## 1-bit to 2-bit Address Driver with 3-state Outputs

# HITACHI

ADE-205-197 (Z) Preliminary 1st. Edition November 1997

#### Description

This 1-bit to 2-bit address driver is designed for 2.3 V to 3.6 V  $V_{CC}$  operation. To ensure the high impedance state during power up or power down,  $\overline{OE}$  should be tied to  $V_{CC}$  through a pullup resistor; the minimum value of the resistor is determined by the current sinking capability of the driver. Active bus hold circuitry is provided to hold unused or floating inputs at a valid logic level. All outputs, which are designed to sink up to 12 mA, include equivalent 26  $\Omega$  resistors to reduce overshoot and undreshoot.

#### Features

- $V_{CC} = 2.3 \text{ V} \text{ to } 3.6 \text{ V}$
- Typical  $V_{OL}$  ground bounce < 0.8 V (@V<sub>CC</sub> = 3.3 V, Ta = 25°C)
- Typical  $V_{OH}$  undershoot > 2.0 V (@V<sub>CC</sub> = 3.3 V, Ta = 25°C)
- High output current  $\pm 12 \text{ mA} (@V_{CC} = 3.0 \text{ V})$
- Bus hold on data inputs eliminates the need for external pullup / pulldown resistors
- All outputs have equivalent 26  $\Omega$  series resistors, so no external resistors are required



## **Function Table**

Inputs			Outputs			
OE1	OE2	Α	1Yn	2Yn		
L	Н	Н	Н	Z		
L	Н	L	L	Z		
Н	L	Н	Z	Н		
Н	L	L	Z	L		
L	L	Н	Н	Н		
L	L	L	L	L		
Н	Н	Х	Z	Z		

H : High level

L : Low level X : Immaterial

Z : High impedance

## **Pin Arrangement**

2Y2 1	80	1Y3					
1Y2 2		2Y3					
1Y2 2 GND 3		GND					
	78						
2Y1 4	77	1Y4					
1Y1 5		2Y4					
V <sub>CC</sub> 6	75	Vcc					
A1 7	74	1Y5					
A2 8	73	2Y5					
GND 9		GND					
A3 10	71	1Y6					
A4 11		2Y6					
GND 12	69	GND					
A5 13		1Y7					
A6 14	67	2Y7					
V <sub>CC</sub> 15	66	Vcc					
A7 16	65	1Y8					
A8 17	64	2Y8					
GND 18	63	GND					
A9 19		1Y9					
OE1 20	61	2Y9					
OE2 21		1Y10					
A10 22		2Y10					
GND 23		GND					
A11 24		1Y11					
A12 25		2Y11					
V <sub>cc</sub> 26		Vcc					
A13 27	54	1Y12					
A13 27 A14 28		2Y12					
GND 29	52	GND					
A15 30	51	1Y13					
A15 50 A16 31		2Y13					
GND 32	50						
	49	GND					
A17 33		1Y14					
A18 34	47	2Y14					
V <sub>CC</sub> 35		V <sub>CC</sub>					
2Y18 <u>36</u>	45	1Y15					
1Y18 <u>37</u>							
GND 38		GND					
2Y17 <u>39</u>		1Y16					
1Y17 40	41	2Y16					
(Top view)							
	· · /						

## **Absolute Maximum Ratings**

Item	Symbol	Ratings	Unit	Conditions	
Supply voltage	V <sub>cc</sub>	-0.5 to 4.6	V		
Input voltage <sup>*1</sup>	V	-0.5 to 4.6	V		
Output voltage *1, 2	Vo	–0.5 to V <sub>cc</sub> +0.5	V		
Input clamp current	I <sub>IK</sub>	-50	mA	V <sub>1</sub> < 0	
Output clamp current	Ι <sub>οκ</sub>	±50	mA	$V_{\rm o}$ < 0 or $V_{\rm o}$ > $V_{\rm cc}$	
Continuous output current	I <sub>o</sub>	±50	mA	$V_{o} = 0$ to $V_{cc}$	
V <sub>cc</sub> , GND current / pin	$I_{\rm CC}$ or $I_{\rm GND}$	±100	mA		
Maximum power dissipation at Ta = 55°C (in still air) $^{3}$	P <sub>T</sub>	1	W	TVSOP	
Storage temperature	T <sub>stg</sub>	-65 to 150	°C		

Notes: Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.

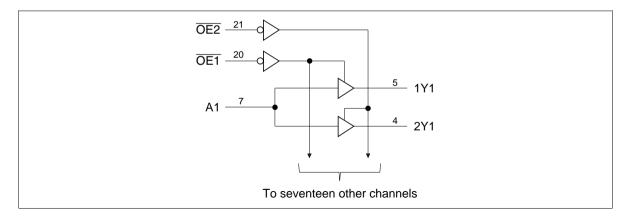
- 1. The input and output negative voltage ratings may be exceeded if the input and output clamp current ratings are observed.
- 2. This value is limited to 4.6 V maximum.
- 3. The maximum package power dissipation is calculated using a junction temperature of 150°C and a board trace length of 750 mils.

Item	Symbol	Min	Max	Unit	Conditions
Supply voltage	V <sub>cc</sub>	2.3	3.6	V	
Input voltage	V	0	V <sub>cc</sub>	V	
Output voltage	Vo	0	V <sub>cc</sub>	V	
High level output current	I <sub>он</sub>	—	-6	mA	$V_{cc} = 2.3 V$
		_	-8		V <sub>cc</sub> = 2.7 V
		_	-12		V <sub>cc</sub> = 3.0 V
Low level output current	I <sub>ol</sub>	—	6	mA	$V_{cc} = 2.3 V$
		_	8		V <sub>cc</sub> = 2.7 V
		_	12		V <sub>cc</sub> = 3.0 V
Input transition rise or fall rate	$\Delta t / \Delta v$	0	10	ns / V	
Operating temperature	T <sub>a</sub>	-40	85	°C	

#### **Recommended Operating Conditions**

Note: Unused control inputs must be held high or low to prevent them from floating.

## Logic Diagram



Item	Symbol	V <sub>cc</sub> (V)	Min	Max	Unit	Test Conditions
Input voltage	$V_{\text{IH}}$	2.3 to 2.7	1.7		V	
		2.7 to 3.6	2.0	_		
	V <sub>IL</sub>	2.3 to 2.7	_	0.7	_	
		2.7 to 3.6	_	0.8	_	
Output voltage	V <sub>OH</sub>	2.3 to 3.6	V <sub>cc</sub> -0.2	_	V	I <sub>OH</sub> = -100 μA
		2.3	1.9	_		$I_{OH} = -4 \text{ mA}, V_{IH} = 1.7 \text{ V}$
		2.3	1.7	_		$I_{OH} = -6 \text{ mA}, V_{IH} = 1.7 \text{ V}$
		3.0	2.4	_		$I_{OH} = -6 \text{ mA}, V_{IH} = 2.0 \text{ V}$
		2.7	2.0	_	_	$I_{OH} = -8 \text{ mA}, V_{IH} = 2.0 \text{ V}$
		3.0	2.0	_		$I_{OH} = -12 \text{ mA}, V_{IH} = 2.0 \text{ V}$
	V <sub>ol</sub>	2.3 to 3.6	_	0.2	_	I <sub>oL</sub> = 100 μA
		2.3	_	0.4	_	$I_{oL} = 4 \text{ mA}, V_{IL} = 0.7 \text{ V}$
		2.3	_	0.55		$I_{ol} = 6 \text{ mA}, V_{il} = 0.7 \text{ V}$
		3.0	_	0.55		$I_{_{OL}} = 6 \text{ mA}, V_{_{IL}} = 0.8 \text{ V}$
		2.7	_	0.6		$I_{oL} = 8 \text{ mA}, V_{IL} = 0.8 \text{ V}$
		3.0	_	0.8		$I_{ol} = 12 \text{ mA}, V_{il} = 0.8 \text{ V}$
Input current	I <sub>IN</sub>	3.6	_	±5	μΑ	$V_{IN} = V_{CC}$ or GND
	I IN (hold)	2.3	45	_	_	V <sub>IN</sub> = 0.7 V
		2.3	-45	_		V <sub>IN</sub> = 1.7 V
		3.0	75	_	_	V <sub>IN</sub> = 0.8 V
		3.0	-75		_	V <sub>IN</sub> = 2.0 V
		3.6	_	±500	_	$V_{IN} = 0$ to 3.6 V <sup>*1</sup>
Off state output current	I <sub>oz</sub>	3.6	_	±10	μΑ	$V_{OUT} = V_{CC}$ or GND
Quiescent supply current	t I <sub>cc</sub>	3.6	_	40	μΑ	$V_{IN} = V_{CC}$ or GND
	$\Delta I_{\rm CC}$	3.0 to 3.6	_	750	μΑ	$V_{IN}$ = one input at (V <sub>cc</sub> -0.6) V, other inputs at V <sub>cc</sub> or GND

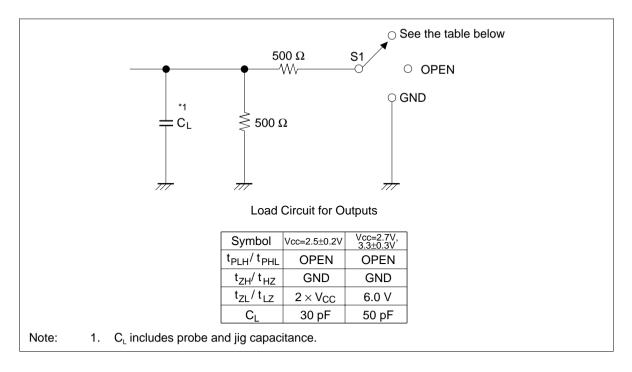
## **Electrical Characteristics** (Ta = -40 to $85^{\circ}$ C)

Note: 1. This is the bus hold maximum dynamic current required to switch the input from one state to another.

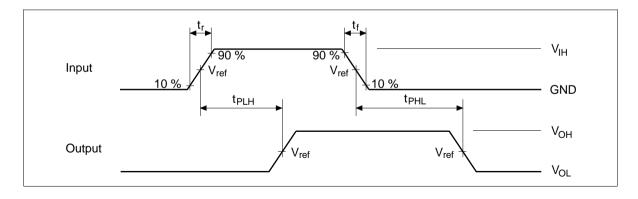
Item	Symbol	V <sub>cc</sub> (V)	Min	Тур	Max	Unit	FROM (Input)	TO (Output)
Propagation delay time	t <sub>PLH</sub>	2.5±0.2	1.2	_	3.8	ns	А	Y
	t <sub>PHL</sub>	2.7	—	—	4.0			
		3.3±0.3	1.7	_	3.5			
Output enable time	t <sub>zH</sub>	2.5±0.2	1.0	—	5.7	ns	ŌĒ	Y
	t <sub>zL</sub>	2.7	_	_	5.7			
		3.3±0.3	1.0	—	4.8			
Output disable time	t <sub>HZ</sub>	2.5±0.2	1.5	—	6.2	ns	ŌĒ	Y
	$t_{LZ}$	2.7	—	—	5.4			
		3.3±0.3	1.7	—	5.2			
Input capacitance	CIN	3.3	—	4.5	_	pF	Control inputs	
		3.3	_	5.0	—		Data inpu	ts
Output capacitance	Co	3.3		7.5		pF		

## **Switching Characteristics** (Ta = -40 to $85^{\circ}$ C)

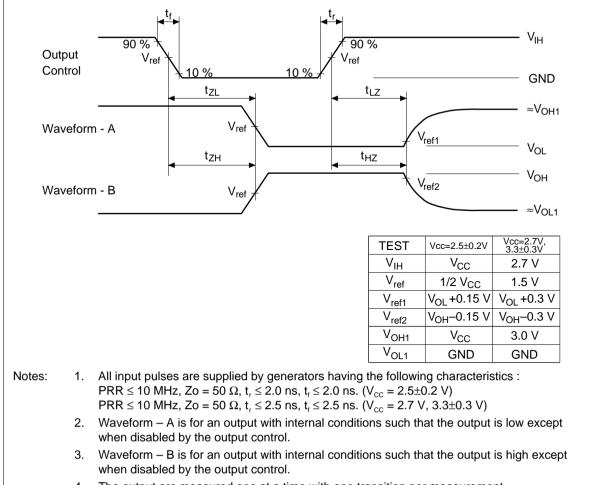
## **Test Circuit**



#### Waveforms - 1



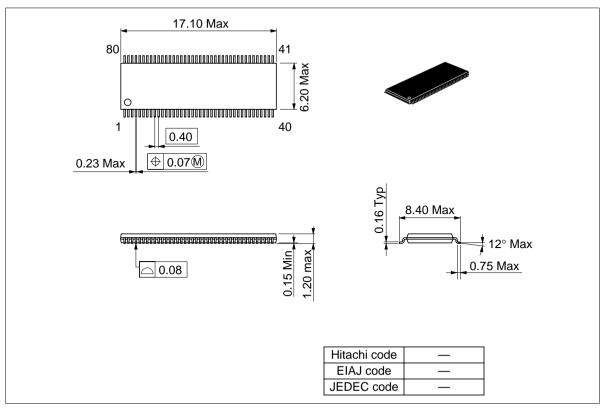
#### Waveforms - 2



4. The output are measured one at a time with one transition per measurement.

## **Package Dimensions**

Unit : mm



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