

SANYO Semiconductors DATA SHEET



Monolithic Digital IC – For CD-ROM Drives Spindle Motor Driver IC

Overview

The LB11699H is a spindle motor driver IC for CD-ROM drives.

Features

• Three-phase brushless motor driver

Functions

- Current linear drive
- Voltage controlled amplifier
- The use of high side current detection means that there is no loss (or voltage drop) due to the current detection resistor.
- Built-in short-circuit braking circuit
- Built-in reverse rotation prevention circuit
- Hall sensor FG output
- Built-in start/stop function
- Built-in current limiter circuit (adjustable)
- Built-in Hall sensor power supply
- Built-in thermal shutdown circuit
- Supports 3.3V DSPs
- Maximum current rating: 2.0A

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Specifications

Maximum Ratings at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage1	V _{CC} 1 max		7.0	V
Supply voltage 2	V _{CC} 2 max		14.4	V
Output apply voltage	V _O max		14.4	V
Input apply voltage	V _I max		V _{CC} 1	V
Output current	I _O max		2.0	А
Allowable internal power	Pd max	Independent IC	0.8	W
dissipation		When mounted on a circuit board *1	1.9	
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		-55 to +150	°C

*1 Specified circuit board : 114.3 \times 76.1 \times 1.6 mm³, glass epoxy.

Operating Conditions at $Ta=25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage 1	V _{CC} 1		4 to 6	V
Supply voltage 2	V _{CC} 2	≥ V _{CC} 1	4 to 13.6	V

Application Example at $Ta = 25^{\circ}C$

(1) 12V model

Power supply pin	Conditions	Ratings	Unit
V _{CC} 1	Regulated voltage	4 to 6	V
V _{CC} 2	Unregulated voltage	4 to 13.6	V

Electrical Characteristics at Ta = 25°C, V_{CC}1 = 5.0V, V_{CC}2 = 12V (unless otherwise specified)

Deremeter	Symbol	Conditions	Ratings			Linit		
Parameter	Symbol		min	typ	max	Unit		
Supply Current								
Supply current 1	I _{CC} 1	VC = VCREF		6.0	9.0	mA		
Supply current 2	I _{CC} 2	VC = VCREF			1.0	mA		
Output stop current 1	I _{CC} 10Q	VS/S = 0V			200	μA		
Output stop current 2	I _{CC} 2OQ	VS/S = 0V			350	μA		
Output Block								
High-side saturation voltage 1	VOU1	I _O = -0.5A		1.0	1.5	V		
Low-side saturation voltage 1	VOD1	I _O = 0.5A		0.3	0.5	V		
High-side saturation voltage 2	VOU2	I _O = -1.5A		1.1	1.8	V		
Low-side saturation voltage 2	VOD2	I _O = 1.5A		0.6	1.2	V		
Hall Sensor Amplifier Block								
Common-mode input voltage	VHCOM		1.2		V _{CC} 1 -	V		
Innut bias current	VHIB			1	1.0			
Hall sensor minimum input level	VHIN		60	I		μA m\/n n		
S/S Pin	vinit		60			шүр-р		
J/J Fill	\/ <u>\$</u> /\$L		0.0		V 4	N		
	VS/SIT		2.0		VCC1	V		
	V 3/3L				0.7	V		
Input current	IS/SI	VS/S = 5V			200	μA		
Leakage current	IS/SL	VS/S = 0V	-30			μΑ		

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Deremeter	Symbol	Conditions	Ratings			Lipit	
Falamelei	Symbol Conditions		min	typ	max	Onit	
Control Block							
VC pin input current	IVC	VC = VCREF = 1.65V	-1			μA	
VCREF pin input current	IVCREF	VC = VCRE F= 1.65V	-1			μA	
Voltage gain	GVCO	ΔVRF/ΔVC		0.4		Times/ deg	
Rising voltage	VCTH	VCREF = 1.65V	1.5		1.8	V	
Rising voltage width	∆VCTH	VCREF = 1.65V	50		150	mV	
Hall Sensor Power Supply							
Hall sensor supply voltage	VH	I _H = 5mA		0.8		V	
Allowable current	IH		20			mA	
Thermal Shutdown Circuit							
Thermal shutdown operating temperature	TTSD	Design target value*	150	180	210	°C	
Thermal shutdown temperature hysteresis	ΔTTSD	Design target value*		15		°C	
Short-Circuit Braking	•			•			
BRAKE pin high-level voltage	VBRH		2.5		5	V	
BRAKE pin low-level voltage	VBRL		0		1	V	
Single Hall Sensor/Three Hall Se	ensor FG Switchi	ng					
FGSEL pin high-level voltage	VFSH		2.5		5	V	
FGSEL pin low-level voltage	VFSL	0		1	V		
Current Limiter Setting							
Current limiter set voltage	VCL1	$REF = 0.39\Omega$, $VLMC = VREF$		0.4		V	
VLMC pin input voltage range	VLMCC	Design target value*	0		1.3	V	
Reference voltage	VREF	IVREF =10μA		1.25		V	

Note: The Hall comparator output goes to the high level when the S/S pin is in the off state (standby mode).

* The design specification items are design guarantees and are not measured.

Package Dimensions

unit : mm (typ) 3234B





Pin Assignment



Top view

Truth Table

			Input		Control voltogo	
	Source \rightarrow Sink	U	V	W	Control Voltage	
4	W phase \rightarrow V phase	Llink		1	High	
1	V phase \rightarrow W phase	High	High	LOW	Low	
	W phase \rightarrow U phase	Llink	1	1	High	
2	U phase \rightarrow W phase	High	LOW	LOW	Low	
V	V phase \rightarrow W phase	Low	Low	High	High	
3	W phase \rightarrow V phase	LOW			Low	
4	U phase \rightarrow V phase		High	Low	High	
4	V phase \rightarrow U phase	LOW			Low	
F	V phase \rightarrow U phase	Lliab	High Low	High	High	
5	U phase \rightarrow V phase	High			Low	
6	U phase \rightarrow W phase	Low	High		High	
b l	W phase \rightarrow U phase	Low High	nign	Low		

Input high: Input 1 is at least 0.2V higher than input 2 for a given phase.

Input low: Input 2 is at least 0.2V higher than input 1 for a given phase.

Brake Operation Truth Table

BRAKE pin	Operation at VC < VCREF	
High	Short-circuit braking	
Low or open Reverse torque braking		



Application Example



The values of the capacitors between power supply and ground, between output and ground, and between the Hall sensor inputs vary depending on the motor used. In particular, the Hall sensor input capacitors may not be required for some motors.

<Information> Current Limiter Setting



The LB11699H current limiter set voltage is the VLMC pin voltage, and varies as shown in the figure to the left. When the VLMC pin voltage is 0V, the current limiter set voltage will be 0V and no output current will flow.

Pin Functions

Pin No.	Pin	Pin voltage	Description	Equivalent Circuit
19	V _{CC} 2	4V to 13.6V	Power supply that provides the source side predriver voltage. Power supply that provides the constant current control amplifier voltage.	
17	V _{CC} 1	4V to 6V	Power supply that provides all voltages other than those for the output transistors, the source side predrivers, and the low-current control amplifier.	
9	RS		Reverse rotation detection Outputs a high level for forward rotation. Outputs a low level for reverse rotation.	V _{CC} 1 100μA 10kΩ * 89
8	FG		One or three Hall sensor Schmitt trigger comparator synthesized output	
15	U _{IN} 1	1.2V to V _{CC} 1-1V	U phase Hall sensor input and reverse rotation detection U phase Schmitt trigger comparator input.	
16	U _{IN} 2		The logical high state indicates the state where $U_{IN}1 > U_{IN}2$.	V _{CC} 1
13	V _{IN} 1		V phase Hall sensor input and reverse rotation detection V phase Schmitt trigger comparator input.	$\begin{array}{c} 15 \\ (13) \\ (11)$
14	V _{IN} 2		The logical high state indicates the state where $V_{IN1} > V_{IN2}$.	25μAΨ 25μAΨ <i>π π π</i>
11	W _{IN} 1		W phase Hall sensor input and reverse rotation detection W phase Schmitt trigger comparator input.	
12	W _{IN} 2		The logical high state indicates the state where $W_{IN}1 > W_{IN}2$.	
10	VH		Provides the Hall sensor low side device voltage.	V _{CC} 1 75μA 30kΩ 2kΩ 2kΩ 2kΩ 30kΩ
6	S/S	0V to V _{CC} 1	All internal circuits are stopped by setting this pin to 0.7V or lower or by setting it open. Set this pin to 2.0V or higher when driving the motor.	
5	SIG GND		Ground for all systems except the output system.	

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Pin No.	Pin	Pin voltage	Description	Equivalent Circuit			
3	FC		Control loop frequency characteristics correction Current control system closed loop oscillations can be prevented by connecting a capacitor between this pin and ground.	V _{CC} 1			
2	VCREF	0V to V _{CC} 1-1.5V	Control system reference voltage input The control system start voltage is determined				
1	VC	0V to V _{CC} 1	by this voltage. Speed control voltage input This is a voltage controlled system in which: The motor turns in the forward direction when VC > VCREF, and The motor turns decelerates when VC < VCREF. (Since the LB11699H includes a reverse rotation prevention circuit, the motor will never turn in the reverse direction.)	15μA (V) 25μA (V) 25μA 51kΩ 100μA 100μA 100μA 100μA 100μA 100μA 100μA 100μA 100μA			
22	WOUT		W phase output				
	FRAME GND		Output transistor ground				
21	Vout		V phase output				
20	UOUT		U phase output				
18	RF		High side output transistor collector (common to all three phases) Connect a resistor between the RF pin and V _{CC} 3 for current detection. The LB11699H detects this voltage to operate the constant current control and current limiter functions.	3.9Ω 			
27	VLMC	0 to 1.3V	This pin determines the current limiter set voltage. The current limiter set voltage can be changed by applying a voltage to this pin.	V _{CC} 1 6μA 6μA 6μA 6μA 200Ω 6ρF 6ρF			
28	VREF		Reference voltage (1.25V typical) output				

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Pin No.	Pin	Pin voltage	Description	Equivalent Circuit
7	BRAKE	ov to V _{CC} 1	Short-circuit braking pin BRAKE : High → brake Low → drive Open	100μA 75kΩ 75kΩ 75kΩ 7 7 8 50kΩ 7 7 7 7 7 7 7 7 7 7 7 7 7
4	FGSEL	ov to VCC1	Single Hall sensor/three Hall sensor FG switching pin FGSEL : High → three Hall senso Low → single Hall sensor Open	100μA 75kΩ W 4 50kΩ 75kΩ

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