16-bit Proprietary Microcontroller

CMOS

F²MC-16LX MB90520A/520B Series

MB90522A/523A/522B/523B/F523B/V520A

■ DESCRIPTION

The MB90520A/520B series is a general-purpose 16-bit microcontroller designed for process control applications in consumer products that require high-speed real-time processing.

The microcontroller instruction set is based on the AT architecture of the F²MC* family with additional instructions for high-level languages, extended addressing modes, enhanced multiplication and division instructions, and a complete range of bit manipulation instructions. The microcontroller has a 32-bit accumulator for processing long word (32-bit) data.

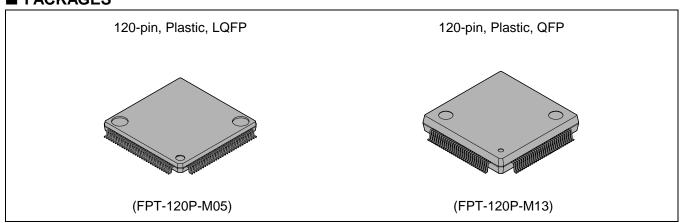
The MB90520A/520B series peripheral resources include an 8/10-bit A/D converter, 8-bit D/A converter, UART (SCI), extended I/O serial interfaces 0 and 1, 8/16-bit up/down counter/timers 0 and 1, 8/16-bit PPG timers 0 and 1, a range of I/O timers (16-bit free-run timers 1 and 2, input capture (ICU) 0 and 1, and output compare (OCU) 0 and 1), an LCD controller/driver, 8 external interrupt inputs, and 8 wakeup interrupts.

*: F2MC stands for FUJITSU Flexible MicroController, a registered trademark of FUJITSU LIMITED.

■ FEATURES

- Clock
- Internal PLL clock multiplication circuit
- Selectable machine clock (PLL clock): Base oscillation divided by two or multiplied by one to four (For a 4 MHz base oscillation, the machine clock range is 4 MHz to 16 MHz).

■ PACKAGES (Continued)





(Continued)

• Sub-clock (32.768 KHz) operation available

Minimum instruction execution time: 62.5 ns (for oscillation = 4 MHz, PLL clock setting = ×4, Vcc = 5.0 V)

• 16MB CPU memory space

Internal 24-bit addressing

Instruction set optimized for controller applications

Rich data types (bit, byte, word, long-word)

Extended addressing modes (23 types)

Enhanced signed multiplication and division instructions and RETI instruction

Enhanced calculation precision using a 32-bit accumulator

• Instruction set designed for high-level language (C) and multi-tasking

System stack pointer

Enhanced pointer-indirect instructions and barrel shift instructions

Faster execution speed

4-byte instruction queue

ROM mirror function (48 Kbytes of bank FF is mirrored in bank 00)

• Program patch function : An address match detection function ($2 \times addresses$)

Interrupt function

32 programmable interrupts with 8 levels

Automatic data transmission function independent of CPU operation

Extended intelligent I/O service function (EI2OS): Up to 16 channels

• Low-power consumption (stand-by) modes

Sleep mode (CPU operating clock stops, peripherals continue to operate.)

Pseudo-clock mode (Only oscillation clock and timebase timer continue to operate.)

Clock mode (Main oscillation clock stops, sub-clock and clock timer continue to operate.)

Stop mode (Main oscillation and sub-clock both stop.)

CPU intermittent operation mode

Hardware stand-by mode (Change to stop mpde by operating hardware stand-by pins.)

Process

CMOS technology

I/O ports

General-purpose I/O ports (CMOS input/output): 53 ports

General-purpose I/O ports (inputs with pull-up resistors): 24 ports

General-purpose I/O ports (Nch open-drain outputs): 8 ports

• Timers

Timebase timer, clock timer, watchdog timer: 1 channel each

8/16-bit PPG timers 0 and 1 : 8-bit \times 2 channels or 16-bit \times 1 channel

16-bit reload timers 0 and 1:2 channels

16-bit I/O timers:

16-bit free-run timers 0 and 1: 2 channels

16-bit input capture 0 : 2 channels (2 channels per unit)

16-bit output compare 0 and 1:8 channels (4 channels per unit)

8/16-bit up/down counter/timers 0 and 1:8-bit × 2 channels or 16-bit × 1 channel

Clock output function: 1 channel

• Communications macro (communication interface)

Extended I/O serial interfaces 0 and 1: 2 channels

UART (full-duplex, double-buffered, SCI: Can also be used for synchronous serial transfer): 1 channel

• External event interrupt control function

DTP/external interrupts: 8 channels (Can be set to detect rising edges, falling edges, "H" levels, or "L" levels) Wake-up interrupts: 8 channels (Detects "L" levels only)

Delayed interrupt generation module: 1 channel (for task switching)

Analog/digital conversion

8/10-bit A/D converter : 8 channels (Can be initiated by an external trigger. Minimum conversion time = 10.2 μ s for a 16 MHz machine clock)

8-bit D/A converter: 2 channels (R-2R type. Settling time = 12.5 μs for a 16 MHz machine clock)

Display function

LCD controller/driver : 32 × segment drivers + 4 × common drivers

• Other

Supports serial writing to flash memory. (Only on versions with on-board flash memory.)

Note: The MB90520A and 520B series cannot be used in external bus mode. Always set these devices to single-chip mode.

■ PRODUCT LINEUP

Parameter	Part Number	MB90522A	MB90523A	MB90522B	MB90523B	MB90F523B	MB90V520A	
Classification	Classification		Mask	ROM		Flash ROM	Evaluation product	
ROM size		64 Kbytes	128 Kbytes	64 Kbytes	128 Kbytes	128 Kbytes	_	
RAM size				4 Kbytes			6 Kbytes	
Separate er power supp		_	_	_	_	_	No	
Process				CM	IOS			
Operating p supply volta		3.0 V to	o 5.5 V	2.7 V t	o 5.5 V	3.0 V t	o 5.5 V	
Internal reg	ulator circuit		not mo	ounted		mou	nted	
CPU function	ons	Instruction siz	Number of instructions : 340 Instruction sizes : 8-bit, 16-bit Instruction length : 1 byte to 7 bytes Data sizes : 1-bit, 8-bit, 16-bit					
		Minimum instruction execution time : 62.5 ns (for a 16 MHz machine clock)						
		Interrupt processing time : 1.5 μs min. (for a 16 MHz machine clock)						
Low power (standby m		Sleep mode, clock mode, pseudo-clock mode, stop mode, hardware standby mode, and CPU intermittent operation mode						
I/O ports		General-purpose I/O ports (CMOS outputs): 53 General-purpose I/O ports (inputs with pull-up resistors): 24 General-purpose I/O ports (Nch open drain outputs): 8 Total: 85						
Timebase ti	mer	18-bit counter Interrupt interval: 1.024 ms, 4.096 ms, 16.384 ms, 131.072 ms (for a 4 MHz base oscillation)						
Watchdog t	imer	Reset trigger period • For a 4 MHz base oscillation: 3.58, 14.33, 57.23, 458.75 ms • For 32.768 sub-clock operation: 0.438, 3.500, 7.000, 14.000 s						
	16-bit freerun timer	Number of channels : 2 Generates an interrupt on overflow						
16-bit 16-bit output compare		Number of chapin change tir		timer register	value equals o	utput compare	register value.	
	16-bit input capture	Number of channels: 2 Saves the value of the freerun timer register when a pin input occurs (rising edge edge, either edge).				g edge, falling		
16-bit reloa	d timer	Number of channels : 2 Count clock frequency : 0.125, 0.5, or 2.0 µs for a 16 MHz machine clock Can be used to count an external event clock.						

Part Number	MB90522A	MB90523A	MB90522B	MB90523B	MB90F523B	MB90V520A		
Parameter Clock timer	15-bit timer							
8/16-bit PPG timer	Number of cha	Interrupt interval : 0.438 , 0.5 , or $2.0 \mu s$ for sub-clock frequency = $32.768 kHz$ Number of channels : 1 (Can be used in 2×8 -bit channel mode) Can generate a pulse waveform output with specified period and 0 to 100% duty ratio.						
8/16 -bit up/down counter/timers	Number of cha	annels : 1 (Car i inputs : 6 cha	be used in 2 ×	8-bit channel				
Clock monitor	Clock output for	requency : Ma	chine clock/21 t	o machine clo	ck/2 ⁸			
Delayed interrupt generation module	Interrupt gene	ration module	for task switchi	ng. (Used by I	REALOS.)			
DTP/External interrupts	Input channels: 8 Generates interrupts to the CPU on rising edges, falling edges with input "H" level, or "L" level. Can be used for external event interrupts and to activate El ² OS.							
Wakeup interrupts	Input channels Triggered by "							
8/10-bit A/D converter (successive approximation type)	Number of channels: 8 Resolution: 8-bit or 10-bit selectable Conversion can be performed sequentially for multiple consecutive channels. • Single-shot conversion mode: Converts specified channel once only. • Continuous conversion mode: Repeatedly converts specified channel. • Intermittent conversion mode: Converts specified channel then halts temporarily.							
8-bit D/A converter (R-2R type)	Number of cha Resolution : 8-							
UART (SCI)	Number of channels : 1 Clock synchronous transfer : 62.5 Kbps to 1 Mbps Clock asynchronous transfer : 1202 bps to 31250 bps Supports bi-directional and master-slave communications.							
Extended I/O serial interface	Number of channels : 2 Clock synchronous transfer : 31.25 Kbps to 1 Mbps (Using internal shift clock) Transmission format : Selectable LSB-first or MSB-first							
LCD controller/driver	Number of seg Number of pov LCD display m	Transmission format : Selectable LSB-first or MSB-first Number of common outputs : 4 Number of segment outputs : 32 Number of power supply pins for LCD drive : 4 LCD display memory : 16 bytes Divider resistor for LCD drive : Internal						

^{*1 :} As for the necessity of a DIP switch setting (S2) when using the emulation pod (MB2145-507) . Refer to the hardware manual for the emulation pod (MB2145-507) fomr details.

^{*2 :} Take note of the maximum operating frequency and A/D converter precision restrictions when operating at 3.0 V to 3.6 V. See the "Electrical Characteristics" section for details.

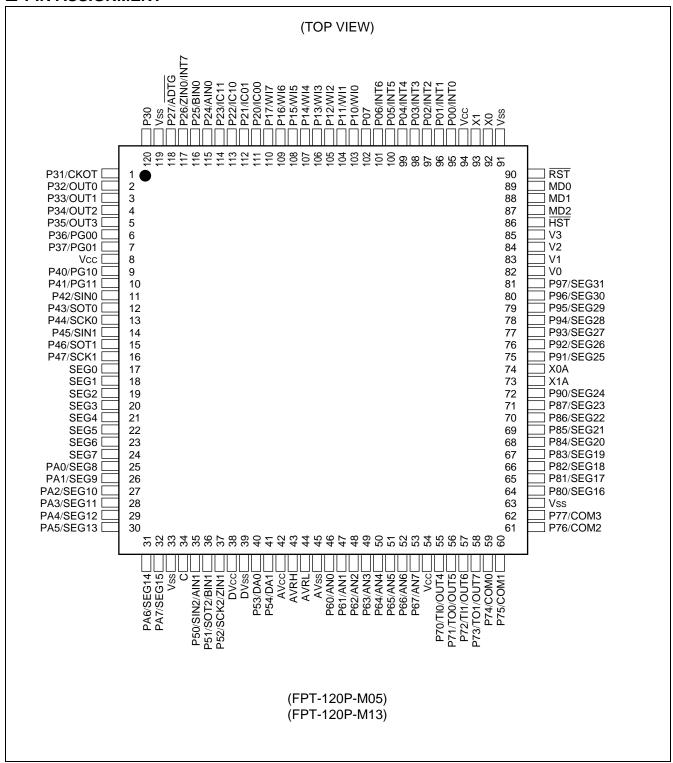
■ PACKAGES AND CORRESPONDING PRODUCTS

Package	MB90522A	MB90523A	MB90522B	MB90523B	MB90F523B	MB90V520A
FPT-120P-M05 (LQFP)	0	0	0	0	0	×
FPT-120P-M13 (QFP)	0	0	0	0	0	×
PGA-256C-A01 (PGA)	×	×	×	×	×	0

 \bigcirc : Available, \times : Not available

Note: See the "■ PACKAGE DIMENSIONS" section for more details.

■ PIN ASSIGNMENT



■ PIN DESCRIPTIONS

Pin No.		0: :/			
LQFP-120*1 QFP-120*2	Pin Name	Circuit Type	Function		
92, 93	X0, X1	Α	Oscillator pin		
74, 73	X0A, X1A	В	Sub-oscillator pin		
89 to 87	MD0 to MD2	С	Input pins for setting the operation mode. Connect directly to Vcc or Vss.		
90	RST	С	External reset input pin		
86	HST	С	Hardware standby input pin		
95 to 101	P00 to P06	D	General-purpose I/O ports The settings in the pull-up resistor setup register (RDR0) are enabled when ports are set as inputs. The RDR0 settings are ignored when ports are set as outputs.		
	INT0 to INT6		Event input pins for ch.0 to ch.6 of the DTP/external interrupt circuit		
102	P07	D	General-purpose I/O port The settings in the pull-up resistor setup register (RDR0) are enabled whe ports are set as inputs. The RDR0 settings are ignored when ports are set as outputs.		
103 to 110	P10 to P17	D	General-purpose I/O ports The settings in the pull-up resistor setup register (RDR1) are enabled when ports are set as inputs. The RDR1 settings are ignored when ports are set as outputs.		
	WI0 to WI7		Event input pins for the wakeup interrupts.		
	P20, P21, P22, P23		General-purpose I/O ports		
111, 112, 113, 114	IC00, IC01, IC10, IC11	E	Trigger input pins for input capture units (ICU) 0 and 1. Input operates continuously when channels 0 and 1 of input capture units (ICU) 0 and 1 are operating. Accordingly, output to the pins from other functions that share this pin must be suspended unless performed intentionally.		
	P24		General-purpose I/O port		
115	AIN0	E	Also can be used as the count clock A input to 8/16-bit up/down counter/timer 0.		
	P25		General-purpose I/O port		
116	BIN0	E	Also can be used as the count clock B input to 8/16-bit up/down counter/timer 0.		
	P26		General-purpose I/O port		
117	ZIN0	Е	Also can be used as the control clock Z input to 8/16-bit up/down counter/timer 0.		
	INT7		Event input pin for ch.7 of the DTP/external interrupt circuit		

*1 : FPT-120P-M05 *2 : FPT-120P-M13

Pin No.		Oima wit	
LQFP-120*1 QFP-120*2	Pin Name	Circuit Type	Function
	118 <u>P27</u> ADTG E		General-purpose I/O port
118			External trigger input to the 8/10-bit A/D converter Input operates continuously when the 8/10-bit A/D converter is performing input. Accordingly, output to the pin from other functions that share this pin must be suspended unless performed intentionally.
120	P30	Е	General-purpose I/O port
	P31		General-purpose I/O port
1	СКОТ	E	Output pin for clock monitor function The clock monitor is output when clock monitor output is enabled.
2	P32	_	General-purpose I/O port Only available when waveform output from output compare 0 is disabled.
2 OUT0		E	Event output pin for ch.0 of output compare unit 0 (OCU) Only available when event output is enabled for output compare unit 0.
3	P33	Е	General-purpose I/O port Only available when waveform output from output compare 1 is disabled.
3	OUT1		Event output pin for ch.1 of output compare unit 0 (OCU) Only available when event output is enabled for output compare unit 0.
4	P34	Е	General-purpose I/O port Only available when waveform output from output compare 2 is disabled.
4	OUT2	- E	Event output pin for ch.2 of output compare unit 0 (OCU) Only available when event output is enabled for output compare unit 0.
5	P35	E	General-purpose I/O port Only available when waveform output from output compare 3 is disabled.
	OUT3	_	Event output pin for ch.3 of output compare unit 0 (OCU) Only available when event output is enabled for output compare unit 0.
6	P36	Е	General-purpose I/O port Only available when waveform output from PG00 is disabled.
	PG00		Output pin for 8/16-bit PPG timer 0 Only available when waveform output is enabled for PG00.
7	P37	E	General-purpose I/O port Only available when waveform output from PG01 is disabled.
/	PG01		Output pin for 8/16-bit PPG timer 0 Only available when waveform output is enabled for PG01.

*1 : FPT-120P-M05 *2 : FPT-120P-M13

Pin No.		0: :	
LQFP-120*1 QFP-120*2	Pin Name	Circuit Type	Function
9, 10	P40, P41	D	General-purpose I/O ports Only available when waveform outputs from PG10 and PG11 are disabled. The settings in the pull-up resistor setup register (RDR4) are enabled when ports are set as inputs. The RDR4 settings are ignored when ports are set as outputs.
	PG10, PG11		Output pins for 8/16-bit PPG timer 1 Only available when waveform output is enabled for PG10 and PG11.
11	P42	D	General-purpose I/O port The settings in the pull-up resistor setup register (RDR4) are enabled when ports are set as inputs. The RDR4 settings are ignored when ports are set as outputs.
''	SIN0		UART (SCI) serial data input pin Input operates continuously when the UART is performing input. Accordingly, output to the pin from other functions that share this pin must be suspended unless performed intentionally.
12	P43		General-purpose I/O port The settings in the pull-up resistor setup register (RDR4) are enabled when ports are set as inputs. The RDR4 settings are ignored when ports are set as outputs.
	SOT0		UART (SCI) serial data output pin Only available when serial data output is enabled for the UART (SCI).
13	P44		General-purpose I/O port The settings in the pull-up resistor setup register (RDR4) are enabled when ports are set as inputs. The RDR4 settings are ignored when ports are set as outputs.
	SCK0		UART (SCI) serial clock input/output pin Only available when serial clock output is enabled for the UART (SCI).
14	P45	D	General-purpose I/O port The settings in the pull-up resistor setup register (RDR4) are enabled when ports set as inputs. The RDR4 settings are ignored when ports set are as outputs.
14	SIN1	U	Data input pin for extended I/O serial interface 1 Input operates continuously when the performing serial input. Accordingly, output to the pin from other functions that share this pin must be suspended unless performed intentionally.
15	P46	D	General-purpose I/O port The settings in the pull-up resistor setup register (RDR4) are enabled when ports set as inputs. The RDR4 settings are ignored when ports are set as outputs.
	SOT1		Data output pin for extended I/O serial interface 1 Only available when serial data output is enabled for SOT1.

*1 : FPT-120P-M05

*2: FPT-120P-M13

Pin No.			
LQFP-120*1 QFP-120*2	Pin Name	Circuit Type	Function
16	P47	D	General-purpose I/O port The settings in the pull-up resistor setup register (RDR4) are enabled when ports are set as inputs. The RDR4 settings are ignored when ports are set as outputs.
	SCK1		Serial clock input/output pin for extended I/O serial interface 1 Only available when serial clock output is enabled for SCK1.
	P50		General-purpose I/O port
35	SIN2	E	Data input pin for extended I/O serial interface 2 Input operates continuously when the performing serial input. Accordingly, output to the pin from other functions that share this pin must be suspended unless performed intentionally.
	AIN1		Also can be used as the count clock A input to 8/16-bit up/down counter/timer 1.
	P51		General-purpose I/O port
36	SOT2	E	Data output pin for extended I/O serial interface 2 Only available when serial data output is enabled for SOT2.
	BIN1		Also can be used as the count clock B input to 8/16-bit up/down counter/timer 1.
	P52		General-purpose I/O port
37	SCK2	Е	Serial clock input/output pin for extended I/O serial interface 2 Only available when serial clock output is enabled for SCK2.
	ZIN1		Also can be used as the control clock Z input to 8/16-bit up/down counter/timer 1.
40, 41	P53, P54	_	General-purpose I/O ports
40, 41	DA0, DA1	ı	Analog output pins for ch.0 and ch.1 of the 8-bit D/A converter
46 to 53	P60 to P67	К	General-purpose I/O ports Port input is enabled when the analog input enable register (ADER) is set to the ports.
40 10 33	AN0 to AN7	K	Analog inputs for the 8/10-bit A/D converter Analog input is enabled when the analog input enable register (ADER) is set.
	P70, P72		General-purpose I/O ports
55, 57	TI0, TI1	E	Event input pins for 16-bit reload timers 0 and 1 Input operates continuously when 16-bit reload timers 0 and 1 input an external clock. Accordingly, output to these pins from other functions that share the pins must be suspended unless performed intentionally.
	OUT4, OUT6		Event output pins for ch. 4 and ch. 6 of output compare unit 1 (OCU) Only available when event output from output compare 1 is enabled.

*1 : FPT-120P-M05 *2 : FPT-120P-M13

Pin No.		Circuit	
LQFP-120*1 QFP-120*2	Pin Name	Type	Function
	P71, P73		General-purpose I/O ports Only available when event outputs from 16-bit reload timers 0 and 1 are disabled.
56, 58	TO0, TO1	Е	Output pins for 16-bit reload timers 0 and 1. Only available when output is enabled for 16-bit reload timers 0 and 1.
	OUT5, OUT7		Event output pins for ch. 5 and ch. 7 of output compare unit 1 (OCU) Only available when event output from output compare 1 is enabled.
F0 to 62	P74 to P77 59 to 62 COM0 to COM3		General-purpose I/O ports Only available when the LCD controller/driver control register is set to the ports.
39 10 62			Common pins for the LCD controller/driver Only available when the LCD controller/driver control register is set to the common outputs.
64 to 71	P80 to P87	L	General-purpose I/O ports Only available when the LCD controller/driver control register is set to the ports.
64 10 7 1	SEG16 to SEG23		LCD segment output pins for the LCD controller/driver Only available when the LCD controller/driver control register is set to the segment outputs.
72,	P90, P91 to P97	M	General-purpose I/O ports (Support up to $lol = 10$ mA) Only available when the LCD controller/driver control register is set to the ports.
75 to 81	SEG24, SEG25 to SEG31	M	LCD segment output pins for the LCD controller/driver Only available when the LCD controller/driver control register is set to the segment outputs.
17 to 24	SEG0 to SEG7	F	LCD segment 00 to 07 pins for the LCD controller/driver
25 to 32	PA0 to PA7	L	General-purpose I/O ports Only available when the LCD controller/driver control register is set up to the ports.
20 10 02	SEG8 to SEG15		LCD segment 08 to 15 pins for the LCD controller/driver Only available when the LCD controller/driver control register is set to the segment outputs.

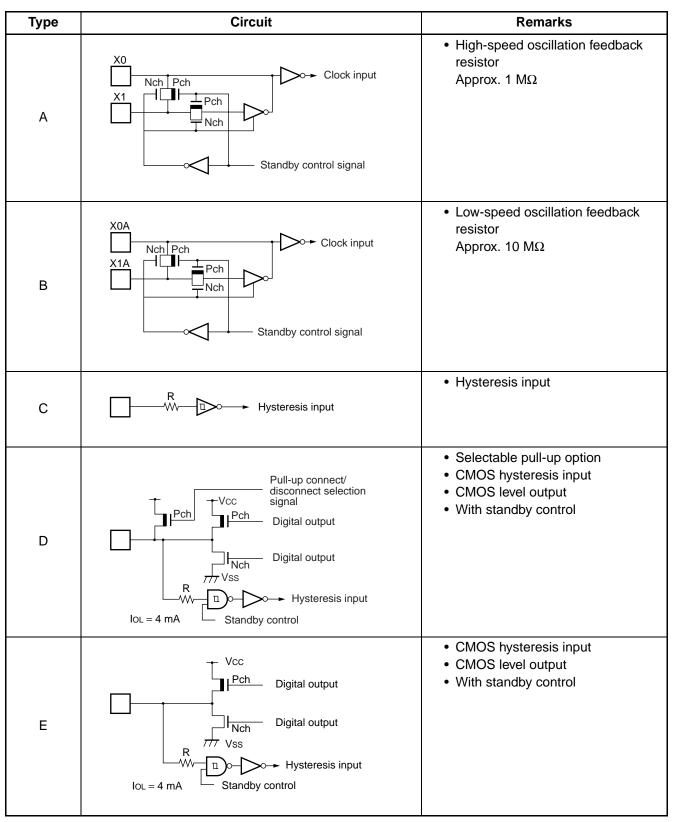
*1 : FPT-120P-M05 *2 : FPT-120P-M13

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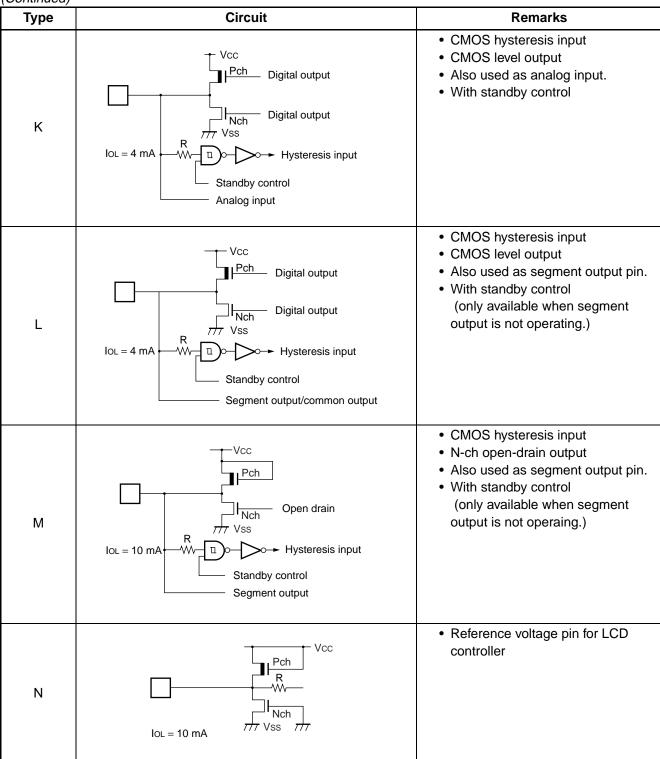
Pin No. LQFP-120 ^{*1} QFP-120 ^{*2}	Pin Name	Circuit Type	Function	
34	С	G	Capacitor connection pin for stabilizing power supply Connect an external ceramic capacitor of approximately 0.1 μ F. If operating at 3.3 V or lower, connect to Vcc.	
82 to 85	V0 to V3	N	Power supply input pins for the LCD controller/driver	
8, 54, 94	Vcc	Power supply	Power supply input pins for the digital circuit	
33, 63, 91, 119	Vss	Power supply	GND level power supply input pins for the digital circuit	
42	AVcc	Н	Power supply input for the analog circuit Ensure that a voltage greater than AVcc is applied to Vcc before turning the analog power supply on or off.	
43	AVRH	J	"H" reference voltage for the A/D converter Ensure that a voltage greater than AVRH is applied to AVcc before turning the power supply to this pin on or off.	
44	AVRL	Н	"L" reference voltage for the A/D converter	
45	AVss	Н	GND level power supply input pin for the analog circuit	
38	DVcc	Н	"H" reference voltage for the D/A converter Ensure that this voltage does not exceed Vcc.	
39	DVss	Н	"L" reference voltage for the D/A converter Apply the same voltage level as Vss.	

*1 : FPT-120P-M05 *2 : FPT-120P-M13

■ I/O CIRCUIT TYPE



Туре	Circuit	Remarks
F	Vcc R W Nch Vss	Segment output pins
G	Vcc Pch Nch Vss	Capacitor connection pin (This is an N.C. pin on the MB90522A and MB90523A.)
Н	Vcc Pch AVP Nch Vss	Analog power supply input protection circuit
I	Vcc Pch Digital output Nch Digital output Nch Standby control Analog output	 CMOS hysteresis input CMOS level output (CMOS output is not available when analog output is operating.) Also used as analog output (Analog output has priority) With standby control
J	Vcc Pch ANE AVP Nch ANE Vss	A/D converter ref+ power supply input pin (Incorporates power supply protection circuit.) (Continued)



■ HANDLING DEVICES

Take note of the following points when handling devices :

- Do not exceed maximum rated voltage (to prevent latch-up)
- Supply voltage stability
- Power-on precautions
- · Power supply pins
- · Crystal oscillator circuit
- · Notes on using an external clock
- · Precautions when not using sub-clock mode
- Treatment of unused pins
- Treatment of N.C. pins
- Treatment of pins when A/D converter is not used
- Sequence for connecting and disconnecting the A/D converter power supply and analog input pins
- Shared use of general-purpose I/O ports and LCD controller/driver SEG/COM pins
- Conditions when output from ports 0 and 1 is undefined
- Initialization
- · Notes on using the DIV A, Ri and DIVW A, RWi instructions
- · Notes on using REALOS

Device Handling Precautions

Do not exceed maximum rated voltage (to prevent latch-up)

Latch-up occurs in CMOS ICs if a voltage greater than $V_{\rm CC}$ or less than $V_{\rm SS}$ is applied to an input or output pin (other than a high or medium withstand voltage pin) or if the voltage applied between $V_{\rm CC}$ and $V_{\rm SS}$ exceeds the rating. If latch-up occurs, the power supply current increases rapidly resulting in thermal damage to circuit elements. Therefore, ensure that maximum ratings are not exceeded in circuit operation.

Similarly, when turning the analog power supply on or off, ensure the analog power supply voltages (AVcc, AVRH, DVcc) and analog input voltages do not exceed the digital voltage (Vcc).

Also ensure that the voltages applied to the LCD power supply pins (V3 to V0) do not exceed the power supply voltage (Vcc).

Supply voltage stability

Rapid changes in supply voltage may cause the device to misoperate, even if the voltage remains within the allowed operating range. Accordingly, ensure that the Vcc supply is stable.

The standard for power supply voltage stability is a peak-to-peak Vcc ripple voltage at the mains supply frequency (50 to 60 Hz) of 10% or less of Vcc and a transient voltage change rate of 0.1 V/ms or less when turning the power supply on or off.

Power-on precautions

To prevent misoperation of the internal regulator circuit at power-on, ensure that the power supply rising time (0.2 V to 2.7 V) is at least 50 μ s.

· Power supply pins

When multiple $V_{\rm CC}$ and $V_{\rm SS}$ pins are provided, connect all $V_{\rm CC}$ and $V_{\rm SS}$ pins to power supply or ground externally. Although pins at the same potential are connected together in the internal device design so as to prevent misoperation such as latch-up, connecting all $V_{\rm CC}$ and $V_{\rm SS}$ pins appropriately minimizes unwanted radiation, prevents misoperation of strobe signals due to increases in the ground level, and keeps the overall output current rating.

Also, ensure that the impedance of the Vcc and Vss connections to the power supply are as low as possible.

Connection of a bypass capacitor of approximately 0.1 μ F between V_{CC} and V_{SS} is recommended to prevent power supply noise. Connect the capacitor close to the V_{CC} and V_{SS} pins.

· Crystal oscillator circuit

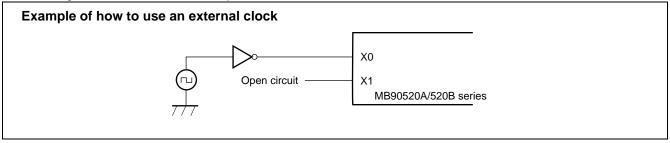
Noise on the X0 and X1 pins can be a cause of device misoperation. Place the X0 and X1 pins, crystal oscillator (or ceramic oscillator), and bypass capacitor to ground as close together as possible. Also, design the circuit board so that the X0 and X1 pin wiring does not cross other wiring.

Surrounding the X0/X1 and X0A/X1A pins with ground in the printed circuit board design is recommended to ensure stable operation.

Notes on using an external clock

When using an external clock, drive the X0 pin only and leave the X1 pin open.

The figure below shows an example of how to use an external clock.



· Precautions when not using sub-clock mode

Connect an oscillator to X0A and X1A, even if not using sub-clock mode.

Treatment of unused pins

Leaving unused input pins unconnected can cause misoperation or permanent damage to the device due to latchup. Always pull-up or pull-down unused pins using a 2 $k\Omega$ or larger resistor.

If some I/O pins are unused, either set as outputs and leave open circuit or set as inputs and treat in the same way as input pins.

Treatment of N.C. pins

Always leave N.C. (non connect) pins open circuit.

• Treatment of pins when A/D converter not used

When not using the A/D converter and D/A converter, always connect AVcc = DVcc = AVRH = Vcc and AVss = AVRL = Vss.

Sequence for connecting and disconnecting the A/D converter power supply and analog input pins

Do not apply voltage to the A/D and D/A converter power supply (AVcc, AVRH, AVRL, DVcc, DVss) or analog inputs (AN0 to AN7) until the digital power supply (Vcc) is turned on.

When turning the device off, turn off the digital power supply after disconnecting the A/D converter power supply and analog inputs. When turning the power on or off, ensure that AVRH and DVcc do not exceed AVcc (turning the analog and digital power supplies on and off simultaneously is OK).

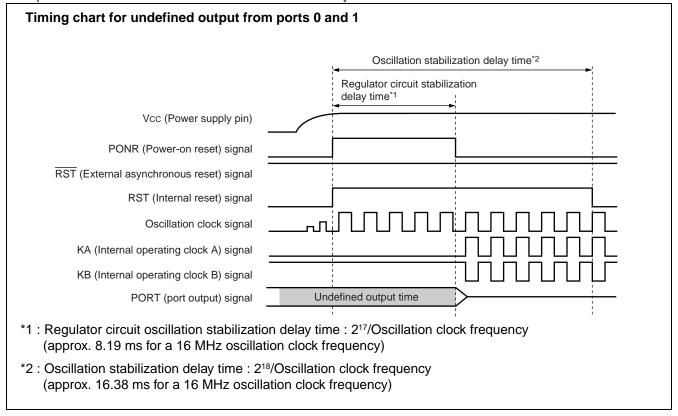
Shared use of general-purpose I/O ports and LCD controller/driver SEG/COM pins

The SEG08 to SEG31 and COM0 to COM3 pins are shared with general-purpose I/O ports. The electrical ratings for SEG08 to SEG23 and COM0 to COM3 are the same as for CMOS outputs and the electrical ratings for SEG24 to SEG31 are the same as for N-ch open-drain ports.

Conditions when output from ports 0 and 1 is undefined

After turning on the power supply, the outputs from ports 0 and 1 are undefined during the oscillation stabilization delay time controlled by the regulator circuit (during the power-on reset) . The figure below shows the timing.

Note that this undefined output period does not occur on products without an internal regulator circuit as these products do not have an oscillation stabilization delay time.



Note: See the "■ PRODUCT LINEUP" section for details of which MB90520A/520B series products have an internal regulator circuit.

Initialization

The device contains internal registers that are only initialized by a power-on reset. To initialize these registers, restart the power supply.

. Notes on using the DIV A, Ri and DIVW A, RWi instructions

Set the corresponding bank registers (DTB, ADB, USB, SSB) to "00H" when using the signed division instructions "DIV A, Ri" and "DIVW A, RWi".

If the corresponding bank registers (DTB, ADB, USB, SSB) are set to other than "00H", the remainder value produced by the instruction is not stored in the instruction operand register.

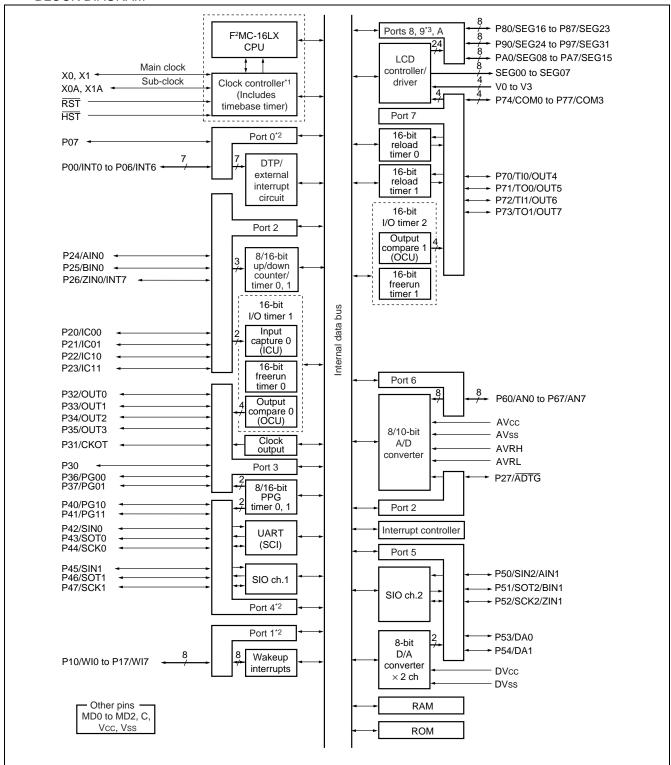
Notes on using REALOS

The extended intelligent I/O service (El²OS) cannot be used when using REALOS.

Caution on Operations during PLL Clock Mode

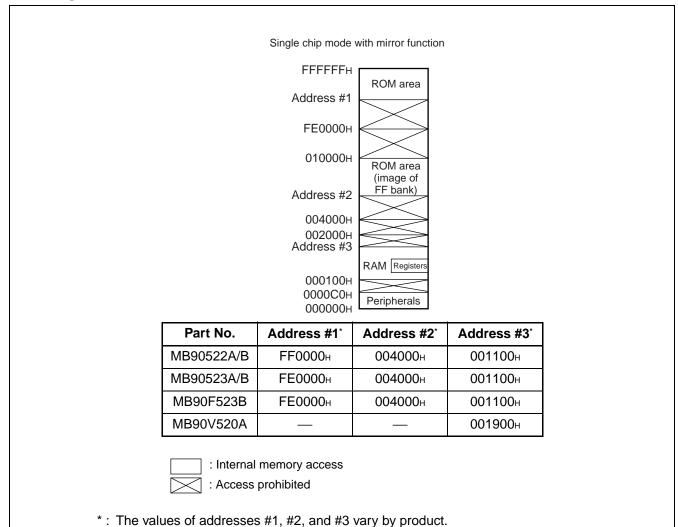
If the PLL clock mode is selected, the microcontroller attempt to be working with the self-oscillating circuit even when there is no external oscillator or external clock input is stopped. Performance of this operation, however, cannot be guaranteed.

BLOCK DIAGRAM



- *1 : The clock control circuit includes the watchdog timer and timebase timer low power consumption control circuits.
- *2 : Incorporates a pull-up register setting register. CMOS level input and output.
- *3 : As this port shares pins with the LCD output, the port uses N-ch open-drain circuits.

■ MEMORY MAP



Note: The upper part of 00 bank contains a mirror of the ROM data in FF bank. This is called the mirror ROM function and enables use of the C compiler's small memory model. As the lower 16 bits of the FF bank and 00 bank addresses are the same, tables located in ROM can be referenced without needing to declare far pointers

For example, accessing $00C000_{\rm H}$ actually accesses the contents of ROM at FFC000_H. Note that, as the FF bank ROM area exceeds 48 KBytes, the entire ROM image cannot be mirrored in 00 bank. Accordingly, as ROM data from FF4000_H to FFFFFF_H is mirrored in $004000_{\rm H}$ to $00FFFF_{\rm H}$, always locate ROM data tables in the range FF4000_H to FFFFFF_H.

■ I/O MAP

Address	Abbreviated Register Name	Register Name	Peripheral Name	Initial Value
000000н	PDR0	Port 0 data register	Port 0	XXXXXXXXB
000001н	PDR1	Port 1 data register	Port 1	XXXXXXXXB
000002н	PDR2	Port 2 data register	Port 2	XXXXXXXXB
000003н	PDR3	Port 3 data register	Port 3	XXXXXXXXB
000004н	PDR4	Port 4 data register	Port 4	XXXXXXXXB
000005н	PDR5	Port 5 data register	Port 5	XXXXXXXXB
000006н	PDR6	Port 6 data register	Port 6	XXXXXXXXB
000007н	PDR7	Port 7 data register	Port 7	XXXXXXXXB
000008н	PDR8	Port 8 data register	Port 8	XXXXXXXXB
000009н	PDR9	Port 9 data register	Port 9	XXXXXXXXB
00000Ан	PDRA	Port A data register	Port A	XXXXXXXXB
00000Вн	LCDCMR	Port 7/COM pin selection register	Port 7, LCD controller/driver	XXXX 0 0 0 0 _B
00000Сн	0004	0011	40 hit 1/0 time or	XXXXXXXXB
00000Дн	OCP4	OCU compare register ch.4	16-bit I/O timer	XXXXXXXXB
00000Ен		(Access proh	ibited)	
00000Fн	EIFR	Wakeup interrupt flag register	Wakeup interrupts	XXXXXXX0 _B
000010н	DDR0	Port 0 direction register	Port 0	0000000В
000011н	DDR1	Port 1 direction register	Port 1	0000000B
000012н	DDR2	Port 2 direction register	Port 2	0000000B
000013н	DDR3	Port 3 direction register	Port 3	0000000B
000014н	DDR4	Port 4 direction register	Port 4	00000000
000015н	DDR5	Port 5 direction register	Port 5	XXX 0 0 0 0 0 _B
000016н	DDR6	Port 6 direction register	Port 6	0000000B
000017н	DDR7	Port 7 direction register	Port 7	0000000B
000018н	DDR8	Port 8 direction register	Port 8	00000000
000019н	DDR9	Port 9 direction register	Port 9	00000000
00001Ан	DDRA	Port A direction register	Port A	00000000
00001Вн	ADER	Analog input enable register	Port 6, A/D converter	11111111В
00001Сн	OCP5	OCU compare register ch.5	16-bit I/O timer	XXXXXXXXB
00001Дн	UCFO	OCO compare register cn.5	10-bit i/O timei	XXXXXXXXB
00001Ен		(Access proh	ibited)	
00001Fн	EICR	Wakeup interrupt enable register	Wakeup interrupts	0000000B

Address	Abbreviated Register Name	Register Name	Peripheral Name	Initial Value			
000020н	SMR	Serial mode register		0000000			
000021н	SCR	Serial control register	UART	00000100в			
000022н	SIDR/ SODR	Serial input data register/ Serial output data register	(SCI)	XXXXXXXX			
000023н	SSR	Serial status register		00001X00 _B			
000024н	SMCS1	Carial made control statue register 1		XXXX 0 0 0 0 _B			
000025н	SIVICST	Serial mode control status register 1	Extended I/O serial interface 1	0000010в			
000026н	SDR1	Serial data register 1		XXXXXXXXB			
000027н	CDCR	Communication prescaler control register	Communication prescaler register	0 XXX 1 1 1 1в			
000028н	CMCCO	Coviet mende control atatus no sistem 2		XXXX 0 0 0 0 _B			
000029н	SMCS2	Serial mode control status register 2	Extended I/O serial interface 2	0000010в			
00002Ан	SDR2	Serial data register 2	mitoriago 2	XXXXXXXXB			
00002Вн		(Access prohibited)					
00002Сн	OCS45	OCU control status register ch.45		0000XX00B			
00002Dн		-5 OCO CONTION STATUS TEGISTER CH45	16-bit I/O timer	XXX 0 0 0 0 0 _B			
00002Ен	00007	OCLL control status register sh 67		0000XX00B			
00002Fн	OCS67	OCU control status register ch.67		XXX 0 0 0 0 0 _B			
000030н	ENIR	DTP/interrupt enable register		00000000			
000031н	EIRR	DTP/interrupt request register	DTP /external interrupt	XXXXXXXX			
000032н	ELVR	Request level setting register	circuit	00000000			
000033н	ELVIN	Request level setting register		00000000			
000034н	OCP6	OCU compare register ch.6	16-bit I/O timer	XXXXXXXX			
000035н	OCFO	OCO compare register cri.o	10-bit i/O timei	XXXXXXXX			
000036н	ADCS	A/D control status register		0000000			
000037н	ADCS	AD Control status register	8/10-bit A/D converter	0000000			
000038н	ADCR	A/D data register	O/ 10-bit A/D converter	XXXXXXXX			
000039н	ADCK	AD data register		00001XXXв			
00003Ан	DADR0	D/A converter data register ch.0		XXXXXXXX			
00003Вн	DADR1	D/A converter data register ch.1	8-bit D/A converter	XXXXXXXX			
00003Сн	DACR0	D/A control register 0	O-DIL DIA CONVENIER	XXXXXXX 0 _B			
00003Dн	DACR1	D/A control register 1		XXXXXXX 0 _B			
00003Ен	CLKR	Clock output enable register	Clock monitor function	XXXX 0 0 0 0 _B			

Address	Abbreviated Register Name	Register Name	Peripheral Name	Initial Value		
00003Fн	03Fн (Access prohibited)					
000040н	PRLL0	PRLL0 PPG0 reload register L		XXXXXXXX		
000041н	PRLH0	PPG0 reload register H	- 	XXXXXXXX		
000042н	PRLL1	PPG1 reload register L	1	XXXXXXXXB		
000043н	PRLH1	PPG1 reload register H	8/16-bit PPG timer 0, 1	XXXXXXXX		
000044н	PPGC0	PPG0 operation mode control register	1	0X000XX1 _B		
000045н	PPGC1	PPG1 operation mode control register		0Х00001в		
000046н	PPGOE	PPG0, 1 output control register		0000000		
000047н		(Access prohib	ited)	1		
000048н	TMCCDO	Time a section of the		0000000B		
000049н	TMCSR0	Timer control status register ch.0	4.C bit valued times 0	XXXX 0 0 0 0 _B		
00004Ан	TMR0/	16-bit timer register ch.0/	16-bit reload timer 0	XXXXXXXX		
00004Вн	TMRLR0	16-bit reload register ch.0		XXXXXXXX		
00004Сн	TMCCD4	Times control atotics societas ab 4	16-bit reload timer 1	0000000		
00004Dн	TMCSR1	Timer control status register ch.1		XXXX 0 0 0 0 _B		
00004Ен	TMR1/	16-bit timer register ch.1/		XXXXXXXX		
00004Fн	TMRLR1	16-bit reload register ch.1		XXXXXXXX		
000050н	IDODO	ICII data ragistar ab 0		XXXXXXXXB		
000051н	IPCP0	ICU data register ch.0		XXXXXXXXB		
000052н	IPCP1	ICI I data register sh 1	16-bit I/O timer	XXXXXXXX		
000053н	IPCPT	ICU data register ch.1		XXXXXXXX		
000054н	ICS01	ICU control status register	1	0000000B		
000055н		(Access prohib	ited)	•		
000056н	TODTO	Francis data register 0		0000000		
000057н	TCDT0	Freerun timer data register 0	16-bit I/O timer	0000000		
000058н	TCCS0	Freerun timer control status register 0	1	0000000		
000059н		(Access prohib	ited)			
00005Ан	OCDO	OCI compare register ship		XXXXXXXXB		
00005Вн	OCP0	OCU compare register ch.0		XXXXXXXX		
00005Сн	0004	OCI compare register shift	16 hit 1/0 times	XXXXXXXX		
00005Дн	OCP1	OCU compare register ch.1	16-bit I/O timer	XXXXXXXXB		
00005Ен	OCDO	OCIL compare register et 2	1	XXXXXXXX		
00005Fн	OCP2	OCU compare register ch.2		XXXXXXXX		

Address	Abbreviated Register Name	Register Name	Peripheral Name	Initial Value		
000060н	0000	0011		XXXXXXXX		
000061н	OCP3	OCU compare register ch.3		XXXXXXXX		
000062н	00004		40 1 1/10 (1)	0 0 0 0 XX 0 0 _B		
000063н	OCS01	OCU control status register ch.0, ch.1	16-bit I/O timer	XXX 0 0 0 0 0 _B		
000064н	00000			0 0 0 0 XX 0 0 _B		
000065н	OCS23	OCU control status register ch.2, ch.3		XXX 0 0 0 0 0 _B		
000066н	TODT4	Francisco de la constante de l		0000000B		
000067н	TCDT1	Freerun timer data register 1	16-bit I/O timer	0000000		
000068н	TCCS1	Freerun timer control status register 1		0000000B		
000069н		(Access prohibi	ited)			
00006Ан	LCR0	LCDC control register 0	LCD controller/driver	00010000B		
00006Вн	LCR1	LCDC control register 1	LCD controller/driver	0000000B		
00006Сн	0007	0011	40 hit 1/0 time on	XXXXXXXX		
00006Dн	OCP7	OCU compare register ch.7	16-bit I/O timer	XXXXXXXXB		
00006Ен	(Access prohibited)					
00006Fн	ROMM	ROM mirror function selection register	ROM mirror function selection module	XXXXXXX1 _B		
000070н to 00007Fн	VRAM	Data memory for LCD display	LCD controller/driver	XXXXXXXXB		
000080н	UDCR0	Up/down count register 0		00000000		
000081н	UDCR1	Up/down count register 1		0000000		
000082н	RCR0	Reload compare register 0	8/16-bit up/down counter/timer 0, 1	0000000		
000083н	RCR1	Reload compare register 1	Counter/timer o, i	0000000		
000084н	CSR0	Counter status register 0		0000000		
000085н		(Reserved)	*3			
000086н	0000			Х000000		
000087н	CCR0	Counter control register 0	8/16-bit up/down counter/timer 0, 1	0000000		
000088н	CSR1	Counter status register 1	Counter/unier 0, 1	0000000		
000089н	(Reserved) *3					
00008Ан	0054		8/16-bit up/down	Х000000		
00008Вн	CCR1	Counter control register 1	counter/timer 0, 1	Х000000		
00008Сн	RDR0	Port 0 input pull-up resistor setup register	Port 0	00000000		
00008Дн	RDR1	Port 1 input pull-up resistor setup register	Port 1	00000000		

Address	Abbreviated Register Name	Register Name	Peripheral Name	Initial Value	
00008Ен	RDR4	Port 4 input pull-up resistor setup register	Port 4	0000000 _B	
00008Fн to 00009Dн		(Access prohib (Area reserved for sys			
00009Ен	PACSR	Address detection control register	Address match detection function	00000000	
00009Fн	DIRR	Delayed interrupt request output/clear register	Delayed interrupt generation module	XXXXXXX 0 _B	
0000А0н	LPMCR	Low power consumption mode control register	Low power consumption	00011000в	
0000А1н	CKSCR	Clock selection register	- (standby) mode	11111100в	
0000A2н to 0000A7н		(Access prohib	ited)		
0000А8н	WDTC	Watchdog timer control register	Watchdog timer	XXXXXXXX	
0000А9н	TBTC	Timebase timer control register	Timebase timer	1 XX 0 0 0 0 0 _B	
0000ААн	WTC	Clock timer control register	Clock timer	1 Х О О 1 О О Ов	
0000ABн to 0000ADн		(Access prohib	ited)		
0000АЕн	FMCS	Flash memory control status register	1 Mbit flash memory	000X0000B	
0000АГн		(Access prohibited)			
0000В0н	ICR00	Interrupt control register 00		00000111в	
0000В1н	ICR01	Interrupt control register 01		00000111в	
0000В2н	ICR02	Interrupt control register 02		00000111в	
0000ВЗн	ICR03	Interrupt control register 03		00000111в	
0000В4н	ICR04	Interrupt control register 04		00000111в	
0000В5н	ICR05	Interrupt control register 05		00000111в	
0000В6н	ICR06	Interrupt control register 06	Interrupt controller	00000111в	
0000В7н	ICR07	Interrupt controller		00000111в	
0000В8н	ICR08	Interrupt control register 08	8		
0000В9н	ICR09	Interrupt control register 09		00000111в	
0000ВАн	ICR10	Interrupt control register 10		00000111в	
0000ВВн	ICR11	Interrupt control register 11		00000111в	
0000ВСн	ICR12	Interrupt control register 12		00000111в	
0000ВДн	ICR13	Interrupt control register 13	1	00000111в	

(Continued)

Address	Abbreviated Register Name	Register Name	Peripheral Name	Initial Value		
0000ВЕн	ICR14	Interrupt control register 14	Interrupt controller	00000111в		
0000ВFн	ICR15	Interrupt control register 15	interrupt controller	00000111в		
0000C0н to 0000FFн	(Access prohibited) *1					
000100н to 00####н		(RAM area)	*2			
00####н to 001FEFн	(Reserved area) [∗] ³					
001FF0н		Detection address setting register 0 (low byte)		XXXXXXXXB		
001FF1н	PADR0	Detection address setting register 0 (middle byte)		XXXXXXXXB		
001FF2н		Detection address setting register 0 (high byte)	Address match	XXXXXXXXB		
001FF3н		Detection address setting register 1 (low byte)	detection function	XXXXXXXXB		
001FF4н	PADR1	Detection address setting register 1 (middle byte)		XXXXXXXXB		
001FF5н		Detection address setting register 1 (high byte)		XXXXXXXXB		
001FF6н to 001FFFн		(Reserved area	a) *3			

Initial value notation

0 : Initial value of bit is "0".1 : Initial value of bit is "1".

X : Initial value of bit is undefined.

- *1 : Access is prohibited to the address range 0000C0_H to 0000FF_H. See the "■ MEMORY MAP" section.
- *2 : See the "■ MEMORY MAP" section for details of the " (RAM area) ".
- *3: "(Reserved areas)" are addresses used internally by the system and may not be used.
- *4 : The " (Area reserved for system use) " contains setting registers used by the evaluation tools.
- Notes: LPMCR, CKSCR, and WDTC are initialized by some types of reset and not by others. The initial values listed are for the case when the registers are initialized.
 - The boundary address "####" between the " (RAM area) " and " (Reserved area) " differs depending on the product. See the "■ MEMORY MAP" section for details.
 - OCU compare registers ch.0 to ch.3 use 16-bit freerun timer 0 and OCU compare registers ch.4 to ch.7 use 16-bit freerun timer 1. Note that 16-bit freerun timer 0 is also used by input capture 0 and 1 (ICU).

■ INTERRUPTS, INTERRUPT VECTORS, AND INTERRUPT CONTROL REGISTERS

Interrunt	El ² OS	Interrupt Vector		Interrupt Control Register		Priority
Interrupt	Support	No.	Address	ICR	Address	Priority
Reset	×	#08	FFFFDCH	_	_	High
INT 9 instruction	×	#09	FFFFD8 _H	_	_	
Exception	×	#10	FFFFD4 _H	_	_	↑
8/10-bit A/D converter	0	#11	FFFFD0 _H	ICR00	000000	
Timebase timer	×	#12	FFFFCCH	ICRUU	0000В0н	
DTP0/DTP1 (external interrupt 0/external interrupt 1)	0	#13	FFFFC8 _H	ICR01	0000В1н	
16-bit freerun timer 0 overflow	×	#14	FFFFC4 _H			
Extended I/O serial interface 1	0	#15	FFFFC0 _H	ICR02	000000	
Wakeup interrupt	×	#16	FFFFBCH	ICRU2	0000В2н	
Extended I/O serial interface 2	0	#17	FFFFB8 _H			
DTP2/DTP3 (external interrupt 2/external interrupt 3)	0	#18	FFFFB4 _H	ICR03	ICR03 0000В3н	
8/16-bit PPG timer 0 counter borrow	×	#19	FFFFB0 _H			
DTP4/DTP5 (external interrupt 4/external interrupt 5)	0	#20	FFFFACH	ICR04 0000В4н		
8/16-bit up/down counter/timer 0 compare match	0	#21	FFFFA8 _H	ICDOE	000005	
8/16-bit up/down counter/timer 0 overflow, up/down direction change	0	#22	FFFFA4 _H	H ICR05 0000B5н		
8/16-bit PPG timer 1 counter borrow	×	#23	FFFFA0 _H			
DTP6/DTP7 (external interrupt 6/external interrupt 7)	0	#24	FFFF9C _H	ICR06	0000В6н	
Output compare 1 (OCU) ch.4, ch.5 match	0	#25	FFFF98 _H	ICR07	0000В7н	
Clock timer	×	#26	FFFF94 _H	ICRU/	0000Б7н	
Output compare 1 (OCU) ch.6, ch.7 match	0	#27	FFFF90 _H	ICR08	0000В8н	
16-bit freerun timer 1 overflow	×	#28	FFFF8C _H	ICKUO	ООООВОН	
8/16-bit up/down counter/timer 1 compare match	0	#29	FFFF88 _H	ICROO 0000RO		
8/16-bit up/down counter/timer 1 overflow, up/down direction change	0	#30	FFFF84 _H	- ICR09 0000В9н		
Input capture 0 (ICU) capture	0	#31	FFFF80 _H	ICR10	0000ВАн	
Input capture 1 (ICU) capture	0	#32	FFFF7C _H		UUUUDAH	
Output compare 0 (OCU) ch.0 match	0	#33	FFFF78 _H	ICR11	0000PP	
Output compare 0 (OCU) ch.1 match	0	#34	FFFF74 _H	IORII	0000ВВн	

(Continued)

Interrupt	El²OS	Interrupt Vector		Interrupt Control Register		Priority
interrupt	Support	No.	Address	ICR	Address	Filority
Output compare 0 (OCU) ch.2 match	0	#35	FFFF70 _H	ICD42 0000DC		
Output compare 0 (OCU) ch.3 match	0	#36	FFFF6C _H	ICR12 0000BC _H		
UART (SCI) receive complete	0	#37	FFFF68 _H	ICR13	0000BDн	
16-bit reload timer 0	0	#38	FFFF64 _H	- ICKIS UUUUBDH		
UART (SCI) send complete	0	#39	FFFF60 _H	- ICR14 0000ВЕн		
16-bit reload timer 1	0	#40	FFFF5C _H	- ICK14 UUUUDEH		
Flash memory	×	#41	FFFF58 _H			₩
Delayed interrupt generation module	×	#42	FFFF54 _H	ICKIS	0000ВFн	Low

○ : Supported

× : Not supported

⊚ : Supported, includes El²OS stop function

■ PERIPHERAL RESOURCES

1. I/O Ports

- The I/O ports can be used as general-purpose I/O ports (parallel I/O ports). The MB90520A and 520B series have 11 ports (85 pins). The ports share pins with the inputs and outputs of the peripheral functions.
- The port data registers (PDR) are used to output data to the I/O pins and capture the input signals from the I/O ports.

Similarly, the port direction registers (DDR) set the I/O direction (input or output) for each individual port bit.

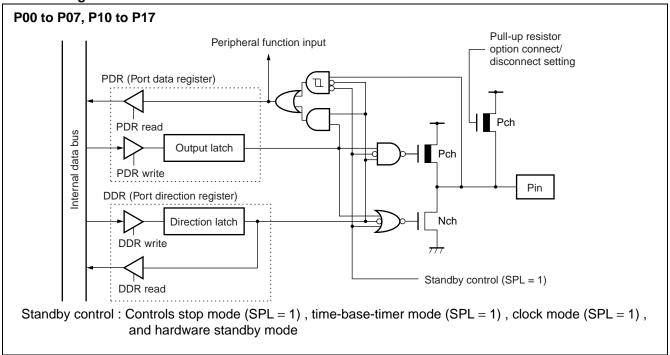
• The following tables list the I/O ports and peripheral functions with which they share pins.

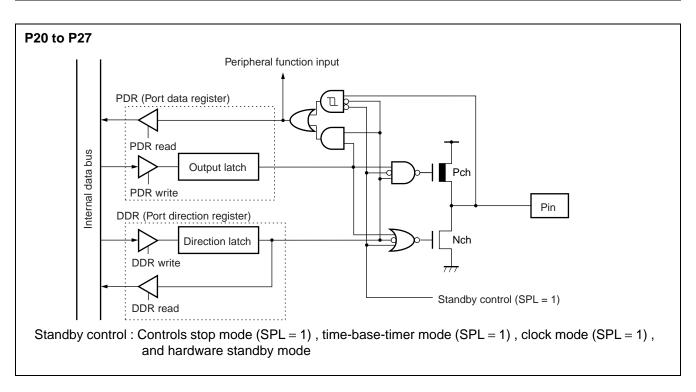
	Pin Name (Port)	Pin Name (Peripheral)	Peripheral Function that Shares Pin
Port 0	P00 – P06	INTO – INT6	External interrupts
FUILU	P07	_	Not shared
Port 1	P10 – P17	WIO – WI7	Wakeup interrupts
	P20 – P23	IN00 – IN11	Input capture (unit 0)
Port 2	P24, P25	AIN0, BIN0	8/16-bit up/down counter/timer 0
	P26	ZIN0/INT7	8/16-bit up/down counter/timer 0, external interrupt
	P30	_	Not shared
Port 3	P31	СКОТ	Clock monitor function
Poils	P32 – P35	OUT0 – OUT3	Output compare (unit 0)
	P36, P37	PPG00, PPG01	8/16-bit PPG timer 0
	P40, P41	PPG10, PPG11	8/16-bit PPG timer 1
Port 4	P42 – P44	SIN0, SOT0, SCK0	UART (SCI)
	P45 – P47	SIN1, SOT1, SCK1	Extended I/O serial interface 0
Port 5	P50 – P52	SIN2/AIN1, SOT1/BIN1, SCK1/ZIN1	8/16-bit up/down counter/timer 0 Extended I/O serial interface 1
	P53, P54	DA0, DA1	8-bit D/A converter
Port 6	P60 – P67	ANO – AN7	8/16-bit A/D converter
Port 7	P70 – P73	TIN0/OUT4, TOT0/OUT5, TIN1/OUT6, TOT1/OUT7	16-bit reload timers 0, 1 Output compare (unit 1)
	P74 – P77	COM0 – COM3	LCD control driver common output
Port 8	P80 – P87	SEG16 – SEG23	LCD control driver segment output
Port 9	P90 – P97	SEG24 – SEG31	LCD control driver segment output
Port A	PA0 – PA7	SEG8 – SEG15	LCD control driver segment output

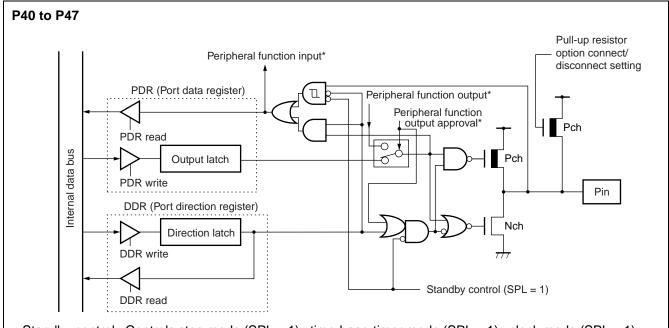
Notes

- Port 9 contains general-purpose I/O ports with N-ch open-drain output circuits.
- Connect an external pull-up resistor when using port 9 pins as outputs.
- Port 6 shares pins with the analog inputs. When using port 6 as a general-purpose port, ensure that the corresponding analog input enable register (ADER) bits are set to "0". ADER is initialized to "FFH" after a reset.

• Block diagrams

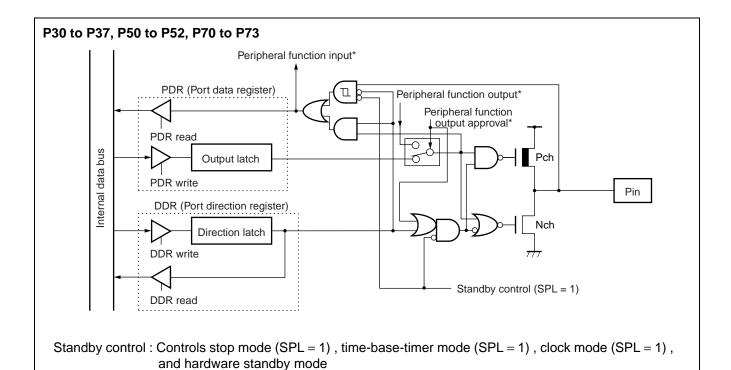




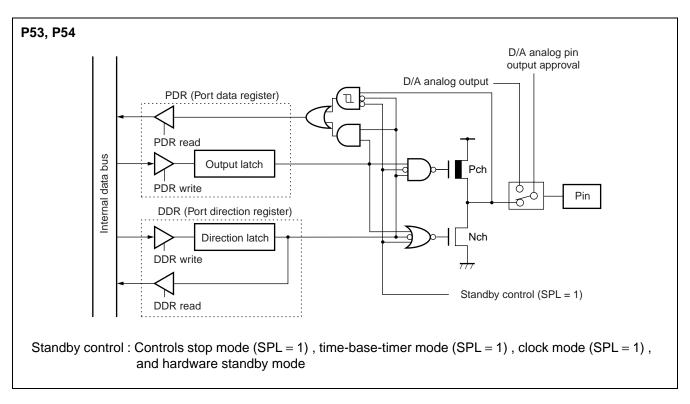


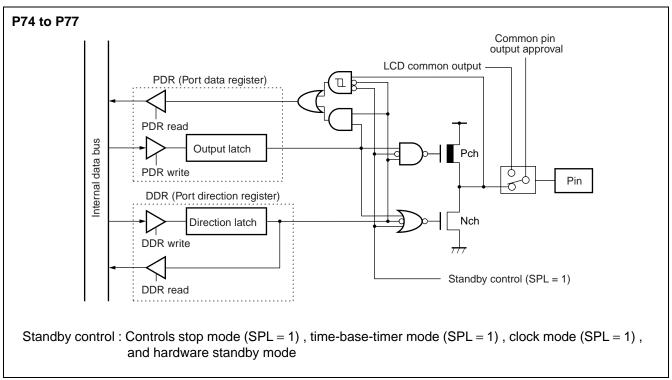
Standby control : Controls stop mode (SPL = 1) , time-base-timer mode (SPL = 1) , clock mode (SPL = 1) , and hardware standby mode

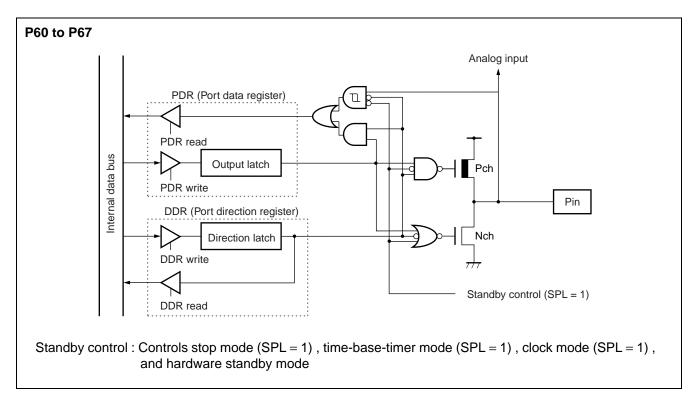
* : Peripheral function I/O is equivalent to I/O of peripheral function.

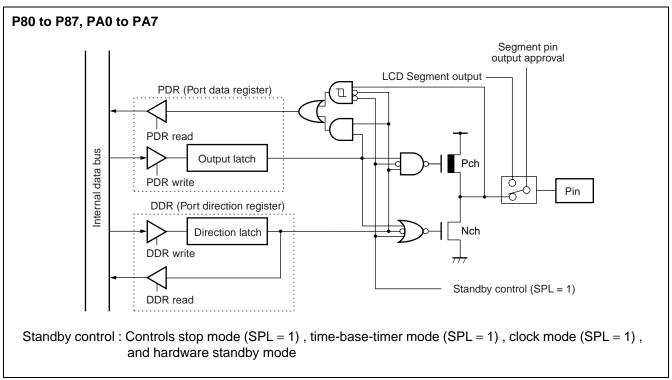


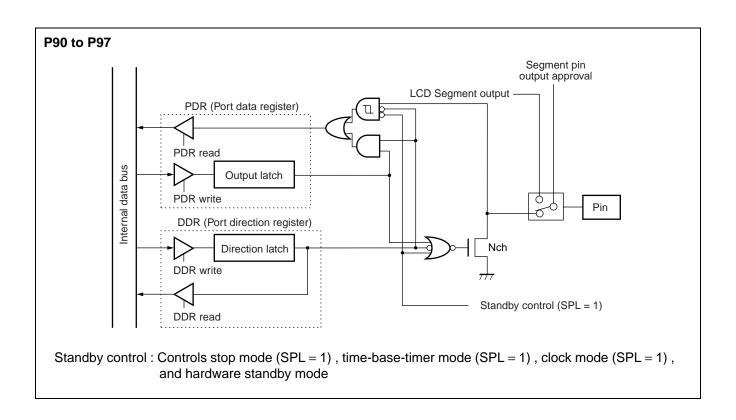
*: Peripheral function I/O is equivalent to I/O of peripheral function.











2. Timebase Timer

- The timebase timer is an 18-bit freerun timer (timebase timer/counter) that counts up synchronized with the main clock (oscillation clock: HCLK divided by 2).
- The timer can generate interrupt requests at a specified interval, with four different interval time settings available.
- The timer supplies the operating clock for peripheral functions including the oscillation stabilization delay timer and watchdog timer.

· Timebase timer interval settings

Internal Count Clock Period	Interval Time
	212/HCLK (approx. 1.024 ms)
2/HCLK (0.5 μs)	2 ¹⁴ /HCLK (approx. 4.096 ms)
2/110ER (0.5 μs)	2 ¹⁶ /HCLK (approx. 16.384 ms)
	2 ¹⁹ /HCLK (approx. 131.072 ms)

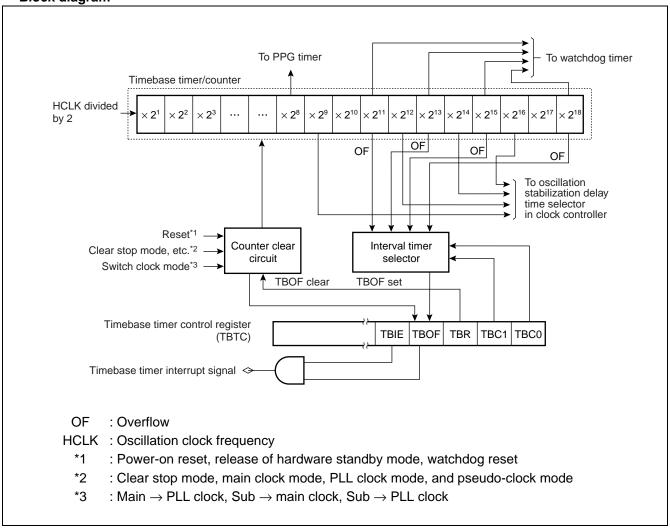
- HCLK : Oscillation clock frequency
- The values enclosed in () indicate the times for a clock frequency of 4 MHz.

· Period of clocks supplied from timebase timer

Peripheral Function	Clock Period				
	210/HCLK (approx. 0.256 ms)				
Oscillation stabilization delay	2 ¹³ /HCLK (approx. 2.048 ms)				
for the main clock	2 ¹⁵ /HCLK (approx. 8.192 ms)				
	2 ¹⁷ /HCLK (approx. 32.768 ms)				
	212/HCLK (approx. 1.024 ms)				
Watchdog timer	2 ¹⁴ /HCLK (approx. 4.096 ms)				
watchdog timei	2 ¹⁶ /HCLK (approx. 16.384 ms)				
	2 ¹⁹ /HCLK (approx. 131.072 ms)				
PPG timer	29/HCLK (approx. 0.128 ms)				

- HCLK : Oscillation clock frequency
- The values enclosed in () indicate the times for a clock frequency of 4 MHz.





The actual interrupt request number for the timebase timer is:

Interrupt request number: #12 (0CH)

3. Watchdog Timer

- The watchdog timer is a timer/counter used to detect faults such as program runaway.
- The watchdog timer is a 2-bit counter that counts the clock signal from the timebase timer or clock timer.
- Once started, the watchdog timer must be cleared before the 2-bit counter overflows. If an overflow occurs, the CPU is reset.

· Interval time for the watchdog timer

HCLK : Oscillation Clock (4 MHz)			SCLK : Sub-Clock (8.192 kHz)		
Min	Max	Clock Period	Min	Max	Clock Period
Approx. 3.58 ms	Approx. 4.61 ms	2 ¹⁴ ± 2 ¹¹ / HCLK	Approx. 0.438 s	Approx. 0.563 s	$2^{12}\pm 2^9$ / SCLK
Approx. 14.33 ms	Approx. 18.30 ms	$2^{16}\pm 2^{13}/\; HCLK$	Approx. 3.500 s	Approx. 4.500 s	$2^{15}\pm 2^{12}/\; SCLK$
Approx. 57.23 ms	Approx. 73.73 ms	$2^{18}\pm 2^{15}$ / HCLK	Approx. 7.000 s	Approx. 9.000 s	$2^{16}\pm 2^{13}$ / SCLK
Approx. 458.75 ms	Approx. 589.82 ms	$2^{21}\pm 2^{18}/\; HCLK$	Approx. 14.00 s	Approx. 18.00 s	$2^{17}\pm 2^{14}$ / SCLK

^{*:} The difference between the maximum and minimum watchdog timer interval times is due to the timing when the counter is cleared.

Watchdog timer count clock

WTC : WDCS	HCLK : Oscillation clock PCLK : PLL clock	SCLK : Sub-clock
"0"	Count the clock timer output.	Count the clock timer output.
"1"	Count the timebase timer output.	Count the clock timer output.

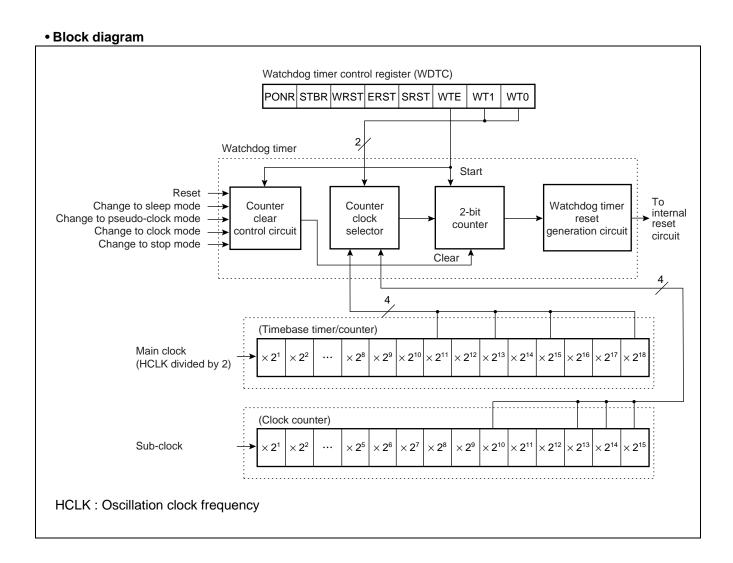
Events that stop the watchdog timer

- 1 : Stop due to a power-on reset
- 2: Reset due to recovery from hardware standby mode
- 3: Watchdog reset

Events that clear the watchdog timer

- 1: External reset input from the RST pin.
- 2: Writing "0" to the software reset bit.
- 3: Writing "0" to the watchdog control bit (second and subsequent times).
- 4: Changing to sleep mode (clears the watchdog timer and temporarily halts the count).
- 5 : Changing to pseudo-clock mode (clears the watchdog timer and temporarily halts the count) .
- 6 : Changing to clock mode (clears the watchdog timer and temporarily halts the count) .
- 7: Changing to stop mode (clears the watchdog timer and temporarily halts the count).

^{*:} As the watchdog timer is a 2-bit counter that counts the carry-up signal from the timebase timer or clock timer, clearing the timebase timer (when operating on HCLK) or the clock timer (when operating on SCLK) lengthens the time until the watchdog timer reset is generated.



4. 8/16-bit PPG (Programmable Pulse Generator) Timers 0 and 1

The 8/16-bit PPG timer is a two-channel reload timer module (PPG0 and PPG1) that can generate pulse outputs with the periods specified in the table below and with duty ratios between 0 and 100%. Note that the pulse periods are different depending on the operation mode.

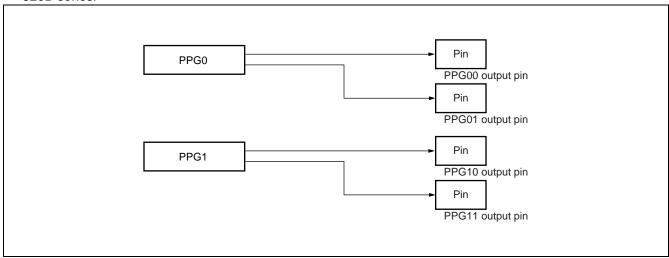
Operation		PPG00, PPG0	01 (PPG ch0)	PPG10, PPG11 (PPG ch1)		
Operation Mode	Count Clock*2	Interval Time	Output Pulse Width	Interval Time	Output Pulse Width	
	φ/1 (62.5 ns)	1/φ to 28/φ	1/φ to 2 ⁹ /φ	1/φ to 28/φ	1/φ to 2 ⁹ /φ	
8-bit	φ/2 (125 ns)	2/φ to 2 ⁹ /φ	2²/φ to 2¹0/φ	2/φ to 2 ⁹ /φ	2²/φ to 2¹0/φ	
PPG output	ф/4 (250 ns)	2²/φ to 2¹0/φ	23/\phi to 211/\phi	2²/φ to 2¹0/φ	2 ³ /φ to 2 ¹¹ /φ	
Independent	ф/8 (500 ns)	2 ³ /φ to 2 ¹¹ /φ	24/\phi to 212/\phi	2 ³ /φ to 2 ¹¹ /φ	24/φ to 212/φ	
2ch operation mode	ф/16 (1000 ns)	24/φ to 212/φ	25/\phi to 213/\phi	2 ⁴ /φ to 2 ¹² /φ	25/φ to 213/φ	
	HCLK/512 (128 μs)	2 ⁹ /HCLK to 2 ¹⁷ /HCLK	2 ¹⁰ /HCLK to 2 ¹⁸ /HCLK	2 ⁹ /HCLK to 2 ¹⁷ /HCLK	2 ¹⁰ /HCLK to 2 ¹⁸ /HCLK	
	φ/1 (62.5 ns)	1/φ to 2 ¹⁶ /φ	1/φ to 2 ¹⁷ /φ	1/φ to 2 ¹⁶ /φ	1/φ to 2 ¹⁷ /φ	
	φ/2 (125 ns)	2/φ to 2 ¹⁷ /φ	2²/φ to 2 ¹⁸ /φ	2/φ to 2 ¹⁷ /φ	2²/φ to 2 ¹⁸ /φ	
16-bit	φ/4 (250 ns)	2²/φ to 2 ¹⁸ /φ	2 ³ /φ to 2 ¹⁹ /φ	2²/φ to 2 ¹⁸ /φ	2 ³ /φ to 2 ¹⁹ /φ	
PPG output operation	φ/8 (500 ns)	2 ³ /φ to 2 ¹⁹ /φ	24/φ to 220/φ	2 ³ /φ to 2 ¹⁹ /φ	24/φ to 220/φ	
mode	ф/16 (1000 ns)	24/φ to 220/φ	25/\phi to 221/\phi	24/φ to 220/φ	25/φ to 221/φ	
	HCLK/512 (128 μs)	2 ⁹ /HCLK to 2 ²⁵ /HCLK	2 ¹⁰ /HCLK to 2 ²⁶ /HCLK	2 ⁹ /HCLK to 2 ²⁵ /HCLK	2 ¹⁰ /HCLK to 2 ²⁶ /HCLK	
	φ/1 (62.5 ns)	1/φ to 2 ⁶ /φ	1/φ to 2 ⁹ /φ	1/φ to 2 ¹⁶ /φ	1/φ to 2 ¹⁷ /φ	
	φ/2 (125 ns)	2/φ to 2 ⁹ /φ	2²/φ to 2¹0/φ	2/φ to 2 ¹⁷ /φ	2²/φ to 2 ¹⁸ /φ	
8 + 8-bit	φ/4 (250 ns)	2²/φ to 2¹0/φ	2 ³ /φ to 2 ¹¹ /φ	2 ² /φ to 2 ¹⁸ /φ	2 ³ /φ to 2 ¹⁹ /φ	
PPG output operation	φ/8 (500 ns)	2 ³ /φ to 2 ¹¹ /φ	24/φ to 212/φ	2 ³ /φ to 2 ¹⁹ /φ	24/φ to 220/φ	
mode*1	φ/16 (1000 ns)	24/φ to 212/φ	25/φ to 213/φ	24/φ to 220/φ	25/φ to 221/φ	
	HCLK/512 (128 μs)	2 ⁹ /HCLK to 2 ¹⁷ /HCLK	2 ¹⁰ /HCLK to 2 ¹⁸ /HCLK	2 ⁹ /HCLK to 2 ²⁵ /HCLK	2 ¹⁰ /HCLK to 2 ²⁶ /HCLK	

^{*1:8+8-}bit PPG output operation mode consists of using the lower 8 bits as a prescaler for the PPG timer.

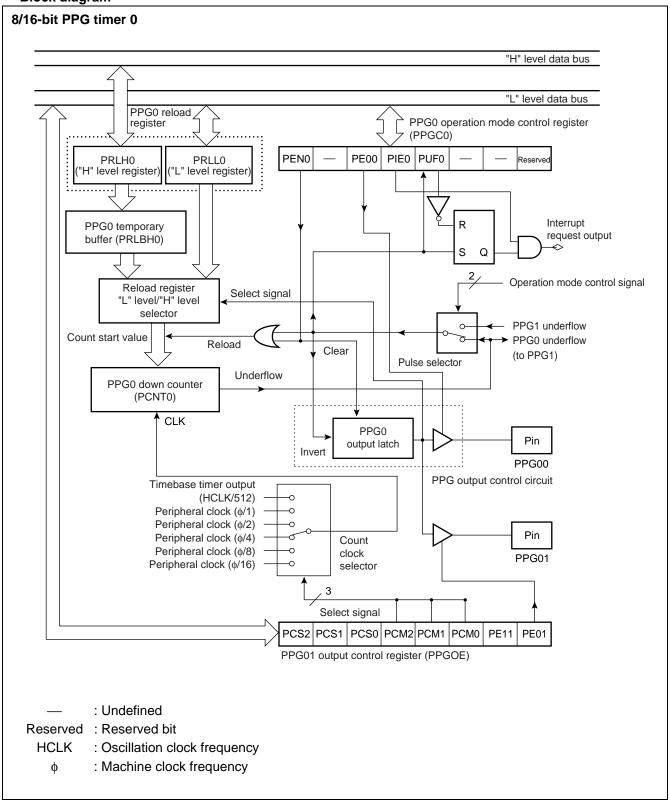
^{*2 :} The values enclosed in () indicate the times for a machine clock frequency of 16 MHz.

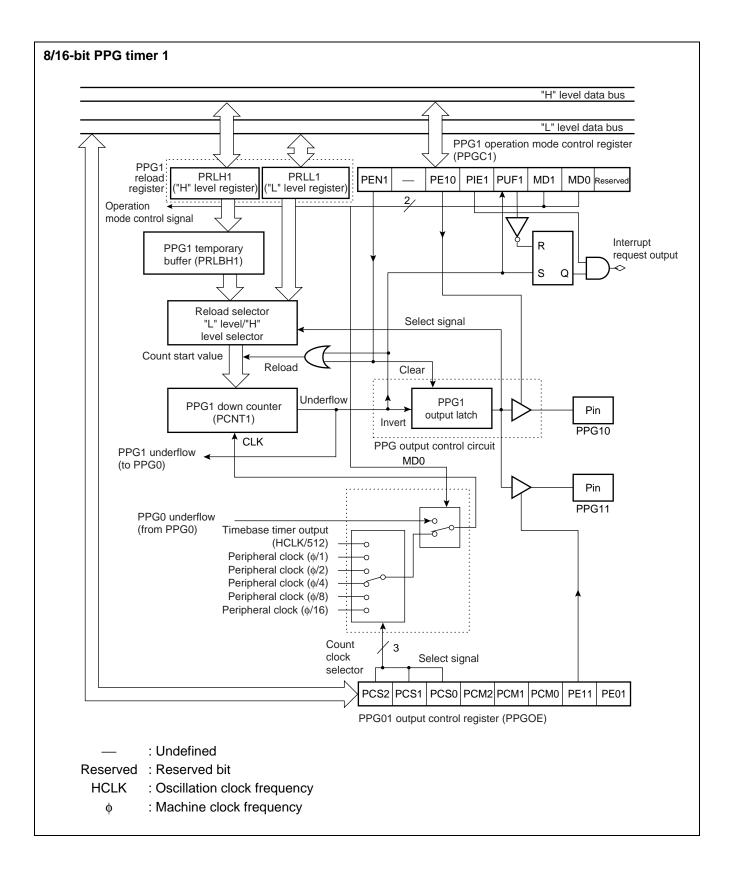
• PPG timer channels and PPG pins

The figure below shows the relationship between the 8/16-bit PPG channels and PPG pins on the MB90520A/520B series.



Block diagram





5. 16-bit Reload Timers 0 and 1 (With Event Count Function)

The 16-bit reload timers have the following functions.

- The count clock can be selected from three internal clock and the external event clock.
- Either software trigger or external trigger can be selected as the start signals for 16-bit reload timers 0 and 1.
- An interrupt to the CPU can be generated when an underflow occurs on 16-bit reload timer 0 and 1. This interrupt allows the timers to be used as interval timers.
- Two different operation modes can be selected when an underflow occurs on 16-bit reload timer 0 and 1: oneshot mode in which timer operation halts when an underflow occurs or reload mode in which the reload register value is loaded into the timer and counting continues.
- Extended intelligent I/O service (EI2OS) is supported.
- The MB90520A/520B series contains two 16-bit reload timer channels.

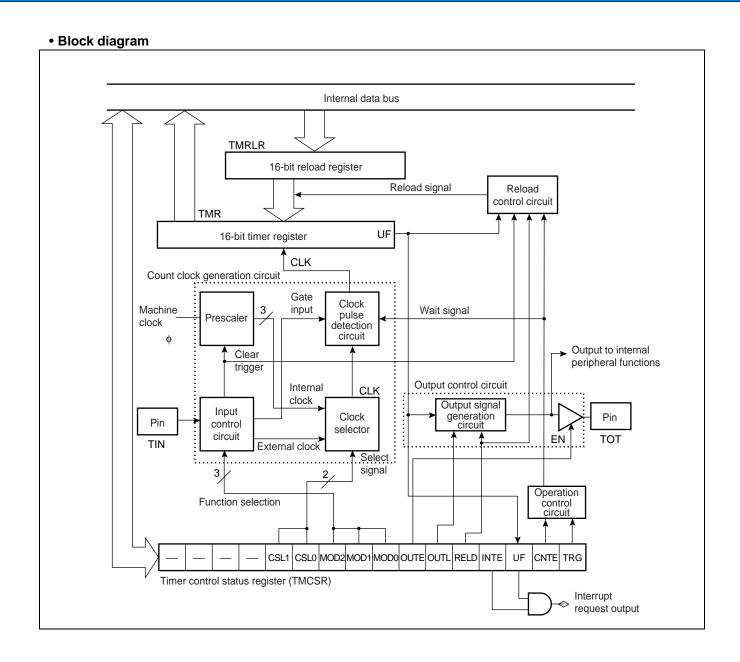
• 16-bit reload timer operation modes

Count Clock	Start Trigger	Operation when an Underflow Occurs
	Software trigger	One-shot mode
Internal clock	Software trigger	Reload mode
(3 clocks available)	Future al triange	One-shot mode
	External trigger	Reload mode
	Software trigger	One-shot mode
Event clock	Software trigger	Reload mode
EVENT CIOCK	External trigger	One-shot mode
	External trigger	Reload mode

• Interval times for the 16-bit reload timers

Count Clock	Count Clock Period Example Interval Times		
	2¹T (0.125 μs)	0.125 μs to 8.192 ms	
Internal clock	2³T (0.5 μs)	0.5 μs to 32.768 ms	
	2 ⁵ T (2.0 μs)	2.0 μs to 131.1 ms	
Event clock	2 ³ T or longer	0.5 μs or longer	

Note: The values enclosed in () and the example interval times are for a machine clock frequency of 16 MHz. "T" is the machine cycle and is 1/ (machine clock frequency).



6. 16-bit I/O Timers

The 16-bit I/O timers consist of a two-channel 16-bit freerun timer, two-channel input capture, and eight-channel output compare. The output compare channels can be used to generate eight independent waveform outputs based on the 16-bit freerun timer. The input capture channels can be used to measure input pulse widths and external clock periods.

• Structure of I/O timers in the MB90520A/520B series

	16-bit Freerun Timer	Output Compare	Input Capture
16-bit I/O timer (unit 0)	16-bit freerun timer 0	Output compare 0 to 3 (unit 0)	Input capture 0 and 1 (unit 0)
16-bit I/O timer (unit 1)	16-bit freerun timer 1	Output compare 4 to 8 (unit 1)	_

16-bit freerun timer functions

- The count value for the 16-bit freerun timer sets the base time for the input capture and output compare functions.
- An interrupt can be generated when the 16-bit freerun timer overflows.
- Extended intelligent I/O service (El²OS) can be generated.
- 16-bit freerun timers 0 and 1 can be cleared to "0000_H" when an external reset is input, on setting the timer clear bit (TCCS: CLR = 1), and when a compare match occurs on output compare 0 to 4.
- The count clock frequency can be selected from the following four clocks : $4/\phi$ (250 ns) , $16/\phi$ (1.0 μ s) , $64/\phi$ (4.0 μ s) , $256/\phi$ (16.0 μ s)

Note: ϕ is the machine clock frequency. The values in () are for 16 MHz machine clock.

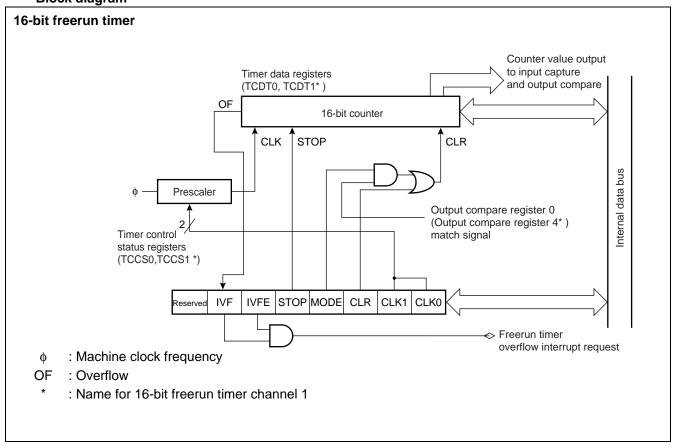
Input capture functions

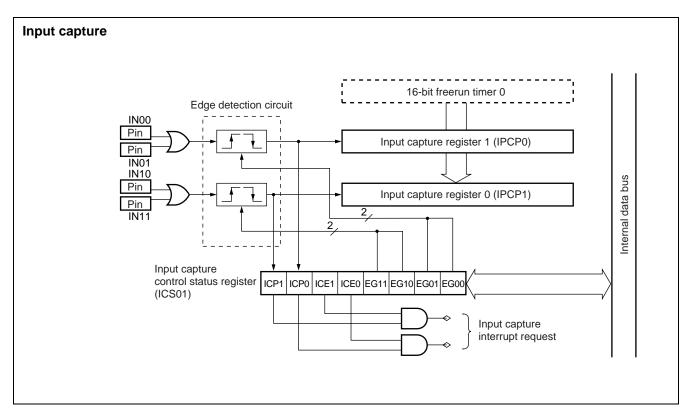
- The input capture saves the value of the 16-bit freerun timer and generates an interrupt request when the specified edge is detected on the trigger input from the external trigger input pin (IC00 or IC01/IC10 or IC11).
- Input capture channels 0 and 1 can perform input capture and generate interrupt request independently.
- Extended intelligent I/O service (EI2OS) can be generated.
- Detection of rising edges, falling edges, or either edge can be selected as the trigger edge.
- When using input capture 0, either the IC00 or IC01 pin can be used. Note, however, that masking one pin only is not possible.
- When using input capture 1, either the IC10 or IC11 pin can be used. Note, however, that masking one pin only is not possible.

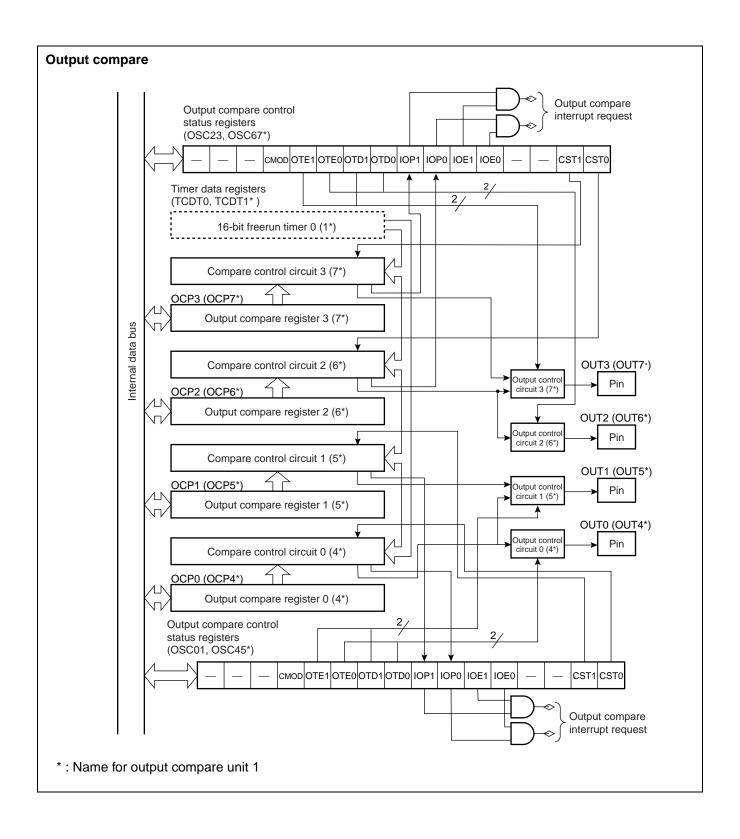
Output compare functions

- The output compare channels compare the values set in output compare registers 0 to 7 with the 16-bit freerun timers 0 and 1 count values and invert the level of the corresponding output compare pin and clear the 16-bit freerun timer to "0000H" when a match is detected.
- Extended intelligent I/O service (El²OS) can be generated.
- The initial output levels at the output compare pins can be set after the microcontroller boots.
- The output levels from the eight output compare channels are controlled independently. Similarly, interrupt requests are also generated independently by each channel.

• Block diagram







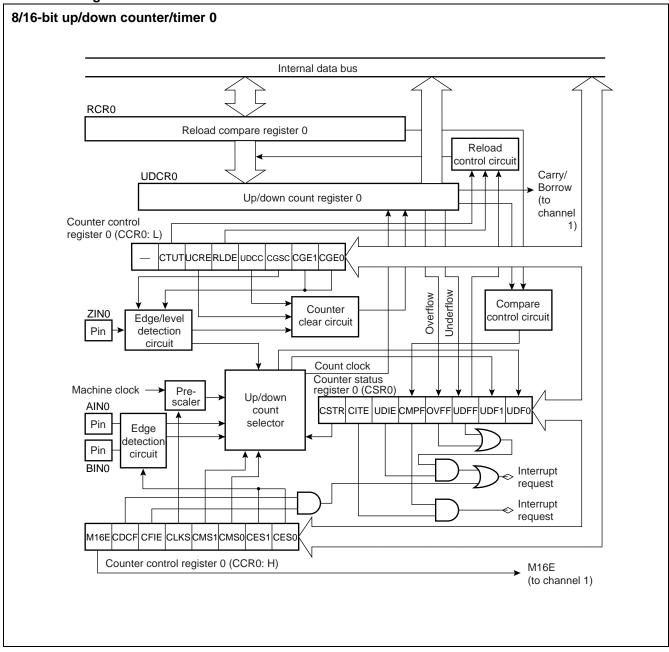
7. 8/16-bit Up/Down Counter/Timers 0 and 1

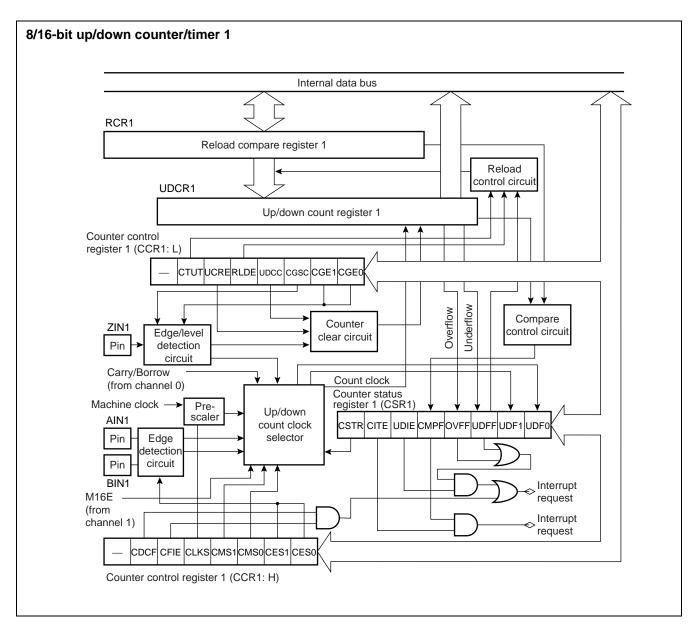
- The 8/16-bit up/down counter/timers can operate in timer mode, up/down count mode, and phase difference count mode.
- The unit can be used as either a 2-channel × 8-bit or 1-channel × 16-bit up/down counter/timer.

• 8/16-bit up/down counter/timer functions

Operation Mode	Count Mode	Count Clock (Count Edge)	Function of ZIN Pin	Other Functions	
	Timer mode	2/φ, 4/φ (φ : Machine clock frequency)	_		
	Up/down count	Counts up on detecting specified edge on the AIN pin.	Counter clear function		
	mode	Counts down on detecting specified edge on the BIN pin.	Gate function		
8-bit	Phase difference count	Reads the AIN pin input level on detecting a rising or falling edge	Counter clear function		
×2-channel mode	mode (multiply by 2)	on the BIN pin and counts up or counts down.	Gate function		
	Dhasa	Reads the AIN pin input level on detecting a rising or falling edge	Counter clear function	Compare function Reload function	
	Phase difference count mode (multiply by 4)	on the BIN pin and counts up or counts down. Similarly, reads the BIN pin input level on detecting a rising or falling edge on the AIN pin and counts up or counts down.	Gate function	 Compare/reload function Compare/reload prohibit The direction of the previous count can be determined from the up/down flag. 	
	Timer mode	2/φ, 4/φ (φ : Machine clock frequency)		Interrupt requests can be generated on the following	
	Up/down count	Counts up on detecting specified edge on the AIN pin.	Counter clear function	conditions : 1 : Compare match	
	mode	Counts down on detecting specified edge on the BIN pin.	Gate function	2 : Underflow or overflow 3 : Count direction	
16-bit	Phase difference count	Reads the AIN pin input level on detecting a rising or falling edge	Counter clear function	change	
× 1-channel mode	mode (multiply by 2)	on the BIN pin and counts up or counts down.	Gate function		
	Dhara	Reads the AIN pin input level on detecting a rising or falling edge	Counter clear function		
	Phase on the BIN pin and counts up or counts down. Similarly, reads the BIN pin input level on detecting a rising or falling edge on the AIN pin and counts up or counts down.		Gate function		

• Block diagram





Pins and interrupt numbers

8/16-bit up/down counter/timer 0

AIN0 pin: P24/AIN0 BIN0 pin: P25/BIN0 ZIN0 pin: P26/ZIN0

Compare match interrupt number: #21 (15H)

Interrupt number for underflow/overflow interrupt, count direction change interrupt : #2 (16H)

8/16-bit up/down counter/timer 1

AIN1 pin : P50/AIN1 BIN1 pin : P51/BIN1 ZIN1 pin : P52/ZIN1

Compare match interrupt number: #29 (1DH)

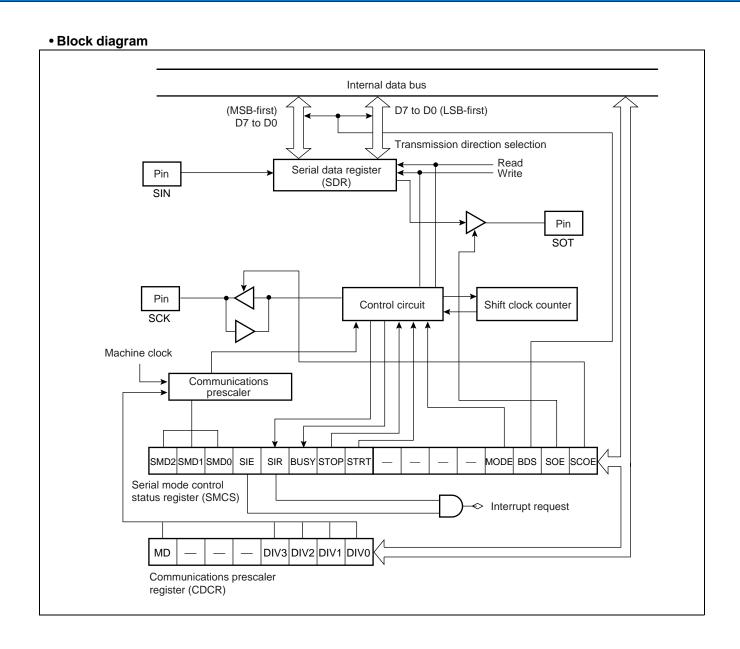
Interrupt number for underflow/overflow interrupt, count direction change interrupt: #3 (1EH)

8. Extended I/O Serial Interfaces 0 and 1

- The extended I/O serial interfaces are serial I/O interfaces that perform clock-synchronized data transfer.
- The MB90520A/520B series contain two internal extended I/O serial interface channels.
- Either LSB-first or MSB-first data transmission format can be selected.

• Extended I/O serial interface functions

	Function
Transmission direction	• Transmit and receive can be handled simultaneously. (A setting is required to select transmit or receive.)
Transmission mode	Clock synchronous (data transfer only)
Transmission clock	 Internal shift clock mode (Uses the communications prescaler output clock.) External shift clock mode (Inputs the clock signal from SCK1 and SCK2.)
Transmission speed	 When using internal shift clock: Up to 1 MHz operation can be achieved (for a 16 MHz machine clock with the divisor setting for the communication prescaler set to 8). Speeds faster than 1 MHz are not possible. When using an external shift clock: As a minimum of 5 machine cycles are required, when the machine clock is 16 MHz the maximum input frequency for the external shift clock is 16 MHz.
Data transmission format	 LSB-first or MSB-first, selectable Data transfer only Number of data bits = 8 (fixed)
Interrupt request generation	Interrupt generated when transfer completes
EI ² OS support	Supports use of the extended intelligent I/O service.



9. UART (SCI: Serial Communication Interface)

- The UART (SCI) is a general-purpose serial communications interface for performing synchronous or asynchronous communications with external devices.
- The interface provides bi-directional communications in both clock synchronous and clock asynchronous modes.
- Includes a master-slave communication function (multi-processor mode) .
- Can generate interrupt requests at receive complete, receive error detected, and transmit complete timings. Also supports EI²OS.

• UART (SCI) functions

	Function
Data buffer	Full-duplex double-buffered
Transmission modes	Clock synchronous (with no start/stop bit, no parity bit)Clock asynchronous (start-stop sync)
Baud rate	 Can use dedicated baud rate generator. Can use external clock input. Can use clock supplied by 16-bit reload timer 0. For machine clock speeds of 6 MHz, 8 MHz, 10 MHz, 12 MHz, and 16 MHz: Available speeds for asynchronous communications: 31250 bps, 9615 bps, 4808 bps, 2404 bps, and 1202 bps Available speeds for synchronous communications: 1 Mbps, 500 Kbps, 250 Kbps, 125 Kbps, and 62.5 Kbps
Number of data bits	7 bits (when parity is used for asynchronous normal mode)8 bits (when parity is not used)
Signal format	Non return to zero (NRZ) format
Receive error detection	 Framing errors (not available in clock synchronous mode) Overrun errors Parity errors (not available in clock synchronous mode and multi-processor mode)
Interrupt requests	 Receive interrupt (Receive complete or receive error detected) Transmit interrupt (Transmission complete) Both transmit and receive support the extended intelligent I/O service (EI²OS) .
Master/slave communication function (multi-processor mode)	Used for 1 (master) to n (slave) communications. (Can only be used as master)
EI2OS support	Supports the extended intelligent I/O service (EI²OS)

• UART (SCI) operation modes

Operation Mode		No. of D	ata Bits	Parit	y Bit	No. of Stop Bits		
	Operation Mode		7 bits	8 bits	None	Use	1 bit	2 bits
Mode 0	Asynchronous	Normal mode (1-to-1)	0	0	0	0	0	0
Mode 1	Asynchronous	Multi-processor mode (1-to-n)	×	O (+1)	0	×	0	0
Mode 2	Clock synchronous	Clock synchronous mode (one-to-one)	×	0	0	×	×	×

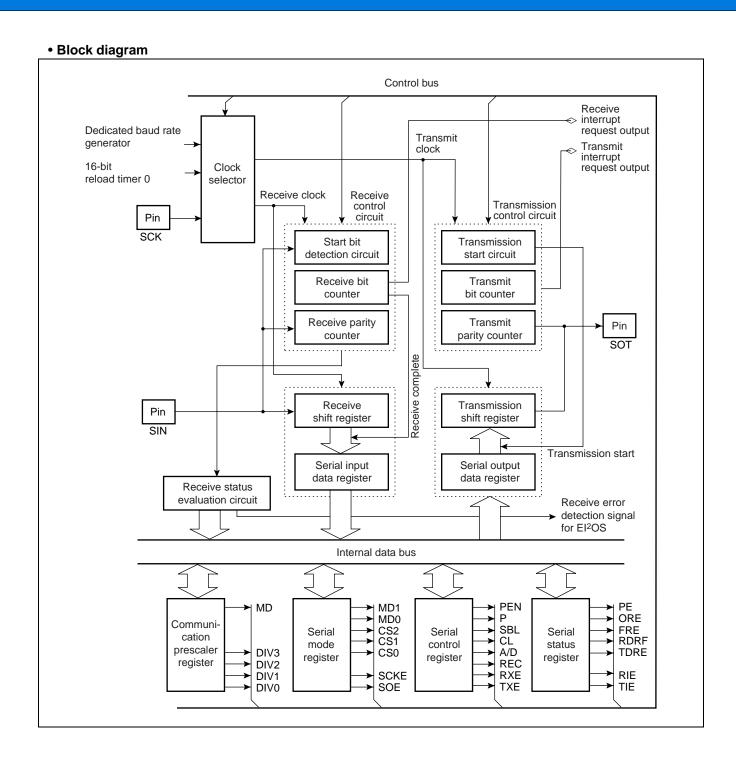
○ : Available

× : Not available

+1: Address/data bit used for communication control

Notes:

- The number of data bits must be set to eight for multi-processor and clock synchronous modes.
- A parity bit cannot be used in multi-processor and clock synchronous modes.
- Only data can be transferred in clock synchronous mode. Start and stop bits cannot be added to the transmission data.

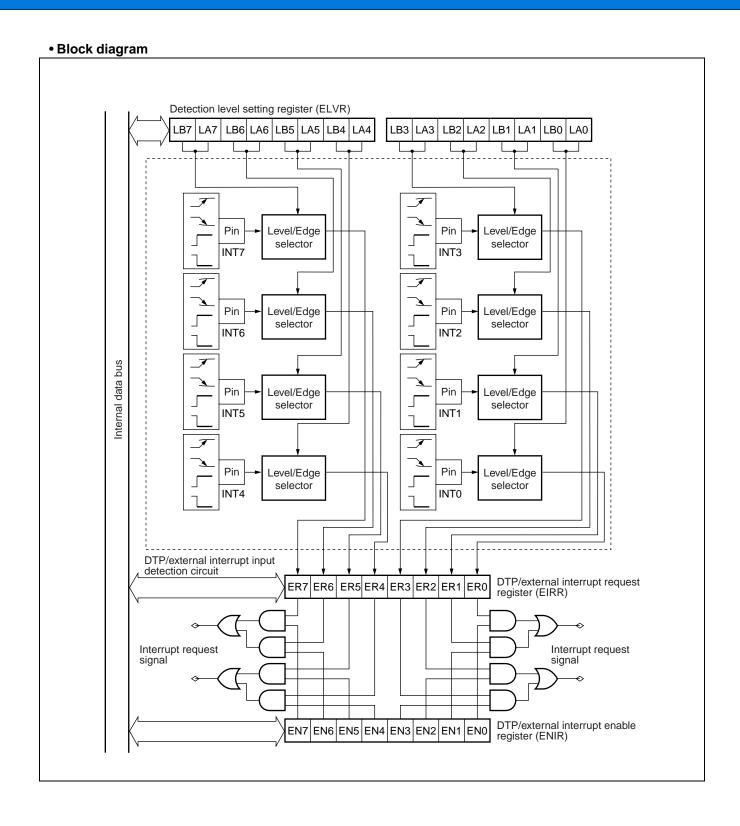


10. DTP (Data Transfer Peripheral) /External Interrupt Circuit

The DTP/external interrupt function detects interrupt requests and data transfer requests input from external devices and passes these to the CPU as external interrupt requests. This block can also activate the extended intelligent I/O service (El^2OS).

• DTP/external interrupt functions

	External Interrupt DTP Function				
Input pins	8 channels (INT0 to INT7)				
Interrupt	• Can be set independently for each channel (each pin) in the detection level setup register (ELVR) .				
conditions	"H" level, "L" level, rising edge, or falling edge input	"H" level or "L" level input			
Interrupt control	• Interrupts can be enabled or disabled in the DTP/external interrupt enable register (ENIR) .				
Interrupt flag	The DTP/external interrupt request register (EIRR) stores interrupt requests.				
Processing selection	• Set El²OS to be disabled (ICR : ISE = 0)	• Set El²OS to be enabled (ICR : ISE = 1)			
Interrupt execution	Jumps to interrupt handler routine	Jumps to interrupt handler routine after automatic data transfer by El ² OS completes.			
El ² OS support	Supports the extended intelligent I/O service (EI²OS)				



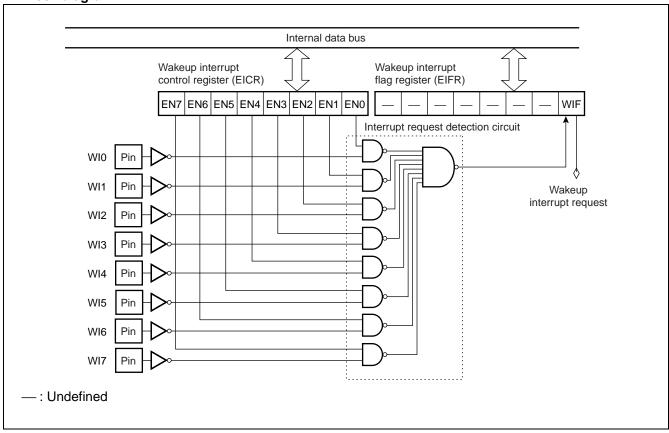
11. Wakeup Interrupts

- The wakeup interrupt function detects wakeup interrupt requests from external devices by detecting "L" levels input to the wakeup interrupt input pins (WI0 to WI7) and passes these to the CPU for interrupt processing.
- Wakeup interrupts can be used to wakeup the microcontroller from standby mode. (However, wakeup interrupts cannot be used to recover from hardware standby mode.)
- Not supported by the extended intelligent I/O service (EI2OS).

Wakeup interrupt functions

	Function and Control
Input pins	8 channels (8 pins : WI0 to WI7)
Interrupt trigger	"L" level inputs. One interrupt flag is shared by all eight channels.
Interrupt control	Interrupt requests can be enabled or disabled in the wakeup interrupt control register (EICR) .
Interrupt flag	Interrupt requests are stored in the wakeup interrupt flag register (EIFR) .
El ² OS support	Not supported by the extended intelligent I/O service (EI²OS) .

• Block diagram



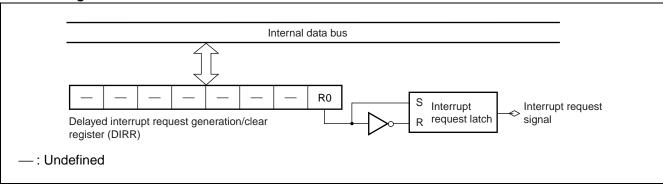
12. Delayed Interrupt Generation Module

The delayed interrupt generation module is used to generate the task switching interrupt. Generation of this hardware interrupt can be specified by software.

• Delayed interrupt generation module functions

	Function and Control	
Interrupt trigger	 Writing "1" to bit R0 of the delayed interrupt request generation/clear register (DIRR: R0 = 1) generates an interrupt request. Writing "0" to bit R0 of the delayed interrupt request generation/clear register (DIRR: R0 = 0) clears the interrupt request. 	
Interrupt control	No enable/disable register is provided for this interrupt.	
Interrupt flag	• Set in bit R0 of the delayed interrupt request generation/clear register (DIRR : R0) .	
El ² OS support	Not supported by the extended intelligent I/O service (EI²OS) .	

Block diagram



13. 8/10-bit A/D Converter

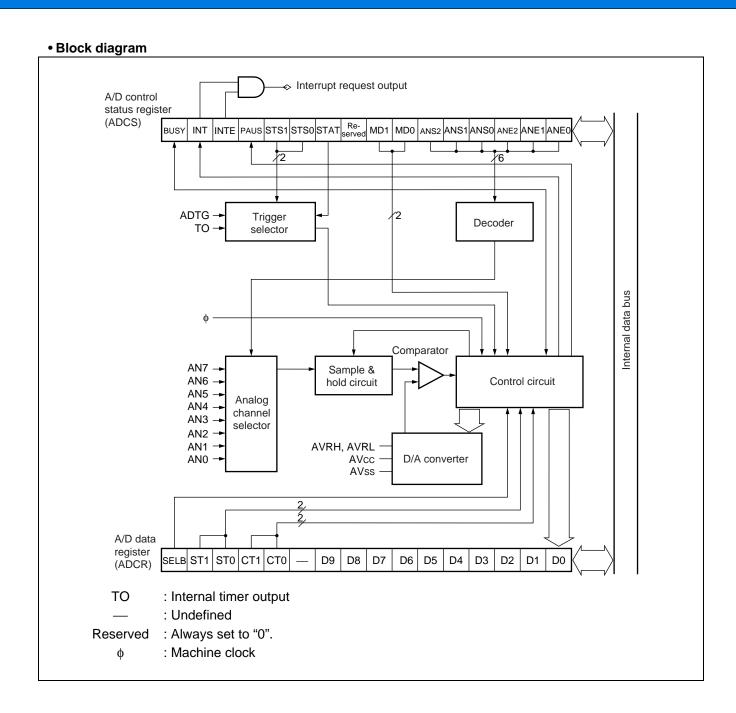
- The 8/10-bit A/D converter uses RC successive approximation to convert analog input voltages to an 8-bit or 10-bit digital value.
- The input signals can be selected from the eight analog input pin channels.
- Either a software trigger, internal timer output, or external pin trigger can be selected to trigger the start of A/D conversion.

• 8/10-bit A/D converter functions

	Function	
A/D conversion time	 Sampling time: Can be selected from 64, 128, or 4096 machine cycles. The minimum is 4 μs. Compare time: Can be selected from 44, 99, or 176 machine cycles. The minimum is 4.4 μs. A/D conversion time = sampling time + conversion time. The minimum A/D conversion time is 10.2 μs. 	
Conversion method	RC successive approximation with sample & hold circuit	
Resolution	8-bit or 10-bit, selectable	
Analog input pins	Up to eight channels can be used. However, two or more channels cannot be used simultaneously.	
Interrupts	An interrupt request can be generated when A/D conversion completes.	
A/D conversion start trigger	Selectable : software, internal timer output, or falling edge on input from external pin	
EI ² OS support	Supported by the extended intelligent I/O service (EI ² OS) .	

• 8/10-bit A/D converter conversion modes

	Description
Single-shot conversion mode	Performs A/D conversion sequentially from the start channel to the end channel. A/D conversion halts after conversion completes for the end channel.
Continuous conversion mode	Performs A/D conversion sequentially from the start channel to the end channel. A/D conversion starts again from the start channel after conversion completes for the end channel.
Incremental conversion mode	A/D conversion is performed for one channel then halts until the next trigger. After conversion is performed for the end channel, the next conversion is performed for the start channel, and repeated this operation.



14. 8-bit D/A Converter

- The 8-bit D/A converter performs R-2R D/A conversion with 8-bit resolution.
- Two D/A converter channels with independent analog outputs are provided.

• D/A converter functions

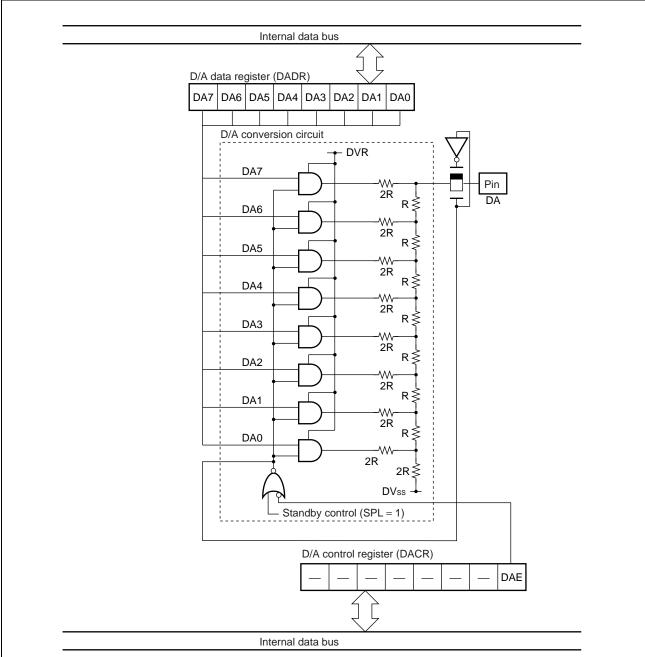
	Function
D/A conversion time	•The settling time is 12.5 μs. This is independent of the machine clock.
Conversion method	R-2R conversion
Resolution	• 8-bit
Analog output pins	Two output pins are provided. Both pins can be used simultaneously.
Interrupts	• None
D/A conversion trigger	Set the digital value in the D/A data register (DADR), then enable D/A output in the D/A control register (DACR) to start analog output from the D/A output pin.
El ² OS support	Not supported by the extended intelligent I/O service (EI²OS) .

• D/A converter theoretical output voltage

D/A Data Register Setting	Theoretical Output Voltage Value
00н	0 / 256 × DVcc voltage (= 0 V)
00н	1 / 256 × DVcc voltage
•••	•••
FEH	254 / 256 × DVcc voltage
FFH	255 / 256 × DVcc voltage

Note: DV $_{\text{CC}}$ voltage: D/A converter reference voltage. This must not exceed V $_{\text{CC}}$. Also, always ensure that DV $_{\text{SS}}$ is equipotential to V $_{\text{SS}}$.

• Block diagram



Standby control : Controls stop mode (SPL = 1) , pseudo-clock mode (SPL = 1) , clock mode (SPL = 1) , and hardware standby mode.

15. Clock Timer

- The clock timer is a 15-bit freerun timer that counts up synchronized with the sub-clock.
- Seven different interval time settings are available.
- This timer provides the clock for the sub-clock's oscillation stabilization delay timer and the watchdog timer.
- This timer always counts the sub-clock, regardless of the settings in the clock selection register (CKSC) .

Clock timer functions

	Function
Interval time	Selectable from the seven settings shown in the table below.
Clock timer size	• 15-bit
Clock supply	Oscillation stabilization delay timer for sub-clock and watchdog timer
Source clock	Sub-oscillation clock divided by four. (SCLK : Sub-clock)
Interrupts	Interval time overflow
EI ² OS support	Not supported by the extended intelligent I/O service (EI²OS) .

Clock timer interval times

Sub-Clock Period	Interval Time
	2º/SCLK (approx. 62.5 ms)
	210/SCLK (approx. 125.0 ms)
	2 ¹¹ /SCLK (approx. 250.0 ms)
SCLK (122 μs)	212/SCLK (approx. 500.0 ms)
	2 ¹³ /SCLK (approx. 1.0 s)
	2 ¹⁴ /SCLK (approx. 2.0 s)
	2 ¹⁶ /SCLK (approx. 4.0 s)

SCLK: Sub-clock frequency

The values enclosed in () are the times for a sub-clock frequency of 8.192 kHz.

Note that the sub-oscillation clock is divided by four to generate the sub-clock frequency. The sub-oscillation clock operates at 32.768 kHz.

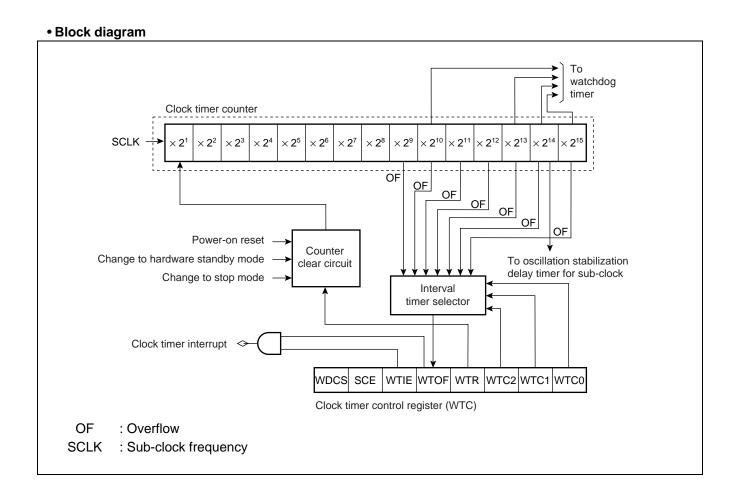
· Clock periods generated by clock timer

Clock Supply	Clock Period
Oscillation stabilization delay timer for sub-clock	2 ¹⁴ /SCLK (approx. 2.0 s)
	210/SCLK (approx. 125.0 ms)
Watahdag timor	213/SCLK (approx. 1.0 s)
Watchdog timer	214/SCLK (approx. 2.0 s)
	216/SCLK (approx. 4.0 s)

SCLK: Sub-clock frequency

The values enclosed in () are the times for a sub-clock frequency of 8.192 kHz.

Note that the sub-oscillation clock is divided by four to generate the sub-clock frequency. The sub-oscillation clock operates at 32.768 kHz.



16. LCD Controller/Driver

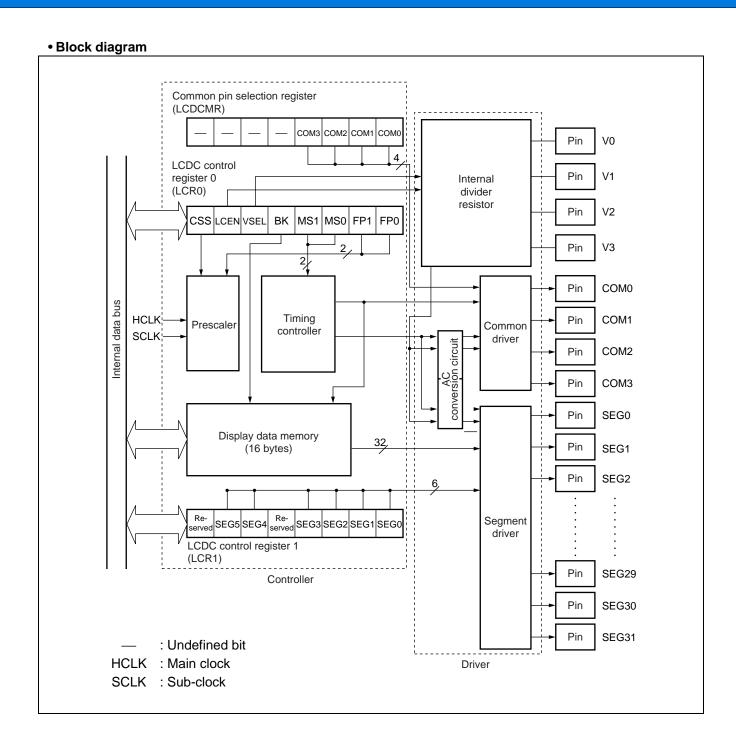
- The LCD controller/driver can drive an LCD (Liquid Crystal Display) directly.
- The LCD is driven by 4 common outputs and 32 segment outputs.
- The output mode can be set to 1/2, 1/3, or 1/4 duty.

• LCD controller/driver functions

	Function
Divider resistor for LCD drive power	$ullet$ Either the internal resistor (approx. 100 k Ω) or an externally connected resistor can be selected.
Common outputs	Max 4 outputs (The corresponding pins cannot be used as I/O ports when using an LCD.)
Segment outputs	Max 32 outputs (of these, 24 pins can be used as I/O ports in blocks of 8 pins.)
Display data memory	16 bytes of RAM for internal display are provided
Duty	• 1/2, 1/3, or 1/4 can be selected.
Bias	• 1/3 only supported
Drive clock	Either the oscillation clock (HCLK) or sub-clock (SCLK) can be used.
Interrupts	• None
El ² OS support	Not supported by the extended intelligent I/O service (EI²OS).

• Bias, duty, and common output combinations

Bias	1/2 Duty Output Mode	1/3 Duty Output Mode	1/4 Duty Output Mode
1/3 bias	COM0 and COM1 outputs	COM0 to COM2 outputs	COM0 to COM3 outputs
170 5100	used	used	used



17. Communications Prescaler

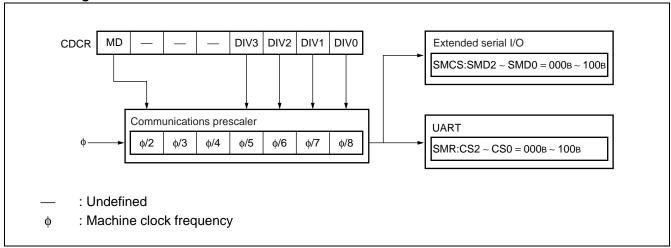
- Supplies the clock to the dedicated baud rate generator used by the UART (SCI) and extended I/O serial interfaces.
- By dividing the machine clock to produce the clock supply to the dedicated baud rate generator, the baud rate can be specified independently of the machine clock speed.
- The communications prescaler can divide the machine clock frequency φ by the following seven ratios to generate the clock supply to the dedicated baud rate generator and extended I/O serial interface : φ/2, φ/3, φ/4, φ/5, φ/6, φ/7, φ/8

• Communications prescaler functions

	Function
Clock supply	Dedicated baud rate generator for the UART (SCI) and the extended I/O serial interface. However, the same clock is supplied to both peripherals.
Divided clock frequency	• φ/2, φ/3, φ/4, φ/5, φ/6, φ/7, φ/8 (φ : Machine clock frequency)
Interrupts	• None
El ² OS support	Not supported by the extended intelligent I/O service (EI²OS) .

Note: As the same output from the communications prescaler is supplied to both the UART (SCI) and the extended I/O serial interface, the transfer clock speed settings must be revised if the communications prescaler settings are changed.

Block diagram



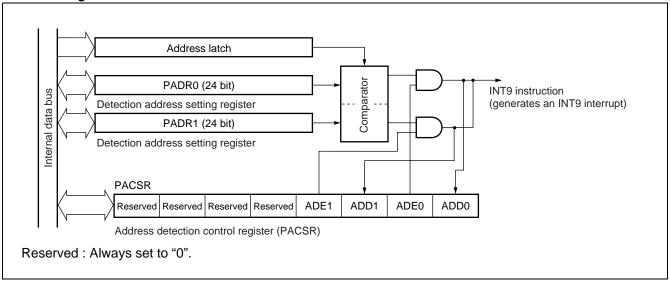
18. Address Match Detection Function

- If the program address during program execution matches the value set in one of the detection address setting
 registers (PADR), the address match detection function replaces the instruction being executed with the INT9
 instruction and executes the interrupt handler program.
- The address match detection function provides a simple method of correcting programming errors (patching) using RAM or similar.

Address match detection functions

	Function
No. of address settings	Two channels (two addresses can be set)
Interrupts	An interrupt is generated when the program address matches the detection address setting register.
El ² OS support	Not supported by the extended intelligent I/O service (EI²OS) .

Block diagram



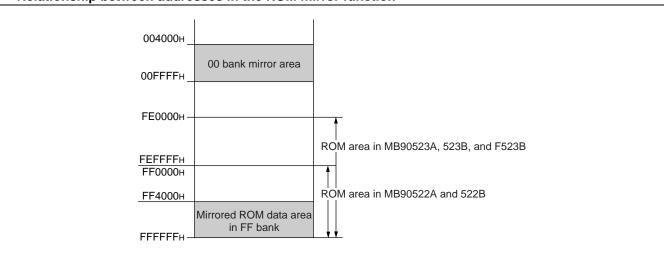
19. ROM Mirror Function Selection Module

The ROM mirror function selection module enables ROM data in FF bank to be read by accessing 00 bank.

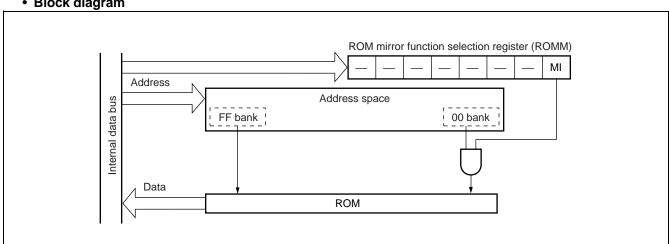
• ROM mirror function selection module functions

	Function	
Mirror setting address	• Data in FFFFFF to FF4000н in FF bank can be read from 00FFFFн to 004000н in 00 bank.	
Interrupts	• None	
El ² OS support	Not supported by the extended intelligent I/O service (EI²OS) .	

• Relationship between addresses in the ROM mirror function



• Block diagram



20. Low Power Consumption (Standby) Modes

The power consumption of $F^2MC-16LX$ devices can be reduced by various settings relating to the operating clock selection.

• Functions of each CPU operation mode

CPU Operation Clock	Operation Mode	Explanation
PLL clock	Normal run	The CPU and peripheral functions operate using the oscillation clock (HCLK) multiplied by the PLL circuit.
	Sleep	The peripheral functions only operate using the oscillation clock (HCLK) multiplied by the PLL circuit.
	Pseudo- clock	The timebase timer only operates using the oscillation clock (HCLK) multiplied by the PLL circuit.
	Stop	The oscillation clock is stopped and the CPU and peripherals halt operation.
Main clock	Normal run	The CPU and peripheral functions operate using the oscillation clock (HCLK) divided by 2.
	Sleep	The peripheral functions only operate using the oscillation clock (HCLK) divided by 2.
	Stop	The oscillation clock is stopped and the CPU and peripherals halt operation.
Sub-clock	Normal run	The CPU and peripheral functions operate using the sub-clock (SCLK) . The oscillation clock stops.
	Sleep	The peripheral functions only operate using the sub-clock (SCLK) . The oscillation clock stops.
	Clock	The clock timer only operates using the sub-clock (SCLK) . The oscillation clock stops.
	Stop	The oscillation clock and sub-clock are stopped and the CPU and peripherals halt operation.
CPU intermittent operation	Normal run	The oscillation clock (HCLK) divided by 2 operates intermittently for fixed time intervals.
Hardware standby	Stop	The oscillation clock and sub-clock are stopped and the CPU and peripherals halt operation.

21. Clock Monitor Function

The clock monitor function outputs the machine clock divided by a specified amount to the clock monitor pin (CKOT).

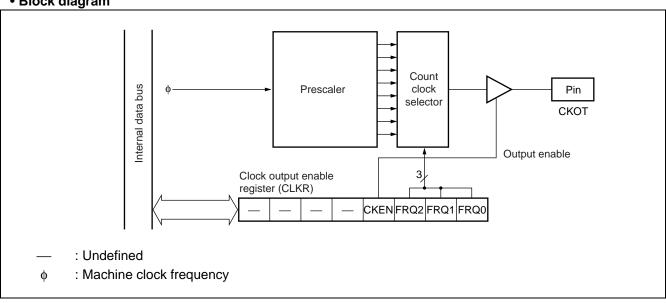
• Clock monitor functions

Function						
Output frequency	Machine clock divided by 2 to 32 (8 settings available)					
Interrupts	• None					
El ² OS support	Not supported by the extended intelligent I/O service (EI²OS) .					

• Output frequency of the clock monitor function

FRQ2 - 0	Machine Clock	When φ = 16 MHz		When ϕ	= 8 MHz	When φ = 4 MHz		
Bits	Divide Ratio	Period	Frequency	Period	Frequency	Period	Frequency	
000в	φ/21	125 ns	8 MHz	250 ns	4 MHz	500 ns	2 MHz	
001в	φ/ 2 ²	250 ns	4 MHz	500 ns	2 MHz	1.0 μs	1 MHz	
010в	φ/2³	500 ns	2 MHz	1.0 μs	1 MHz	2.0 μs	500 kHz	
011в	φ/24	1.0 μs	1 MHz	2.0 μs	500 kHz	4.0 μs	250 kHz	
100в	φ/25	2.0 μs	500 kHz	4.0 μs	250 kHz	8.0 μs	125 kHz	
101в	φ/26	4.0 μs	250 kHz	8.0 μs	125 kHz	16.0 μs	62.5 kHz	
110в	φ/2 ⁷	8.0 μs	125 kHz	16.0 μs	62.5 kHz	32.0 μs	31.25 kHz	
111в	φ/28	16.0 μs	62.5 kHz	32.0 μs	31.25 kHz	64.0 μs	15.625 kHz	

• Block diagram



22. 1 Mbit Flash Memory

- This section describes the flash memory on the MB90F523B and does not apply to evaluation products and MASK ROM versions.
- The flash memory is located in banks FE to FF in the CPU memory map.

• Flash memory functions

	Function
Memory size	• 1 Mbit (128 KBytes)
Memory configuration	• 128 KWords × 8 bits or 64 KWords × 16 bits
Sector configuration	• 16 KBytes + 8 KBytes + 8 KBytes + 32 KBytes + 64 KBytes
Sector protect function	Selectable for each sector
Programming algorithm	Automatic programming algorithm (Embedded Algorithm*: Equivalent to MBM29F400TA)
Operation commands	 Compatible with JEDEC standard commands Includes an erase pause and restart function Data polling and toggle bit write/erase completion Erasing by sector available (sectors can be combined in any combination)
No. of write/erase cycles	Min 10,000 guaranteed
Memory write/erase method	 Can be written and erased using a parallel writer (Minato Electronics model 1890A, Ando Denki AF9704, AF9705, AF9706, AF9708, and AF9709) Can be written and erased using a dedicated serial writer (YDC AF200, AF210, AF120, and AF110) Can be written and erased by the program
Interrupts	Write and erase completion interrupts
El ² OS support	Not supported by the extended intelligent I/O service (EI²OS) .

^{*:} Embedded Algorithm is a trademark of Advanced Micro Devices.

Sector configuration of flash memory

Flash memory	CPU address	Writer address*
CAO (CA Kh. +=)	FE0000н	60000н
SA0 (64 Kbyte)	FEFFFH	6FFFFH
SA1 (32 Kbyte)	FF0000H	70000н
SAT (32 Rbyle)	FF7FFFH	і 77FFFн
SA2 (8 Kbyte)	FF8000H	78000н
SAZ (6 KDyte)	FF9FFFH	_ 79FFFн
CA2 (0 Khyta)	FFA000H	¦ 7А000н
SA3 (8 Kbyte)	FFBFFFH	, 7BFFFн
0.0.4 (4.0.16)	FFC000H	7C000н
SA4 (16 Kbyte)	FEFFFFH	7FFFFH

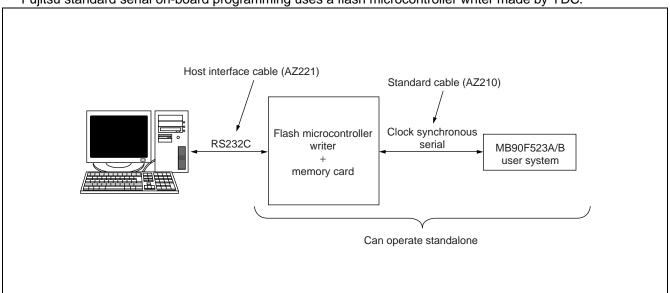
^{*:} The writer address is the address to use instead of the CPU address when writing data from a parallel flash memory writer. Use the writer address when programming or erasing using a general-purpose parallel writer.

• Pins used for Fujitsu standard serial on-board programming

Pin	Function	Explanation
MD2, MD1, MD0	Mode pins	Setting $MD2 = MD1 = 1$, $MD0 = 0$ selects flash memory serial programming mode.
X0, X1	Oscillation input pin	Flash memory serial programming mode uses the PLL clock with the multiplier set to 1 as the machine clock. Set the oscillation frequency used for serial programming to between 3 MHz and 16 MHz.
P00, P01	Write program activation pins	Input P00 = 0 ("L" level) and P01 = 1 ("H" level)
RST	Reset pin	_
HST	Hardware standby pin	Input an "H" level during flash memory serial programming mode.
SIN0	Serial data input pin	
SOT0	Serial data output pin	Uses the UART (SCI) in clock synchronous mode.
SCK0	Serial clock input pin	
С	C pin	Capacitor pin for power supply stabilization. Connect an external capacitor of approx. 0.1 $\mu\text{F}.$
Vcc	Power supply voltage pins	If the user system can provide the programming voltage (5 V \pm 10%) , do not need to connect to the flash microcontroller writer.
Vss	GND pin	Connect to common GND with the flash microcontroller writer.

Overall configuration of connection between serial writer and MB90F523A

Fujitsu standard serial on-board programming uses a flash microcontroller writer made by YDC.



Note: Contact YDC for details of the functions and operation of the flash microcontroller writer (AF220, AF210, AF120, or AF110), standard connection cable (AZ210), and connectors.

■ Electrical Characteristics\

1. Absolute Maximum Ratings

(Vss = AVss = 0.0 V)

Parameter	Symbol	Rat	ting	Unit	Remarks
raiailletei	Зуппоп	Min	Max	Oilit	Remarks
	Vcc	Vss - 0.3	Vss + 6.0	V	
	AVcc	Vss - 0.3	Vss + 6.0	V	*1
Power supply voltage	AVRH, AVRL	Vss - 0.3	Vss + 6.0	V	*1
	DVcc	Vss - 0.3	Vss + 6.0	V	*2
Input voltage	Vı	Vss - 0.3	Vss + 6.0	V	*3
Output voltage	Vo	Vss - 0.3	Vss + 6.0	V	*3
"L" level maximum output current	lol	_	15	mA	*4
"L" level average output current	lolav	_	4	mA	*5
"L" level total maximum output current	Σ loL	_	100	mA	
"L" level total average output current	Σ lolav	_	50	mA	*6
"H" level maximum output current	Іон	_	-15	mA	*4
"H" level average output current	І онаv	_	-4	mA	*5
"H" level total maximum output current	ΣІон	_	-100	mA	
"H" level total average output current	Σ lohav	_	-50	mA	*6
Power consumption	Pd		400	mW	MB90522A/523A/ F523B
			300	mW	MB90522B/523B
Operating temperature	Та	-40	+85	°C	
Storage temperature	Tstg	- 55	+150	°C	

^{*1 :} AVcc, AVRH, AVRL, and DVcc shall never exceed Vcc . AVRH and AVRL shall never exceed AVcc. Also, AVRL shall never exceed AVRH.

Note : Average output current = operating current \times operating ratio

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

^{*2 :} $Vcc \ge AVcc \ge DVcc \ge 3.0 \text{ V}.$

^{*3 :} V_1 and V_2 shall never exceed $V_{CC} + 0.3 V$.

^{*4 :} The maximum output current is the peak value for a single pin.

^{*5 :} The average output current is the average current value for a single pin during a 100 ms period.

^{*6:} The total average current is the average current for all pins during a 100 ms period.

2. Recommended Operating Conditions

(Vss = AVss = 0.0 V)

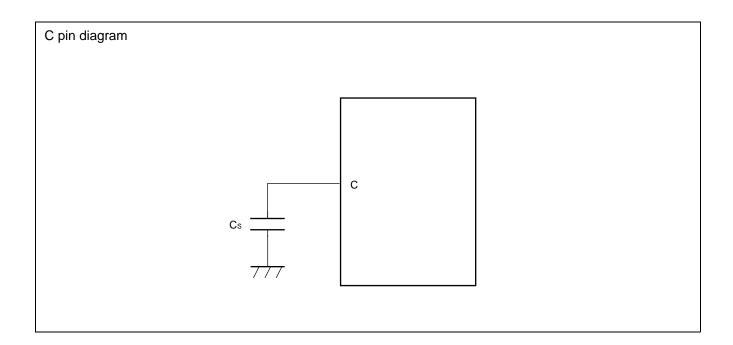
Parameter	Symbol	Va	lue	Unit	Remarks
raiailletei	Symbol	Min	Max	Oille	Kemarks
Power supply voltage	Vcc	3.0	5.5	V	
Smoothing capacitor	Cs	0.1	1.0	μF	
Operating temperature	Та	-40	+85	°C	

Note: Use a ceramic capacitor or other capacitor with equivalent frequency characteristics. The capacitance of the smoothing capacitor connected to the Vcc pin must be greater than Cs.

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representatives beforehand.



3. DC Characteristics

(AVcc = Vcc = 5.0 V \pm 10%, AVss = Vss = DVss = 0.0 V, Ta = -40 °C to +85 °C)

Dovemeter	Sym-	<u> </u>	Candition	,	Value	·		
Parameter	bol	Pin Name	Condition	Min	Тур	Max	Unit	Remarks
"H" level input voltage	Vihs	P20 to P27, P30 to P37, P53, P54, P70 to P77, P80 to P87, PA0 to PA7		0.8 Vcc	_	Vcc + 0.3	V	
	Vінм	MD0 to MD2	Vcc = 3.0 V to 5.5 V	Vcc - 0.3	_	Vcc + 0.3	V	
"L" level input voltage	VILS	P20 to P27, P30 to P37, P53, P54, P70 to P77, P80 to P87, PA0 to PA7	vcc = 3.0 v to 5.3 v	Vss - 0.3	_	0.2 Vcc	V	
	VILM	MD0 to MD2		Vss - 0.3		Vss + 0.3	V	
"H" level output voltage	Vон	All output pins other than P90 to P97	$V_{CC} = 4.5 \text{ V}$ $I_{OH} = -2.0 \text{ mA}$	Vcc - 0.5	_	_	V	
"L" level output voltage	Vol	All output pins	Vcc = 4.5 V IoL = 2.0 mA	_		0.4	V	
Input leak current	lι∟	All output pins other than P90 to P97	Vcc = 5.5 V Vss < Vı < Vcc	- 5	_	5	μА	
Open-drain output leak current	leak	P90 to P97 output pins	_	_	0.1	5	μА	
Pull-up resistor	Rup	P00 to P07, P10 to P17 P40 to P47, MD0, MD1	_	50	100	200	kΩ	
Pull-down resistor	RDOWN	MD2		50	100	200	kΩ	
Damas area			For Vcc = 5 V,	_	40	65	mA	MB90522A/ 523A
Power supply current*	Icc	Vcc	internal frequency = 16 MHz,		30	60	mA	MB90F523B
			normal operation		30	40	mA	MB90522B/ 523B

(Continued)

(AVcc = Vcc = 5.0 V \pm 10%, AVss = Vss = DVss = 0.0 V, Ta = -40 °C to +85 °C)

Deversates	Sym-	Din Name	Condition		Value	112	Domostko	
Parameter	bol	Pin Name	Condition	Min	Тур	Max	Unit	Remarks
			For Vcc = 5 V,		20	25	mA	MB90522A/ 523A
			internal frequency = 8 MHz,	_	15	20	mA	MB90F523B
			normal operation		15	20	mA	MB90522B/ 523B
			For Vcc = 5 V, internal frequency		50	70	mA	MB90522A/ 523A
			= 16 MHz,	_	45	65	mA	MB90F523B
			A/D operation in progress		35	45	mA	MB90522B/ 523B
			For Vcc = 5 V, internal frequency	_	25	30	mA	MB90522A/ 523A
			= 8 MHz,	_	20	25	mA	MB90F523B
	Icc	Vcc	A/D operation in progress	_	20	25	mA	MB90522B/ 523B
			For Vcc = 5 V, internal frequency = 16 MHz, D/A operation in progress For Vcc = 5 V, internal frequency = 8 MHz,	_	55	70	mA	MB90522A/ 523A
				_	50	70	mA	MB90F523B
Power supply current*				_	40	50	mA	MB90522B/ 523B
Current				_	30	35	mA	MB90522A/ 523A
				_	25	30	mA	MB90F523B
			D/A operation in progress		20	25	mA	MB90522B/ 523B
			Writing or erasing flash memory	_	50	75	mA	MB90F523B
			For Vcc = 5 V, internal frequency	_	8	15	mA	MB90522A/ 523A
	Iccs		= 16 MHz, sleep mode	_	15	20	mA	MB90F523B /522B/523B
	ICCS		For Vcc = 5 V, internal frequency	_	7	10	mA	MB90522A/ 523A
			= 8 MHz, sleep mode		12	18	mA	MB90F523B /522B/523B
	Iccl	,			0.1	1.0	mA	MB90522A/ 523A/522B/ 523B
			sub-clock mode, Ta = 25 °C	_	4	7	mA	MB90F523B

(Continued)

(Continued)

(AVcc = Vcc = $5.0 \text{ V} \pm 10\%$, AVss = Vss = DVss = 0.0 V, Ta = -40 °C to +85 °C)

Parameter	Sym-	Pin Name	Condition		Value		Unit	Remarks
Parameter	bol	Pin Name	Condition	Min	Тур	Max	Unit	Remarks
Power supply current	Iccls		For Vcc = 5 V, internal frequency = 8 kHz, sub-sleep mode, Ta = 25 °C	_	30	50	μА	
	Ісст	Vcc	For Vcc = 5 V, internal frequency = 8 kHz, clock mode, Ta = 25 °C	_	15	30	μΑ	
	Іссн		Sleep mode, Ta = 25 °C	_	5	20	μΑ	
Input capacitance	Cin	Other than AVcc, AVss, C, Vcc, and Vss		_	10	80	pF	
LCD divider resistor	RLCD	V0 – V1, V1 – V2, V2 – V3		50	100	200	kΩ	
Output impedance for COM0 to COM3	Rvcом	COM0 to COM3	V1 to V3 = 5.0 V	_		2.5	kΩ	
Output impedance for SEG00 to SEG31	Rvseg	SEG00 to SEG31	V 1 10 V 3 = 3.0 V	_		15	kΩ	
LCDC leak current	ILEDE	V0 to V3, COM0 to COM3, SEG00 to SEG31	_	_	_	±5	μΑ	

^{*:} Current values are provisional and are subject to change without notice to allow for improvements to the characteristics. The power supply current is measured with an external clock.

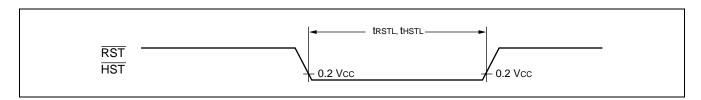
4. AC Characteristics

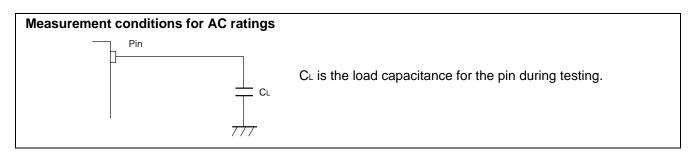
(1) Reset and Hardware Standby Input Timings

 $(AVcc = Vcc = 5.0 \text{ V} \pm 10\%, AVss = Vss = DVss = 0.0 \text{ V}, Ta = -40 ^{\circ}\text{C to} +85 ^{\circ}\text{C})$

Parameter	Symbol	Symbol Pin		Value		Unit	Remarks
i arameter	Symbol	Name	Condition	Min	Тур	Oilit	itema ks
Reset input time	t RSTL	RST		4 t cp*	_	ns	
Hardware standby input time	t HSTL	HST		4 t cp*	_	ns	

^{*:} See "(3) Clock Timings" for more information about tcp (internal operating clock cycle time).





(2) Power-On Reset

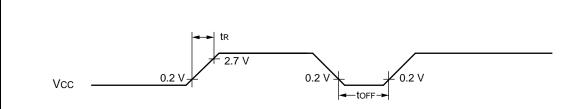
 $(AVcc = Vcc = 5.0 \text{ V} \pm 10\%, AVss = Vss = DVss = 0.0 \text{ V}, Ta = -40 ^{\circ}\text{C to} +85 ^{\circ}\text{C})$

Parameter	Symbol	Pin	Condi-	Value		Unit	Remarks
raiailletei	Syllibol	Name	tion	Min	Тур	Oilit	ixemarks
Power supply rise time	t R	Vcc		0.05	30	ms	*
Power supply cutoff time	t off	Vcc		4		ms	For repeated operation

^{*:} Vcc must be less than 0.2 V before power-on.

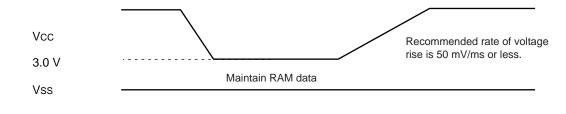
Notes: • The above rating values are for generating a power-on reset.

- When HST = "L", always apply the power supply in accordance with the above ratings regardless of whether a power-on reset is required.
- Some internal registers are only initialized by a power-on reset. Always apply the power supply in cordance with the above ratings if you wish to initialize these registers.



Sudden changes in the power supply voltage may cause a power-on reset.

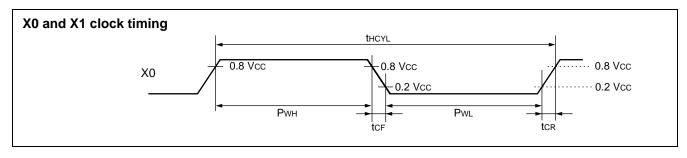
The recommended practice if you wish to change the power supply voltage while the device is operating is to raise the voltage smoothly as shown below. Also, changes to the supply voltage should be performed when the PLL clock is not in use. The PLL clock may be used, however, if the rate of voltage change is 1 V/s or less.

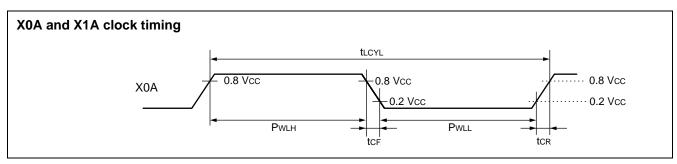


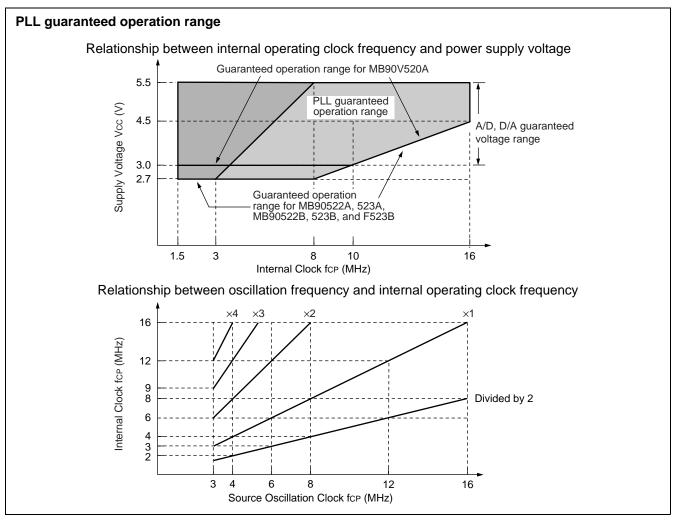
(3) Clock Timings

(AVcc = Vcc = $5.0 \text{ V} \pm 10\%$, AVss = Vss = DVss = 0.0 V, Ta = -40 °C to +85 °C)

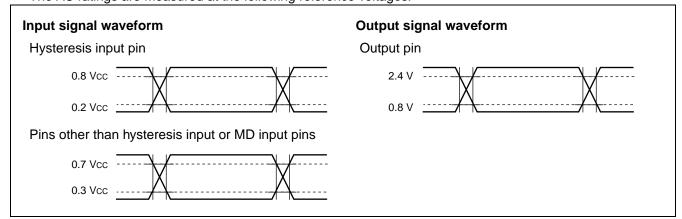
Parameter	Sym-	Pin	Condi-		Value		Unit	Remarks
Parameter	bol	Name	tion	Min	Тур	Max	Offic	Remarks
Clock frequency	Fc	X0, X1	_	3		16	MHz	
Clock frequency	FcL	X0A, X1A		_	32.768	_	kHz	
Clock cycle time	thcyl	X0, X1	_	62.5		333	ns	
Clock cycle time	t LCYL	X0A, X1A	_	_	30.5	_	μs	
long to along the suidth	Pwh PwL	X0		10	_		ns	Recommended duty
Input clock pulse width	Pwlh Pwll	X0A		_	15.2	_	μs	ratio = 30% to 70%
Input clock rise/fall time	tcr tcr	X0		_	_	5	ns	When using an external clock
Internal operating	fср	_	_	1.5	_	16	MHz	When using main clock
clock frequency	fLCP	_	_	_	8.192	_	kHz	When using sub-clock
Internal operating	t CP	_	_	62.5	_	666	ns	When using main clock
clock cycle time	tLCP	_			122.1		μs	When using sub-clock







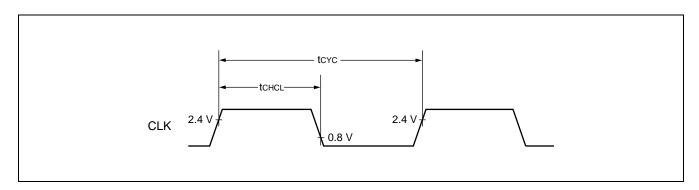
The AC ratings are measured at the following reference voltages.



(4) Clock Output Timings

(AVcc = Vcc = 5.0 V \pm 10%, AVss = Vss = DVss = 0.0 V, Ta = -40 °C to +85 °C)

Parameter	Symbol	Pin	Condition	Va	lue	Unit	Remarks
raiametei	Symbol	Name	Condition	Min	Тур		iveillai ka
Cycle time	t cyc	CLK	$Vcc = 5.0 V \pm 10\%$	62.5	_	ns	
$CLK \uparrow \to CLK \downarrow$	t chcl	CLK		20	_	ns	



(5) UART (SCI) Timings

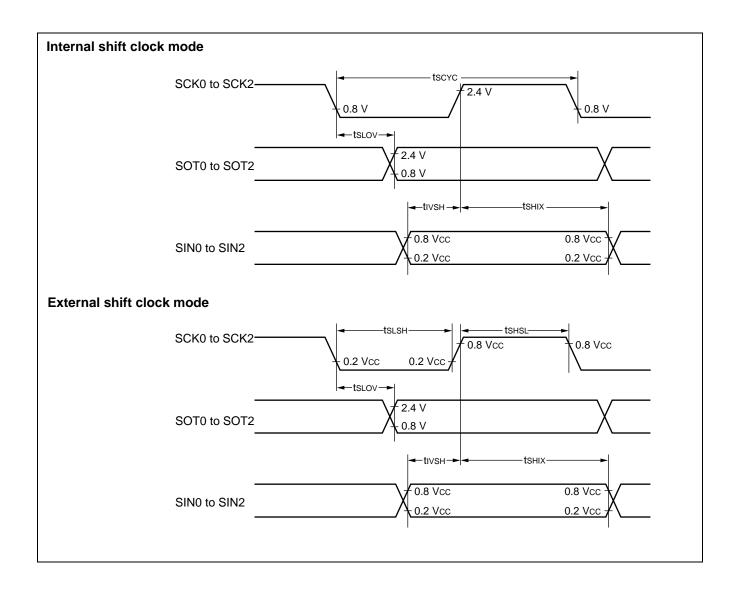
(AVcc = Vcc = $5.0 \text{ V} \pm 10\%$, AVss = Vss = DVss = 0.0 V, Ta = -40 °C to +85 °C)

Parameter	Sym- Pin Name		Condition	Value		Unit	Re-
raiailletei	bol	Fill Name	Condition	Min Typ		Ollic	marks
Serial clock cycle time	tscyc	SCK0 to SCK2		8 t cp*	_	ns	
$SCK \downarrow \to SOT$ delay time	t sLov	SCK0 to SCK2 SOT0 to SOT2	Internal shift clock mode, output pin	-80	80	ns	
$Valid\;SIN\toSCK\;\!\!\uparrow$	t ıvsh	SCK0 to SCK2 SIN0 to SIN2	load is C _L = 80 pF + 1 TTL	100	_	ns	
$SCK \uparrow \to valid SIN hold time$	t shix	SCK0 to SCK2 SIN0 to SIN2		60	_	ns	
Serial clock "H" pulse width	tshsl	SCK0 to SCK2		4 t cp*	_	ns	
Serial clock "L" pulse width	t slsh	SCK0 to SCK2		4 t cp*	_	ns	
$SCK \downarrow \to SOT$ delay time	t sLov	SCK0 to SCK2 SOT0 to SOT2	External shift clock mode, output pin	_	150	ns	
Valid SIN → SCK ↑	t ıvsh	SCK0 to SCK2 SIN0 to SIN2	load is C _L = 80 pF + 1 TTL	60		ns	
$SCK \uparrow \rightarrow valid SIN hold time$	t sнıx	SCK0 to SCK2 SIN0 to SIN2		60	_	ns	

^{*:} See "(3) Clock Timings" for more information about tcp (internal operating clock cycle time).

Notes: • These are the AC ratings for CLK synchronous mode.

 \bullet $C_{\text{\tiny L}}$ is the load capacitor connected to the pin for testing.

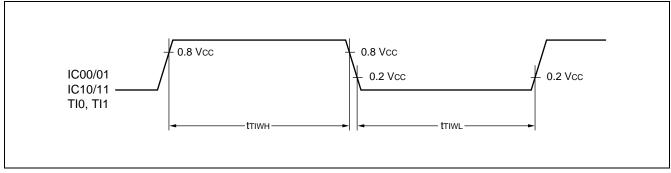


(6) Timer Input Timings

(AVcc = Vcc = $5.0 \text{ V} \pm 10\%$, AVss = Vss = DVss = 0.0 V, Ta = -40 °C to +85 °C)

Parameter	Symbol Pin Name Condition		Va	lue	Unit	Remarks	
raiailletei	Symbol	riii Naiile	Condition	Min	Тур	Oilit	Nemarks
Input pulse width	t тıwн t тıwL	IC00/01, IC10/11 TI0, TI1	_	4 tcp*	_	ns	

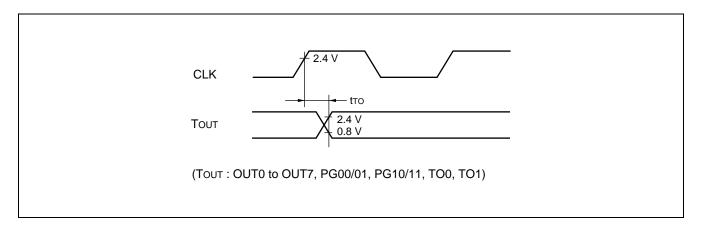
*: See "(3) Clock Timings" for more information about tcp (internal operating clock cycle time).



(7) Timer Output Timings

(AVcc = Vcc = $5.0 \text{ V} \pm 10\%$, AVss = Vss = DVss = 0.0 V, Ta = -40 °C to +85 °C)

Parameter	Symbol Pin Name		Condition	Val	lue	Unit	Remarks
Farameter	Syllibol	Fili Name	Condition	Min	Тур	Oilit	iveillai ks
CLK ↑ → То∪т change time	tто	OUT0 to OUT7 PG00/01 PG10/11 TO0, TO1	_	30	_	ns	



5. Electrical Characteristics for the A/D Converter

(AVcc = Vcc = $5.0 \text{ V} \pm 10\%$, AVss = Vss = DVss = 0.0 V, $3.0 \text{ V} \le \text{AVRH} - \text{AVRL}$, Ta = $-40 \,^{\circ}\text{C}$ to $+85 \,^{\circ}\text{C}$)

Doromotor	Sym-	Pin Name		Value	Unit	Remarks	
Parameter	bol	Pin Name	Min	Тур	Max	Unit	Remarks
Resolution	_	_	_	8/10	_	bit	
Total error	_	_	_	_	±5.0	LSB	
Linearity error	_	_	_	_	±2.5	LSB	
Differential linearity error	_	_	_	_	±1.9	LSB	
Zero transition voltage	Vот	AN0 to AN7	AVss - 3.5 LSB	AVss + 0.5 LSB	AVss + 4.5 LSB	mV	
Full-scale transition voltage	V _{FST}	AN0 to AN7	AVRH - 6.5 LSB	AVRH – 1.5 LSB	AVRH + 1.5 LSB	mV	
A/D conversion time		_	163 tcp	_	_	ns	At machine clock = 16 MHz
Compare time		_	99 tcp	_	_	ns	At machine clock = 16 MHz
Analog port input current	Iain	AN0 to AN7	_	_	10	μΑ	
Analog input voltage	Vain	AN0 to AN7	AVRL	_	AVRH	V	
Reference voltage	_	AVRH	AVRL + 3.0	_	AVcc	V	
Neierence voltage		AVRL	0		AVRH – 3.0	V	
Power supply current	lΑ	AVcc	_	5	_	mA	
Tower supply current	Іан	AVcc	_		5	μΑ	*
Reference voltage supply	lR	AVRH	_	400	_	μΑ	
current	IRH	AVRH			5	μΑ	*
Variation between channels		AN0 to AN7	_	_	4	LSB	

^{* :} Current when 8/10-bit A/D converter not used and CPU in stop mode (Vcc = AVcc = AVRH = 5.0 V)

Note: See "(3) Clock Timings" in "4. AC Ratings" for more information about tcp (internal operating clock cycle time).

6. A/D Converter Glossary

Resolution : The change in analog voltage that can be recognized by the A/D converter.

Linearity error : The deviation between the actual conversion characteristics and the line linking the

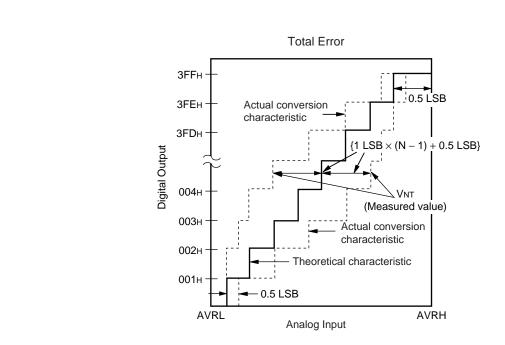
zero transition point ("00 0000 0000 $^{\circ}$ " \longleftrightarrow "00 0000 0001 $^{\circ}$ ") and the full scale transi-

tion point ("11 1111 1110 $_B$ " \longleftrightarrow "11 1111 1111 $_B$ ").

Differential linearity error: The variation from the ideal input voltage required to change the output code by 1 LSB.

Total error : The total error is the difference between the actual value and the theoretical value.

This includes the zero-transition error, full-scale transition error, and linearity error.



1 LSB = (Theoretical value)
$$\frac{AVRH - AVRL}{1024^{\circ}}$$
 [V]

Total error for digital output N =
$$\frac{V_{NT} - \{1 \text{ LSB} \times (N-1) + 0.5 \text{ LSB}\}}{1 \text{ LSB}}$$
 [LSB]

Vot (Theoretical value) = AVRL + 0.5 LSB [V]

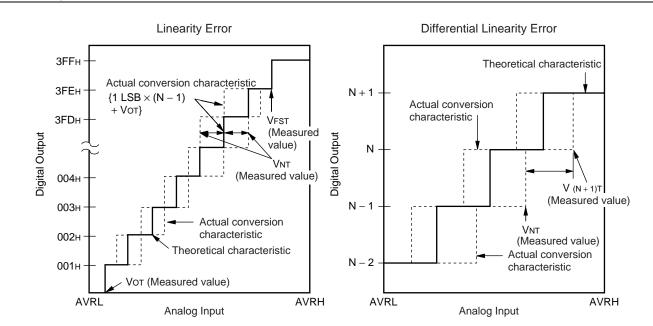
V_{FST} (Theoretical value) = AVRH - 1.5 LSB [V]

 V_{NT} : Voltage at which digital output changes from (N-1) to N

*: For 10-bit resolution, this value is 1024 (210). For 8-bit resolution, this value is 256 (28).

(Continued)





 $\label{eq:linearity} \text{Linearity error for digital output N = } \frac{V_{\text{NT}} - \{1 \text{ LSB} \times (\text{N} - 1) + V_{\text{OT}}\}}{1 \text{ LSB}} \text{ [LSB]}$

Differential linearity error for digital output N = $\frac{V(N+1)T-VNT}{1LSB}$ - 1 LSB [LSB]

$$1 LSB = \frac{V_{FST} - V_{OT}}{1022^*} [V]$$

Vot : Voltage at which digital output changes from "000H" to "001H" VFST : Voltage at which digital output changes from "3FEH" to "3FFH"

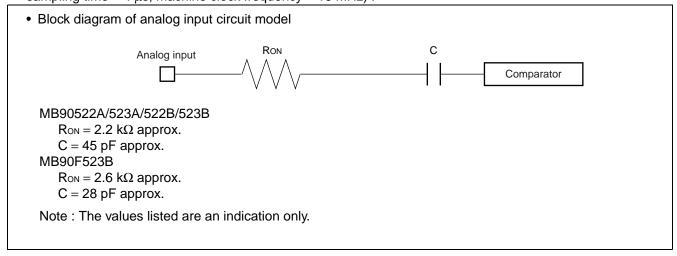
*: For 10-bit resolution, this value is $1022 (2^{10} - 2)$. For 8-bit resolution, this value is $254 (2^8 - 2)$.

7. Notes for A/D Conversion

The recommended external circuit impedance of analog inputs for MB90V520 is approximately 5 k Ω or less, that for MB90F523B is approximately 15.5 k Ω or less, and that for MB90522A/523A/522B/523B is approximately 10 k Ω or less.

If using an external capacitor, the capacitance should be several thousand times the level of the chip's internal capacitor to allow for the partial potential between the external and internal capacitance.

If the impedance of the external circuit is too high, the analog voltage sampling interval may be too short. (for sampling time = $4 \mu s$, machine clock frequency = 16 MHz).



• Error

The relative error increases as |AVRH – AVRL| becomes smaller.

8. Electrical Characteristics for the D/A Converter

(AVcc = Vcc = 5.0 V \pm 10%, AVss = Vss = DVss = 0.0 V, Ta = -40 °C to +85 °C)

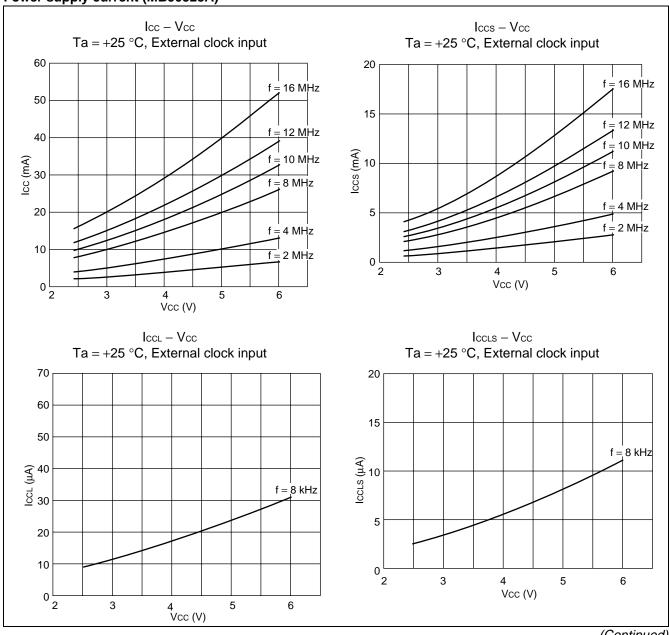
Parameter	Symbol	Pin		Value		Unit	Remarks
Farameter	Syllibol	Name	Min	Тур	Max	Offic	iveillai ks
Resolution	_		_	8	_	bit	
Differential linearity error	_		_	_	±0.9	LSB	
Absolute accuracy			_	_	±1.2	%	
Linearity error			_	_	±1.5	LSB	
Conversion time	_	_	_	10	20	μs	For load capacitance = 20 pF
Analog reference voltage	_	DVcc	Vss + 3.0	_	AVcc	V	
Current consumption for	I DVR	DVcc	_	120	300	μΑ	
reference voltage	Idvrs	DVCC	_	_	10	μΑ	Stop mode
Analog output impedance	_	_	_	20	_	kΩ	

9. Flash Memory Program/Erase

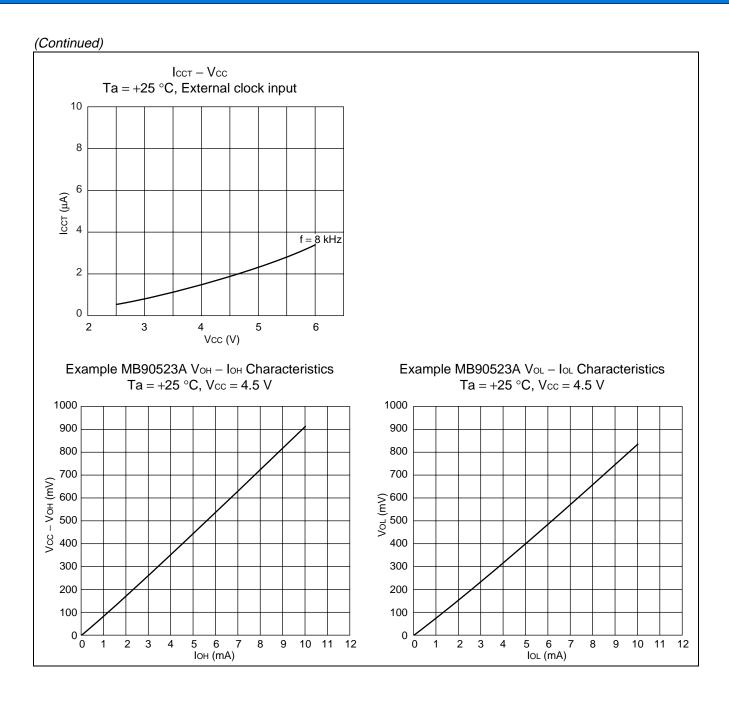
Parameter	r Condition Value Un		Unit	Remarks		
raiametei	Condition	Min	Тур	Max	Offic	iveillai ka
Sector erase time			1	15	s	Excludes 00H programming prior erasure
Chip erase time	Ta = + 25 °C Vcc = 5.0 V		5		S	Excludes 00H programming prior erasure
Word (16-bit width) programming time			16	3,600	μs	Excludes system-level overhead
Program/Erase cycle	_	10,000	_	_	cycle	
Data hold time	_	100 K	_		h	

■ EXAMPLE CHARACTERISTICS

Power supply current (MB90523A)



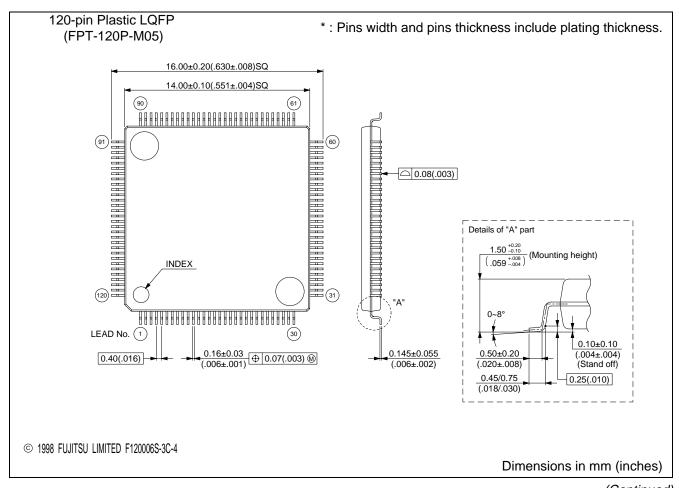
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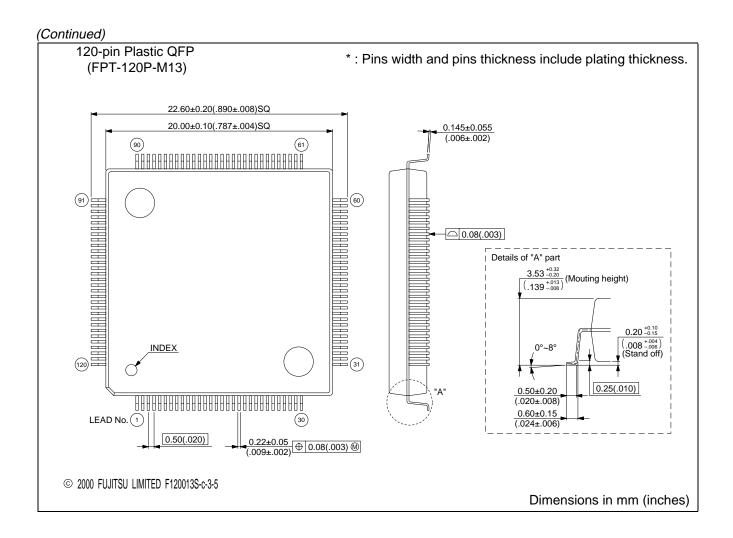
■ ORDERING INFORMATION

Part No.	Package	Remarks
MB90522APFF MB90523APFF MB90522BPFF MB90F523BPFF	120-pin, Plastic LQFP (FPT-120P-M05)	
MB90522APFV MB90523APFV MB90522BPFV MB90F523BPFV	120-pin, Plastic QFP (FPT-120P-M13)	

■ PACKAGE DIMENSIONS



(Continued)



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