

Integrated Power Hybrid IC for  
 Appliance Motor Drive Applications.

**with Internal Shunt Resistor**

### Description

International Rectifier's IRAMS10UP60B is an Integrated Power Module developed and optimized for electronic motor control in appliance applications such as washing machines and refrigerators. Plug N Drive technology offers an extremely compact, high performance AC motor-driver in a single isolated package for a very simple design. An internal shunt is also included and offers easy current feedback and overcurrent monitor for precise and safe operation. A built-in temperature monitor and over-current protection, along with the short-circuit rated IGBTs and integrated under-voltage lockout function, deliver high level of protection and fail-safe operation. The integration of the bootstrap diodes for the high-side driver section, and the single polarity power supply required to drive the internal circuitry, simplify the utilization of the module and deliver further cost reduction advantages.

### Features

- Internal Shunt Resistor
- Integrated Gate Drivers and Bootstrap Diodes
- Temperature Monitor
- Fully Isolated Package
- Low  $V_{CE(on)}$  Non Punch Through IGBT Technology
- Undervoltage lockout for all channels
- Matched propagation delay for all channels
- Schmitt-triggered input logic
- Cross-conduction prevention logic
- Lower  $di/dt$  gate driver for better noise immunity
- Motor Power range 0.4~0.75kW / 85~253 Vac
- Isolation 2000V<sub>RMS</sub>/1min and CTI > 600V
- Recognized by UL (E252584), RoHS Compliant



### Absolute Maximum Ratings

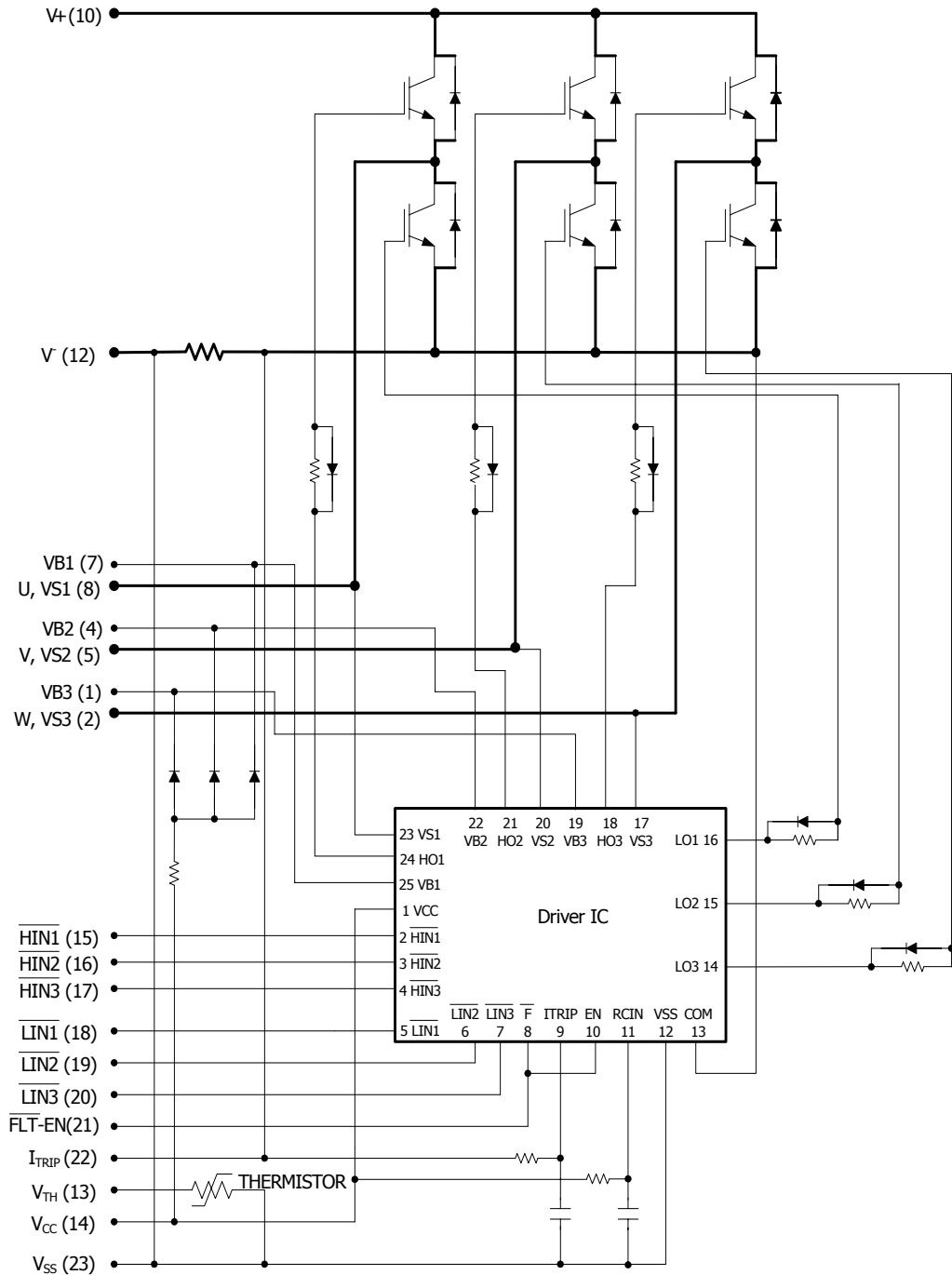
Parameter	Description	Value	Units
$V_{CES} / V_{RRM}$	IGBT/Diode Blocking Voltage	600	V
$V^+$	Positive Bus Input Voltage	450	
$I_O @ T_C=25^\circ C$	RMS Phase Current (Note 1)	10	A
$I_O @ T_C=100^\circ C$	RMS Phase Current (Note 1)	5	
$I_O$	Pulsed RMS Phase Current (Note 2)	15	
$F_{PWM}$	PWM Carrier Frequency	20	kHz
$P_D$	Power dissipation per IGBT @ $T_C = 25^\circ C$	27	W
$V_{ISO}$	Isolation Voltage (1min)	2000	V <sub>RMS</sub>
$T_J$ (IGBT & Diodes)	Operating Junction temperature Range	-40 to +150	°C
$T_J$ (Driver IC)	Operating Junction temperature Range	-40 to +150	
T	Mounting torque Range (M3 screw)	0.5 to 1.0	Nm

Note 1: Sinusoidal Modulation at  $V^+=400V$ ,  $T_J=150^\circ C$ ,  $F_{PWM}=20kHz$ , Modulation Depth=0.8, PF=0.6, See Figure 3.

Note 2:  $t_p < 100ms$ ;  $T_C=25^\circ C$ ;  $F_{PWM}=20kHz$ . Limited by  $I_{BUS-ITRIP}$ , see Table "Inverter Section Electrical Characteristics"

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## Internal Electrical Schematic - IRAMS10UP60B



**Absolute Maximum Ratings (Continued)**

Symbol	Parameter	Min	Max	Units	Conditions
$I_{BDF}$	Bootstrap Diode Peak Forward Current	---	4.5	A	$t_p = 10\text{ms}$ , $T_j = 150^\circ\text{C}$ , $T_C = 100^\circ\text{C}$
$P_{BR \text{ Peak}}$	Bootstrap Resistor Peak Power (Single Pulse)	---	80	W	$t_p = 100\mu\text{s}$ , $T_C = 100^\circ\text{C}$ ESR / ERJ series
$V_{S1,2,3}$	High side floating supply offset voltage	$V_{B1,2,3} - 25$	$V_{B1,2,3} + 0.3$	V	
$V_{B1,2,3}$	High side floating supply voltage	-0.3	600	V	
$V_{CC}$	Low Side and logic fixed supply voltage	-0.3	20	V	
$V_{IN}, V_{EN}, V_{ITRIP}$	Input voltage LIN, HIN, EN, $I_{Trip}$	-0.3	Lower of ( $V_{SS} + 15\text{V}$ ) or $V_{CC} + 0.3\text{V}$	V	

**Inverter Section Electrical Characteristics @ $T_j = 25^\circ\text{C}$**

Symbol	Parameter	Min	Typ	Max	Units	Conditions
$V_{(BR)CES}$	Collector-to-Emitter Breakdown Voltage	600	---	---	V	$V_{IN} = 5\text{V}$ , $I_C = 250\mu\text{A}$
$\Delta V_{(BR)CES} / \Delta T$	Temperature Coefficient of Breakdown Voltage	---	0.57	---	V/ $^\circ\text{C}$	$V_{IN} = 5\text{V}$ , $I_C = 1.0\text{mA}$ ( $25^\circ\text{C} - 150^\circ\text{C}$ )
$V_{CE(ON)}$	Collector-to-Emitter Saturation Voltage	---	1.70	2.00	V	$I_C = 5\text{A}$ , $V_{CC} = 15\text{V}$
		---	2.00	2.40		$I_C = 5\text{A}$ , $V_{CC} = 15\text{V}$ , $T_j = 150^\circ\text{C}$
$I_{CES}$	Zero Gate Voltage Collector Current	---	5	80	$\mu\text{A}$	$V_{IN} = 5\text{V}$ , $V^+ = 600\text{V}$
		---	10	---		$V_{IN} = 5\text{V}$ , $V^+ = 600\text{V}$ , $T_j = 150^\circ\text{C}$
$V_{FM}$	Diode Forward Voltage Drop	---	1.80	2.35	V	$I_C = 5\text{A}$
		---	1.30	1.70		$I_C = 5\text{A}$ , $T_j = 150^\circ\text{C}$
$V_{BDFM}$	Bootstrap Diode Forward Voltage Drop	--	--	1.25	V	$I_F = 1\text{A}$
		---	---	1.10		$I_F = 1\text{A}$ , $T_j = 150^\circ\text{C}$
$R_{BR}$	Bootstrap Resistor Value	---	2	---	$\Omega$	$T_j = 25^\circ\text{C}$
$\Delta R_{BR} / R_{BR}$	Bootstrap Resistor Tolerance	---	---	$\pm 5$	%	$T_j = 25^\circ\text{C}$
$I_{BUS\_TRIP}$	Current Protection Threshold (positive going)	13.1	---	16.4	A	$T_j = -40^\circ\text{C}$ to $125^\circ\text{C}$ See fig. 2

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## Inverter Section Switching Characteristics @ $T_J = 25^\circ\text{C}$

Symbol	Parameter	Min	Typ	Max	Units	Conditions
$E_{ON}$	Turn-On Switching Loss	---	200	235	$\mu\text{J}$	$I_C=5\text{A}$ , $V^+=400\text{V}$ $V_{CC}=15\text{V}$ , $L=2\text{mH}$ Energy losses include "tail" and diode reverse recovery
$E_{OFF}$	Turn-Off Switching Loss	---	75	100		
$E_{TOT}$	Total Switching Loss	---	275	335		
$E_{REC}$	Diode Reverse Recovery energy	---	15	25		
$t_{RR}$	Diode Reverse Recovery time	---	70	100	ns	See CT1
$E_{ON}$	Turn-On Switching Loss	---	300	360	$\mu\text{J}$	$I_C=5\text{A}$ , $V^+=400\text{V}$ $V_{CC}=15\text{V}$ , $L=2\text{mH}$ , $T_J=150^\circ\text{C}$ Energy losses include "tail" and diode reverse recovery
$E_{OFF}$	Turn-off Switching Loss	---	135	165		
$E_{TOT}$	Total Switching Loss	---	435	525		
$E_{REC}$	Diode Reverse Recovery energy	---	30	40		
$t_{RR}$	Diode Reverse Recovery time	---	100	145	ns	See CT1
$Q_G$	Turn-On IGBT Gate Charge	---	29	44	nC	$I_C=15\text{A}$ , $V^+=400\text{V}$ , $V_{GE}=15\text{V}$
RBSOA	Reverse Bias Safe Operating Area	FULL SQUARE				$T_J=150^\circ\text{C}$ , $I_C=5\text{A}$ , $V_P=600\text{V}$ $V^+=450\text{V}$ $V_{CC}=+15\text{V}$ to $0\text{V}$ See CT3
SCSOA	Short Circuit Safe Operating Area	10	---	---	$\mu\text{s}$	$T_J=150^\circ\text{C}$ , $V_P=600\text{V}$ , $V^+=360\text{V}$ , $V_{CC}=+15\text{V}$ to $0\text{V}$ See CT2
$I_{CSC}$	Short Circuit Collector Current	---	47	---	A	$T_J=150^\circ\text{C}$ , $V_P=600\text{V}$ , $t_{SC}<10\mu\text{s}$ $V^+=360\text{V}$ , $V_{GE}=15\text{V}$ $V_{CC}=+15\text{V}$ to $0\text{V}$ See CT2

## Recommended Operating Conditions Driver Function

The Input/Output logic timing diagram is shown in Figure 1. For proper operation the device should be used within the recommended conditions. All voltages are absolute referenced to COM/ $I_{TRIP}$ . The  $V_S$  offset is tested with all supplies biased at 15V differential (Note 3)

Symbol	Definition	Min	Max	Units
$V_{B1,2,3}$	High side floating supply voltage	$V_S+12$	$V_S+20$	V
$V_{S1,2,3}$	High side floating supply offset voltage	Note 4	450	
$V_{CC}$	Low side and logic fixed supply voltage	12	20	V
$V_{ITRIP}$	$I_{TRIP}$ input voltage	$V_{SS}$	$V_{SS}+5$	
$V_{IN}$	Logic input voltage LIN, HIN	$V_{SS}$	$V_{SS}+5$	V
$V_{EN}$	Logic input voltage EN	$V_{SS}$	$V_{SS}+5$	V

Note 3: For more details, see IR21363 data sheet

Note 4: Logic operational for  $V_S$  from COM-5V to COM+600V. Logic state held for  $V_S$  from COM-5V to COM- $V_{BS}$ . (please refer to DT97-3 for more details)

### Static Electrical Characteristics Driver Function

$V_{BIAS}$  ( $V_{CC}$ ,  $V_{BS1,2,3}$ )=15V, unless otherwise specified. The  $V_{IN}$  and  $I_{IN}$  parameters are referenced to COM/ $I_{TRIP}$  and are applicable to all six channels. (Note 3)

Symbol	Definition	Min	Typ	Max	Units
$V_{INH}$ , $V_{ENH}$	Logic "0" input voltage	3.0	---	---	V
$V_{INL}$ , $V_{ENL}$	Logic "1" input voltage	---	---	0.8	V
$V_{CCUV+}$ , $V_{BSUV+}$	$V_{CC}$ and $V_{BS}$ supply undervoltage Positive going threshold	10.6	11.1	11.6	V
$V_{CCUV-}$ , $V_{BSUV-}$	$V_{CC}$ and $V_{BS}$ supply undervoltage Negative going threshold	10.4	10.9	11.4	V
$V_{CCUVH}$ , $V_{BSUVH}$	$V_{CC}$ and $V_{BS}$ supply undervoltage lock-out hysteresis	---	0.2	---	V
$V_{IN,Clamp}$	Input Clamp Voltage (HIN, LIN, $I_{TRIP}$ ) $I_{IN}=10\mu A$	4.9	5.2	5.5	V
$I_{QBS}$	Quiescent $V_{BS}$ supply current $V_{IN}=0V$	---	---	165	$\mu A$
$I_{QCC}$	Quiescent $V_{CC}$ supply current $V_{IN}=0V$	---	---	3.35	mA
$I_{LK}$	Offset Supply Leakage Current	---	---	60	$\mu A$
$I_{IN+}$ , $I_{EN+}$	Input bias current $V_{IN}=5V$	---	200	300	$\mu A$
$I_{IN-}$ , $I_{EN-}$	Input bias current $V_{IN}=0V$	---	100	220	$\mu A$
$I_{TRIP+}$	$I_{TRIP}$ bias current $V_{ITRIP}=5V$	---	30	100	$\mu A$
$I_{TRIP-}$	$I_{TRIP}$ bias current $V_{ITRIP}=0V$	---	0	1	$\mu A$
$V(I_{TRIP})$	$I_{TRIP}$ threshold Voltage	440	490	540	mV
$V(I_{TRIP}, HYS)$	$I_{TRIP}$ Input Hysteresis	---	70	---	mV
$R_{ON/FLT}$	Fault Output ON Resistance	---	50	100	ohm

### Dynamic Electrical Characteristics

Driver only timing unless otherwise specified.)

Symbol	Parameter	Min	Typ	Max	Units	Conditions
$T_{ON}$	Input to Output propagation turn-on delay time (see fig.11)	---	590	---	ns	$V_{CC}=V_{BS}= 15V$ , $I_C=10A$ , $V^+=400V$
$T_{OFF}$	Input to Output propagation turn-off delay time (see fig. 11)	---	700	---	ns	
$T_{FLIN}$	Input Filter time (HIN, LIN)	100	200	---	ns	$V_{IN}=0$ & $V_{IN}=5V$
$T_{BLT-TRIP}$	$I_{TRIP}$ Blanking Time	100	150	---	ns	$V_{IN}=0$ & $V_{IN}=5V$
$D_T$	Dead Time ( $V_{BS}=V_{DD}=15V$ )	220	290	360	ns	$V_{BS}=V_{CC}=15V$
$M_T$	Matching Propagation Delay Time (On & Off)	---	40	75	ns	$V_{CC}= V_{BS}= 15V$ , external dead time > 400ns
$T_{ITrip}$	$I_{Trip}$ to six switch to turn-off propagation delay (see fig. 2)	---	---	1.75	$\mu s$	$V_{CC}=V_{BS}= 15V$ , $I_C=10A$ , $V^+=400V$
$T_{FLT-CLR}$	Post $I_{Trip}$ to six switch to turn-off clear time (see fig. 2)	---	7.7	---	ms	$T_C = 25^\circ C$
		---	6.7	---		$T_C = 100^\circ C$

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## Thermal and Mechanical Characteristics

Symbol	Parameter	Min	Typ	Max	Units	Conditions
$R_{th(J-C)}$	Thermal resistance, per IGBT	---	4.2	4.7	°C/W	Flat, greased surface. Heatsink compound thermal conductivity 1W/mK
$R_{th(J-C)}$	Thermal resistance, per Diode	---	5.5	6.5		
$R_{th(C-S)}$	Thermal resistance, C-S	---	0.1	---		
$C_D$	Creepage Distance	3.2	---	---	mm	See outline Drawings

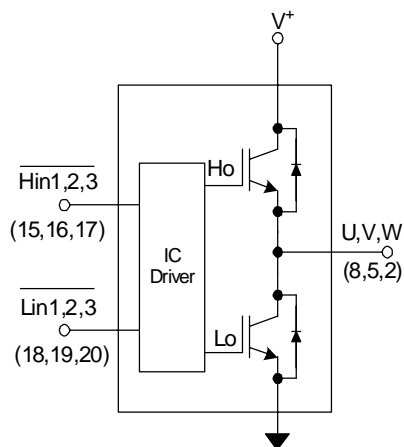
## Internal Current Sensing Resistor - Shunt Characteristics

Symbol	Parameter	Min	Typ	Max	Units	Conditions
$R_{Shunt}$	Resistance	33.0	33.3	33.7	mΩ	$T_C = 25^\circ C$
$T_{Coeff}$	Temperature Coefficient	0	---	200	ppm/°C	$-40^\circ C < T_C < 100^\circ C$
$P_{Shunt}$	Power Dissipation	---	---	2.2	W	
$T_{Range}$	Temperature Range	-40	---	125	°C	

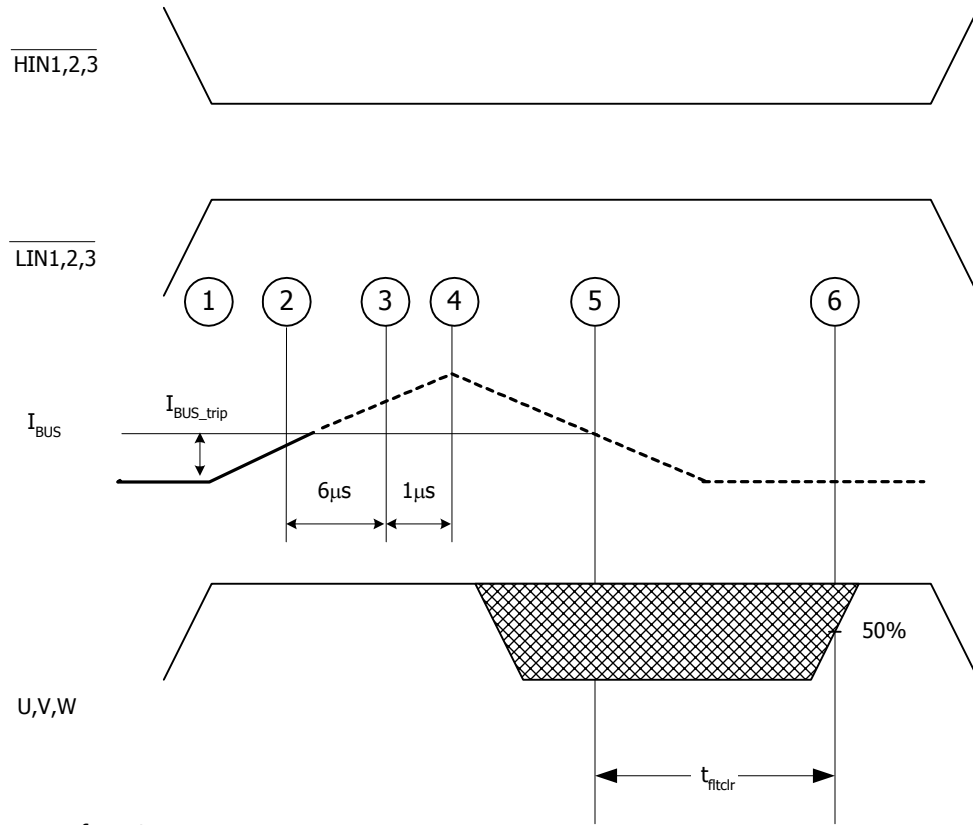
## Internal NTC - Thermistor Characteristics

Parameter	Definition	Min	Typ	Max	Units	Conditions
$R_{25}$	Resistance	97	100	103	kΩ	$T_C = 25^\circ C$
$R_{125}$	Resistance	2.25	2.52	2.80	kΩ	$T_C = 125^\circ C$
B	B-constant (25-50°C)	4165	4250	4335	k	$R_2 = R_1 e^{[B(1/T_2 - 1/T_1)]}$
Temperature Range		-40		125	°C	
Typ. Dissipation constant			1		mW/°C	$T_C = 25^\circ C$

## Input-Output Logic Level Table



FLT- EN	$I_{TRIP}$	$\overline{HIN1,2,3}$	$\overline{LIN1,2,3}$	U,V,W
1	0	0	1	$V^+$
1	0	1	0	0
1	0	1	1	Off
1	1	X	X	Off
0	X	X	X	Off



Sequence of events:

- 1-2) Current begins to rise
- 2) Current reaches  $I_{BUS\_Trip}$  level
- 2-3) Current is higher than  $I_{BUS\_Trip}$  for at least  $6\mu s$ . This value is the worst-case condition with very low over-current. In case of high current (short circuit), the actual delay will be smaller.
- 3-4) Delay between driver identification of over-current condition and disabling of all outputs
- 4) Current starts decreasing, eventually reaching 0
- 5) Current goes below  $I_{BUS\_trip}$ , the driver starts its auto-reset sequence
- 6) Driver is automatically reset and normal operation can resume (over-current condition must be removed by the time the drivers automatically resets itself)

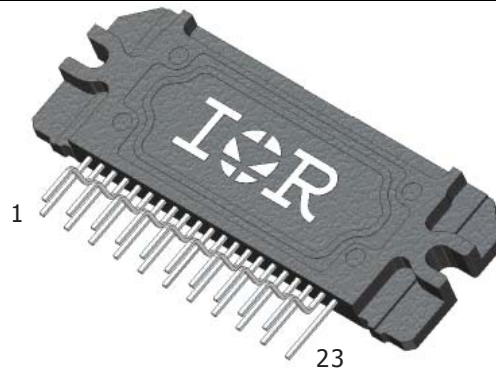
Figure 2.  $I_{TRIP}$  Timing Waveform

Note 5: The shaded area indicates that both high-side and low-side switches are off and therefore the half-bridge output voltage would be determined by the direction of current flow in the load.

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## Module Pin-Out Description

Pin	Name	Description
1	$V_{B3}$	High Side Floating Supply Voltage 3
2	$W, V_{S3}$	Output 3 - High Side Floating Supply Offset Voltage
3	NA	none
4	$V_{B2}$	High Side Floating Supply voltage 2
5	$V, V_{S2}$	Output 2 - High Side Floating Supply Offset Voltage
6	NA	none
7	$V_{B1}$	High Side Floating Supply voltage 1
8	$U, V_{S1}$	Output 1 - High Side Floating Supply Offset Voltage
9	NA	none
10	$V^+$	Positive Bus Input Voltage
11	NA	none
12	$V^-$	Negative Bus Input Voltage
13	$V_{TH}$	Temperature Feedback
14	$V_{CC}$	+15V Main Supply
15	$\overline{H}_{IN1}$	Logic Input High Side Gate Driver - Phase 1
16	$\overline{H}_{IN2}$	Logic Input High Side Gate Driver - Phase 2
17	$\overline{H}_{IN3}$	Logic Input High Side Gate Driver - Phase 3
18	$\overline{L}_{IN1}$	Logic Input Low Side Gate Driver - Phase 1
19	$\overline{L}_{IN2}$	Logic Input Low Side Gate Driver - Phase 2
20	$\overline{L}_{IN3}$	Logic Input Low Side Gate Driver - Phase 3
21	$\overline{FLT}/\text{Enable}$	Fault Output and Enable Pin
22	$I_{TRIP}$	Current Sense and Itrip Pin
23	$V_{SS}$	Negative Main Supply







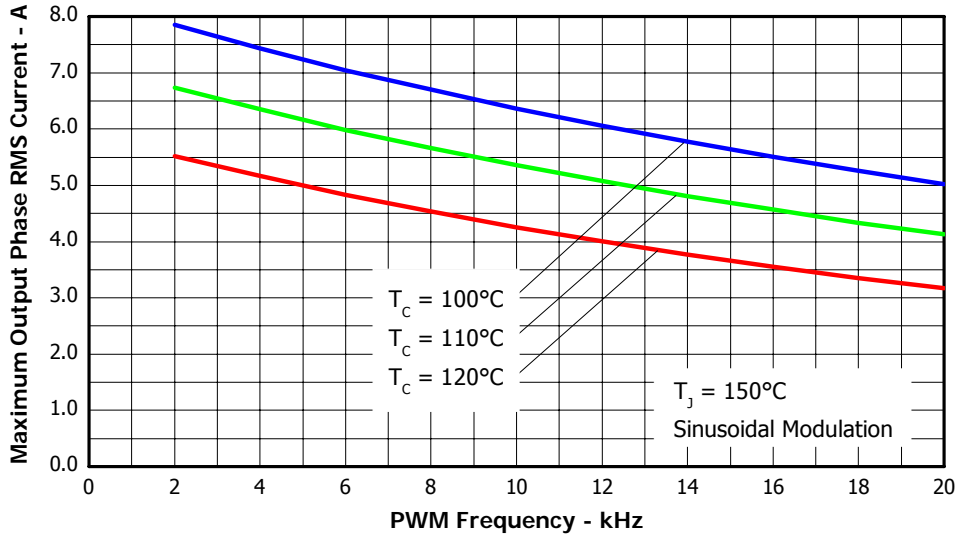


Figure 3. Maximum Sinusoidal Phase Current vs. PWM Switching Frequency  
 $V^+=400\text{V}$  ,  $T_j=150^\circ\text{C}$ , Modulation Depth=0.8, PF=0.6

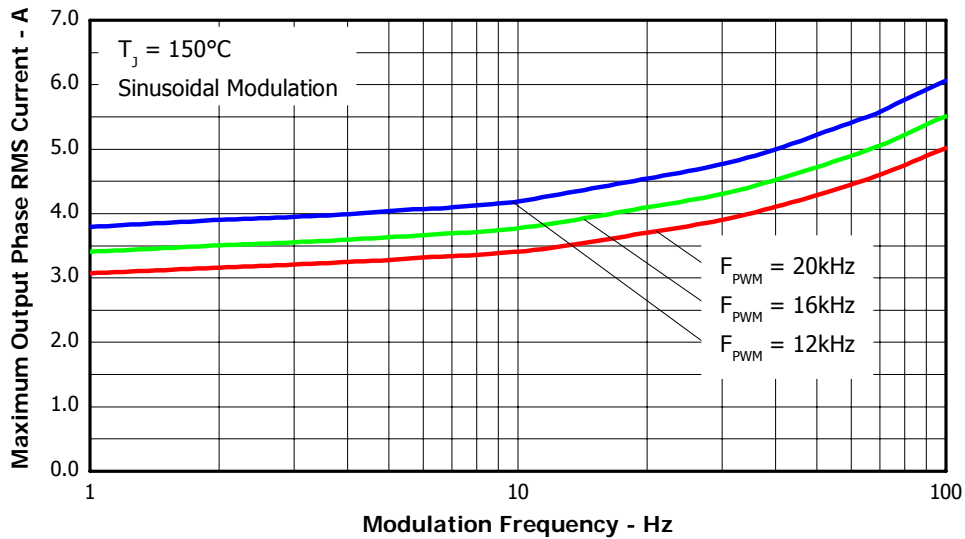


Figure 4. Maximum Sinusoidal Phase Current vs. Modulation Frequency  
 $V^+=400\text{V}$ ,  $T_j=150^\circ\text{C}$ ,  $T_c=100^\circ\text{C}$ , Modulation Depth=0.8, PF=0.6

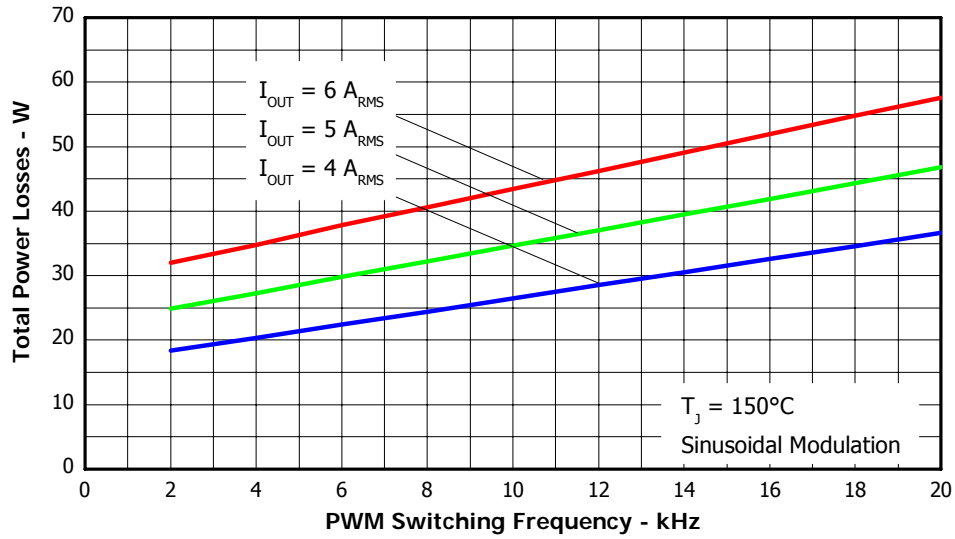


Figure 5. Total Power Losses vs. PWM Switching Frequency, Sinusoidal modulation  
 $V^+=400\text{V}$  ,  $T_j=150^\circ\text{C}$ , Modulation Depth=0.8, PF=0.6

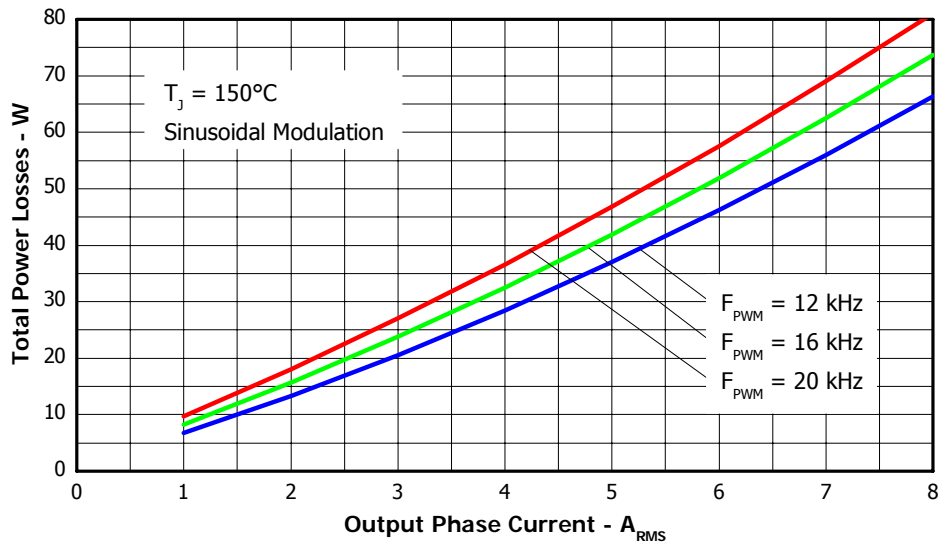


Figure 6. Total Power Losses vs. Output Phase Current, Sinusoidal modulation  
 $V_{BUS}=400\text{V}$  ,  $T_j=150^\circ\text{C}$ , Modulation Depth=0.8, PF=0.6

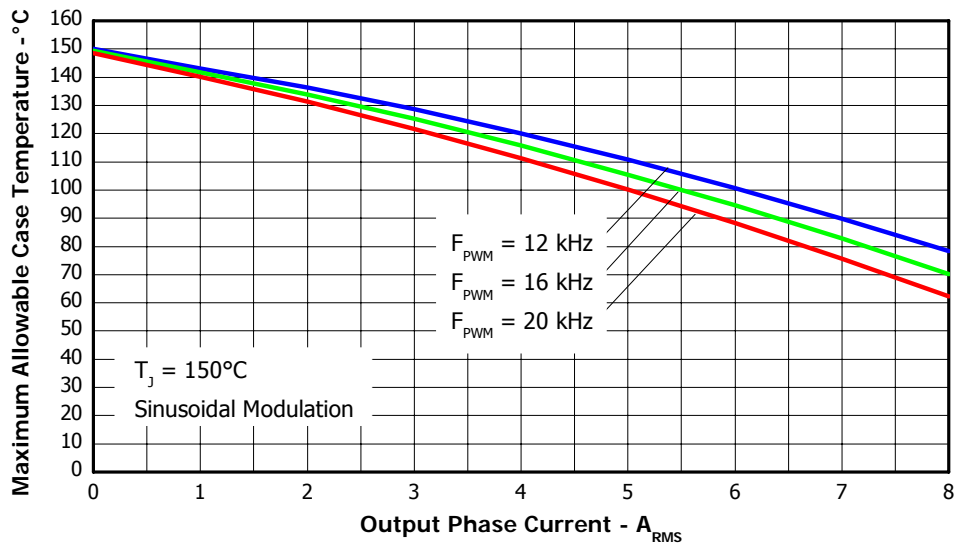


Figure 7. Maximum Allowable Case temperature vs. Output RMS Current per Phase

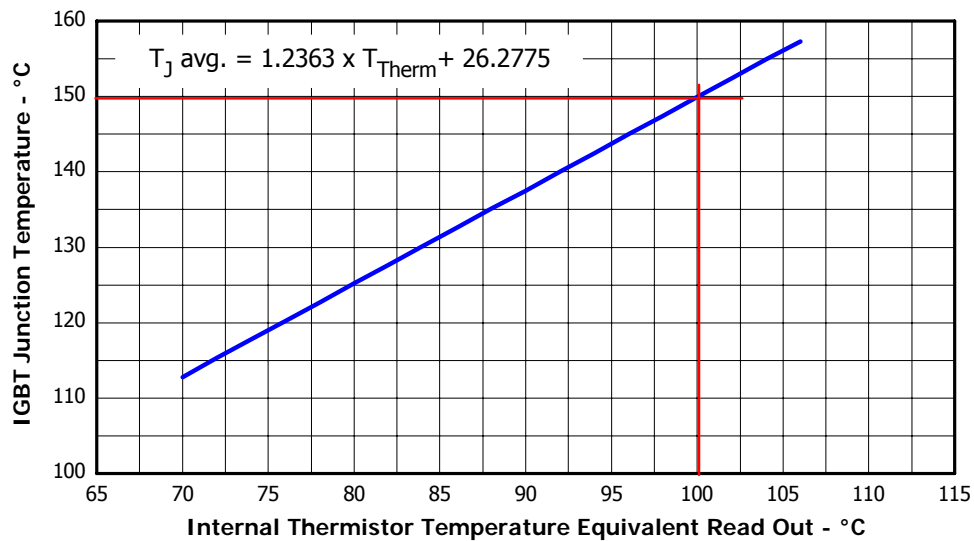


Figure 8. Estimated Maximum IGBT Junction Temperature vs. Thermistor Temperature

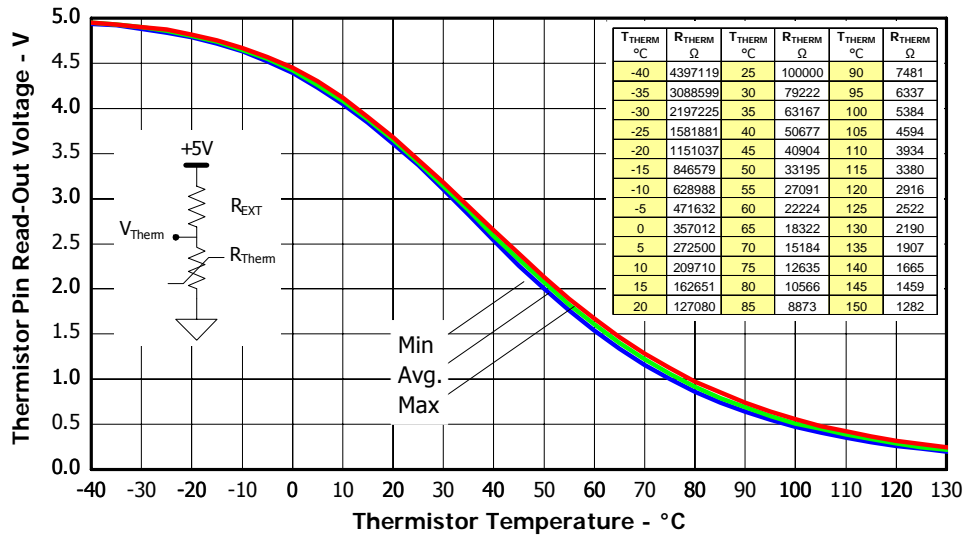


Figure 9. Thermistor Readout vs. Temperature (47kohm pull-up resistor, 5V) and Nominal Thermistor Resistance values vs. Temperature Table.

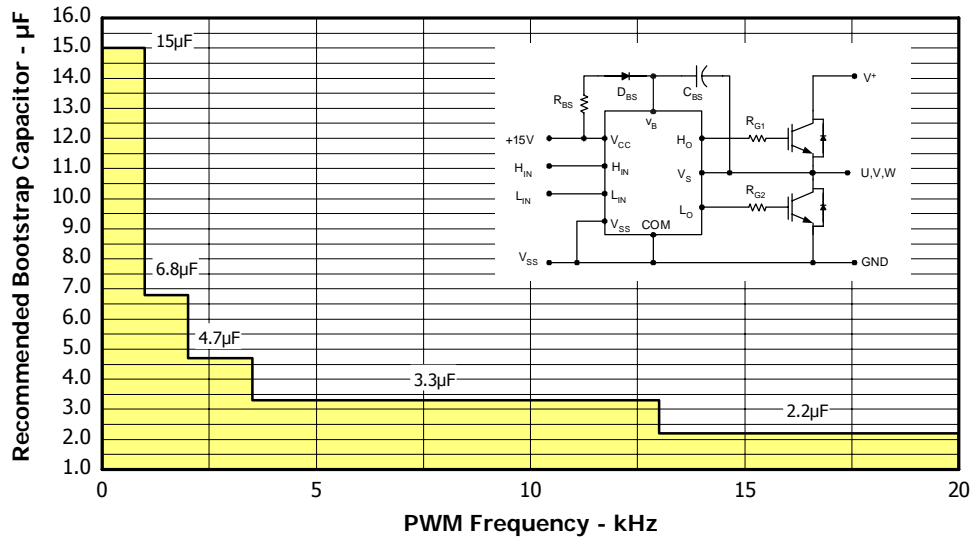


Figure 10. Recommended Bootstrap Capacitor Value vs. Switching Frequency

Figure 11. Switching Parameter Definitions

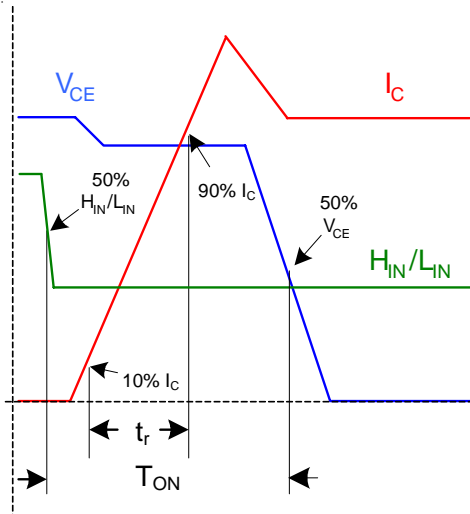


Figure 11a. Input to Output Propagation turn-on Delay Time

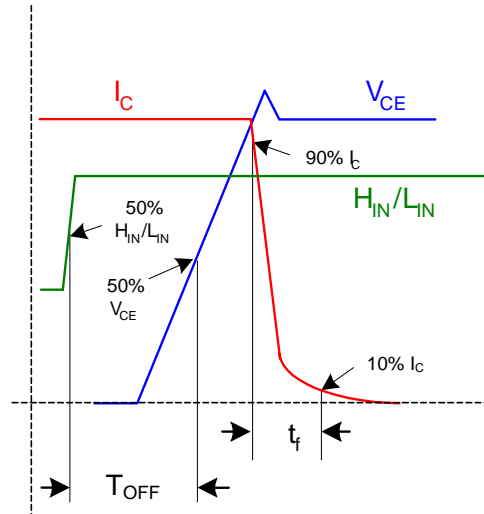


Figure 11b. Input to Output Propagation turn-off Delay Time

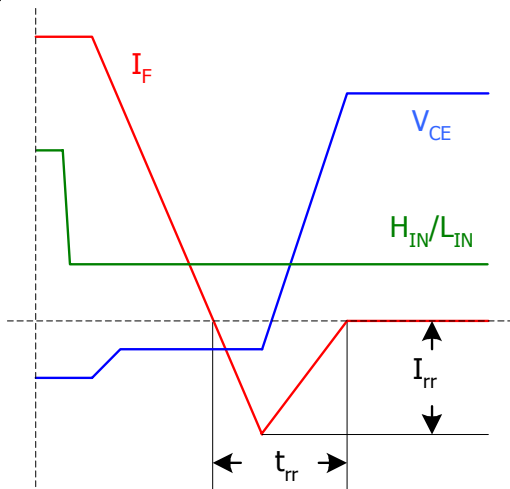


Figure 11c. Diode Reverse Recovery

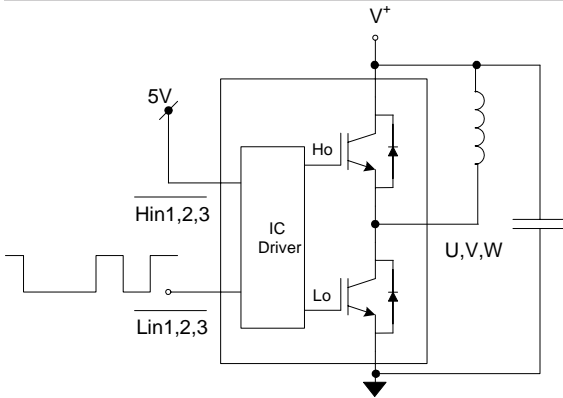


Figure CT1. Switching Loss Circuit

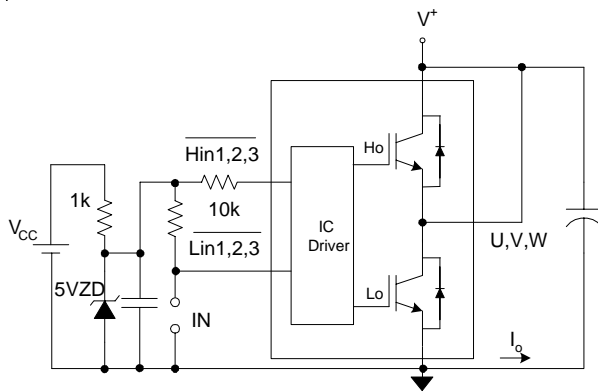


Figure CT2. S.C.SOA Circuit

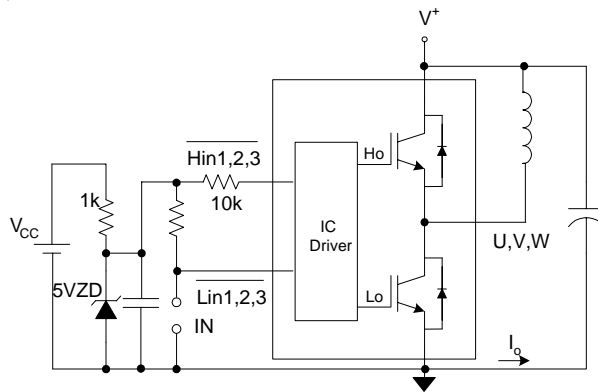
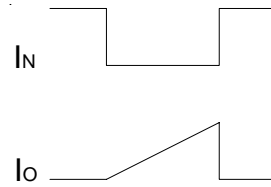
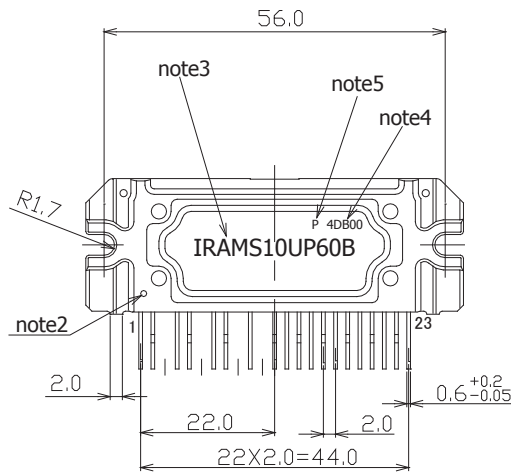


Figure CT3. R.B.SOA Circuit

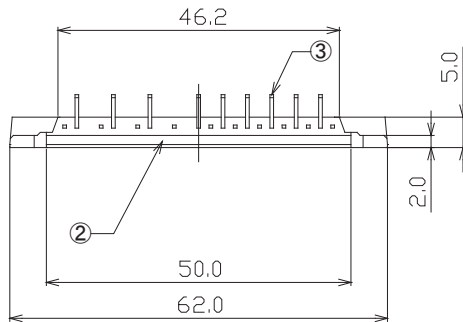
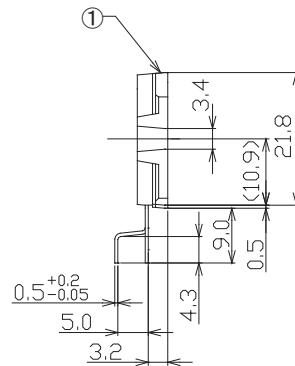


# IRAMS10UP60B

## Package Outline IRAMS10UP60B



missing pin : 3,6,9,11

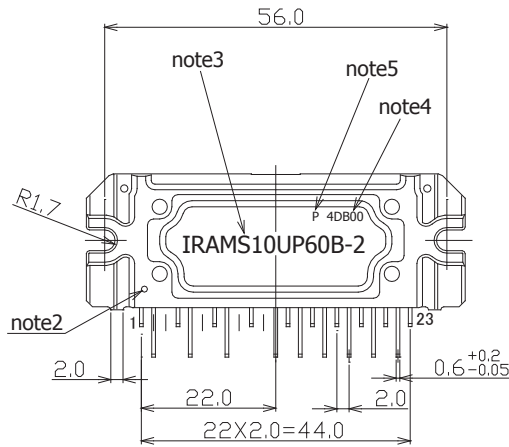


- note1: Unit Tolerance is +0.5mm, Unless Otherwise Specified.
- note2: Mirror Surface Mark indicates Pin1 Identification.
- note3: Part Number Marking. Characters Font in this drawing differs from Font shown on Module.
- note4: Lot Code Marking. Characters Font in this drawing differs from Font shown on Module.
- note5: "P" Character denotes Lead Free. Characters Font in this drawing differs from Font shown on Module.

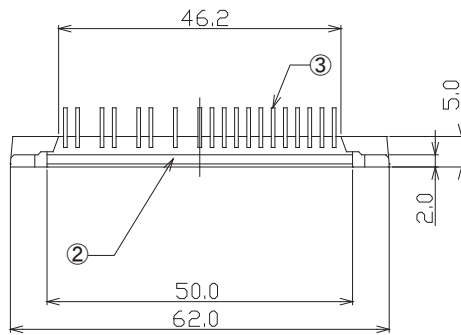
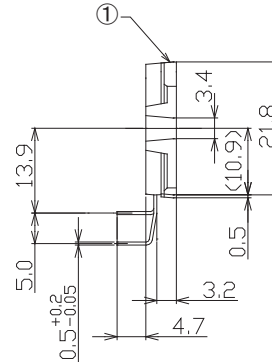
Dimensions in mm  
For mounting instruction see AN-1049



## Package Outline IRAMS10UP60B-2



missing pin : 3,6,9,11



- note1: Unit Tolerance is +0.5mm, Unless Otherwise Specified.
- note2: Mirror Surface Mark indicates Pin1 Identification.
- note3: Part Number Marking. Characters Font in this drawing differs from Font shown on Module.
- note4: Lot Code Marking. Characters Font in this drawing differs from Font shown on Module.
- note5: "P" Character denotes Lead Free. Characters Font in this drawing differs from Font shown on Module.

Dimensions in mm  
 For mounting instruction see AN-1049