

## M52036SP

## SYNC SIGNAL PROCESSOR

REJ03F0086-0100Z Rev.1.0 Sep.22.2003

### **Description**

The M52036SP is a semiconductor integrated circuit for the automatic selection and rectification of sync waveforms. The IC operates with synchronizing signals in three forms, that is, separate sync(positive or negative polarity, 1 to 5 Vp-p), composite sync (positive or negative polarity, 1 to 5 Vp-p), and synchronous video (negative sync). This IC is optimal for processing sync signals for multi-scan-type displays.

### **Features**

- Indicates the presence or absence of synchronizing-signal input and the polarities of the signals
- Pulse-output circuit is for open-collector output
- Clamp-pulse output and Clamp-pulse trigger is generated at the front edge for separate sync and composite sync input, and at the rear edge for sync on video input.
- 20-pin shrink-DIP

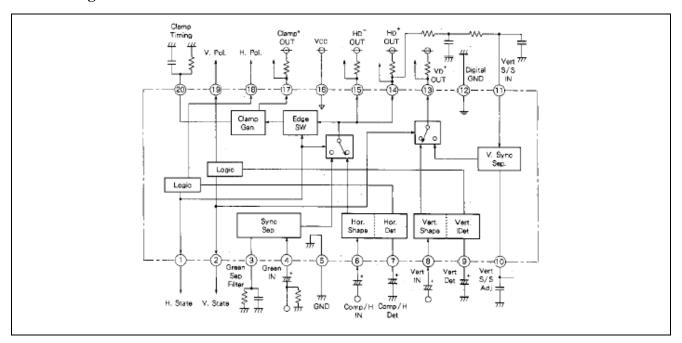
### **Application**

Display Monitor

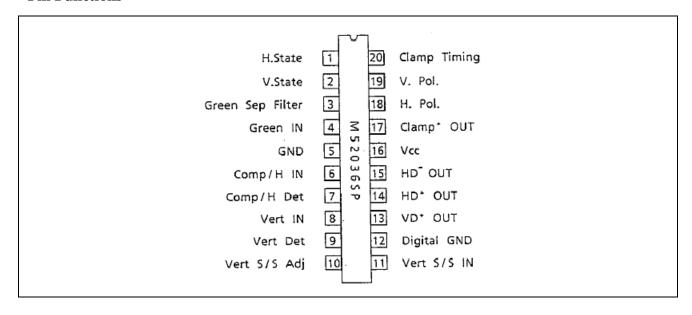
### **Recommended Operating Condition**

Supply voltage range: 11 to 13 VRated supply voltage: 12 V

### **Block Diagram**

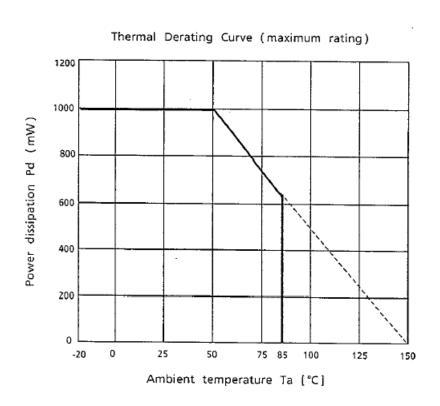


### **Pin Functions**



### **Absolute Maximum Rating**

Item	Symbol	Rated values	Units	
Supply voltage	Vcc	14.0	V	
Power dissipation	Pd	1000	mW	
Operating ambient temperature	Topr	-20 to 85	°C	
Storing temperature	Tstg	-40 to 150	°C	



## **Electrical Characteristics**

 $(Ta = 25^{\circ}C\ Vcc = 12\ V,\ V_{DD} = Open)$ 

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	8		7.5µs 16xHz	7.5µs 16KHz	∏7.5µs 16KHz 0.7Vp·p	7.5µs 16KHz	7.5µs 16KHz	7.5µs 16KHz	7.5µ5 16KH2	∏7.5µs 16KHz	7.5µs 16KHz	7.5µs 16KH2	∏7.5µs 16KHz	U7.5µs 16KHz	7.5µs 16KHz	]∫7.5µs	][7.5µs	][7.5µ	
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## **Electrical Characteristics (cont.)**

 $(Ta = 25^{\circ}C\ Vcc = 12\ V,\ V_{DD} = Open)$ 

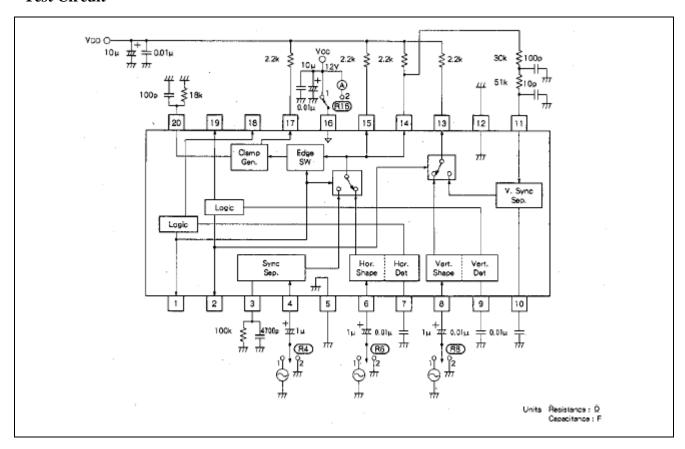
Remarks  le input signal 0.1Ve+ is a  mmy noise signal.		The input signal 0.1Vr- is a dummy noise signal.	If malfunction by noise occurs is checked.				
Types	of Unit	۸	>	>	>	. >	>
sən	Max.	0.1	1	0.5	0.5	0.5	0.5
Rated values	Typ: Max.	ı	1	ı	-	_	1
Rate	Min.	-	0.2	ı	ı	- 1	1
Output	waveforms	No pulse should be output,	16KHz  The should be output in this duretion.	7 v Mess		Л V Меаs	J v Meas
Output	pins	14	4	15	14	17	13
Input	conditions	7 1.5µ 16KHz 0.1Vp-p	1.5µ 16KHz 0.2Vp.p	TZ.5µs 16KHz	JL7.5µs 16KHz	J 7.5µs 16KHz	][7.5µs 16KHz
Input	pins	4	4	4/6	4/6	4/6	60
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conditions	80	2	74	2	~	2	-
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Switch	Ф	-	-	-	·-	-	2
Sum both	27.00	SS-NV	N1-55	1201	140L	170L	130L
		Maximum noise amplitude of voltage of input signal	Minimum voltage amplitude of input signal	15pin HO" Output Low level	14pin HD* Output Low level	17pin CP* Output Low level	13pin VD* Output Low level
Ş		11	12	13	14	15	16

## **Electrical Characteristics (cont.)**

 $(Ta = 25^{\circ}C\ Vcc = 12\ V,\ V_{DD} = Open)$ 

Remarks		•	-					
Types of Unit	\$	ŞĒ.	SC.	Sir.	SU.	. Sr	ž	Su
×	350	350	350	350	350	950	350	350
Rated values in. Typ. Max.	120	150	120	100	120	700	120	5
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Output	15	15	14	14	11	. 17	13	13
Input	7.5µs 16KHz	7.5µs 16KHz	7.5µs 16xHz	7.5µs 16XHz	J. 7.5µs 16KHz	7.5µs 16KHz	T7.5µs 16KHz	] 7.5µs  6KHz
Input pins	4/6	4/6	4/6	4/6	4/6	4/6	ω .	8
16 16	-	-	-	-	-	-	-	-
Switch conditions	2	7	- 2	7	~	. 7	-	-
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Symbols	HD - DA	80 GH	HD+-DA	HD:08	CP* - DT	. σο - − σο	VDDA	VD* D8
Items	HD"delay time (A)	HD <sup>*</sup> delay time (B)	HD*—delay time (A)	HD⁺delay time (B)	CP* - delay time	CP• — PULSE → WIDTH	VD⁺—delay time (A)	VD'-delay time (8)
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## **Test Circuit**

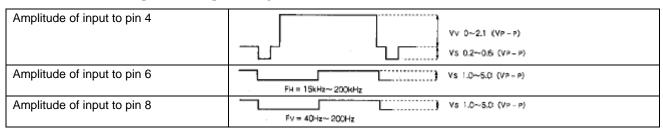


### **Logic Table**

**Table.1 Decoder Logic Output** 

Input to pin 6 HD.COMP	Input to pin 8 VD	Output pins				
		1	2	18	19	
HD. COMP. (POS)	NON	Н	L	L	L	
HD. COMP. (POS)	VD (POS)	Н	Н	L	L	
HD. COMP. (POS)	VD (NEG)	Н	Н	L	Н	
HD. COMP. (NEG)	NON	Н	L	Н	L	
HD. COMP. (NEG)	VD (POS)	Н	Н	Н	L	
HD. COMP. (NEG)	VD (NEG)	Н	Н	Н	Н	
NON	NON	L	L	L	L	
NON	VD (POS)	L	Н	L	L	
NON	VD (NEG)	L	Н	L	Н	

Table.2 Allowable Amplitude of Input Voltage



**Table.3 Output Priority** 

Input signal	ls (pin)		Output signals (pin)					
4 pin	6 pin	8 pin	14 pin 15 pin	13 pin	17 pin			
О	×	×	4	11	4			
O	О	×	6	11	6			
O	×	О	4	8	4			
O	О	О	6	8	6			
×	×	×	×	×	×			
×	О	×	6	11	6			
×	×	О	×	8	×			
X	0	О	6	8	6	•		

# Table.4 Pulse Duty Ratio for Allowable Maximum Input Signal Input Pulse to Pin 6 (HD.COMP.)

 $F_H = 16 \; kHz$ 

Maximum voltage amplitude (V <sub>P-P</sub> )		1.0	3.3	4.0	5.0
POS.	%	15.0	13.8	11.2	9.0
	Time (μs)	9.38	8.63	7.00	8.63
NEG.	%	15.0	13.0	10.5	8.8
	Time (µs)	9.38	8.13	6.56	5.50

### Input Pulse to Pin 8 (VD)

Fv = 60 Hz

Maximum voltage amplitude (V <sub>P-P</sub> )		1.0	3.3	4.0	5.0
POS.	%	14.1	12.1	9.8	7.7
	Time (ms)	2.35	2.02	1.63	1.28
NEG.	%	14.8	11.3	9.2	7.5
	Time (ms)	2.47	1.88	1.53	1.25

## **Precautions for Application**

### 1. Input

1) Green (Sync on Video) input (pins [3] and [4])

The input signals must be in sync negative polarity.

For sync separation, a method is used in which the sync tip is clamped by a capacitor attached externally to pin [4] and by the C and R attached to pin [3].

Then sync tip of pin [4] shows approximately 4 V.

### 2) Comp Sync/H sync, V sync input

Connect the composite sync input to pin [6]. For the separate sync input, connect H and V to pins[6] and [8] respectively. The bias and impedance at pins [6] and [8] are 6 V and 10 k $\Omega$ , respectively.

Waveform shaping and polarity detection are performed by a double threshold converter installed inside.

The internal circuit is as shown in Fig.B. The average DC voltage is set to approximately  $0.7\ V$  higher and lower than  $V_2$ .

Thus, as shown in Fig. A, this processor is energized by an input signal 0.7 Vp-p or over when the duty ratio is small. On the other hand, approximately 1.4 Vp-p is suitable when the duty ratio is large. Fig. C indicates an allowable standard value for the input duty.

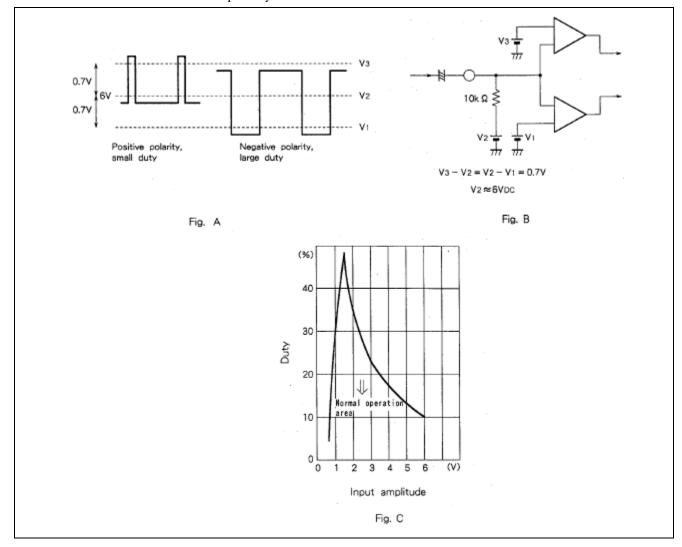
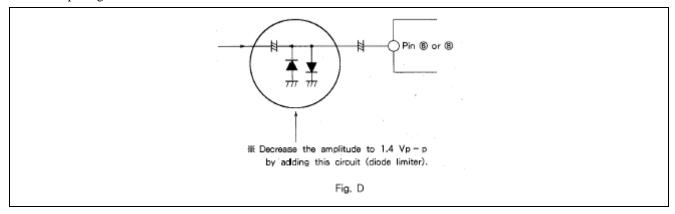
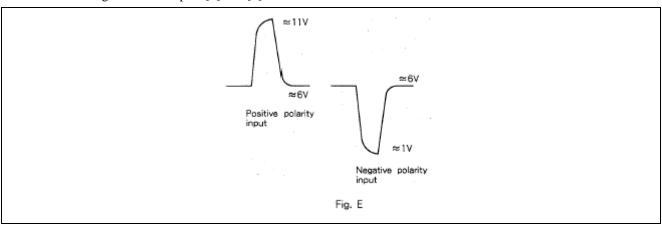


Fig. D shows an example of the measures for improving the allowable duty ratio in a range of 1.4 Vp-p or over of the input signal.



For use in a range outside the specified value, confirm that the waveform complies with Fig. E when measured it after removing the filters in pins [7] and [9].



### 3) Polarity detection and empty input detection (pins [7] and [9])

A capacitor is required to be installed external as a filter for polarity detection and empty input detection. The large the capacitance, the smaller the ripple and reduces malfunction. However, the detecting time is lengthened. For an input of 15 kHz, a capacitor of 0.05  $\mu$ F or larger is recommended. For 60 Hz, a 10  $\mu$ F or larger is sufficient. If it is necessary to use a capacitor of smaller capacitance, measure the waveform at the filter terminal under the condition of the lowest frequency of the input sync signal to be used and the smallest duty ratio. And make sure that the signal shows 7.5 V (actually 6.6 V) or over for positive polarity input or 4.5 V (actually 5.5 V) or lower for a negative polarity input.

### 4) VERT S/S IN (pins [11])

For V sync separation, signals are generated by externally integrating composite sync signals, and are then input. The composite sync signals that are input to pin [6] (H + V) ore output to pin [14]  $HD^+$ . For V sync separation, pin [14]  $HD^+$  output is externally integrated, and input to pin [11]. Check pin [11] waveform to see if the H element is adequately low.

In the IC, the sync separation threshold level is set to approximately 1 V when no external adjustment is provided.

### 5) VERT S/S ADJ (pins [10])

The threshold voltage is approximately 1 V when no external adjustment is provided. The threshold voltage is dependent on IC internal resistance. Pin [10] may be open; however, if noise may give adverse effect, ground the pin with capacitor.

When the H element cannot be lowered sufficiently, connect resistance between pin [10] and Vcc to change the threshold level. (Provide resistance such that when  $V_{DD}$  (Digital Vcc) is 12 V, the threshold voltage will be 8 V or less; and when  $V_{DD}$  1s 5 V, the threshold voltage will be 4 V or less.)

When there are serration pulses or other pulses during the V period, provide resistance such that the threshold voltage will be half as high as  $V_{DD}$ .

### 2. CP-Width

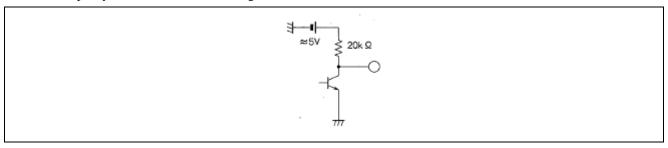
Timing terminal (pins [20])

The time constant depends on the current flowing out through pin [20] and the capacitance of the timing terminal. The current flowing out through pin [20] is usually determined by the terminal voltage and the resistance of externally attached resistor. A pulse width of 0.7  $\mu$  sec is obtained by an 18 k $\Omega$  (or 200  $\mu$ A) resistor and a 100 pF capacitor both installed externally.

### 3. Output stage

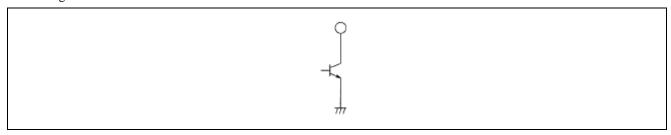
1) Logic output (pins [1], [2], [18] and [19])

This output system is illustrated in the figure shown below. The internal load resistance of this IC is  $20 \text{ k}\Omega$ .



2) Pulse output (pins [13], [14], [15] and [17])

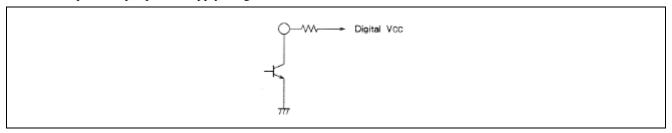
This output system is of open collector type as illustrated in the figure shown below. Approximately 6 mA can be charged in.



3) Power supply

Supply 12 V to pin [16].

For the pulse output power, supply a digital Vcc of 5 to 12 V as illustrated below.



### 4. Other

Differences between M52036SP and M52346SP

The clamp pulse trigger is different between M52036SP and M52346SP when "S on G" and "H/H + V" are input simultaneously, or when only "H/H + V" is input.

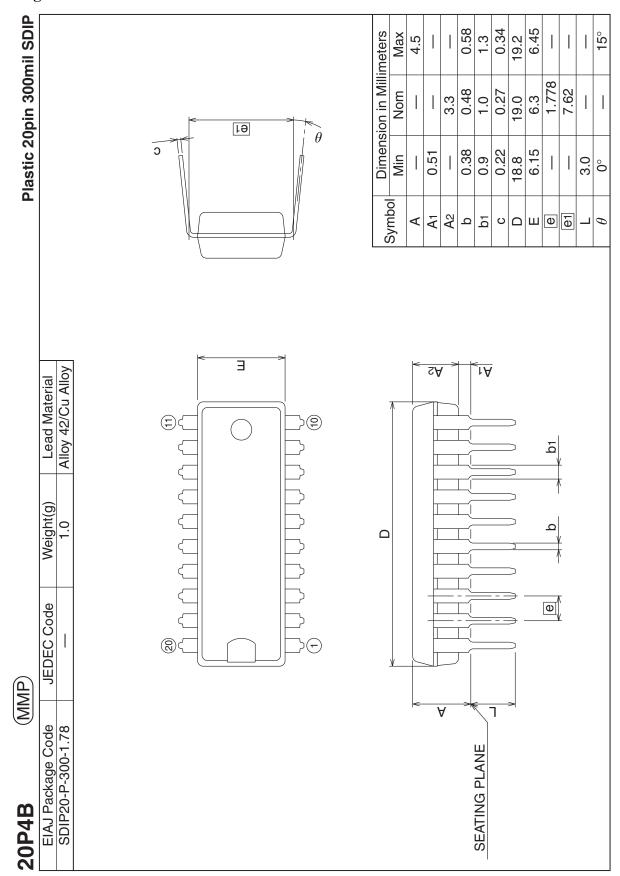
M52036SP: Generated at the first edge of "H/H + V" input.

M52346SP: Generated at the latter edge of "H/H + V" input.

M52346SP clamp pulses are generated at the latter edge of signals that have been given priority.

The M52036SP pin configuration is the same as that of M52346SP.

## **Package Dimensions**



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