# **8-Input Priority Encoder**

The MC10H165 is an 8-Input Priority Encoder. This 10H part is a functional/pinout duplication of the standard MECL 10K family part, with 100% improvement in propagation delay, and no increases in power-supply current.

- Propagation Delay, Data-to-Output, 2.2 ns Typical
- Improved Noise Margin 150 mV (Over Operating Voltage and Temperature Range)
- Voltage Compensated
- MECL 10K-Compatible

#### **MAXIMUM RATINGS**

Characteristic	Symbol	Rating	Unit
Power Supply (V <sub>CC</sub> = 0)	V <sub>EE</sub>	-8.0 to 0	Vdc
Input Voltage (V <sub>CC</sub> = 0)	٧ <sub>I</sub>	0 to V <sub>EE</sub>	Vdc
Output Current — Continuous — Surge	l <sub>out</sub>	50 100	mA
Operating Temperature Range	T <sub>A</sub>	0 to +75	°C
Storage Temperature Range — Plastic — Ceramic	T <sub>stg</sub>	-55 to +150 -55 to +165	°C

#### ELECTRICAL CHARACTERISTICS (VEE = -5.2 V ±5%) (See Note)

	(							
		<b>0</b> °		25°		<b>75</b> °		
Characteristic	Symbol	Min	Max	Min	Max	Min	Max	Unit
Power Supply Current	ΙE	_	144	1	131	_	144	mA
Input Current High Pin 4 Data Inputs	l <sub>inH</sub>		510 600		320 370		320 370	μAdc
Input Current Low	l <sub>inL</sub>	0.5	_	0.5	_	0.3	_	μΑ
High Output Voltage	Vон	-1.02	-0.84	-0.98	-0.81	-0.92	-0.735	Vdc
Low Output Voltage	VOL	-1.95	-1.63	-1.95	-1.63	-1.95	-1.60	Vdc
High Input Voltage	VIH	-1.17	-0.84	-1.13	-0.81	-1.07	-0.735	Vdc
Low Input Voltage	V <sub>IL</sub>	-1.95	-1.48	-1.95	-1.48	-1.95	-1.45	Vdc

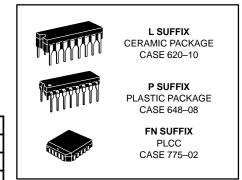
#### **AC PARAMETERS**

Propagation Delay Data Input → Output Clock Input → Output	<sup>t</sup> pd	0.7 0.7	3.4 2.2	0.7 0.7	3.4 2.2	0.7 0.7	3.4 2.2	ns
Set-up Time	t <sub>set</sub>	3.0	ı	3.0	1	3.0	1	ns
Hold Time	thold	0.5	ı	0.5	ı	0.5	1	ns
Rise Time	t <sub>r</sub>	0.5	2.4	0.5	2.4	0.5	2.4	ns
Fall Time	t <sub>f</sub>	0.5	2.4	0.5	2.4	0.5	2.4	ns

#### NOTE:

Each MECL 10H series circuit has been designed to meet the dc specifications shown in the test table, after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse air flow greater than 500 lfpm is maintained. Outputs are terminated through a 50-ohm resistor to -2.0 volts.

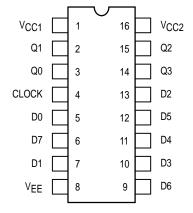
## MC10H165



#### **TRUTH TABLE**

	DATA INPUTS							OUTI	PUTS	i	
D0	D1	D2	D3	D4	D5	D6	D7	Q3	Q2	Q1	Q0
H L L L L L L L	XHLLLLL	XXHLLLL	XXXHLLLL	X X X H L L L	X X X X H L	X X X X X H L	X X X X X X H				

### DIP PIN ASSIGNMENT



Pin assignment is for Dual–in–Line Package. For PLCC pin assignment, see the Pin Conversion Tables on page 6–11 of the Motorola MECL Data Book (DL122/D).

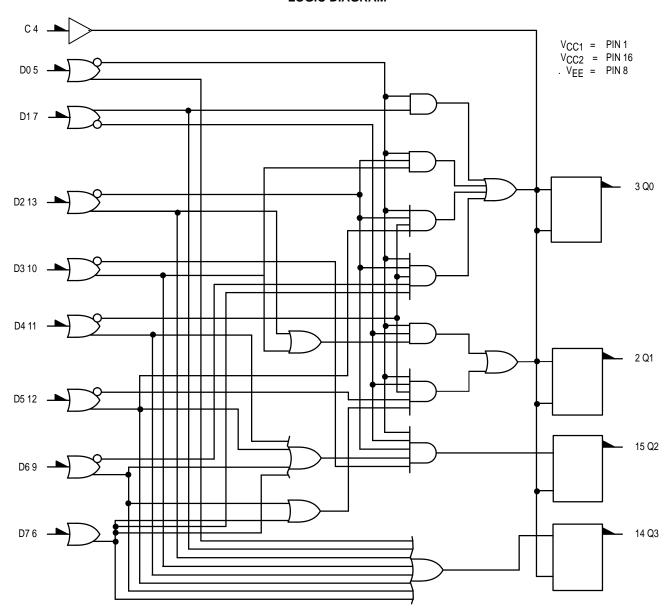
#### **8-INPUT PRIORITY ENCODER**

The MC10H165 is a device designed to encode eight inputs to a binary coded output. The output code is that of the highest order input. Any input of lower priority is ignored. Each output incorporates a latch allowing synchronous operation. When the clock is low the outputs follow the inputs and latch when the clock goes high. This device is very useful for a variety of applications in checking system status in control processors, peripheral

controllers, and testing systems.

The input is active when high, (e.g., the three binary outputs are low when input D0 is high). The Q3 output is high when any input is high. This allows direct extension into another priority encoder when more than eight inputs are necessary. The MC10H165 can also be used to develop binary codes from random logic inputs, for addressing ROMs, RAMs, or for multiplexing data.

#### LOGIC DIAGRAM



Numbers at ends of terminals denote pin numbers for L and P packages.

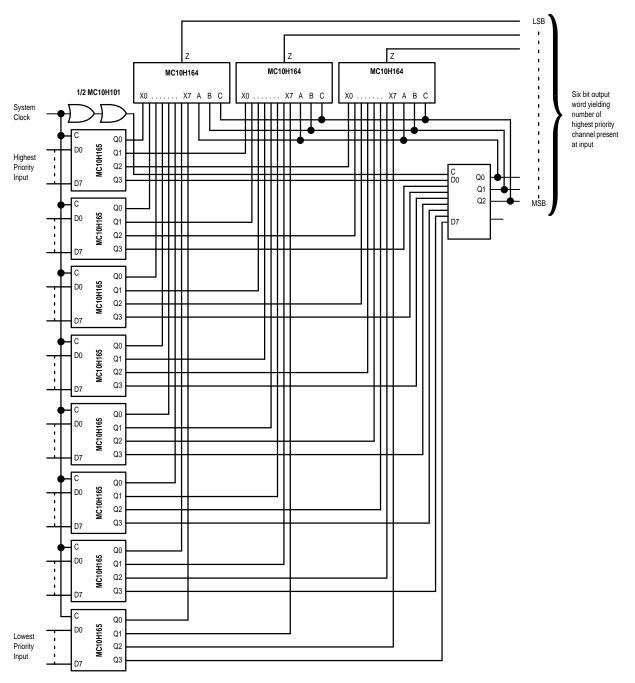
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#### **APPLICATION INFORMATION**

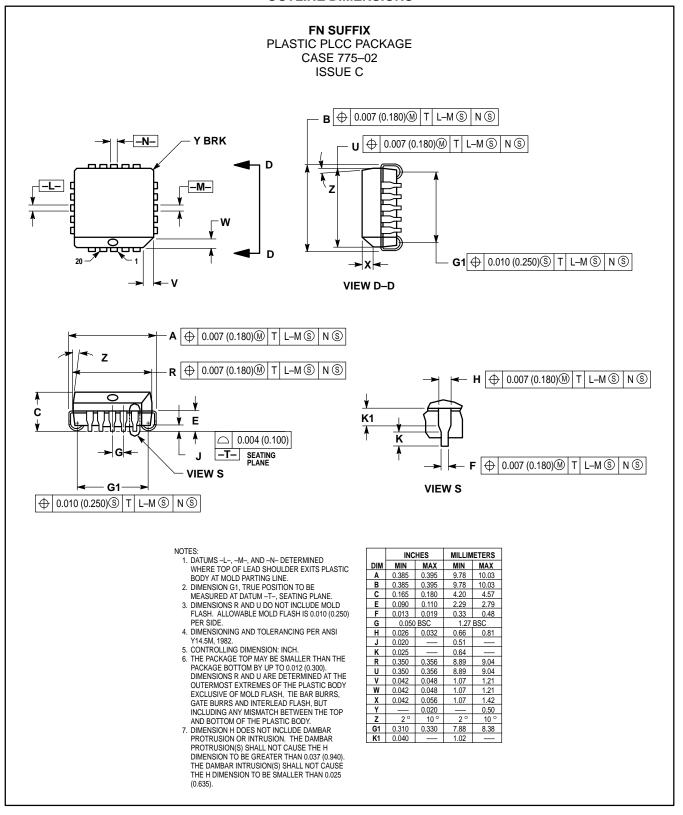
A typical application of the MC10H165 is the decoding of system status on a priority basis. A 64–line priority encoder is shown in the figure below. System status lines are connected to this encoder such that, when a given condition exists, the respective input will be at a logic high level. This scheme will select the one of 64 different

system conditions, as represented at the encoder inputs, which has priority in determining the next system operation to be performed. The binary code showing the address of the highest priority input present will appear at the encoder outputs to control other system logic functions.

### **64-LINE PRIORITY ENCODER**

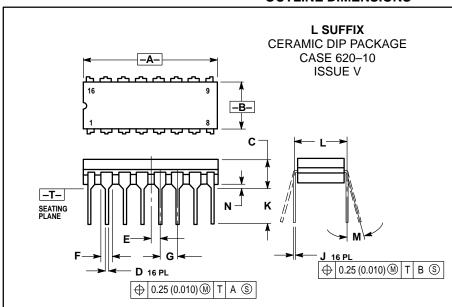


#### **OUTLINE DIMENSIONS**



MOTOROLA 2–264

#### **OUTLINE DIMENSIONS**

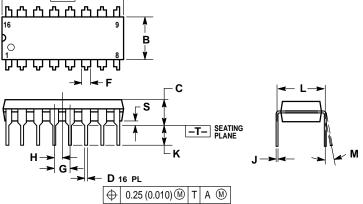


#### NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982. CONTROLLING DIMENSION: INCH.
- DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
- DIMENSION F MAY NARROW TO 0.76 (0.030) WHERE THE LEAD ENTERS THE CERAMIC

	INC	HES	MILLIMETERS		
DIM	MIN	MAX	MIN	MAX	
Α	0.750	0.785	19.05	19.93	
В	0.240	0.295	6.10	7.49	
С		0.200		5.08	
D	0.015	0.020	0.39	0.50	
Е	0.050	BSC	1.27 BSC		
F	0.055	0.065	1.40	1.65	
G	0.100	BSC	2.54 BSC		
Н	0.008	0.015	0.21	0.38	
K	0.125	0.170	3.18	4.31	
L	0.300	BSC	7.62 BSC		
M	0°	15°	0°	15°	
N	0.020	0.040	0.51	1.01	





- NOTES:
  1. DIMENSIONING AND TOLERANCING PER ANSI
- Y14.5M, 1982. CONTROLLING DIMENSION: INCH.
- DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL
- DIMENSION B DOES NOT INCLUDE MOLD FLASH.
- ROUNDED CORNERS OPTIONAL

	INC	HES	MILLIM	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.740	0.770	18.80	19.55
В	0.250	0.270	6.35	6.85
С	0.145	0.175	3.69	4.44
D	0.015	0.021	0.39	0.53
F	0.040	0.70	1.02	1.77
G	0.100	BSC	2.54	BSC
Н	0.050	BSC	1.27	BSC
J	0.008	0.015	0.21	0.38
K	0.110	0.130	2.80	3.30
L	0.295	0.305	7.50	7.74
М	0°	10°	0°	10 °
S	0.020	0.040	0.51	1.01

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