs with	$V_{CC} = 9.5V, V_{OL} = 1.0V$	15		mA
High Current Options ( $I_{OL}$ )	$V_{CC} = 6.3V, V_{OL} = 1.0V$	11		mA
	$V_{CC} = 4.5V, V_{OL} = 1.0V$	7.5		mA
G <sub>0</sub> -G <sub>3</sub> and D <sub>0</sub> -D <sub>3</sub> Outputs with	$V_{CC} = 9.5V, V_{OL} = 1.0V$	30		mA
Very High Current Options ( $I_{OL}$ )	$V_{CC} = 6.3V, V_{OL} = 1.0V$	22		mA
	$V_{CC} = 4.5V, V_{OL} = 1.0V$	15		mA
CKI (single-pin RC oscillator)	$V_{CC} = 4.5V, V_{IH} = 3.5V$	2		mA
CKO	$V_{CC} = 4.5V, V_{OL} = 0.4V$	0.2		mA
<b>Output Source Current</b>				
<b>Standard Configuration,</b>				
All Outputs ( $I_{OH}$ )	$V_{CC} = 9.5V, V_{OH} = 2.0V$	- 140	- 800	μA
	$V_{CC} = 6.3V, V_{OH} = 2.0V$	- 75	- 480	μA
	$V_{CC} = 4.5V, V_{OH} = 2.0V$	- 30	- 250	μA
<b>Push-pull Configuration</b>				
SO and SK Outputs ( $I_{OH}$ )	$V_{CC} = 9.5V, V_{OH} = 4.75V$	- 1.4		mA
	$V_{CC} = 6.3V, V_{OH} = 2.4V$	- 1.4		mA
	$V_{CC} = 4.5V, V_{OH} = 1.0V$	- 1.2		mA
<b>LED Configuration, L<sub>0</sub>-L<sub>7</sub></b>				
<b>Outputs, Low Current</b>				
Driver Option ( $I_{OH}$ )	$V_{CC} = 9.5V, V_{OH} = 2.0V$	- 1.5	- 18	mA
	$V_{CC} = 6.0V, V_{OH} = 2.0V$	- 1.5	- 13	mA
<b>LED Configuration, L<sub>0</sub>-L<sub>7</sub></b>				
<b>Outputs, High Current</b>				
Driver Option ( $I_{OH}$ )	$V_{CC} = 9.5V, V_{OH} = 2.0V$	- 3.0	- 35	mA
	$V_{CC} = 6.0V, V_{OH} = 2.0V$	- 3.0	- 25	mA
<b>TRI-STATE® Configuration,</b>				
L <sub>0</sub> -L <sub>7</sub> Outputs, Low	$V_{CC} = 9.5V, V_{OH} = 5.5V$	- 0.75		mA
Current Driver Option ( $I_{OH}$ )	$V_{CC} = 6.3V, V_{OH} = 3.2V$	- 0.8		mA
	$V_{CC} = 4.5V, V_{OH} = 1.5V$	- 0.9		mA
<b>TRI-STATE® Configuration,</b>				
L <sub>0</sub> -L <sub>7</sub> Outputs, High	$V_{CC} = 9.5V, V_{OH} = 5.5V$	- 1.5		mA
Current Driver Option ( $I_{OH}$ )	$V_{CC} = 6.3V, V_{OH} = 3.2V$	- 1.6		mA
	$V_{CC} = 4.5V, V_{OH} = 1.5V$	- 1.8		mA
Input Load Source Current	$V_{CC} = 5.0V, V_{IL} = 0V$	- 10	- 140	μA
<b>CKO Output</b>				
<b>RAM Power Supply Option</b>				
Power Requirement	$V_R = 3.3V$		3.0	mA
<b>TRI-STATE® Output Leakage</b>				
<b>Current</b>				
		- 2.5	+ 2.5	μA
<b>Total Sink Current Allowed</b>				
<b>All Outputs Combined</b>				
D, G Ports			120	mA
L <sub>7</sub> -L <sub>4</sub>			4	mA
L <sub>3</sub> -L <sub>0</sub>			4	mA
All Other Pins			1.5	mA
<b>Total Source Current Allowed</b>				
<b>All I/O Combined</b>				
L <sub>7</sub> -L <sub>4</sub>			120	mA
L <sub>3</sub> -L <sub>0</sub>			60	mA
Each L Pin			60	mA
All Other Pins			30	mA
			1.5	mA

## ETL9320/L9321/L9322

## ABSOLUTE MAXIMUM RATINGS

Parameter	Value	Unit
Voltage at Any Pin Relative to GND	– 0.5 to + 10	V
Ambient Operating Temperature	– 40 to + 85	°C
Ambient Storage Temperature	– 65 to + 150	°C
Lead Temperature (soldering, 10seconds)	300	°C
Power Dissipation ETL9320/L9321 ETL9322	0.75W at 25°C 0.4W at 85°C 0.65W at 25°C 0.20W at 85°C	
Total Source Current	120	mA
Total Sink Current	120	mA

Absolute maximum ratings indicate limits beyond which damage to the device may occur. DC and AC electrical specifications are not ensured when operating the device at absolute maximum ratings.

**DC ELECTRICAL CHARACTERISTICS** –  $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ ,  $4.5\text{V} \leq V_{\text{CC}} \leq 7.5\text{V}$   
(unless otherwise specified).

Parameter	Test Conditions	Min.	Max.	Unit
Standard Operating Voltage ( $V_{\text{CC}}$ )	Note 1	4.5	5.5	V
Optional Operating Voltage ( $V_{\text{CC}}$ )		4.5	7.5	V
Power Supply Ripple	Peak to Peak		0.5	V
Operating Supply Current	All Input and Outputs Open		11	mA
Input Voltage Levels				
CKI Input Levels				
Crystal Input				
Logic High ( $V_{\text{IH}}$ )		2.2		V
Logic Low ( $V_{\text{IL}}$ )		– 0.3	0.3	V
Schmitt Trigger Input				
Logic High ( $V_{\text{IH}}$ )		$0.7 V_{\text{CC}}$		V
Logic Low ( $V_{\text{IL}}$ )		– 0.3	0.4	V
RESET Input Levels	Schmitt Trigger Input			
Logic High		$0.7 V_{\text{CC}}$		V
Logic Low		– 0.3	0.4	V
SO Input Level (test mode)		2.2	2.5	V
All Other Inputs				
Logic High	$V_{\text{CC}} = \text{Max.}$	3.0		V
Logic High	With TTL trip level options selected, $V_{\text{CC}} = 5\text{V} \pm 5\%$	2.2		V
Logic Low	with high trip level options selected.	– 0.3	0.6	V
Logic High		3.6		V
Logic Low		– 0.3	1.2	V
Input Capacitance			7	pF
Hi-Z Input Leakage		– 2	+ 2	$\mu\text{A}$
Output Voltage Levels				
LSTTL Operation	$V_{\text{CC}} = 5\text{V} \pm 5\%$			
Logic High ( $V_{\text{OH}}$ )	$I_{\text{OH}} = -20\mu\text{A}$	2.7		V
Logic Low ( $V_{\text{OL}}$ )	$I_{\text{OL}} = 0.36\text{mA}$		0.4	V
CMOS Operation				
Logic High	$I_{\text{OH}} = -10\mu\text{A}$	$V_{\text{CC}} - 1$		V
Logic Low	$I_{\text{OL}} = +10\mu\text{A}$		0.2	V

Note : 1.  $V_{\text{CC}}$  voltage change must be less than 0.5V in a 1ms period to maintain proper operation.

ETL9320/L9321/L9322

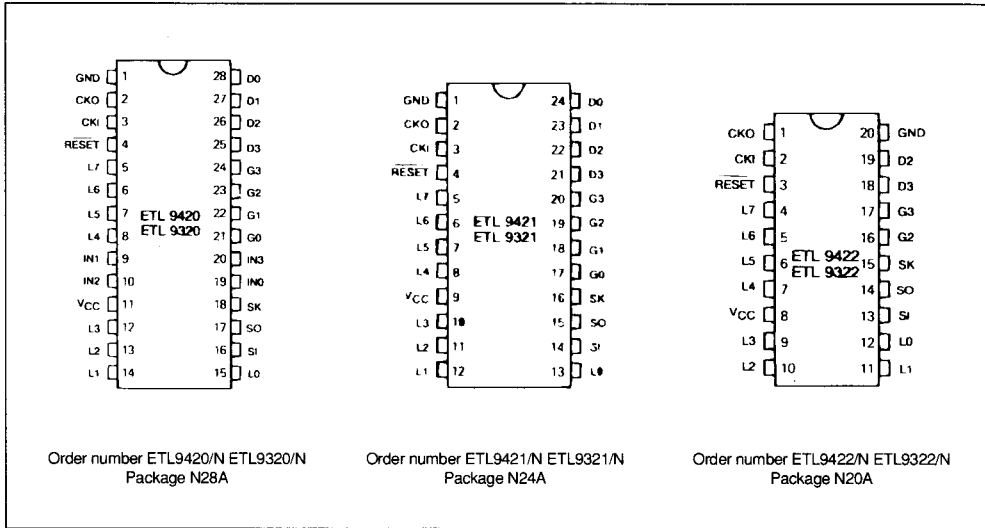
DC ELECTRICAL CHARACTERISTICS (continued)

Parameter	Test Conditions	Min.	Max.	Unit
Output Current Levels				
Output Sink Current				
SO and SK Outputs (I <sub>OL</sub> )	V <sub>CC</sub> = 7.5V, V <sub>OL</sub> = 0.4V	1.4		mA
	V <sub>CC</sub> = 5.5V, V <sub>OL</sub> = 0.4V	1.0		mA
	V <sub>CC</sub> = 4.5V, V <sub>OL</sub> = 0.4V	0.8		mA
L <sub>0</sub> -L <sub>7</sub> Outputs and Standard	V <sub>CC</sub> = 7.5V, V <sub>OL</sub> = 0.4V	0.6		mA
G <sub>0</sub> -G <sub>3</sub> , D <sub>0</sub> -D <sub>3</sub> Outputs (I <sub>OL</sub> )	V <sub>CC</sub> = 5.5V, V <sub>OL</sub> = 0.4V	0.5		mA
	V <sub>CC</sub> = 4.5V, V <sub>OL</sub> = 0.4V	0.4		mA
G <sub>0</sub> -G <sub>3</sub> and D <sub>0</sub> -D <sub>3</sub> Outputs with	V <sub>CC</sub> = 7.5V, V <sub>OL</sub> = 1.0V	12		mA
High Current Options (I <sub>OL</sub> )	V <sub>CC</sub> = 5.5V, V <sub>OL</sub> = 1.0V	9		mA
	V <sub>CC</sub> = 4.5V, V <sub>OL</sub> = 1.0V	7		mA
G <sub>0</sub> -G <sub>3</sub> and D <sub>0</sub> -D <sub>3</sub> Outputs with	V <sub>CC</sub> = 7.5V, V <sub>OL</sub> = 1.0V	24		mA
Very High Current Options (I <sub>OL</sub> )	V <sub>CC</sub> = 5.5V, V <sub>OL</sub> = 1.0V	18		mA
	V <sub>CC</sub> = 4.5V, V <sub>OL</sub> = 1.0V	14		mA
CKI (single-pin RC oscillator)	V <sub>CC</sub> = 4.5V, V <sub>IH</sub> = 3.5V	2		mA
CKO	V <sub>CC</sub> = 4.5V, V <sub>OL</sub> = 0.4V	0.2		mA
Output Source Current				
Standard Configuration,				
All Outputs (I <sub>OH</sub> )	V <sub>CC</sub> = 7.5V, V <sub>OH</sub> = 2.0V	- 100	- 900	μA
	V <sub>CC</sub> = 5.5V, V <sub>OH</sub> = 2.0V	- 55	- 600	μA
	V <sub>CC</sub> = 4.5V, V <sub>OH</sub> = 2.0V	- 28	- 350	μA
Push-pull Configuration				
SO and SK Outputs (I <sub>OH</sub> )	V <sub>CC</sub> = 7.5V, V <sub>OH</sub> = 3.75V	- 0.85		mA
	V <sub>CC</sub> = 5.5V, V <sub>OH</sub> = 2.0V	- 1.1		mA
	V <sub>CC</sub> = 4.5V, V <sub>OH</sub> = 1.0V	- 1.2		mA
LED Configuration, L <sub>0</sub> -L <sub>7</sub>	V <sub>CC</sub> = 7.5V, V <sub>OH</sub> = 2.0V	- 1.4	- 27	mA
Outputs, Low Current	V <sub>CC</sub> = 6.0V, V <sub>OH</sub> = 2.0V	- 1.4	- 17	mA
Driver Option (I <sub>OH</sub> )	V <sub>CC</sub> = 5.5V, V <sub>OH</sub> = 2.0V	- 0.7	- 15	mA
LED Configuration, L <sub>0</sub> -L <sub>7</sub>	V <sub>CC</sub> = 7.5V, V <sub>OH</sub> = 2.0V	- 2.7	- 54	mA
Outputs, High Current	V <sub>CC</sub> = 6.0V, V <sub>OH</sub> = 2.0V	- 2.7	- 34	mA
Driver Option (I <sub>OH</sub> )	V <sub>CC</sub> = 5.5V, V <sub>OH</sub> = 2.0V	- 1.4	- 30	mA
TRI-STATE® Configuration,	V <sub>CC</sub> = 7.5V, V <sub>OH</sub> = 4.0V	- 0.7		mA
L <sub>0</sub> -L <sub>7</sub> Outputs, Low	V <sub>CC</sub> = 5.5V, V <sub>OH</sub> = 2.7V	- 0.6		mA
Current Driver Option (I <sub>OH</sub> )	V <sub>CC</sub> = 4.5V, V <sub>OH</sub> = 1.5V	- 0.9		mA
TRI-STATE® Configuration,	V <sub>CC</sub> = 7.5V, V <sub>OH</sub> = 4.0V	- 1.4		mA
L <sub>0</sub> -L <sub>7</sub> Outputs, High	V <sub>CC</sub> = 5.5V, V <sub>OH</sub> = 2.7V	- 1.2		mA
Current Driver Option (I <sub>OH</sub> )	V <sub>CC</sub> = 4.5V, V <sub>OH</sub> = 1.5V	- 1.8		mA
Input Load Source Current	V <sub>CC</sub> = 5.0V, V <sub>OL</sub> = 0V	- 10	- 200	μA
CKO Output				
RAM Power Supply Option				
Power Requirement	V <sub>R</sub> = 3.3V		4.0	mA
TRI-STATE® Output Leakage Current				
		- 5	+ 5	μA
Total Sink Current Allowed				
All Outputs Combined				
D, G Ports			120	mA
L <sub>7</sub> -L <sub>4</sub>			4	mA
L <sub>3</sub> -L <sub>0</sub>			4	mA
All Other Pins			1.5	mA
Total Source Current Allowed				
All I/O Combined				
L <sub>7</sub> -L <sub>4</sub>			60	mA
L <sub>3</sub> -L <sub>0</sub>			60	mA
Each L Pin			30	mA
All Other Pins			1.5	mA

**AC ELECTRICAL CHARACTERISTICS**ETL9420/L9421/L9422 :  $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$ ,  $4.5\text{V} \leq V_{CC} \leq 9.5\text{V}$  (unless otherwise specified)ETL9320/L9321/L9322 :  $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ ,  $4.5\text{V} \leq V_{CC} \leq 7.5\text{V}$  (unless otherwise specified)

Parameter	Test Conditions	Min.	Max.	Unit
Instruction Cycle Time – $t_c$ CKI		16	40	$\mu\text{s}$
Input Frequency – $f_i$	+ 32 Mode	0.8	2.0	MHz
	+ 16 Mode	0.4	1.0	MHz
	+ 8 Mode	0.2	0.5	MHz
	+ 4 Mode	0.1	0.25	MHz
Duty Cycle		30	60	%
Rise Time	$f_i = 2\text{MHz}$		120	ns
Fall Time			80	ns
CKI Using RC (+ 4)	R = $56\text{k}\Omega \pm 5\%$ C = $100\text{pF} \pm 10\%$			
Instruction Cycle Time CKO as SYNC Input		16	28	$\mu\text{s}$
$t_{\text{SYNC}}$		400		ns
INPUTS : IN <sub>3</sub> -IN <sub>0</sub> , G <sub>3</sub> -G <sub>0</sub> , L <sub>7</sub> -L <sub>0</sub>				
$t_{\text{SETUP}}$			8.0	$\mu\text{s}$
$t_{\text{HOLD}}$			1.3	$\mu\text{s}$
SI				
$t_{\text{SETUP}}$			2.0	$\mu\text{s}$
$t_{\text{HOLD}}$			1.0	$\mu\text{s}$
OUTPUT PROPAGATION DELAY	Test Condition : $C_L = 50\text{pF}$ , $R_L = 20\text{k}\Omega$ , $V_{\text{OUT}} = 1.5\text{V}$			
SO, SK Outputs $t_{\text{PD1}}$ , $t_{\text{PD0}}$			4.0	$\mu\text{s}$
All Other Outputs $t_{\text{PD1}}$ , $t_{\text{PD0}}$			5.6	$\mu\text{s}$

Figure 2 : Connection Diagrams.



Pin	Description
L7-L0	8 Bidirectional I/O Ports with TRI-STATE®
G3-G0	4 Bidirectional I/O Ports
D3-D0	4 General Purpose Outputs
IN3-IN0	4 General Purpose Inputs (ETL9420/L9320 only)
SI	Serial Input (or counter input)
SO	Serial Output (or general purpose output)
SK	Logic-controlled Clock (or general purpose output)
CKI	System Oscillator Input
CKO	System Oscillator Output (or general purpose input, RAM power supply, or SYNC input)
RESET	System Reset Input
VCC	Power Supply
GND	Ground

Figure 3 : Input/Output Timing Diagrams (crystal divide-by-16 mode).

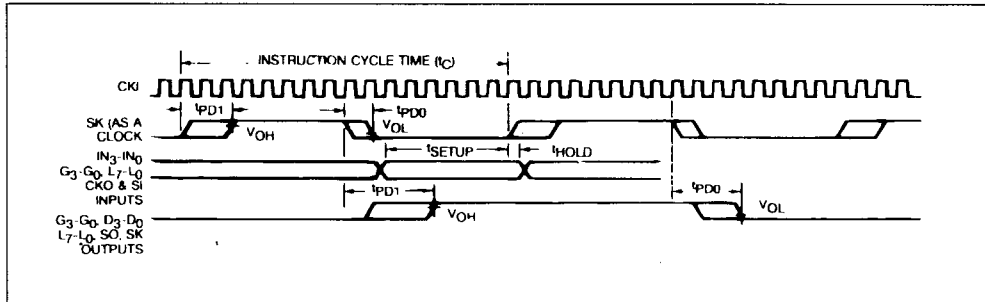
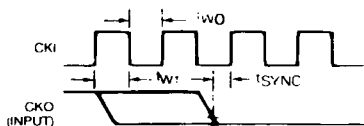




Figure 3a : Synchronization Timing.



## FUNCTIONAL DESCRIPTION

For ease of reading this description, only ETL9420 and/or ETL9421 are referenced ; however, all such references apply also to ETL9320, L9321, L9322 or ETL9422.

A block diagram of the ETL9420 is given in figure 1. Data path are illustrated in simplified form to depict how the various logic elements communicate with each other in implementing the instruction set of the device. Positive logic is used. When a bit is set, it is a logic "1" (greater than 2 volts). When a bit is reset, it is a logic "0" (less than 0.8 volts).

## PROGRAM MEMORY

Program Memory consists of a 1.024 byte ROM. As can be seen by an examination of the ETL9420, L9421, L9422 instruction set, these words may be program instructions, program data or ROM addressing data. Because of the special characteristics associated with the JP, JSRP, JID and LQID instructions, ROM must often be thought of as being organized into 16 pages of 64 words each.

ROM addressing is accomplished by a 10-bit PC register. Its binary value selects one of the 1.024 8-bit words contained in ROM. A new address is loaded into the PC register during each instruction cycle. Unless the instruction is a transfer of control instruction, the PC register is loaded with the next sequential 10-bit binary count value. Three levels of subroutine nesting are implemented by the 10-bit subroutine save registers, SA, SB and SC, providing a last-in, first-out (LIFO) hardware subroutine stack.

ROM instruction words are fetched, decoded and executed by the Instruction Decode, Control and Skip Logic circuitry.

## DATA MEMORY

Data memory consists of a 256-bit RAM, organized as 4 data registers of 16 4-bit digits. RAM addressing is implemented by a 6-bit B register whose up-

per 2 bits (Br) select 1 of 4 data registers and lower 4 bits (Bd) select 1 of 16 4-bit digits in the selected data register. While the 4-bit contents of the selected RAM digit (M) is usually loaded into or from, or exchanged with, the A register (accumulator), it may also be loaded into or from the Q latches or loaded from the L ports. RAM addressing may also be performed directly by the LDD and XAD instructions based upon the 6-bit contents of the operand field of these instructions. The Bd register also serves as a source register for 4-bit data sent directly to the D outputs.

## INTERNAL LOGIC

The 4-bit A register (accumulator) is the source and destination register for most I/O, arithmetic, logic and data memory access operations. It can also be used to load the Br and Bd portions of the B register, to load and input 4 bits of the 8-bit Q latch data, to input 4 bits of the 8-bit L I/O port data and to perform data exchanges with the SIO register.

At 4-bit adder performs the arithmetic and logic functions of the ETL9420, L9421, L9422, storing its results in A. It also outputs a carry bit to the 1 bit C register, most often employed to indicate arithmetic overflow. The C register, in conjunction with the XAS instruction and the EN register, also serves to control the SK output. C can be output directly to SK or can enable SK to be a sync clock each instruction cycle time. (See XAS instruction and EN register description, below).

Four general-purpose inputs, IN<sub>3</sub>-IN<sub>0</sub>, are provided.

The D register provides 4 general-purpose outputs and is used as the destination register for the 4-bit contents of Bd. The D outputs can be directly connected to the digits of a multiplexed LED display.

The G register contents are outputs to 4 general-purpose bidirectional I/O ports. G I/O ports can be directly connected to the digits of a multiplexed LED display.

The Q register is an internal, latched, 8-bit register, used to hold data loaded to or from M and A, as well as 8-bit data from ROM. Its contents are outputted to the L I/O ports when the L drivers are enabled under program control (See LEI instruction).

The 8 L drivers, when enabled, output the contents of latched Q data to the L I/O ports. Also, the contents of L may be read directly into A and M. L I/O ports can be directly connected to the segments of a multiplexed LED display (using the LED Direct Drive output configuration option) with Q data being output to the Sa-Sg and decimal point segments of the display.

The SIO register functions as a 4-bit serial-in/serial-out shift register or as a binary counter depending on the contents of the EN register. (See EN register description, below). Its contents can be exchanged with A, allowing it to input or output a continuous serial data stream. SIO may also be used to provide additional parallel I/O by connecting SO to external serial-in/parallel-out shift registers.

The XAS instruction copies C into the SKL latch. In the counter mode, SK is the output of SKL ; in the shift register mode, SK outputs SKL ANDed with the clock.

The EN register is an internal 4-bit register loaded under program control by the LEI instruction. The state of each bit of this register selects or deselects the particular feature associated with each bit of the EN register (EN<sub>3</sub>-EN<sub>0</sub>).

1. The least significant bit of the enable register, EN<sub>0</sub>, selects the SIO register as either a 4-bit shift

register or a 4-bit binary counter. With EN<sub>0</sub> set, SIO is an asynchronous binary counter, *decrementing* its value by one upon each low-going pulse ("1" to "0") occurring on the SI input. Each pulse must be at least two instruction cycles wide. SK outputs the value of SKL. The SO output is equal to the value of EN<sub>3</sub>. With EN<sub>0</sub> reset, SIO is a serial shift register shifting left each instruction cycle time. The data present at SI goes into the least significant bit of SIO. SO can be enabled to output the most significant bit of SIO each cycle time. (see 4 below). The SK output becomes a logic-controlled clock.

2. With EN<sub>1</sub> set the IN<sub>1</sub> input is enabled as an interrupt input. Immediately following an interrupt, EN<sub>1</sub> is reset to disable further interrupts.
3. With EN<sub>2</sub> set, the L drivers are enabled to output the data in Q to the L I/O ports. Resetting EN<sub>2</sub> disables the L drivers, placing the L I/O ports in a high-impedance input state.
4. EN<sub>3</sub> in conjunction with EN<sub>0</sub>, affects the SO output. With EN<sub>0</sub> set (binary counter option selected) SO will output the value loaded into EN<sub>3</sub>. With EN<sub>0</sub> reset (serial shift register option selected), setting EN<sub>3</sub> enables SO as the output of the SIO shift register outputting serial shifted data each instruction time. Resetting EN<sub>3</sub> with the serial shift register option selected disables SO as the shift register output ; data continues to be shifted through SIO and can be exchanged with A via an XAS instruction but SO remains reset to "0". The table below provides a summary of the modes associated with EN<sub>3</sub> and EN<sub>0</sub>.

**Enable Register Modes - Bits EN<sub>3</sub> and EN<sub>0</sub>**

EN <sub>3</sub>	EN <sub>0</sub>	SIO	SI	SO	SK
0	0	Shift Register	Input to Shift Register	0	If SKL = 1, SK = Clock If SKL = 0, SK = 0
1	0	Shift Register	Input to Shift Register	Serial Out	If SKL = 1, SK = Clock If SKL = 0, SK = 0
0	1	Binary Counter	Input to Binary Counter	0	If SKL = 1, SK = 1 If SKL = 0, SK = 0
1	1	Binary Counter	Input to Binary Counter	1	If SKL = 1, SK = 1 If SKL = 0, SK = 0

**INTERRUPT**

The following features are associated with the IN<sub>1</sub> interrupt procedure and protocol and must be considered by the programmer when utilizing interrupts.

- a. The interrupt, once acknowledged as explained below, pushes the next sequential program counter address (PC + 1) onto the stack, pushing in turn the contents of the other subroutine-save registers to the next lower level

(PC + 1 → SA → SB → SC). Any previous contents of SC are lost. The program counter is set to hex address 0FF (the last word of page 3) and EN<sub>1</sub> is reset.

- b. An interrupt will be acknowledged only after the following conditions are met :
  1. EN<sub>1</sub> has been set.
  2. A low-going pulse ("1" to "0") at least two instruction cycles wide occurs on the IN<sub>1</sub> input.

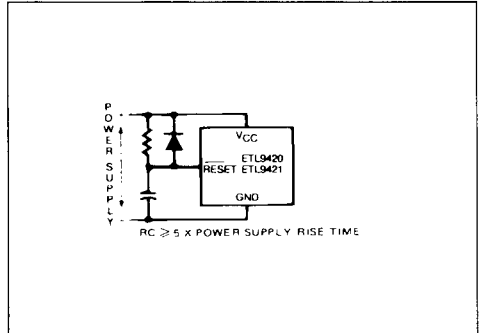
3. A currently executing instruction has been completed.
4. All successive transfer of control instructions and successive LBIs have been completed (e.g., if the main program is executing a JP instruction which transfers program control to another JP instruction, the interrupt will not be acknowledged until the second JP instruction has been executed.
- c. Upon acknowledgement of an interrupt, the skip logic status is saved and later restored upon popping of the stack. For example, if an interrupt occurs during the execution of ASC (Add with Carry, Skip on Carry) instruction which results in carry, the skip logic status is saved and program control is transferred to the interrupt servicing routine at hex address 0FF. At the end of the interrupt routine, a RET instruction is executed to "pop" the stack and return program control to the instruction following the original ASC. *At this time*, the skip logic is enabled and skips this instruction because of the previous ASC carry. Sub-routines and LQID instructions should not be nested within the interrupt servicing routine since their popping the stack will enable any previously saved main program skips, interfering with the orderly execution of the interrupt routine.
- d. The first instruction of the interrupt routine at hex address 0FF must be a NOP.
- e. A LEI instruction can be put immediately before the RET to re-enable interrupts.

#### INITIALIZATION

The Reset Logic will initialize (clear) the device upon power-up if the power supply rise time is less than 1ms and greater than 1 $\mu$ s. If the power supply rise time is greater than 1ms, the user must provide an external RC network and diode to the RESET pin as shown below. The RESET pin is configured as a Schmitt trigger input. If not used it should be connected to Vcc. Initialization will occur whenever a logic "0" is applied to the RESET input, provided it stays low for at least three instruction cycle times.

Upon initialization, the PC register is cleared to 0 (ROM address 0) and the A, B, C, D, EN, and G registers are cleared. The SK output is enabled as a SYNC output, providing a pulse each instruction cycle time. *Data Memory (RAM) is not cleared upon initialization.* The first instruction at address 0 must be a CLRA.

#### Power-up Clear Circuit



#### OSCILLATOR

There are three basic clock oscillator configurations available as shown by figure 4.

- a. **Crystal Controlled Oscillator.** CKI and CKO are connected to an external crystal. The instruction cycle time equals the crystal frequency divided by 32 (optional by 16 or 8).
- b. **External Oscillator.** CKI is an external clock input signal. The external frequency is divided by 32 (optional by 16 or 8) to give the instruction cycle time. CKO is now available to be used as the RAM power supply ( $V_R$ ), as a general purpose input, or as a SYNC input.
- c. **RC Controlled Oscillator.** CKI is configured as a single pin RC controlled Schmitt trigger oscillator. The instruction cycle equals the oscillation frequency divided by 4. CKO is available as the RAM power supply ( $V_R$ ) or as a general purpose input.

**CKO PIN OPTIONS**

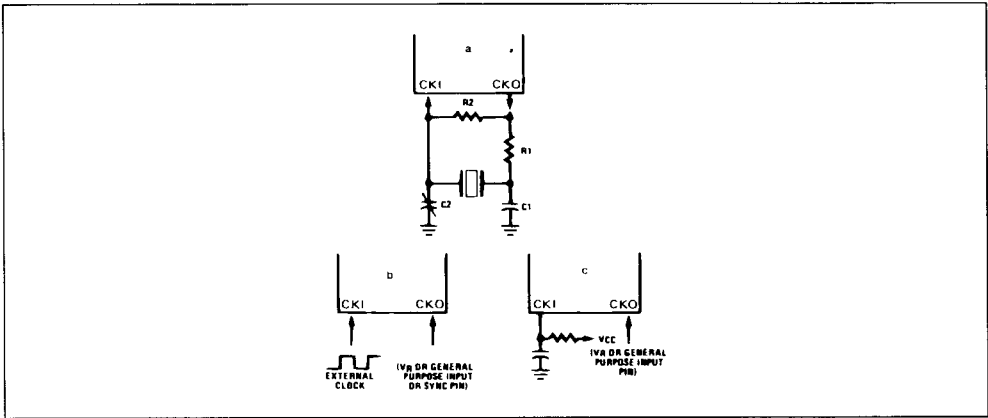
In a crystal controlled oscillator system, CKO is used as an output to the crystal network. As an option CKO can be a SYNC input as described above. As another option CKO can be a general purpose input, read into bit 2 of A (accumulator) upon execution of an INIL instruction. As another option, CKO can be a RAM power supply pin ( $V_R$ ), allowing its connection to a standby/backup power supply to maintain the integrity of RAM data with minimum power drain where the main supply is inoperative or shut down to conserve power. Using either option is appropriate in application where the ETL9420/L9421/L9422 system timing configuration does not require use of the CKO pin.

RAM KEEP-ALIVE OPTION (not available on ETL9422).

Selecting CKO as the RAM power supply ( $V_R$ ) allows the user to shut off the chip power supply ( $V_{CC}$ ) and maintain data in the RAM. To insure that RAM data integrity is maintained, the following conditions must be met :

1. RESET must go low before  $V_{CC}$  goes below spec during power-off ;  $V_{CC}$  must be within spec before RESET goes high on power-up.
2. During normal operation  $V_R$  must be within the operating range of the chip, with  $(V_{CC} - 1) \leq V_R \leq V_{CC}$ .
3.  $V_R$  must be  $\geq 3.3V$  with  $V_{CC}$  off.

**Figure 4 :** ETL9420/L9421/L9422 Oscillator.



**CRYSTAL OSCILLATOR**

Crystal Value	Component Values			
	R1 ( $\Omega$ )	R2 ( $\Omega$ )	C1 (pF)	C2 (pF)
455kHz	4.7k	1M	220	220
2.097MHz	1k	1M	30	6-36

**RC CONTROLLED OSCILLATOR**

R (k $\Omega$ )	C (pF)	Instruction Cycle Time ( $\mu$ s)
51	100	19 $\pm$ 15%
82	56	19 $\pm$ 13%

**Note :** 200k  $\geq R \geq$  25k.  
360pF  $\geq C \geq$  50pF.

## I/O OPTIONS

ETL9420/L9421/L9422 outputs have the following optional configurations, illustrated in figure 5 :

- a. **Standard** - an enhancement mode device to ground in conjunction with a depletion-mode device to  $V_{CC}$ , compatible with LSTTL and CMOS input requirements. Available on SO, SK and all D and G outputs.
  - b. **Open-Drain** - an enhancement-mode device to ground only, allowing external pull-up as required by the user's application. Available on SO, SK, and all D and G outputs.
  - c. **Push-Pull** - An enhancement-mode device to ground in conjunction with a depletion-mode device paralleled by an enhancement-mode device to  $V_{CC}$ . This configuration has been provided to allow for fast rise and fall times when driving capacitive loads. Available on SO and SK outputs only.
  - d. **Standard L** - same as a., but may be disabled. Available on L outputs only.
  - e. **Open Drain L** - same as b., but may be disabled. Available on L outputs only.
  - f. **LED Direct Drive** - an enhancement-mode device to ground and to  $V_{CC}$ , meeting the typical current sourcing requirements of the segments of an LED display. The sourcing device is clamped to limit current flow. These devices may be turned off under program control (see Functional Description, EN Register), placing the outputs in a high-impedance state to provide required LED segment blanking for a multiplexed display. Available on L outputs only.
  - g. **TRI-STATE® Push-Pull** - an enhancement-mode device to ground and  $V_{CC}$ . These outputs are TRI-STATE outputs, allowing for connection of these outputs to a data bus shared by other bus drivers. Available on L outputs only.
- ETL9420/L9421/L9422 inputs have the following optional configurations.
- h. An on-chip depletion load device to  $V_{CC}$ .

- i. A Hi-Z input which must be driven to a "1" or "0" by external components.

The above input and output configurations share common enhancement-mode and depletion-mode devices. Specifically, all configurations use one or more of six devices (numbered 1-6, respectively). Minimum and maximum current ( $I_{OUT}$  and  $V_{OUT}$ ) curves are given in figure 6 for each of these devices to allow the designer to effectively use these I/O configurations in designing a ETL9420/L9421 system.

The SO, SK outputs can be configured as shown in a., b., or c. The D and G outputs can be configured as shown in a. or b. Note that when inputting data to the G ports, the G outputs should be set to "1". The L outputs can be configured as in d., e., f. or g.

An important point to remember if using configuration d. or f. with the L drivers is that even when the L drivers are disabled, the depletion load device will source a small amount of current (see figure 6, device 2) ; however, when the L lines are used as inputs, the disabled depletion device *cannot* be relied on to source sufficient current to pull an input to a logic 1.

## ETL9421

If the ETL9420 is bonded as a 24-pin device, it becomes the ETL9421, illustrated in figure 2, ETL9420/L9421 Connection Diagrams. Note that the ETL9421 does not contain the four general purpose IN inputs ( $IN_3$ - $IN_0$ ). Use of this option precludes, of course, use of the IN options and the interrupt feature. All other options are available for the ETL9421.

## ETL9422

If the ETL9420 is bonded as a 20-pin device, it becomes the ETL9422, as illustrated in figure 2. Note that the ETL9422 contains all the ETL9421 pins except  $D_0$ ,  $D_1$ ,  $G_0$ , and  $G_1$ , ETL9422 also does not allow RAM power supply input as a valid CKO pin option.

Figure 5 : Output Configurations.

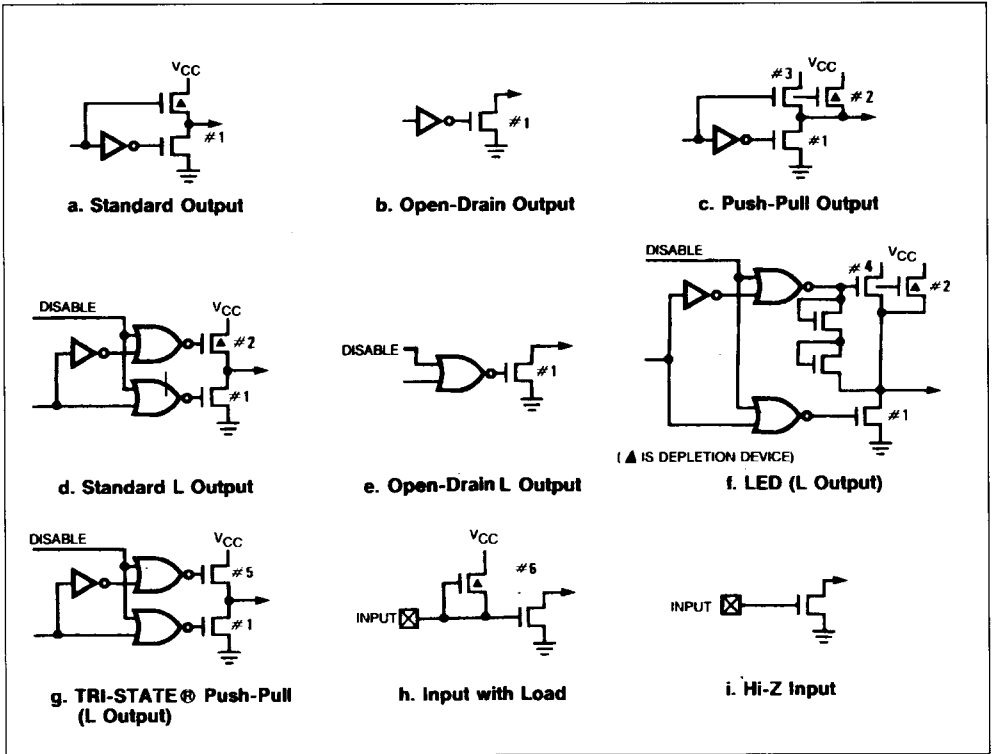


Figure 6 : ETL9420/L9421/L9422 Input/Output Characteristics.

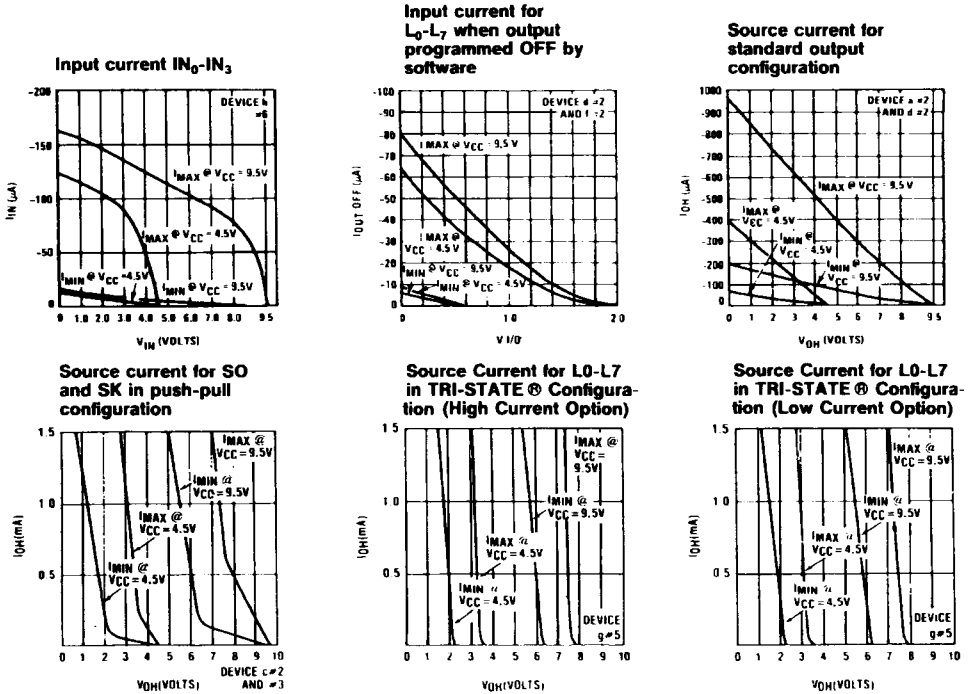
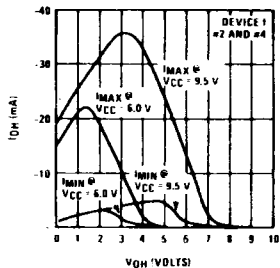
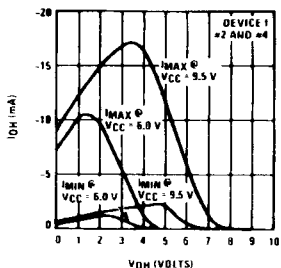


Figure 6 : ETL9420/L9421/L9422 Input/Output Characteristics (continued).

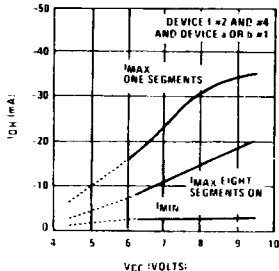
**LED output source current (for high current LED option)**



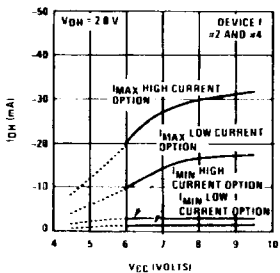
**LED output source current (for low current LED option)**



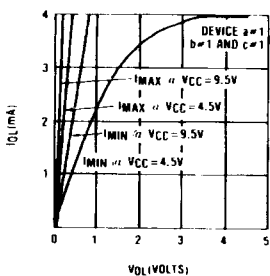
**LED Output Direct Segment and Digit Drive (High Current Options on L0-L7) (Very High Current Options on D0-D3 or G0-G3)**



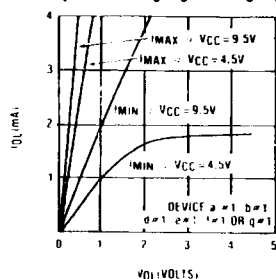
**LED Output Direct Segment Drive**



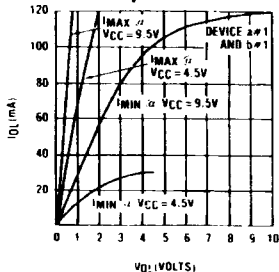
**Output sink current for SO and SK**



**Output sink current for L0-L7 and standard drive option for D0-D3 and G0-G3**



**Output Sink Current G0-G3 and D0-D3 with Very High Current Option**



**Output sink current for G0-G3 and D0-D3 (for high current option)**

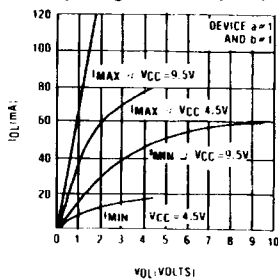
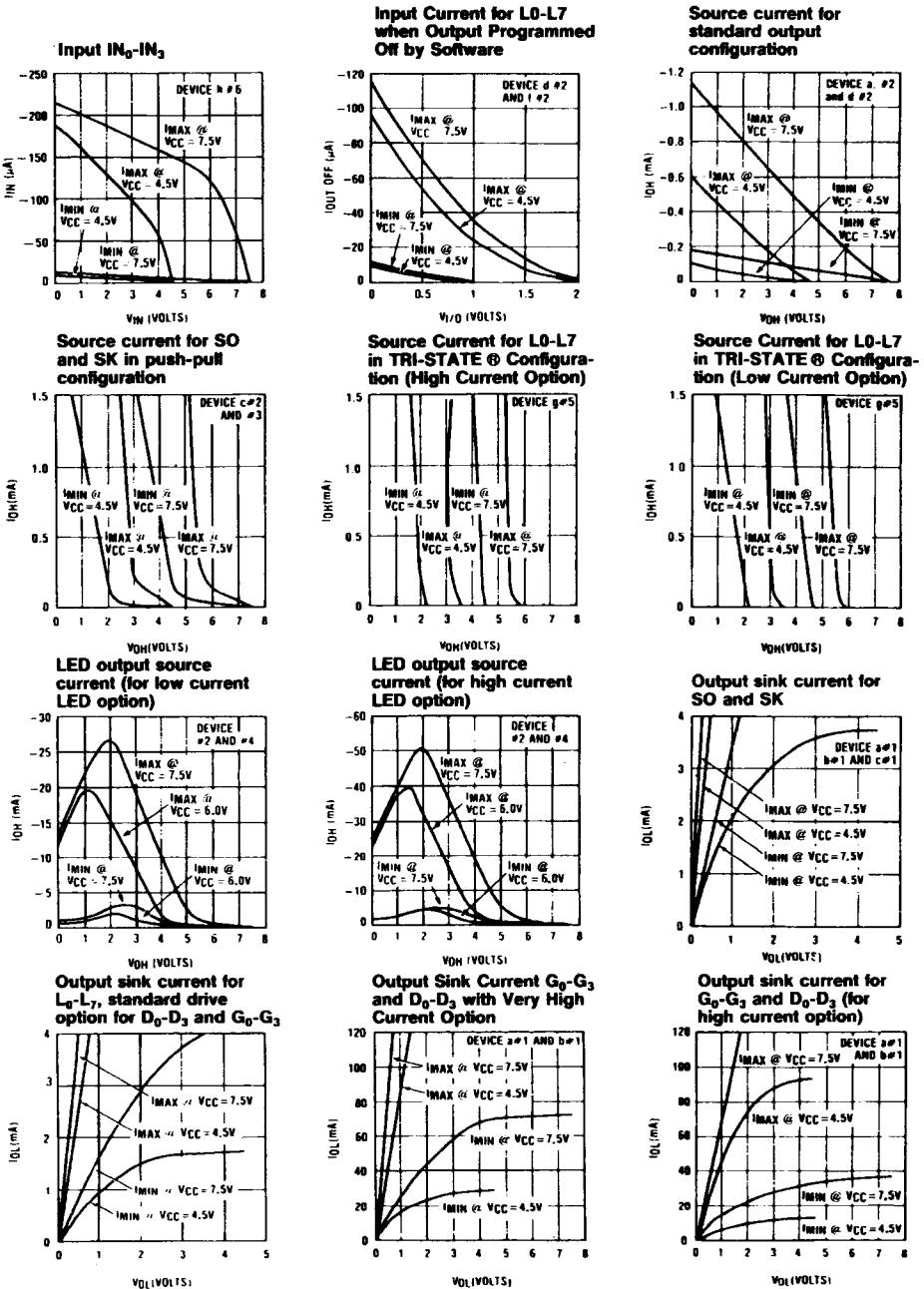




Figure 7 : ETL9320/L9321/L9322 Input/Output Characteristics.



**ETL9420/L9421/L9422 - INSTRUCTION SET**

Table 1 is a symbol table providing internal architecture, instruction operand and operational symbols used in the instruction set table.

**Table 1 : ETL9420/L9421/L9422 Instruction Set Table Symbols.**

**INTERNAL ARCHITECTURE SYMBOLS**

Symbol	Definition
A	4-bit Accumulator
B	6-bit RAM Address Register
Br	Upper 2 Bits of B (register address)
Bd	Lower 4 Bits of B (digit address)
C	1-bit Carry Register
D	4-bit Data Output Port
EN	4-bit Enable Register
G	4-bit Register to Latch Data for G I/O Port
IL	Two 1-bit latches associated with the IN <sub>3</sub> or IN <sub>0</sub> inputs.
IN	4-bit Input Port
L	8-bit TRI-STATE I/O Port
M	4-bit contents of RAM memory pointed to by B register.
PC	10-bit ROM Address Register (program counter)
Q	8-bit Register to Latch Data for L I/O Port
SA	10-bit Subroutine Save Register A
SB	10-bit Subroutine Save Register B
SC	10-bit Subroutine Save Register C
SIO	4-bit Shift Register and Counter
SK	Logic-controlled Clock Output

Table 2 provides the mnemonic, operand, machine code, data flow, skip conditions, and description associated with each instruction in the ETL9420/L9421/L9422 instruction set.

**INSTRUCTION OPERAND SYMBOLS**

Symbol	Definition
d	4-bit Operand Field, 0-15 Binary (RAM digit select)
r	2-bit Operand Field, 0-3 Binary (RAM register select)
a	10-bit Operand Field, 0-1023 Binary (ROM address)
y	4-bit Operand Field, 0-15 Binary (immediate data)
RAM(s)	Contents of RAM location addressed by s.
ROM(t)	Contents of ROM location addressed by t.

**OPERATIONAL SYMBOLS**

Symbol	Definition
+	Plus
-	Minus
→	Replaces
↔	Is exchanged with.
≡	Is equal to.
A	The one's complement of A.
⊕	Exclusive-OR
:	Range of Values

Table 2 : ETL9420/L9421/9422 Instruction Set.

ARITHMETIC INSTRUCTIONS

Mnem	Operand	Hex Code	Machine Language Code (binary)	Data Flow	Skip Conditions	Description
ASC		30	0 0 1 1   0 0 0 0	$A + C + RAM(B) \rightarrow A$ Carry $\rightarrow C$	Carry	Add with Carry, Skip on Carry
ADD		31	0 0 1 1   0 0 0 1	$A + RAM(B) \rightarrow A$	None	Add RAM to A
ADT		4A	0 1 0 0   1 0 1 0	$A + 10_{10} \rightarrow A$	None	Add Ten to A
AISC	y	5-	0 1 0 1   y	$A + y \rightarrow A$	Carry	Add Immediate, Skip on Carry ( $y \neq 0$ )
CASC		10	0 0 0 1   0 0 0 0	$\bar{A} + RAM(B) + C \rightarrow A$ Carry $\rightarrow C$	Carry	Complement and Add with Carry, Skip on Carry
CLRA		00	0 0 0 0   0 0 0 0	$0 \rightarrow A$	None	Clear A
COMP		40	0 1 0 0   0 0 0 0	$\bar{A} \rightarrow A$	None	Ones Complement of A to A
NOP		44	0 1 0 0   0 1 0 0	None	None	No Operation
RC		32	0 0 1 1   0 0 1 0	"0" $\rightarrow C$	None	Reset C
SC		22	0 0 1 0   0 0 1 0	"1" $\rightarrow C$	None	Set C
XOR		02	0 0 0 0   0 0 1 0	$A \oplus RAM(B) \rightarrow A$	None	Exclusive-OR Ram with A

TRANSFER OF CONTROL INSTRUCTIONS

Mnem	Operand	Hex Code	Machine Language Code (binary)	Data Flow	Skip Conditions	Description
JID		FF	1 1 1 1   1 1 1 1	ROM ( $PC_{9:8}$ A, M) $\rightarrow PC_{7:0}$	None	Jump Indirect (note 3)
JMP	a	6-	0 1 1 0   0 0   a <sub>9:8</sub>     a <sub>7:0</sub>	$a \rightarrow PC$	None	Jump
JP	a		1   a <sub>6:0</sub>   (pages 2,3 only) or   1 1   a <sub>5:0</sub>   (all other pages)	$A \rightarrow PC_{6:0}$  $A \rightarrow PC_{5:0}$	None	Jump within Page (note 4)
JSRP	a		1 0   a <sub>5:0</sub>	$PC+1 \rightarrow SA \rightarrow SB \rightarrow SC$ $0010 \rightarrow PC_{9:6}$ $a \rightarrow PC_{5:0}$	None	Jump to Subroutine Page (note 5)
JSR	a	6-	0 1 1 0   1 0   a <sub>9:8</sub>     a <sub>7:0</sub>	$PC+1 \rightarrow SA \rightarrow SB \rightarrow SC$ $a \rightarrow PC$	None	Jump to Subroutine
RET		48	0 1 0 0   1 0 0 0	$SC \rightarrow SB \rightarrow SA \rightarrow PC$	None	Return from Subroutine
RETSK		49	0 1 0 0   1 0 0 1	$SC \rightarrow SB \rightarrow SA \rightarrow PC$	Always Skip on Return	Return from Subroutine then Skip

MEMORY REFERENCE INSTRUCTIONS

Mnem	Operand	Hex Code	Machine Language Code (binary)	Data Flow	Skip Conditions	Description
CAMQ		33	0 0 1 1   0 0 1 1	A → Q <sub>7:4</sub>	None	Copy A, RAM to Q
		3C	0 0 1 1   1 1 0 0	RAM (B) → Q <sub>3:0</sub>		
CQMA		33	0 0 1 1   0 0 1 1	Q <sub>7:4</sub> → RAM(B)	None	Copy Q to RAM, A
		2C	0 0 1 0   1 1 0 0	Q <sub>3:0</sub> → A		
LD	r	-5	0 0   r   0 1 0 1	RAM(B) → A Br • r → Br	None	Load RAM into A, Exclusive-OR Br with r
LDD	r, d	23	0 0 1 0   0 0 1 1     0 0   r   d	RAM(r, d) → A	None	Load A with RAM pointed to directly by r, d.
LQID		BF	1 0 1 1   1 1 1 1	ROM (PC <sub>9:8</sub> A, M) → Q SB → SC	None	Load Q Indirect (note 3)
RMB	0	4C	0 1 0 0   1 1 0 0	0 → RAM(B) <sub>0</sub>	None	Reset RAM Bit
	1	45	0 1 0 0   0 1 0 1	0 → RAM(B) <sub>1</sub>		
	2	42	0 1 0 0   0 0 1 0	0 → RAM(B) <sub>2</sub>		
	3	43	0 1 0 0   0 0 1 1	0 → RAM(B) <sub>3</sub>		
SMB	0	4D	0 1 0 0   1 1 0 1	1 → RAM(B) <sub>0</sub>	None	Set RAM Bit
	1	47	0 1 0 0   1 1 0 1	1 → RAM(B) <sub>1</sub>		
	2	46	0 1 0 0   0 1 1 0	1 → RAM(B) <sub>2</sub>		
	3	4B	0 1 0 0   1 0 1 1	1 → RAM(B) <sub>3</sub>		
STII	y	7-	0 1 1 1   y	y → RAM(B) Bd + 1 → Bd	None	Store Memory Immediate and Increment Bd
X	r	-6	0 0   r   0 1 1 0	RAM (B) ↔ A Br ⊕ r → Br	None	Exchange RAM with A, Exclusive-OR Br with r
XAD	r, d	23	0 0 1 0   0 0 1 1     1 0   r   d	RAM(r, d) ↔ A	None	Exchange A with RAM pointed to directly by r, d.
XDS	r	-7	0 0   r   0 1 1 1	RAM(B) ↔ A Bd - 1 → Bd Br ⊕ r → Br	Bd decrements past 0.	Exchange RAM with A and Decrement Bd, Exclusive-OR Br with r
XIS	r	-4	0 0   r   0 1 0 0	RAM (B) ↔ A Bd + 1 → Bd Br ⊕ r → Br	Bd increments past 15.	Exchange RAM with A and Increment Bd, Exclusive-OR Br with r

REGISTER REFERENCE INSTRUCTIONS

Mnem	Operand	Hex Code	Machine Language Code (binary)	Data Flow	Skip Conditions	Description
CAB		50	0 1 0 1   0 0 0 0	A → Bd	None	Copy A to Bd
CBA		4E	0 1 0 0   1 1 1 0	Bd → A	None	Copy Bd to A
LBI	r, d	33	0 0   r   (d-1) (d = 0.9:15) or 0 0 1 1   0 0 1 1 1 0   r   d (any d)	r, d → B	Skip until not a LBI	Load B Immediate with r, d (note 6)
LEI	y	33 6-	0 0 1 1   0 0 1 1 0 1 1 0   y	y → EN	None	Load EN Immediate (note 7)
XABR		12	0 0 0 1   0 0 1 0	A → Br (0.0 → A <sub>3</sub> , A <sub>2</sub> )	None	Exchange A with Br

TEST INSTRUCTIONS

Mnem	Operand	Hex Code	Machine Language Code (binary)	Data Flow	Skip Conditions	Description
SKC		20	0 0 1 0   0 0 0 0		C = "1"	Skip if C is true.
SKE		21	0 0 1 0   0 0 0 1		A = RAM(B)	Skip if A Equals RAM
SKGZ		33 21	0 0 1 1   0 0 1 1 0 0 1 0   0 0 0 1		G <sub>3:0</sub> = 0	Skip if G is zero (all 4 bits).
SKGBZ	0 1 2 3	01 11 03 13	0 0 1 1   0 0 1 1 0 0 0 0   0 0 0 1 0 0 0 1   0 0 0 1 0 0 0 0   0 0 1 1 0 0 0 1   0 0 1 1	1st Byte 2nd Byte	G <sub>0</sub> = 0 G <sub>1</sub> = 0 G <sub>2</sub> = 0 G <sub>3</sub> = 0	Skip if G Bit is zero.
SKMBZ	0 1 2 3	01 11 03 13	0 0 0 0   0 0 0 1 0 0 0 1   0 0 0 1 0 0 0 0   0 0 1 1 0 0 0 1   0 0 1 1		RAM(B) <sub>0</sub> = 0 RAM(B) <sub>1</sub> = 0 RAM(B) <sub>2</sub> = 0 RAM(B) <sub>3</sub> = 0	Skip if RAM bit is zero.
SKT		41	0 1 0 0   0 0 0 1		A time-base counter carry has occurred since last test.	Skip on Timer (note 3)

INPUT/OUTPUT INSTRUCTIONS

Mnem	Operand	Hex Code	Machine Language Code (binary)	Data Flow	Skip Conditions	Description																
ING		33 2A	<table border="1"><tr><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><td>0</td><td>0</td><td>1</td><td>0</td><td>1</td><td>0</td><td>1</td><td>0</td></tr></table>	0	0	1	1	0	0	1	1	0	0	1	0	1	0	1	0	G → A	None	Input G Ports to A
0	0	1	1	0	0	1	1															
0	0	1	0	1	0	1	0															
ININ		33 28	<table border="1"><tr><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><td>0</td><td>0</td><td>1</td><td>0</td><td>1</td><td>0</td><td>0</td><td>0</td></tr></table>	0	0	1	1	0	0	1	1	0	0	1	0	1	0	0	0	IN → A	None	Input IN Inputs to A (note 2)
0	0	1	1	0	0	1	1															
0	0	1	0	1	0	0	0															
INIL		33 29	<table border="1"><tr><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><td>0</td><td>0</td><td>1</td><td>0</td><td>1</td><td>0</td><td>0</td><td>1</td></tr></table>	0	0	1	1	0	0	1	1	0	0	1	0	1	0	0	1	IL <sub>3</sub> , CKO, "0", IL <sub>0</sub> → A	None	Input IL Latches to A (note 3)
0	0	1	1	0	0	1	1															
0	0	1	0	1	0	0	1															
INL		33 2E	<table border="1"><tr><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><td>0</td><td>0</td><td>1</td><td>0</td><td>1</td><td>1</td><td>1</td><td>1</td></tr></table>	0	0	1	1	0	0	1	1	0	0	1	0	1	1	1	1	L <sub>7:4</sub> → RAM(B) L <sub>3:0</sub> → A	None	Input L Ports to RAM, A
0	0	1	1	0	0	1	1															
0	0	1	0	1	1	1	1															
OBD		33 3E	<table border="1"><tr><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><td>0</td><td>0</td><td>1</td><td>1</td><td>1</td><td>1</td><td>1</td><td>1</td></tr></table>	0	0	1	1	0	0	1	1	0	0	1	1	1	1	1	1	Bd → D	None	Output Bd to D Outputs
0	0	1	1	0	0	1	1															
0	0	1	1	1	1	1	1															
OGI	y	33 5-	<table border="1"><tr><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><td>0</td><td>1</td><td>0</td><td>1</td><td>y</td><td></td><td></td><td></td></tr></table>	0	0	1	1	0	0	1	1	0	1	0	1	y				y → G	None	Output to G Ports Immediate
0	0	1	1	0	0	1	1															
0	1	0	1	y																		
OMG		33 3A	<table border="1"><tr><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><td>0</td><td>0</td><td>1</td><td>1</td><td>1</td><td>0</td><td>1</td><td>0</td></tr></table>	0	0	1	1	0	0	1	1	0	0	1	1	1	0	1	0	RAM(B) → G	None	Output RAM to G Ports
0	0	1	1	0	0	1	1															
0	0	1	1	1	0	1	0															
XAS		4F	<table border="1"><tr><td>0</td><td>1</td><td>0</td><td>0</td><td>1</td><td>1</td><td>1</td><td>1</td></tr></table>	0	1	0	0	1	1	1	1	A ↔ SIO, C → SKL	None	Exchange A with SIO (note 3)								
0	1	0	0	1	1	1	1															

**Note :** 1. All subscripts for alphabetical symbols indicate bit numbers unless explicitly defined (e.g., Br and Bd are explicitly defined). Bits are numbered 0 to N where 0 signifies the least significant bit (low-order, right-most bit). For example, A<sub>3</sub> indicates the most significant (left-most) bit of the 4-bit A register.

**Note :** 2. The ININ instruction is only available on the 28-pin ETL9420 as the other devices do not contain the IN inputs.

**Note :** 3. For additional information on the operation of the XAS, JID, LQID, INIL, and SKT instructions, see below.

**Note :** 4. The JP instruction allows a jump, while a subroutine pages 2 or 3, to any ROM location within the two-page boundary of pages 2 or 3. The JP instruction, otherwise, permits a jump to a ROM location within the current 64-word page. JP may not jump to the last word of a page.

**Note :** 5. A JSRP transfers program control to subroutine page 2 (0010 is loaded into the upper 4 bits of P). A JSRP may not be used when in pages 2 or 3. JSRP may not jump to the last word in page 2.

**Note :** 6. LBI is a single-byte instruction if d = 0, 9, 10, 11, 12, 13, 14 or 15. The machine code for the lower 4 bits equals the binary value of the "d" data minus 1, e.g., to load the lower four bits of B (Bd) with the value 9 (1001<sub>2</sub>), the lower 4 bits of the LBI instruction equal 8 (1000<sub>2</sub>). To load 0, the lower 4 bits of the LBI instruction should equal 15 (1111<sub>2</sub>).

**Note :** 7. Machine code for operand field y for LEI instruction should equal the binary value to be latched into EN, where a "1" or "0" in each bit of EN corresponds with the selection or deselection of a particular function associated with each bit. (see Functional Description EN Register).

The following information is provided to assist the user in understanding the operation of several unique instructions and to provide note useful to programmers in writing ETL9420/L9421/L9422 programs.

XAS INSTRUCTION

XAS (Exchange A with SIO) exchanges the 4-bit contents of the accumulator with the 4-bit contents of the SIO register. The contents of SIO will contain serial-in/serial-out shift register or binary counter data, depending on the value of the EN register. An XAS instruction will also affect the SK output. (see Functional Description, EN Register, above). If SIO is selected as a shift register, an XAS instruction must be performed once every 4 instruction cycles to effect a continuous data stream.

JID INSTRUCTION

JID (Jump Indirect) is an indirect addressing instruction, transferring program control to a new ROM location pointed to indirectly by A and M. It loads the lower 8 bits of the ROM address register PC with the contents of ROM addressed by the 10-bit word, PC<sub>9:8</sub>, A, M, PC<sub>9</sub> and PC<sub>8</sub> are not affected by this instruction.

Note that JID requires 2 instruction cycles to execute.

INIL INSTRUCTION

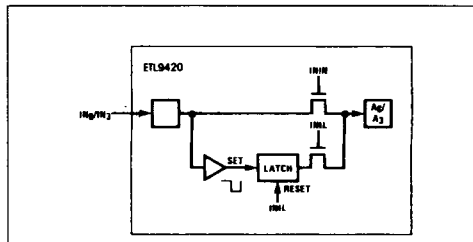
INIL (Input IL Latches to A) inputs 2 latches, IL<sub>3</sub> and IL<sub>0</sub> (see figure 8) and CKO into A. The IL<sub>3</sub> and IL<sub>0</sub> latches are set if a low-going pulse ("1" to "0") has occurred on the IN<sub>3</sub> and IN<sub>0</sub> inputs since the last INIL

instruction, provided the input pulse stays low for at least two instruction times. Execution of an INIL inputs  $IL_3$  and  $IL_0$  into A3 and A0 respectively, and resets these latches to allow them to respond to subsequent low-going pulses on the  $IN_3$  and  $IN_0$  lines. If CKO is mask programmed as a general purpose input, an INIL will input the state of CKO into A2. If CKO has not been so programmed, a "1" will be placed in A2. A "0" is always placed in A1 upon the execution of an INIL. The general purpose inputs  $IN_3$ - $IN_0$  are input to A upon execution of an ININ instruction. (see table 2, ININ instruction). INIL is useful in recognizing pulses of short duration or pulses which occur too often to be read conveniently by an ININ instruction. IL latches are not cleared on reset.

### LQID INSTRUCTION

LQID (Load Q Indirect) loads the 8-bit Q register with the contents of ROM pointed to by the 10-bit word  $PC_9$ ,  $PC_8$ , A, M. LQID can be used for table lookup or code conversion such as BCD to seven-segment. The LQID instruction "pushes" the stack ( $PC + 1 \rightarrow SA \rightarrow SB \rightarrow SC$ ) and replaces the least significant 8 bits of PC as follows:  $A \rightarrow PC_{7,4}$ ,  $RAM(B) \rightarrow PC_{3,0}$ , leaving  $PC_9$  and  $PC_8$  unchanged. The ROM data pointed to by the new address is fetched and loaded into the Q latches. Next, the stack is "popped" ( $SC \rightarrow SB \rightarrow SA \rightarrow PC$ ), restoring the saved value of PC to continue sequential program execution. Since LQID pushes  $SB \rightarrow SC$ , the previous contents of SC are lost. Also, when LQID pops the stack, the previously pushed contents of SB are left in SC. The net result is that the contents of SB are placed in SC ( $SB \rightarrow SC$ ). Note that LQID takes two instruction cycle times to execute.

Figure 8 : INIL Hardware Implementation.



### SKT INSTRUCTION

The SKT (Skip On Timer) instruction tests the state of an internal 10-bit time-base counter. This counter divides the instruction cycle clock frequency by 1024 and provides a latched indication of counter overflow. The SKT instruction tests this latch, executing the next program instruction if the latch is not set. If the latch has been set since the previous test, the next program instruction is skipped and the latch is reset. The features associated with this instruction, therefore, allow the ETL9420/L9421/L9422 to generate its own time-base for real-time processing rather than relying on an external input signal.

For example, using a 2.097MHz crystal as the time-base to the clock generator, the instruction cycle clock frequency will be 65kHz (crystal frequency 32) and the binary counter output pulse frequency will be 64Hz. For time-of-day or similar real-time processing, the SKT instruction can call a routine which increments a "seconds" counter every 64 ticks.

### INSTRUCTION SET NOTES

- The first word of a ETL9420/L9421/L9422 program (ROM address 0) must be a CLRA (Clear A) instruction.
- Although skipped instructions are not executed, one instruction cycle time is devoted to skipping each byte of the skipped instruction. Thus all program paths except JID and LQID take the same number of cycle times whether instructions are skipped or executed. JID and LQID instructions take 2 cycles if executed and 1 cycle if skipped.
- The ROM is organized into 16 pages of 64 words each. The Program Counter is a 10-bit binary counter, and will count through page boundaries. If a JP, JSRP, JID or LQID instruction is located in the last word of a page, the instruction operates as if it were in the next page. For example: a JP located in the last word of a page will jump to a location in the next page. Also, a LQID or JID located in the last word of page 3, 7, 11, or 15 will access data in the next group of four pages.

**OPTION LIST**

The ETL9420/L9421/L9422 mask-programmable options are assigned numbers which correspond with the ETL9420 pins.

The following is a list of ETL9420 options. When specifying a ETL9421 chip, Options 9, 10, 19, and 20 must all be set to zero. When specifying a ETL9422 chip, options 9, 10, 19, and 20 must all be set to zero ; options 21 and 22 may not be set to one, three or five ; and option 2 may not be set to one. The options are programmed at the same time as the ROM pattern to provide the user with the hardware flexibility to interface to various I/O components using little or no external circuitry.

Option 1 = 0 : Ground Pin - no options available

Option 2 : CKO Output

- = 0 : clock generator output to crystal/resonator (0 not allowable value if Option 3 = 3)
- = 1 : pin is RAM power supply ( $V_R$ ) input (not available on the ETL9422)
- = 2 : general purpose input with load device to  $V_{CC}$
- = 3 : general purpose input, Hi-Z

Option 3 : CKI Input

- = 0 : oscillator input divided by 32 (2MHz max.)
- = 1 : oscillator input divided by 16 (1MHz max.)
- = 2 : oscillator input divided by 8 (500kHz max.)
- = 3 : single-pin RC controlled oscillator (+ 4)
- = 4 : Schmitt trigger clock input (+ 4)

Option 4 : RESET Input

- = 0 : load device to  $V_{CC}$
- = 1 : Hi-Z input

Option 5 : L<sub>7</sub> Driver

- = 0 : Standard output
- = 1 : Open-drain output
- = 2 : High current LED direct segment drive output
- = 3 : High current TRI-STATE® push-pull output
- = 4 : Low-current LED direct segment drive output
- = 5 : Low-current TRI-STATE® push-pull output

Option 6 : L<sub>6</sub> Driver

same as Option 5

Option 7 : L<sub>5</sub> Driver

same as Option 5

Option 8 : L<sub>4</sub> Driver

same as Option 5

Option 9 : IN<sub>1</sub> Input

- = 0 : load device to  $V_{CC}$
- = 1 : Hi-Z input

Option 10 : IN<sub>2</sub> Input

same as Option 9

Option 11 : V<sub>CC</sub> pin

- = 0 : Standard  $V_{CC}$
- = 1 : Optional higher voltage  $V_{CC}$

Option 12 : L<sub>3</sub> Driver

same as Option 5

Option 13 : L<sub>2</sub> Driver

same as Option 5

Option 14 : L<sub>1</sub> Driver

same as Option 5

Option 15 : L<sub>0</sub> Driver

same as Option 5

Option 16 : SI Input

same as Option 9

Option 17 : SO Driver

- = 0 : standard output
- = 1 : open-drain output
- = 2 : push-pull output

Option 18 : SK Driver

same as Option 17

Option 19 : IN<sub>0</sub> Input

same as Option 9

Option 20 : IN<sub>3</sub> Input

same as Option 9

Option 21 : G<sub>0</sub> I/O Port

- = 0 : very-high current standard output
- = 1 : very-high current open-drain output
- = 2 : high current standard output
- = 3 : high current open-drain output
- = 4 : standard LSTTL output (fanout = 1)
- = 5 : open-drain LSTTL output (fanout = 1)

Option 22 : G<sub>1</sub> I/O Port

same as Option 21

Option 23 : G<sub>2</sub> I/O Port

same as Option 21

Option 24 : G<sub>3</sub> I/O Port

same as Option 21

Option 25 : D<sub>3</sub> Output

same as Option 21

Option 26 : D<sub>2</sub> Output

same as Option 21



Option 27 : D<sub>1</sub> Output  
same as Option 21

Option 28 : D<sub>0</sub> Output  
same as Option 21

Option 29 : L Input Levels  
= 0 : standard TTL input levels  
("0" = 0.8V, "1" = 2.0V)  
= 1 : higher voltage input levels  
("0" = 1.2V, "1" = 3.6V)

Option 30 : IN Input Levels  
same as Option 29

Option 31 : G Input Levels  
same as Option 29

Option 32 : SI Input Levels  
same as Option 29

Option 33 :  $\overline{\text{RESET}}$  Input

- = 0 : Schmitt trigger input
- = 1 : standard TTL input levels
- = 2 : higher voltage input levels

Option 34 : CKO Input Levels (CKO = input ; Option  
2 = 2, 3)  
same as Option 29

Option 35 COP Bonding

- = 0 : ETL9420 (28-pin device)
- = 1 : ETL9421 (24-pin device)
- = 2 : 28 and 24-pin versions
- = 3 : ETL9422 (20-pin device)
- = 4 : 28- and 20-pin versions
- = 5 : 24- and 20- pin versions
- = 6 : 28-, 24-, and 20-pin versions

**TEST MODE** (Non-Standard Operation)

The SO output has been configured to provide for standard test procedures for the custom-programmed ETL9420. With SO forced to logic "1", two test modes are provided, depending upon the value of SI :

- a. RAM and Internal Logic Test Mode (SI = 1).
- b. ROM Test Mode (SI = 0).

These special test modes should not be employed by the user ; they are intended for manufacturing test only.

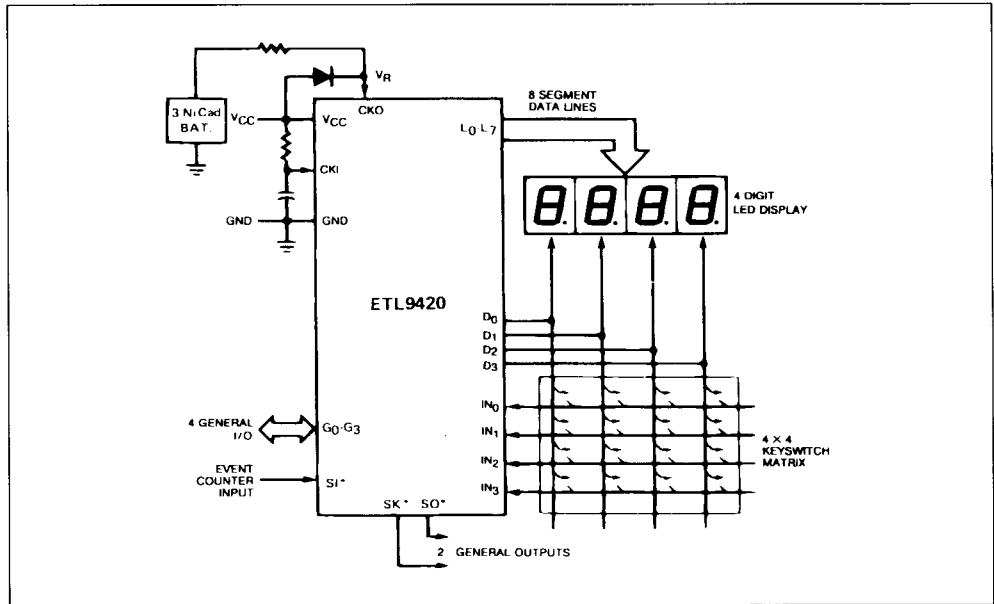
**APPLICATION 1** : ETL9420 General Controller

Figure 9 shows an interconnect diagram for a ETL9420 used as a general controller. Operation of the system is as follows :

- 1. The L7-L0 outputs are configured as LED Direct Drive outputs, allowing direct connection to the segments of the display.

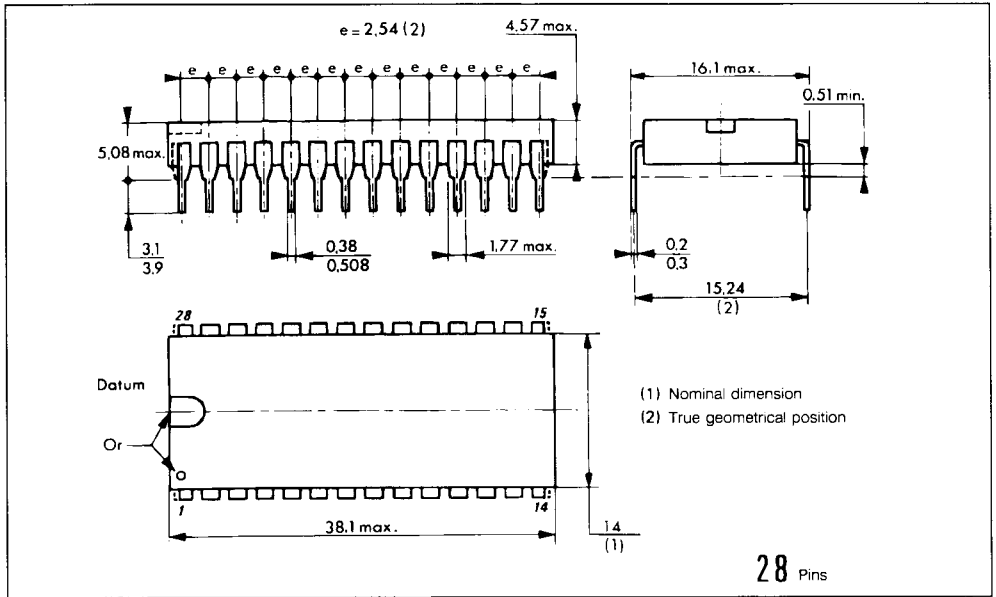
- 2. The D3-D0 outputs drive the digits of the multiplexed display directly and scan the columns of the 4 x 4 keyboard matrix.
- 3. The IN3-IN0 inputs are used to input the 4 rows of the keyboard matrix. Reading the IN lines in conjunction with the current value of the D outputs allows detection, debouncing, and decoding of any one of the 16 keyswitches.
- 4. CKI is configured as a single-pin oscillator input allowing system timing to be controlled by a single-pin RC network. CKO is therefore available for use as a V<sub>R</sub> RAM power supply pin. RAM data integrity is thereby assured when the main power supply is shut down (see RAM Keep-Alive option description).
- 5. SI is selected as the input to a binary counter input. With SIO used as a binary counter, SO and SK can be used as general purpose outputs.
- 6. The 4 bidirectional G I/O ports (G3-G0) are available for use as required by the user's application.

**Figure 9** : ETL9420 Keyboard/Display Interface.

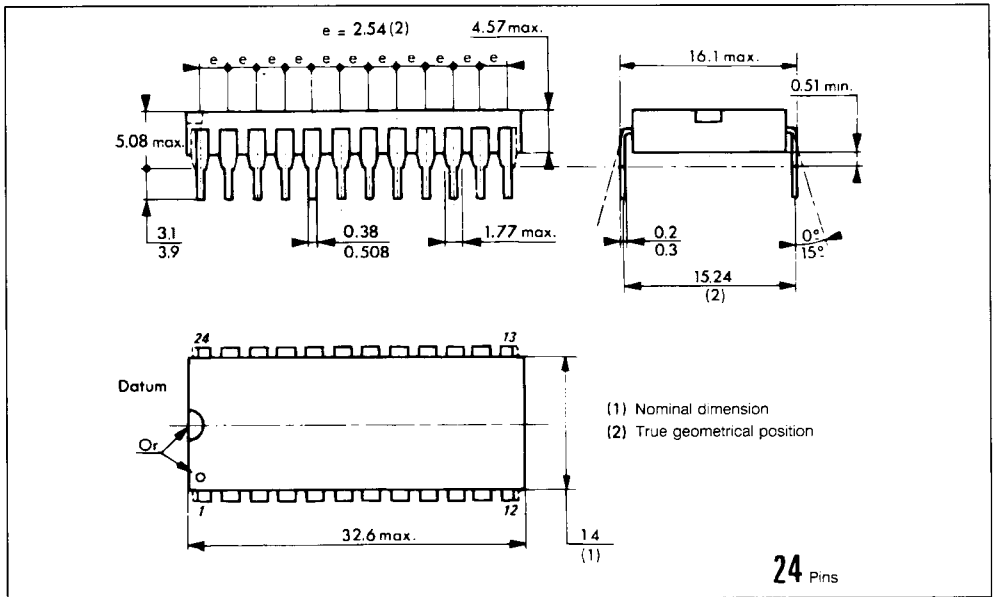


PHYSICAL DIMENSIONS

28-PINS – PLASTIC PACKAGE



24-PINS – PLASTIC PACKAGE



PHYSICAL DIMENSIONS (continued)

20-PINS - PLASTIC PACKAGE

