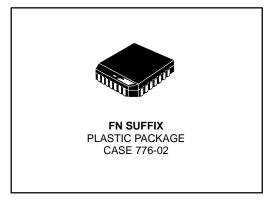
# 3-Bit Scannable Registered Bus Transceiver

The MC10E/100E337 is a 3-bit registered bus transceiver with scan. The bus outputs (BUS0–BUS2) are specified for driving a  $25\Omega$  bus; the receive outputs (Q0 – Q2) are specified for  $50\Omega$ . The bus outputs feature a normal HIGH level (VOH) and a cutoff LOW level — when LOW, the outputs go to – 2.0V and the output emitter-follower is "off", presenting a high impedance to the bus. The bus outputs also feature edge slow-down capacitors.

- Scannable Version of E336
- 25Ω Cutoff Bus Outputs
- 50Ω Receiver Outputs
- Scannable Registers
- · Sync. and Async. Bus Enables
- Non-inverting Data Path
- 1500ps Max. Clock to Bus (Data Transmit)
- 1000ps Max. Clock to Q (Data Receive)
- Bus Outputs Feature Internal Edge Slow-Down Capacitors
- Additional Package Ground Pins
- Extended 100E V<sub>EE</sub> Range of 4.2V to 5.46V
- 75kΩ Input Pulldown Resistors

## MC10E337 MC100E337

3-BIT SCANNABLE REGISTERED BUS TRANSCEIVER



Both drive and receive sides feature the same logic, including a loopback path to hold data. The HOLD/LOAD function is controlled by Transmit Enable (TEN) and Receive Enable (REN) on the transmit and receive sides respectively, with a HIGH selecting LOAD. Note that the implementation of the E337 Receive Enable differs from that of the E336.

A synchronous bus enable (SBUSEN) is provided for normal, non-scan operation. The asynchronous bus disable (ABUSDIS) disables the bus immediately for scan mode.

The SYNCEN input is provided for flexibility when re-enabling the bus after disabling with ABUSDIS, allowing either <u>synchron</u>ous or asynchronous re-enabling. An alternative use is asynchronous-only operation with ABUSDIS, in which case SYNCEN is tied LOW, or left open. SYNCEN is implemented as an overriding SET control (active-LOW) to the enable flip-flop.

Scan mode is selected by a HIGH at the SCAN input. Scan input data is shifted in through S\_IN and output data appears at the Q2 output.

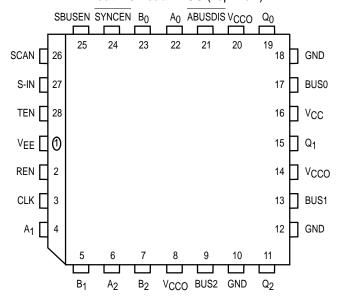
All registers are clocked on the positive transition of CLK. Additional lead-frame grounding is provided through the Ground pins (GND) which should be connected to 0V. The GND pins are not electrically connected to the chip.

#### **PIN NAMES**

Pin	Function							
A <sub>0</sub> – A <sub>2</sub>	Data Inputs A							
$B_0 - B_2$	Data Inputs B							
S-IN	Serial (Scan) Data Input							
TEN, REN	HOLD/LOAD Controls							
SCAN	Scan Control							
ABUSDIS	Asynchronous Bus Disable							
SBUSEN	Synchronous Bus Enable							
SYNCEN	Synchronous Enable Control							
CLK	Clock							
BUS0 - BUS2	25 $\Omega$ Cutoff Bus Outputs							
$Q_0 - Q_2$	Receive Data Outputs (Q2 serves as SCAN_OUT in scan mode)							

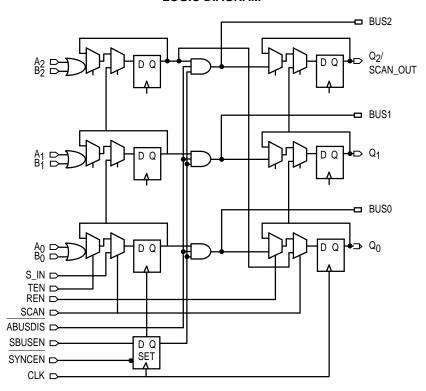


#### Pinout: 28-Lead PLCC (Top View)



 $^{\star}$  All VCC and VCCO pins are tied together on the die.

#### **LOGIC DIAGRAM**



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### **DC CHARACTERISTICS** (VEE = VEE(min) to VEE(max); VCC = VCCO = GND)

		0°C		25°C			85°C					
Symbol	Characteristic	min	typ	max	min	typ	max	min	typ	max	Unit	Condition
VCUT	Cut-off Output Voltage1	- 2.10		- 2.03	- 2.10		- 2.03	- 2.10		- 2.03	V	
lін	Input HIGH Current All Other Inputs			150			150			150	μΑ	
IEE	Power Supply Current 10E 100E		145 145	174 174		145 145	174 174		145 167	174 200	mA	

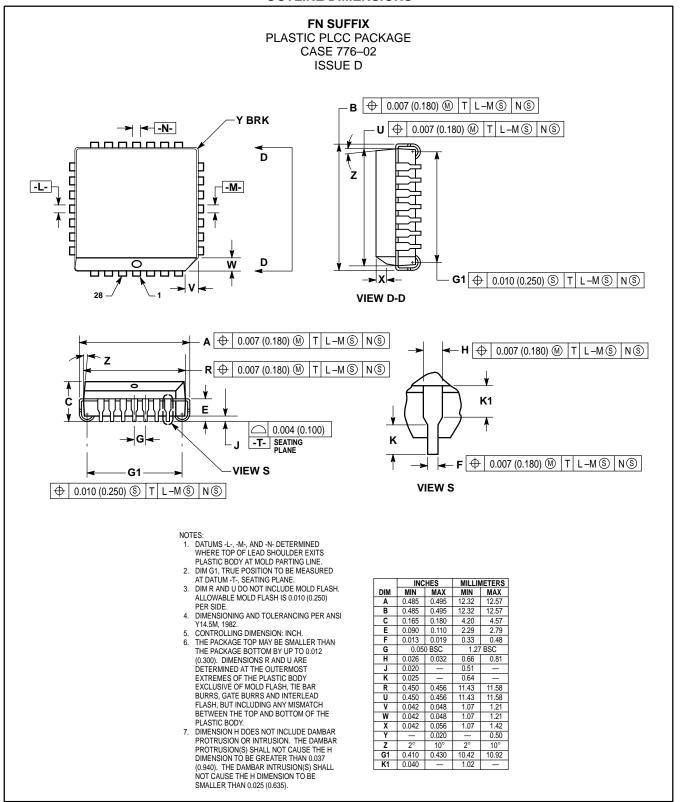
<sup>1.</sup> measured with  $V_{TT} = -2.10V$ 

## **AC CHARACTERISTICS** ( $V_{EE} = V_{EE}(min)$ to $V_{EE}(max)$ ; $V_{CC} = V_{CCO} = GND$ )

		0°C		25°C			85°C					
Symbol	Characteristic	min	typ	max	min	typ	max	min	typ	max	Unit	Condition
tPLH	Propagation Delay to Output										ps	
t <sub>PHL</sub>	Clk to Q	450		1000	450		1000	450		1000		
	Clk to BUS	800		1800	800		1800	800		1800		
	<u>ABUSDIS</u>	500		1500	500		1500	500		1500		
	SYNCEN	800		1800	800		1800	800		1800		
t <sub>S</sub>	Setup Time										ps	
	BUS	350			350			350				
	SBUSEN	100			100			100				
	Data, S-IN	400			400			400				
	TEN, REN, SCAN	550			550			550				
th	Hold Time										ps	
	BUS	350			350			350				
İ	SBUSEN	500			500			500				
	Data, S-IN	350			350			350				
	TEN, REN, SCAN	200			200			200				
tpW	Minimum Pulse Width										ps	
' ''	CLk	400			400			400			i i	
t <sub>r</sub>	Rise/Fall Times										ps	
t <sub>f</sub>	20 - 80% (Qn)	300		800	300		800	300		800		
	20 - 80% (BUSn Rise)	500		1000	500		1000	500		1000		
	20 - 80% (BUSn Fall)	300		800	300		800	300		800		

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#### **OUTLINE DIMENSIONS**



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