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# KP106 Kit Evalkit for Pressure Sensors

User's Manual Rev. 1.0

Sense & Control



Never stop thinking

Edition 2007-08-20

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#### **KP106 Kit Evalkit for Pressure Sensors**

#### Revision History: 2007-08-20, Rev. 1.0

s Version:
Subjects (major changes since last revision)

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# KP106 Kit Evalkit for Pressure Sensors

# User's Manual

Version 2.6

# 1 Overview

The Pressure Evaluation and Demo Board is intended for following purpose:

#### Evalkit with PC Interface for Pressure Sensors KP106 Family

A PGSISI interface box is used to inferface the KP106 sensor.

It has several analog and digital in- and output ports to power the sensor and communicate via SPI and the Manchester-coded current interface.

For evaluation purposes in a laboratory environment, the PGSISI box can be used program the EEPROM registers in the sensor.

With an optional pressure coupling unit, it can be connected with a tube to a pressure source.





Product Name	Product Type	Ordering Code			
KP106 Kit	Evalkit for Pressure Sensors	SP000367787			



Accessories

# 2 Accessories

### 2.1 Hardware

Following equipment is necessary for the PC-Interface:

- PGSISI box
- KP106 demoboard
- Power supply unit
- Different power supply adapters
- USB connector cable
- Optional: RS232 connector cable



Figure 1 PC-Interface Hardware

### 2.2 Software

Following software is necessary for the PC-Interface:

- FTDI USB Driver
  - driver files can be found in the FTDI subfolder of the CD-ROM
- KP106 Evalkit V2.6 Installer
  - setup.exe can be found in the Volume subfolder of the CD-ROM
- Settings file KP106.ini
  - this file is provided directly by Infineon Technologies and has to be copied to C:\Program Files\KP106 Evalkit V2.6\data or the appropriate installation folder.



Accessories

# 2.3 Block Diagram



Figure 2 Block Diagram Hardware and Software Setup

The board is connected to the PGSISI box via a 25 pin D-shaped connector. The box can be connected to the computer either via USB or a RS-232 serial cable. User interaction is possible via a LabVIEW GUI which is communicating with the PGSISI box firmware.



Installation

# 3 Installation

# 3.1 PGSISI Driver Unit

The hardware must be connected as shown in **Figure 1**. The USB connector has to be connected to a free USB port of the PC, alternatively the RS-232 cable can be used.

Note: Be sure not to connect both of them!

After connecting the PGSISI box with your PC (Operating System Windows 2000 or Windows XP) the Installation Wizard will start automatically to install the correct driver. During the installation the *specify a location* option (see **Figure 3**) should be enabled. The appropriate driver can be found on the CD-ROM in the subfolder *FTDI*. *Note: The installation routine operates twice, for the USB to serial converter and the virtual COM port!* 

Locate Dr Where	iver Files do you want Windows to search for driver files?
Search	for driver files for the following hardware device:
- Porton	USB <-> Serial
The wiz any of t	ard searches for suitable drivers in its driver database on your computer and in ne following optional search locations that you specify.
To start insert th	the search, click Next. If you are searching on a floppy disk or CD-ROM drive, e floppy disk or CD before clicking Next.
Option	al search locations:
	loppy <u>d</u> isk drives
Πį	D-ROM drives
	pecify a location
	Aicrosoft Windows Llodate

Figure 3 Installer Wizard

# 3.2 KP106 Evalkit V2.6 Installer

To install the KP106 Evalkit V2.6 software, insert the provided CD in your CD-ROM drive. Start the *setup.exe* file in the *Volume* folder. The KP106 Evalkit Installer Wizard will start. Follow the installation instructions. Afterwards you will be able to start the GUI (*Start Menu -> Programs -> KP106 Evalkit -> KP106 Evalkit V2.6*).

# 3.3 Settings file *KP106.ini*

This file has to be copied to C:\Program Files\KP106 Evalkit V2.6\data or the appropriate installation folder. It contains some settings for communication and EEPROM programming.



Installation

# 3.4 Insertion of the Sensor

Make sure to insert the sensor with the large GND pin aligned to the marking in the socket, like shown in Figure 4.





With an optional pressure coupling unit, it can be connected with a tube to a pressure source, see Figure 5.



Figure 5 Pressure Connector for the Evalboard



# 4 Graphic User Interface

After installing the KP106 Evalkit Software and connecting the PGSISI box to your PC, the application can be started (*Start -> Programs -> KP106 Evalkit -> KP106 Evalkit V2.6*). The first page is always the power supply page.

# 4.1 Power Supply Page

Both sensors can be powered with different voltages. They can be activated by pressing the on/off button.

The *sensor in test mode/sensor in normal operation* button indicates the test mode status. Pressing this button toggles test mode (this feature is available at every page).

Note: The supply voltage settings at this page are the base settings for every page, e.g. the supply voltage during test mode.



Figure 6 Power Supply Page

The program can be closed by pressing the *EXIT* button on the right hand side or the "close" button on top right of the window. But before, running tasks such as receiving Manchester have to be stopped!



# 4.2 EEPROM Page

The EEPROM page gives the possibility to read out and program the EEPROM shadow register. Therefore, the test mode must be activated. Switching to the EEPROM page automatically activates test mode.

KP106 Evalkit V2.6.vi	
Power Supply EEPROM Margin	SPI       Manchester       Pressure Visualization       Extras       KP106-AD       Sensor0 in test mode       Sensor1 in normal operation       EXIT
Sensor0 Sensor1	read from file write to file all zero all one even checkerboard odd checkerboard
Read EEPROM	16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
Burn only changes	00 0 1 1 0 1 0 0 0 1 0 1 0 0 0 0 1 Hex Code
Burn every cell	
Margin Mode	
	1 1 1 0 0 0 0 1 0 1 1 1 1 C2F3 ÷

Figure 7 EEPROM Page

To read the EEPROM content press the *Read EEPROM* button at the left hand side (be sure you have selected the right sensor channel with the *Sensor0 - Sensor1* button before). The result will be shown in the EEPROM matrix. Besides, the content of every register will be shown as hexadecimal code (*Hex Code*) at the right hand side from the EEPROM matrix.

Note: The Hex Code will only show the result of the 16 LSB of every register (the parity bit is not considered).

To modify the EEPROM, every EEPROM cell inside the EEPROM matrix can be toggled by pressing it or changing the hex code value. All parity bits are calculated automatically. After the modification, either all cells can be burned by the *burn every cell* button, but it is recommended to *burn only changes* because already correct cells will not be charged twice.

Inside the EEPROM matrix the supplier area is also changeable, but these changes have no influence on the sensor's EEPROM. If the customer area of the EEPROM is protected with the customer memory lock bit, there is also no possibility to program the EEPROM.

Above the EEPROM matrix there are some helpful functions like saving the EEPROM content into a file or general settings of the EEPROM matrix. Further settings for the EEPROM handling are available in the Extra page (e.g. file path settings or programming conditions; see **Chapter 4.7**).



# 4.3 EEPROM Margin Page

On this page the voltage of all programmed EEPROM cells can be checked. Switching to the EEPROM margin page automatically activates the test mode.

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wer Supply EEPROM Margin SPI Ma	nchester	Pressur	re Visua	lization	Ext	ras	KP10	6-AD		Sensor	0 in tes	t mode		Senso	r1 in noi	mal ope	eration	EXI
unner voltage [V] 5.00 🚍	Bit 16								Bit 8								Bit O	
ower voltage [V]		2,70	2,70	•	2,60	•	•	•	2,70	•	2,70	•	•	•	•	•	2,80	Byte O
voltage per step [V] 0,10 🗧	2,80	Í.	-	•	2,70	Í.	•	•	Í.	•	<u> </u>	2,60	- I	Ī	Í -	-	2,70	
	2,70	•	-	2,70	2,70	2,70	•	•	•	•	-	2,70	-	•	2,70	2,70	2,70	
Define Margin Voltage "1"		·	· .	· .	·	·	•	· .	·	•	-	•	•	<b>·</b>	•	-		
	2,70		<u> </u>	<u> </u>	<u> </u>	2,70	2,70	Ŀ	2,70	•		2,70	2,70	Ŀ	2,60	2,60		
Check Margin Voltage "0"		$\Box$	$\Box$		$\Box$	$\Box$		$\Box$	$\Box$				<u> </u>	Ŀ	•	<u> </u>	$\Box$	
	2,80												2,70	Ŀ	-	-	Ŀ	
Save to file	2,70		<u> </u>		2,70		•	<u> </u>		<u> </u>	<u> </u>	2,70	<u> </u>	Ŀ	-	-	2,70	
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	2,80	Ŀ	<u> </u>	<u> </u>	<u> </u>	2,70	2,80	2,70	Ŀ	<u> </u>	<u> </u>	2,70	2,70					
		2,70	2,60	2,70		Ŀ	2,70		Ŀ			2,70		<u> -</u>	2,80	<u> </u>	Ŀ	
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	•		2,70	<u> </u>	-		- I	· ·	2,70	-	· ·	-	2,70	<u> </u>	-	2,70		

Figure 8 EEPROM Margin Page

#### Defining Margin Voltage "1":

For Ones it can be specified in which range (between lower and upper voltage) and with which granularity (voltage per step) the margin voltage is checked. By hitting the *check margin voltage "1"* button, several readouts with margin voltages from *lower voltage* to *upper voltage* are executed. The voltage level a bit toggles from one to zero is displayed for each bit in the EEPROM table.

Zeros in EEPROM are marked with " - ". If the bit is outside the given range, "low" or "high" will be displayed.

#### Checking Margin Voltage "0":

Here it is checked wether all *Zeros* are below a level of 0.43 volts (this value is taken from the **Settings file KP106.ini**). Zeros that are below this level are marked *"ok"*, otherwise *"ERR"*.



### 4.4 SPI Page

The SPI page allows sending SPI commands to the sensor. The SPI command can be a read or write command to the given address. The *data in* field defines the data which should be written to the selected register. After executing the SPI command the previous content of the addressed register is shown in the *data out* field.

Ele Help	Fineon KD106 Evalkit Pressure Sensor for Side Crash Detection
Power Supply EEPROM Margin SPI Manchester Pressure Visualization Sensor0 Sensor1 write adr [hex] C  send single SPI command send continuous commands	Extras         KP106-AD         Sensor0 in normal operation         Sensor1 in normal operation         EXIT           65535         -
data in data in [bin] 15 14 13 12 11 10 09 08 07 06 05 04 03 02 01 00 0 0 0 1 0 0 1 0 0 1 1 0 1 0 0 data in [dec] 4660 data in [hex] 1234	data out         data out [bin]         16       15       14       13       12       11       10       09       08       07       06       05       04       03       02       01       00         0       1       1       1       0       0       0       1       0       0       1       0       0       0       1       0       0       0       1       0       0       0       1       0       0       0       1       0       0       0       1       0       0       0       1       0       0       0       1       0       0       0       1       0       0       0       1       0       0       0       1       0       0       0       1       0

Figure 9 SPI Page

Single commands operate only once, continuous commands will be sent until the PGSISI box is stopped. After stopping there is the possibility to save the received data to a file.

Note: The SPI register graph is only updated in continuous mode, but the binary representation of data out is not updated!



# 4.5 Manchester Page

The Manchester page allows reception of *asynchronous* or *synchronous* Manchester frames. For synchronous reception the values for *sync pulse length*, *sync pulse period* and *sync pulse voltage* have to be set. *Bias voltage* is updated automatically according to the voltage on the **Power Supply Page** and vice versa.

Power is automatically deactivated and reactivated before beginning reception, to make sure the first frame after the initialization phase of the sensor is received.



Figure 10 Manchester Page

The graph displaying the *differential relative pressure*  $\Delta p/p_0$  is always shown; the text field left to it is updated after stopping Manchester reception. Then it is possible to save the received data to a textfile. Unless the box use fixed file for Manchester data on the Extras Page is checked, a filename must be specified.

The number of frames to receive is only limited by the speed of the PC, i.e. receiving data at the (USB to) serial port, processing the Manchester data inside the program and possibly the speed of writing to the hard disk. If a buffer overflow the serial port occurs, Manchester reception is automatically stopped.

Note: The coordinate axes of the graph are adjustable by changing the displayed values (e.g. mark the maximum value "256" with the cursor and type "50")



# 4.6 Pressure Visualization Page

The Pressure Visualization page reads all pressure registers (p,  $p_0 \& \Delta p/p_0$ ) via SPI command. The *Actual Pressure* (*p*), the *Ambient Pressure* (*p*<sub>0</sub>) and the *Differential relative Pressure* ( $\Delta p/p_0$ ) buttons give the possibility to select which graphs should be displayed.

If the  $\Delta p/p_0$  value is outside a range set on the **Extras Page**, the *No Impact / Crash Impact* button will flash. It can be reset by press it.



Figure 11 Pressure Visualization Page

Note: The coordinate axes of the graph are adjustable by changing the displayed values (e.g. mark the maximum voltage "256" with the cursor and type "50")



# 4.7 Extras Page

On the Extras page special settings can be done, such as fixed paths for EEPROM and measurement files or the EEPROM programming voltage and timings. The default values usually should be the best.

Additionally, the Manchester data files saved from the Manchester Page can be analyzed here.

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	_					-
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BI-BI-			eui			
A start and	-			ressure Sel	nsor for Sia	le Crash Detecti
	× × .	The second secon		_		
ower Supply EEPROM Margi	n SPI Mancheste	Pressure Visualization Extr	as KP106-AD	Sensor0 in nor	mal operation Sens	or1 in normal operation EXI
Path Programming Settings		ster Analysis				
Fact Frogramming Decorgs	Visualization handle					
	frame no.   hex	binary (LSB)	Δр/р0			
open file	0 0x5240	0101.0010.0100.0000	2 🔺	255 -		
C1	1 0x9284	1001.0010.1000.0100	33	240 -		
file information	2 0x9208	1001.0010.0000.1000	16			
Manchester data file	3 0x72E4	0111.0010.1110.0100	39	220 -		
created by KP106 Evalkit	4 0x521C	0101.0010.0001.1100	56			
2.6.2	5 0x7200	0111.0010.0000.0000	0	Q 200-		
	6 0x7200	0111.0010.0000.0000	0	9 190 -		
Sensor: KP106-AD	7 0xD26C	1101.0010.0110.1100	54	<100-		
	8 0x92B0	1001.0010.1011.0000	13	5 160-		
date: 2007-08-16, 17:10:18	9 0xDE74	1101.1110.0111.0100	46	SS		
	10 0xDE74	1101.1110.0111.0100	46	ក្ដ័ 140-		
bias voltage: 5000 mV	11 0xDE74	1101.1110.0111.0100	46	Ū.		
syncronous transmission	12 0xDE74	1101.1110.0111.0100	46	⊉ 120-		
sync pulse voltage: 8600 mv	13 0xDE74	1101.1110.0111.0100	46	iii iiiiiiiiiiiiiiiiiiiiiiiiiiiiiiiiii		
sync pulse length: 20 µs	14 OxDE74	1101.1110.0111.0100	46	- 100 - <b></b>		
sync palse penoa; 512 µs	15 0xDE74	1101.1110.0111.0100	46	Ê.		
Mapchaster bits: 19	16 0xDE74	1101.1110.0111.0100	46	0 80-		
Manchester type: 1	17 0xDE74	1101.1110.0111.0100	46	₩ co_		
Manchester data start: 0	18 0xDE74	1101.1110.0111.0100	46			
Manchester data ston: 8	19 0xDE74	1101.1110.0111.0100	46	40-		National Action
	20 0xDE74	1101.1110.0111.0100	46			
total number of frames:	21 0xDE74	1101.1110.0111.0100	46	20-		
3264	22 0xDE74	1101.1110.0111.0100	46			
	23 0xDE74	1101,1110,0111,0100	46	0-		
	24 0xDR74	1101 1110 0111 0100	46	0 500	1000 1500 2	00 2500 3000 3500
	25 0xDE74	1101 1110 0111 0100	46 -		frames	
	LO UNDERT					

Figure 12 Extras Page



### 4.8 Menu bar

*Reconnect to PGSISI Box* will close the (virtual) COM port, reopen it and start the boot loader again. This can be used when the connection has been lost or the box was powered down.

Open manual shows this document and About KP106 Evalkit presents some version information.



#### Figure 13 Extras Page - File



Figure 14 Extras Page - Help

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