4-bit Parallel-Access Shift Register

HITACHI

Description

This shift register features parallel inputs, parallel outputs, J- \overline{K} serial inputs, Shift/Load control input, and a direct overriding clear. This shift register can operate in two modes: Parallel load; shift from Q_A towards Q_D .

Paralle loading is accomplished by applying the four bits of data, and taking the Shift/Load control Input low. The data is loaded into the associated flip-flops and appears at the outputs after the positive transition of the clock input. During parallel loading, serial data flow is inhibited. Serial shifting occurs synchronously when the Shift/Load control input is high. Serial data for this mode is entered at the J- \overline{K} inputs. These inputs allow the first stage to perform as a J- \overline{K} or toggle flip-flop as shown in the function table.

Features

• High Speed Operation: t_{pd} (Clock to Q) = 13 ns typ ($C_L = 50 \text{ pF}$)

• High Output Current: Fanout of 10 LSTTL Loads

• Wide Operating Voltage: $V_{CC} = 2$ to 6 V

• Low Input Current: 1 µA max

• Low Quiescent Supply Current: I_{CC} (static) = 4 μ A max (Ta = 25°C)



Function Table

Inputs

	Shift/		Serial		Para	llel			Outp	Outputs				
Clear	Load	Clock	J	K	Α	В	С	D	$\mathbf{Q}_{_{\mathrm{A}}}$	$Q_{\scriptscriptstyle B}$	Q _c	$\mathbf{Q}_{\scriptscriptstyle \mathrm{D}}$	$\mathbf{Q}_{\scriptscriptstyle \mathrm{D}}$	
L	Х	Χ	Χ	Х	Х	Х	Х	Х	L	L	L	L	Н	
Н	L	\int	Χ	Χ	а	b	С	d	а	b	С	d	\overline{d}	
Н	Н	L	Χ	Х	Х	Х	Х	Х	Q_{A0}	Q_{B0}	Q_{co}	Q_{D0}	\overline{Q}_{D0}	
Н	Н	\int	L	Н	Х	Х	Х	Х	Q_{A0}	Q_{A0}	Q_{Bn}	Q _{Cn}	\overline{Q}_{Cn}	
Н	Н	\int	L	L	Х	Х	Χ	Х	L	\mathbf{Q}_{An}	\mathbf{Q}_{Bn}	Q_{Cn}	$\overline{\mathbf{Q}}_{Cn}$	
Н	Н	\int	Н	Н	Х	Х	Χ	Х	Н	Q_{An}	Q_{Bn}	Q_{Cn}	\overline{Q}_{Cn}	
Н	Н	\int	Н	L	Х	Х	Χ	Х	Q_{An}	Q_{An}	Q_{Bn}	Q_{Cn}	\overline{Q}_{Cn}	

H : high level (steady state)L : low level (steady state)

X: don't care

: transition from low to high level.

a, b, c, d: the level of steady-state input at inputs A, B, C or D respectively.

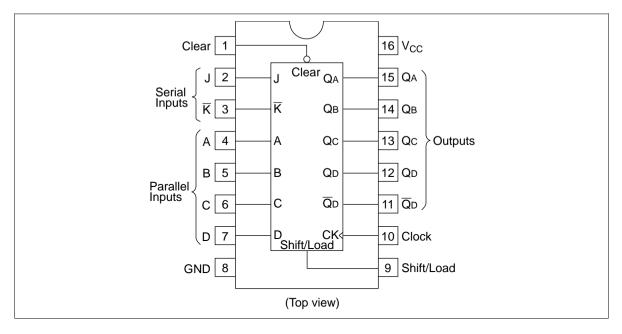
 $Q_{A0},\,Q_{B0},\,Q_{C0},\,Q_{D0}\quad :\quad \text{the level of }Q_{A},\,Q_{B},\,Q_{C}\,\,\text{or}\,\,Q_{D}\,\,\text{respectively, before the indicated steady-state input}$

conditions were established.

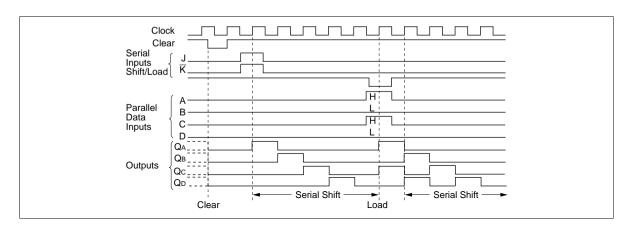
 $Q_{An}, Q_{Bn}, Q_{Cn}, Q_{Dn}$: the level of Q_{A}, Q_{B}, Q_{C} or Q_{D} respectively before the most recent $\sqrt{}$ transition of

the clock.

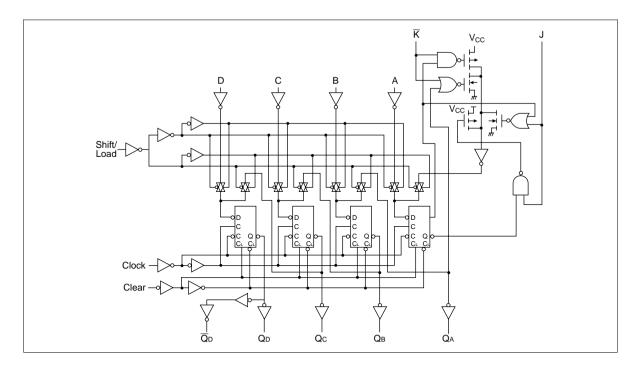
Pin Arrangement



Timing Diagram



Logic Diagram



DC Characteristics

			Ta = 25°C		Ta = −40 to +85°C					
Item	Symbol	V _{cc} (V)	Min	Тур	Max	Min	Max	Unit	Test Condition	ns
Input voltage	V_{IH}	2.0	1.5	_	_	1.5	_	V		
		4.5	3.15	_	_	3.15	_	_		
		6.0	4.2	_	_	4.2	_	_		
	V _{IL}	2.0	_	_	0.5	_	0.5	V		_
		4.5	_	_	1.35	_	1.35	_		
		6.0	_	_	1.8	_	1.8	_		
Output voltage	V_{OH}	2.0	1.9	2.0	_	1.9	_	V	$Vin = V_{IH} \text{ or } V_{IL}$	$I_{OH} = -20 \mu A$
		4.5	4.4	4.5	_	4.4	_	_		
		6.0	5.9	6.0	_	5.9	_	_		
		4.5	4.18	_	_	4.13	_			$I_{OH} = -4 \text{ mA}$
		6.0	5.68	_	_	5.63	_	_		$I_{OH} = -5.2 \text{ mA}$
	V _{OL}	2.0	_	0.0	0.1	_	0.1	V	$Vin = V_{IH} \text{ or } V_{IL}$	I _{OL} = 20 μA
		4.5	_	0.0	0.1	_	0.1			
		6.0	_	0.0	0.1	_	0.1	_		
		4.5	_	_	0.26	_	0.33	=		I _{OL} = 4 mA
		6.0	_	_	0.26	_	0.33	_		$I_{OL} = 5.2 \text{ mA}$
Input current	lin	6.0	_	_	±0.1	_	±1.0	μΑ	Vin = V _{CC} or GN	ND
Quiescent supply current	I _{cc}	6.0	_	_	4.0	_	40	μΑ	Vin = V _{cc} or GN	ND, lout = 0 μA

AC Characteristics ($C_L = 50 \text{ pF}$, Input $t_r = t_f = 6 \text{ ns}$)

		V _{cc} (V)	Ta = 25°C			Ta = −40 to +85°C				
Item	Symbol		Min	Тур	Max	Min	Max	Unit	Test Conditions	
Maximum clock	f _{max}	2.0	_	_	6		5	MH_z		
frequency		4.5	_	_	30	_	24	_		
		6.0	_	_	35	_	28	_		
Propagation delay	t _{PHL}	2.0	_	_	140	_	175	ns	Clock to Q	
time		4.5	_	13	28	_	35	=		
		6.0	_	_	24	_	30	_		
	t _{PLH}	2.0	_	_	140	_	175	ns	_	
		4.5	_	13	28	_	35	_		
		6.0	_	_	24	_	30	_		
	t _{PHL}	2.0	_	_	150	_	190	ns	Clear to Q	
		4.5	_	15	30	_	38	=		
		6.0	_	_	26	_	33	_		
Pulse width	t _w	2.0	80	_	_	100	_	ns	Clock to Clear	
		4.5	16	7	_	20	_	=		
		6.0	14	_	_	17	_	_		
Setup time	t _{su}	2.0	100	_	_	125	_	ns	A, B, C, D, J, K to Clock	
		4.5	20	6	_	25	_	=		
		6.0	17	_	_	21	_	_		
		2.0	100	_	_	125	_	ns	Shift/Load to Clock	
		4.5	20	13	_	25	_	_		
		6.0	17	_	_	21	_	_		
Hold time	t _h	2.0	0	_	_	0	_	ns	Any input except Shift/Load	
		4.5	0	-3	_	0	_	=		
		6.0	0	_	_	0	_	_		
Removal time	t _{rem}	2.0	75	_	_	95	_	ns	Shift/Load to Clock	
		4.5	15	8	_	19	_	_		
		6.0	13	_	_	16	_	=		
		2.0	25	_	_	31	_	ns	Clear inactive to Clock	
		4.5	5	0	_	6	_	_		
								_		

6.0

AC Characteristics ($C_L = 50 \text{ pF}$, Input $t_r = t_f = 6 \text{ ns}$) (cont)

		V _{cc} (V)	Ta = 25°C			1a = +85°	–40 to C		
Item	Symbol		Min	Тур	Max	Min	Max	Unit	Test Conditions
Output rise/fall	t _{TLH}	2.0	_	_	75	_	95	ns	
time	$t_{\scriptscriptstyle THL}$	4.5	_	5	15	_	19		
		6.0	_	_	13		16	_	
Input capacitance	Cin	_	_	5	10		10	рF	

Unit: mm 19.20 20.00 Max 16 7.40 Max 6.30 1.3 1.11 Max 7.62 5.06 Max 2.54 Min 0.51 Min $0.25^{+0.13}_{-0.05}$ 0.48 ± 0.10 2.54 ± 0.25 $0^{\circ} - 15^{\circ}$ Hitachi Code DP-16 **JEDEC** Conforms EIAJ Conforms Weight (reference value) 1.07 g

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