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**MSM7541/7542**

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**Single Rail CODEC**

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**GENERAL DESCRIPTION**

The MSM7541 and MSM7542 are single-channel CODEC CMOS ICs for voice signals ranging from 300 to 3400 Hz. These devices contain filters for A/D and D/A conversion.

Designed especially for a single-power supply and low-power applications, these devices are optimized for telephone terminals in digital wireless systems.

The MSM7541 and MSM7542 use newly designed operational amplifiers to maintain small current deviations caused by power voltage fluctuations.

The devices use the same transmission clocks as those used in the MSM7508B and MSM7509B. The analog output signal, which is of a differential type, directly drives a piezoelectric type handset receiver.

**FEATURES**

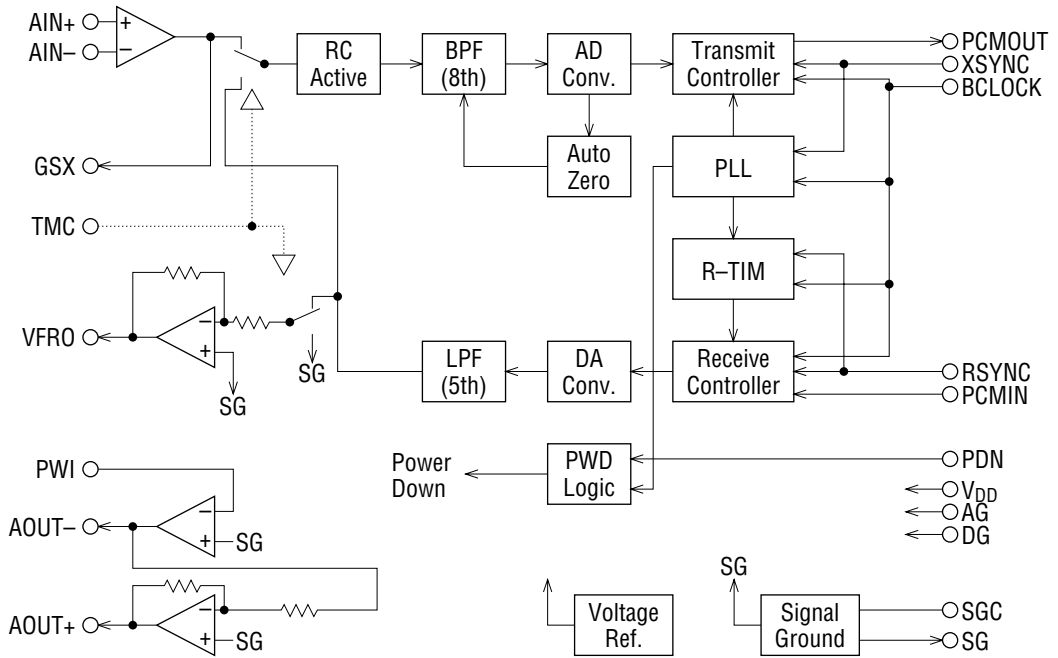
- Single power supply: +3.0 V to +3.8 V
- Low power consumption
 

Operating mode:	23 mW Typ.	$V_{DD} = 3.3 \text{ V}$
Power save mode:	1 mW Typ.	$V_{DD} = 3.3 \text{ V}$
Power down mode:	0.04 mW Typ.	$V_{DD} = 3.3 \text{ V}$
- ITU-T Companding law
 

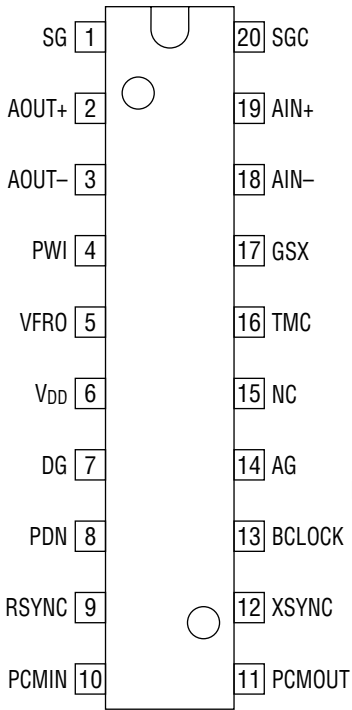
MSM7541:	$\mu$ -law
MSM7542:	A-law
- Built-in PLL eliminates a master clock
- Serial data rate: 64/128/256/512/1024/2048 kHz  
96/192/384/768/1536/1544/200 kHz
- Adjustable transmit gain
- Adjustable receive gain
- Built-in reference voltage supply
- Built-in analog loop back test mode
- Differential type analog output. Directly drives a piezoelectric type receiver equivalent to 1.2 k $\Omega$  + 55 nF
- Package options:
 

20-pin plastic skinny DIP (DIP20-P-300-2.54-S1)	(Product name : MSM7541RS)
	(Product name : MSM7542RS)
24-pin plastic SOP (SOP24-P-430-1.27-K)	(Product name : MSM7541GS-K)
	(Product name : MSM7542GS-K)
26-pin plastic TSOP (TSOPII26/20-P-300-1.27-K)	(Product name : MSM7541TS-K)
	(Product name : MSM7542TS-K)

**BLOCK DIAGRAM**

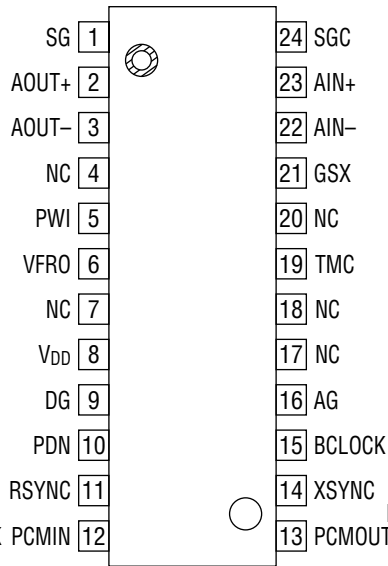


**PIN CONFIGURATION (TOP VIEW)**



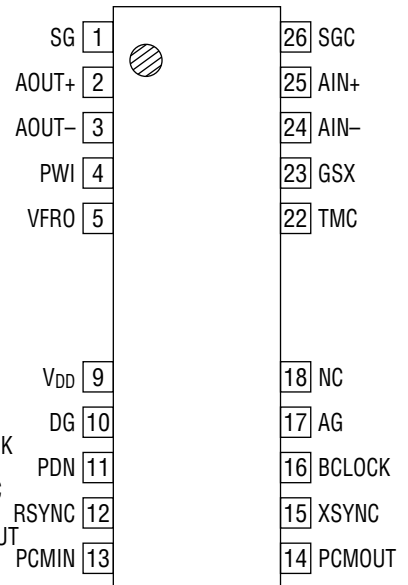
NC : No connect pin

**20-Pin Plastic Skinny DIP**



NC : No connect pin

**24-Pin Plastic SOP**



NC : No connect pin

**26-Pin Plastic TSOP**

## PIN AND FUNCTIONAL DESCRIPTIONS

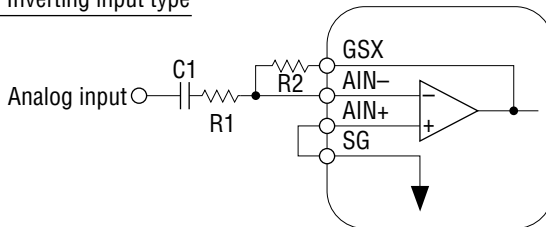
### AIN+, AIN-, GSX

Transmit analog input and transmit level adjustment.

AIN+ is a non-inverting input to the op-amp; AIN- is an inverting input to the op-amp; GSX is connected to the output of the op-amp and is used to adjust the level, as shown below.

When not using AIN- and AIN+, connect AIN- to GSX and AIN+ to SG. During power saving and power down modes, the GSX output is at AG voltage.

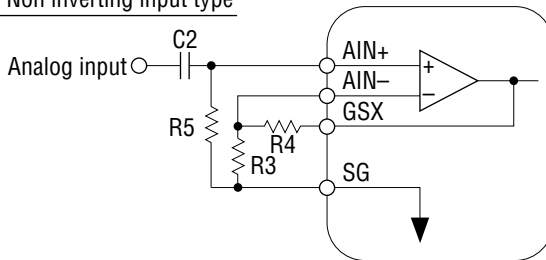
#### 1) Inverting input type



R1 : variable  
 R2 > 20 kΩ  
 $C1 > 1/(2 \times 3.14 \times 30 \times R1)$

$$\text{Gain} = R2/R1 \leq 10$$

#### 2) Non inverting input type



R3 > 20 kΩ  
 R4 > 20 kΩ  
 R5 > 50 kΩ  
 $C2 > 1/(2 \times 3.14 \times 30 \times R5)$

$$\text{Gain} = 1 + R4 / R3 \leq 10$$

### AG

Analog signal ground.

### VFRO

Receive filter output.

The output signal has an amplitude of 2.0 V<sub>PP</sub> above and below the signal ground voltage (SG) when the digital signal of +3 dBm<sub>O</sub> is input to PCMIN and can drive a load of 20 kΩ or more.

For driving a load of 20 kΩ or less, the output signal of AOUT+ and AOUT- is available.

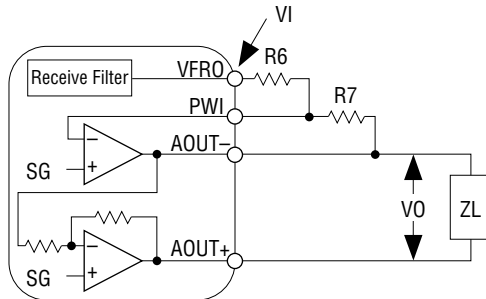
To apply the output signal of AOUT+ and AOUT- for driving, connect a resistor of 20 kΩ or more between the pins VFRO and PWL.

When adding the frequency characteristics to the receive signal, refer to the application example.

During power saving or power down mode, the output of VFRO is at the voltage level of AG.

**PWI, AOUT+, AOUT-**

PWI is connected to the inverting input of the receive driver. The receive driver output is connected to the AOUT- pin. Therefore, the receive level can be adjusted with the pins VFRO, PWI, and AOUT-. When the PWI pin is not used, connect the PWI pin to the AOUT- pin, and leave open the pins AOUT- and AOUT+. The output of AOUT+ is inverted with respect to the output of AOUT-. Since the signal from which provides differential drives of an impedance of 1.2 kΩ + 55 nF, these outputs can directly be connected to a receiver of handset using a piezoelectric earphone. Refer to the application example.



$R6 > 20 \text{ k}\Omega$   
 $ZL \geq 2.4 \text{ k}\Omega$   
 $\text{Gain} = VO/VI = 2 \times R7/R6 \leq 2$

During power saving and power down modes, the outputs of AOUT+ and AOUT- are in a high impedance state. The electrical driving capability of the AOUT- pin and AOUT+ pin is ±1.3 V maximum. The output load resistor has a minimum value of 1.2 kΩ. If an output amplitude less than ±1.3 V is allowed, these outputs can drive a load resistance less than that described above. For more details, refer to SINGLE POWER SUPPLY PCM CODEC APPLICATION NOTE.

**VDD**

Power supply for +3.0 V to +3.8 V. (Typically 3.3 V)

**PCMIN**

PCM signal input.

A serial PCM signal input to this pin is converted to an analog signal in synchronization with the RSYNC signal and BCLOCK signal.

The data rate of the PCM signal is equal to the frequency of the BCLOCK signal.

The PCM signal is shifted at a falling edge of the BCLOCK signal and latched into the internal register when shifted by eight bits.

The start of the PCM data (MSD) is identified at the rising edge of RSYNC.

**BCLOCK**

Shift clock signal input for the PCMIN and PCMOUT signal.

The frequency, equal to the data rate, is 64, 96, 128, 192, 256, 384, 512, 768, 1024, 1536, 1544, 2048, or 200 kHz. Setting this signal to logic "1" or "0" drives both transmit and receive circuits to the power saving state.

**RSYNC**

Receive synchronizing signal input.

Eight required bits are selected from serial PCM signals on the PCMIN pin by the receive synchronizing signal.

Signals in the receive section are synchronized by this synchronizing signal. This signal must be synchronized in phase with the BCLOCK. The frequency should be 8 kHz  $\pm$ 50 ppm to guarantee the AC characteristics which are mainly the frequency characteristics of the receive section.

However, if the frequency characteristic of an applied system is not specified exactly, this device can operate in the range of 8 kHz  $\pm$ 2 kHz, but the electrical characteristics in this specification are not guaranteed.

**XSYNC**

Transmit synchronizing signal input.

The PCM output signal from the PCMOUT pin is output in synchronization with this transmit synchronizing signal. This synchronizing signal triggers the PLL and synchronizes all timing signals of the transmit section.

This synchronizing signal must be synchronized in phase with BCLOCK.

The frequency should be 8 kHz  $\pm$ 50 ppm to guarantee the AC characteristics which are mainly the frequency characteristics of the transmit section.

However, if the frequency characteristic of an applied system is not specified exactly, this device can operate in the range of 8 kHz  $\pm$ 2 kHz, but the electrical characteristics in this specification are not guaranteed.

Setting this signal to logic "1" or "0" drives both transmit and receive circuits to the power saving state.

**TMC**

Control signal input for mode selection.

This pin select the normal operating mode or the analog loop-back mode.

In the analog loop-back mode, the receive filter output is connected to the transmit filter input and the digital signal input to the PCMIN pin is converted from a digital to an analog signal (D/A conversion). Next, the analog signal is converted to a digital signal (A/D conversion) through the receive filter and transmit filter. The result is output to the PCMOUT pin.

When in the analog loop-back mode, the VFRO pin outputs the SG level. (signal ground)

TMC Input	Mode
$< 0.16 \times V_{DD}$	Normal operation
$> 0.45 \times V_{DD}$	Analog loop-back

**DG**

Ground for the digital signal circuits.

This ground is separate from the analog signal ground. The DG pin must be connected to the AG pin on the printed circuit board to make a common analog ground.

**PDN**

Power down control signal.

A logic "0" level drives both transmit and receive circuits to a power down state.

**PCMOUT**

PCM signal output.

The PCM output signal is output from MSD in a sequential order, synchronizing with the rising edge of the BCLOCK signal.

MSD may be output at the rising edge of the XSYNC signal, based on the timing between BCLOCK and XSYNC.

This pin is in a high impedance state except during 8-bit PCM output. It is also in a high impedance state during power saving or power down modes.

A pull-up resistor must be connected to this pin because its output is configured as an open drain. This device is compatible with the ITU-T recommendation on coding law and output coding format.

The MSM7542(A-law) outputs the character signal, inverting the even bits.

Input/Output Level	PCMIN/PCMOUT															
	MSM7541 ( $\mu$ -law)				MSM7542 (A-law)											
+Full scale	MSD				MSD											
	1	0	0	0	0	0	0	0	1	0	1	0	1	0	1	0
+0	1	1	1	1	1	1	1	1	1	1	0	1	0	1	0	1
-0	0	1	1	1	1	1	1	1	0	1	0	1	0	1	0	1
-Full scale	0	0	0	0	0	0	0	0	0	0	1	0	1	0	1	0

**SG**

Signal ground voltage output.

The output voltage is 1/2 of the power supply voltage.

The output drive current capability is  $\pm 200 \mu\text{A}$ .

This pin provides the SG level for CODEC peripherals.

This output voltage level is undefined during power saving or power down modes.

**SGC**

Used to generate the signal ground voltage level by connecting a bypass capacitor.

Connect a  $0.1 \mu\text{F}$  capacitor with excellent high frequency characteristics between the AG pin and the SGC pin.



## ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Condition	Rating	Unit
Power Supply Voltage	$V_{DD}$	—	0 to 7	V
Analog Input Voltage	$V_{AIN}$	—	-0.3 to $V_{DD} + 0.3$	V
Digital Input Voltage	$V_{DIN}$	—	-0.3 to $V_{DD} + 0.3$	V
Storage Temperature	$T_{STG}$	—	-55 to +150	°C

## RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Power Supply Voltage	$V_{DD}$	Voltage must be fixed	3.0	3.3	3.8	V
Operating Temperature	$T_a$	—	-30	+25	+85	°C
Analog Input Voltage	$V_{AIN}$	Connect AIN- and GSX	—	—	1.4	$V_{PP}$
Digital Input High Voltage	$V_{IH}$	XSYNC, RSYNC, BCLOCK, PCMIN, PDN, TMC	$0.45 \times V_{DD}$	—	$V_{DD}$	V
Digital Input Low Voltage	$V_{IL}$		0	—	$0.16 \times V_{DD}$	V
Clock Frequency	$F_C$	BCLOCK	64, 128, 256, 512, 1024, 2048, 96, 192, 384, 768, 1536, 1544, 200			kHz
Sync Pulse Frequency	$F_S$	XSYNC, RSYNC	6.0	8.0	10.0	kHz
Clock Duty Ratio	$D_C$	BCLOCK	40	50	60	%
Digital Input Rise Time	$t_{Ir}$	XSYNC, RSYNC, BCLOCK,	—	—	50	ns
Digital Input Fall Time	$t_{If}$	PCMIN, PDN, TMC	—	—	50	ns
Transmit Sync Pulse Setting Time	$t_{XS}$	BCLOCK→XSYNC, See Timing Diagram	100	—	—	ns
	$t_{SX}$	XSYNC→BCLOCK, See Timing Diagram	100	—	—	ns
Receive Sync Pulse Setting Time	$t_{RS}$	BCLOCK→RSYNC, See Timing Diagram	100	—	—	ns
	$t_{SR}$	RSYNC→BCLOCK, See Timing Diagram	100	—	—	ns
Sync Pulse Width	$t_{WS}$	XSYNC, RSYNC	1 BCLK	—	100	μs
PCMIN Set-up Time	$t_{DS}$	—	100	—	—	ns
PCMIN Hold Time	$t_{DH}$	—	100	—	—	ns
Digital Output Load	$R_{DL}$	Pull-up resistor	0.5	—	—	kΩ
	$C_{DL}$	—	—	—	100	pF
Analog Input Allowable DC Offset	$V_{off}$	Transmit gain stage, Gain = 1	-100	—	+100	mV
		Transmit gain stage, Gain = 10	-10	—	+10	mV
Allowable Jitter Width	—	XSYNC, RSYNC, BCLOCK	—	—	500	ns

## ELECTRICAL CHARACTERISTICS

## DC and Digital Interface Characteristics

(V<sub>DD</sub> = 3.0 V to 3.8 V, T<sub>a</sub> = -30°C to +85°C)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Power Supply Current	I <sub>DD1</sub>	Operating mode V <sub>DD</sub> = 3.8 V	—	10.0	12.0	mA
	I <sub>DD4</sub>		V <sub>DD</sub> = 3.3 V	—	7.0	9.0
	I <sub>DD2</sub>	Power-save mode, PDN = 1, XSYNC or BCLOCK → OFF	—	0.3	1.0	mA
	I <sub>DD3</sub>	Power-down mode, PDN = 0	—	5	50	μA
Input High Voltage	V <sub>IH</sub>	—	0.45 × V <sub>DD</sub>	—	V <sub>DD</sub>	V
Input Low Voltage	V <sub>IL</sub>	—	0.0	—	0.16 × V <sub>DD</sub>	V
High Level Input Leakage Current	I <sub>IH</sub>	—	—	—	2.0	μA
Low Level Input Leakage Current	I <sub>IL</sub>	—	—	—	0.5	μA
Digital Output Low Voltage	V <sub>OL</sub>	Pull-up resistance > 500 Ω	0.0	0.2	0.4	V
Digital Output Leakage Current	I <sub>O</sub>	—	—	—	10	μA
Input Capacitance	C <sub>IN</sub>	—	—	5	—	pF

**Transmit Analog Interface Characteristics**

(V<sub>DD</sub> = 3.0 V to 3.8 V, T<sub>a</sub> = -30°C to +85°C)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Input Resistance	R <sub>INX</sub>	AIN+, AIN-	10	—	—	MΩ
Output Load Resistance	R <sub>LGX</sub>	GSX with respect to SG	20	—	—	kΩ
Output Load Capacitance	C <sub>LGX</sub>		—	—	50	pF
Output Amplitude	V <sub>OGX</sub>		-0.7	—	+0.7	V
Offset Voltage	V <sub>OSGX</sub>		Gain = 1	-20	—	+20

**Receive Analog Interface Characteristics**

(V<sub>DD</sub> = 3.0 V to 3.8 V, T<sub>a</sub> = -30°C to +85°C)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Input Resistance	R <sub>IINPW</sub>	PWI	10	—	—	MΩ
Output Load Resistance	R <sub>LVF</sub>	VFRO with respect to SG	20	—	—	kΩ
	R <sub>LAO</sub>	AOUT+, AOUT- (each) with respect to SG	1.2	—	—	kΩ
Output Load Capacitance	C <sub>LVF</sub>	VFRO	—	—	100	pF
	C <sub>LAO</sub>	AOUT+, AOUT-	—	—	50	pF
Output Amplitude	V <sub>OVF</sub>	VFRO, R <sub>L</sub> = 20 kΩ with respect to SG	-1.0	—	+1.0	V
	V <sub>OA0</sub>	AOUT+, AOUT-, R <sub>L</sub> = 1.2 kΩ with respect to SG	-1.3	—	+1.3	V
Offset Voltage	V <sub>OSVF</sub>	VFRO with respect to SG	-100	—	+100	mV
	V <sub>OSAO</sub>	AOUT+, AOUT-, Gain = 1 with respect to SG	-100	—	+100	mV

AC Characteristics

(V<sub>DD</sub> = 3.0 V to 3.8 V, Ta = -30°C to +85°C)

Parameter	Symbol	Freq. (Hz)	Level (dBm0)	Condition	Min.	Typ.	Max.	Unit
Transmit Frequency Response	Loss T1	60	0		20	26	—	dB
	Loss T2	300			-0.15	+0.1	+0.20	
	Loss T3	1020			Reference			
	Loss T4	2020			-0.15	—	+0.20	
	Loss T5	3000			-0.15	—	+0.20	
	Loss T6	3400			0	—	0.80	
Receive Frequency Response	Loss R1	300	0		-0.15	—	+0.20	dB
	Loss R2	1020			Reference			
	Loss R3	2020			-0.15	—	+0.20	
	Loss R4	3000			-0.15	—	+0.20	
	Loss R5	3400			0.0	—	0.80	
Transmit Signal to Distortion Ratio	SD T1	1020	3	*1	35	43	—	dB
	SD T2		0		35	42	—	
	SD T3		-30		35	39	—	
	SD T4		-40		28	30.5	—	
	SD T5		-45		23	25	—	
Receive Signal to Distortion Ratio	SD R1	1020	3	*1	36	43	—	dB
	SD R2		0		36	41	—	
	SD R3		-30		36	41	—	
	SD R4		-40		30	33	—	
	SD R5		-45		24	27	—	
Transmit Gain Tracking	GT T1	1020	3		-0.2	0	+0.2	dB
	GT T2		-10		Reference			
	GT T3		-40		-0.2	-0.02	+0.2	
	GT T4		-50		-0.5	+0.2	+0.5	
	GT T5		-55		-1.2	+0.4	+1.2	
Receive Gain Tracking	GT R1	1020	3		-0.2	0	+0.2	dB
	GT R2		-10		Reference			
	GT R3		-40		-0.2	-0.06	+0.2	
	GT R4		-50		-1.0	-0.10	+1.0	
	GT R5		-55		-1.5	-0.20	+1.5	

\*1 Psophometric filter is used

AC Characteristics (Continued)

(V<sub>DD</sub> = 3.0 V to 3.8 V, T<sub>a</sub> = -30°C to +85°C)

Parameter	Symbol	Freq. (Hz)	Level (dBm0)	Condition	Min.	Typ.	Max.	Unit
Idle Channel Noise	Nidle T	—	—	A <sub>IN</sub> = SG *1	—	-70	-68	dBmOp
	Nidle R	—	—	*1 *2	—	-76	-74	
Absolute Level (Initial Difference)	AV T	1020	0	V <sub>DD</sub> = 3.3 V T <sub>a</sub> = 25°C *3	0.338	0.35	0.362	V <sub>rms</sub>
	AV R				0.483	0.50	0.518	
Absolute Level (Deviation of Temperature and Power)	AV Tt	1020	0	V <sub>DD</sub> = +3 to 3.8 V T <sub>a</sub> = -30 to +85°C *3	-0.2	—	+0.2	dB
	AV Rt				-0.2	—	+0.2	dB
Absolute Delay	Td	1020	0	A to A BCLOCK = 64 kHz	—	—	0.60	ms
Transmit Group Delay	tgd T1	500	0	*4	—	0.19	0.75	ms
	tgd T2	600			—	0.11	0.35	
	tgd T3	1000			—	0.02	0.125	
	tgd T4	2600			—	0.05	0.125	
	tgd T5	2800			—	0.07	0.75	
Receive Group Delay	tgd R1	500	0	*4	—	0.00	0.75	ms
	tgd R2	600			—	0.00	0.35	
	tgd R3	1000			—	0.00	0.125	
	tgd R4	2600			—	0.09	0.125	
	tgd R5	2800			—	0.12	0.75	
Crosstalk Attenuation	CR T	1020	0	TRANS → RECV	75	85	—	dB
	CR R			RECV → TRANS	65	70	—	

\*1 Psophometric filter is used

\*2 Input "0" code to PCMIN

\*3 AVR is defined at VFRO output

\*4 Minimum value of the group delay distortion

AC Characteristics (Continued)

(V<sub>DD</sub> = 3.0 V to 3.8 V, T<sub>a</sub> = -30°C to +85°C)

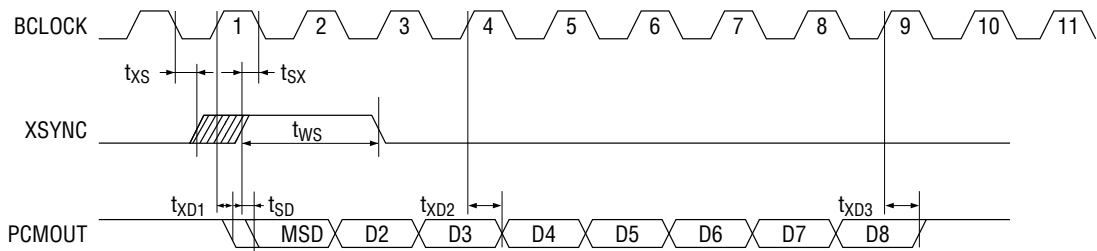
Parameter	Symbol	Freq. (Hz)	Level (dBm0)	Condition	Min.	Typ.	Max.	Unit
Discrimination	DIS	4.6 kHz to 72 kHz	0	0 to 4000 Hz	30	32	—	dB
Out-of-band Spurious	S	300 to 3400	0	4.6 kHz to 100 kHz	—	-37.5	-35	dBm0
Intermodulation Distortion	IMD	f <sub>a</sub> = 470 f <sub>b</sub> = 320	-4	2f <sub>a</sub> - f <sub>b</sub>	—	-52	-35	dBm0
D-to-D Mode Gain	—	1020	0	TMC = 1 PCMIN to PCMOUT	-1.0	—	+1.0	dB
Power Supply Noise Rejection Ratio	PSR T	0 to 50 kHz	50 mV <sub>pp</sub>	*1	—	30	—	dB
	PSR R							
Digital Output Delay Time	t <sub>SD</sub>	C <sub>L</sub> = 100 pF + 1 LSTTL			50	—	200	ns
	t <sub>XD1</sub>				50	—	200	
	t <sub>XD2</sub>				50	—	200	
	t <sub>XD3</sub>				50	—	200	

\*1 The measurement under idle channel noise

## TIMING DIAGRAM

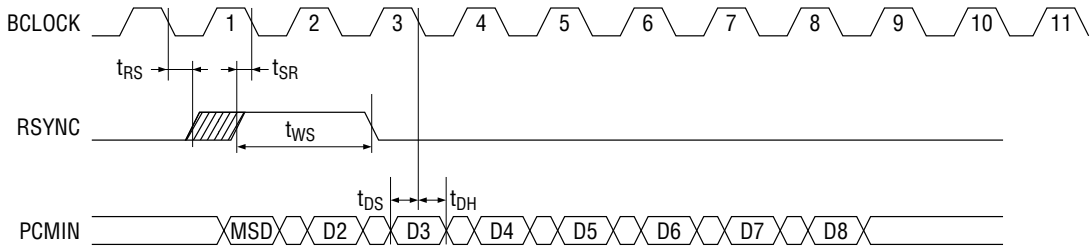
### PCM Data Input/Output Timing

#### Transmit Timing

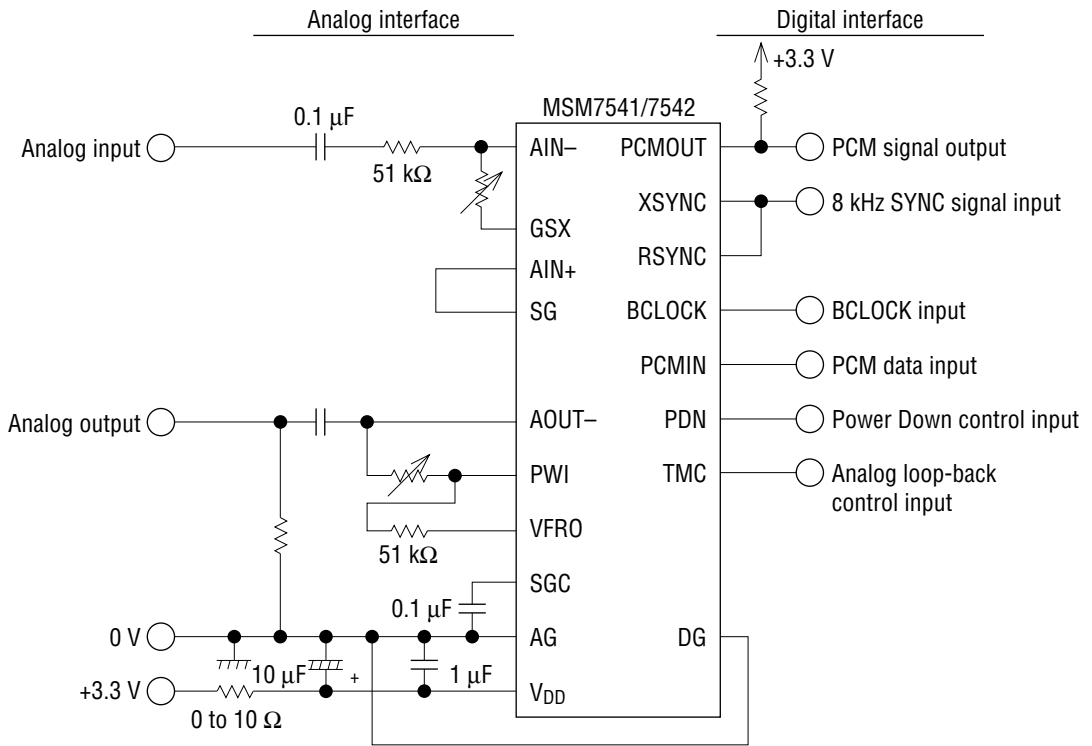


When  $t_{XS} \leq 1/2 \cdot F_c$ , the Delay of the MSD bit is defined as  $t_{XD1}$ .  
 When  $t_{SX} \leq 1/2 \cdot F_c$ , the Delay of the MSD bit is defined as  $t_{SD}$ .

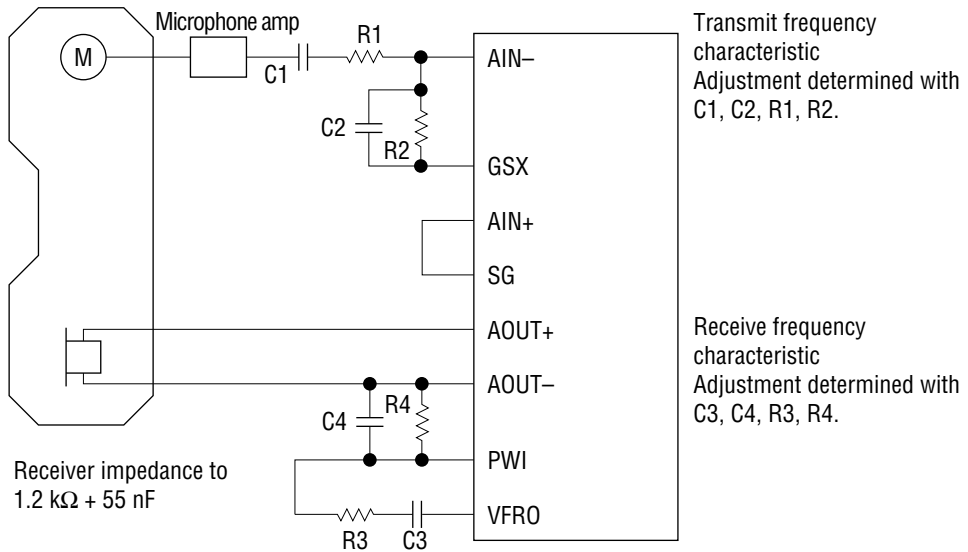
#### Receive Timing



**APPLICATION CIRCUIT**



**FREQUENCY CHARACTERISTICS ADJUSTMENT CIRCUIT**



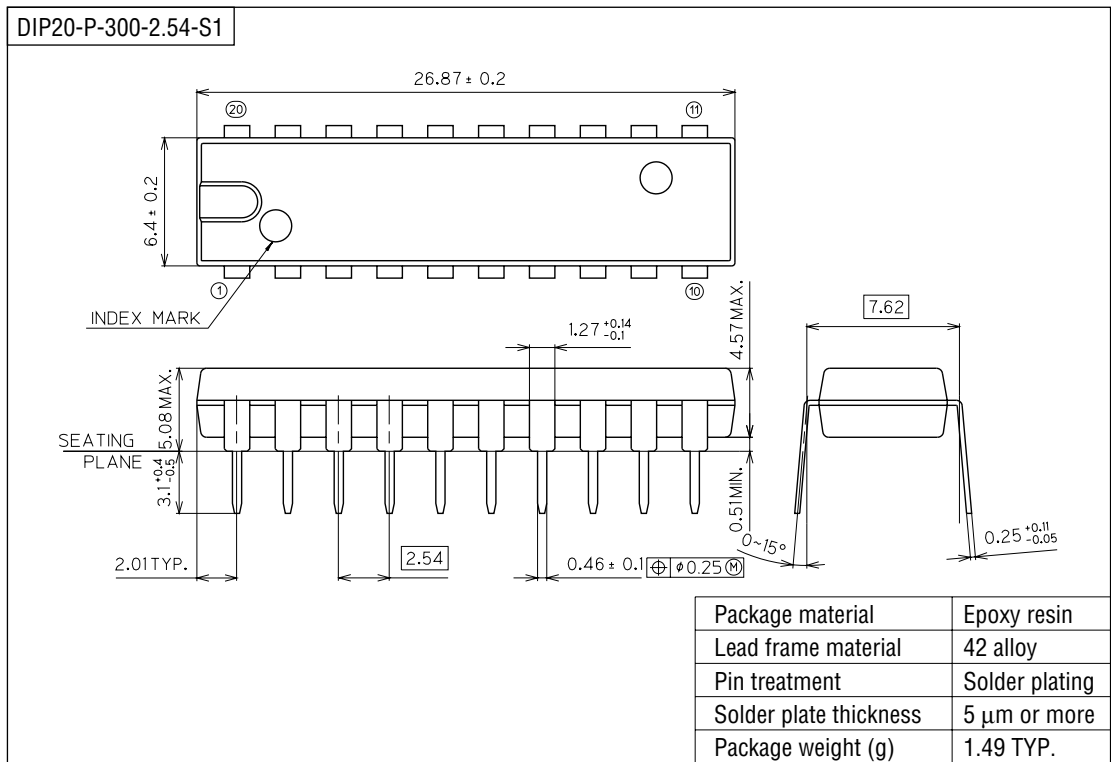


## RECOMMENDATIONS FOR ACTUAL DESIGN

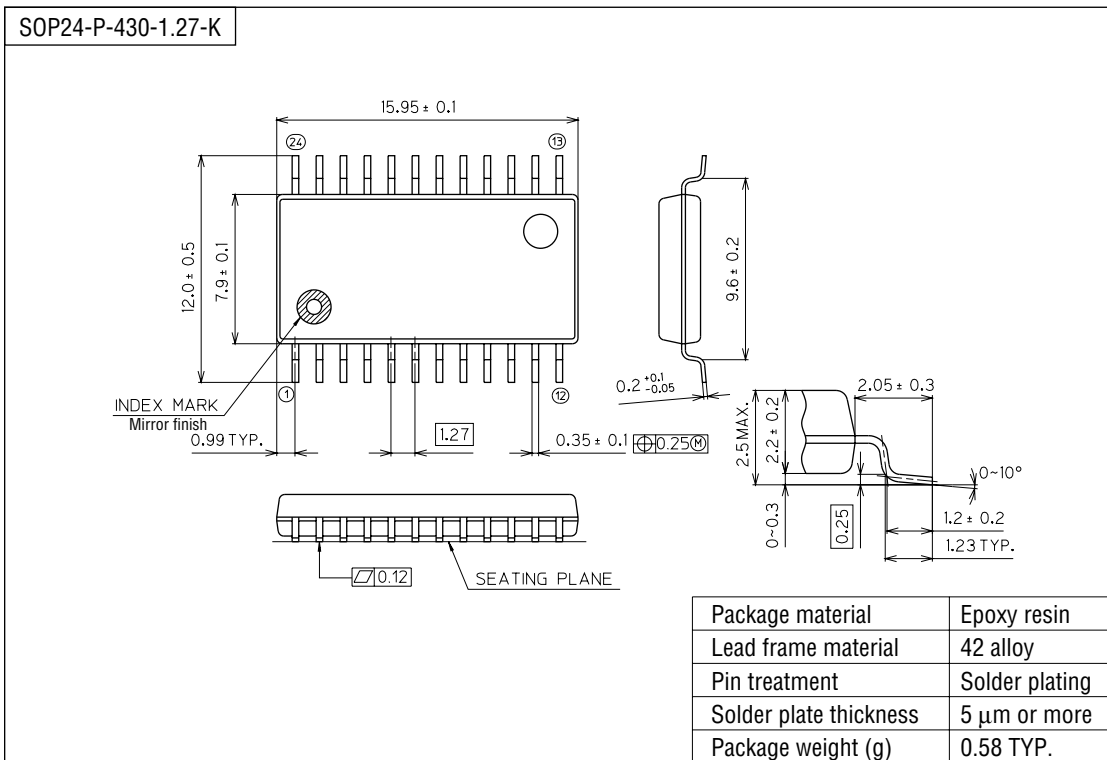
- To assure proper electrical characteristics, use bypass capacitors with excellent high frequency characteristics for the power supply and keep them as close as possible to the device pins.
- Connect the AG pin and the DG pin each other as close as possible. Connect to the system ground with low impedance.
- Mount the device directly on the board when mounted on PCBs. Do not use IC sockets. If an IC socket is unavoidable, use the short lead type socket.
- When mounted on a frame, use electro-magnetic shielding, if any electro-magnetic wave source such as power supply transformers surround the device.
- Keep the voltage on the  $V_{DD}$  pin not lower than  $-0.3\text{ V}$  even instantaneously to avoid latch-up phenomenon when turning the power on.
- Use a low noise (particularly, low level type of high frequency spike noise or pulse noise) power supply to avoid erroneous operation and the degradation of the characteristics of these devices.

PACKAGE DIMENSIONS

(Unit : mm)



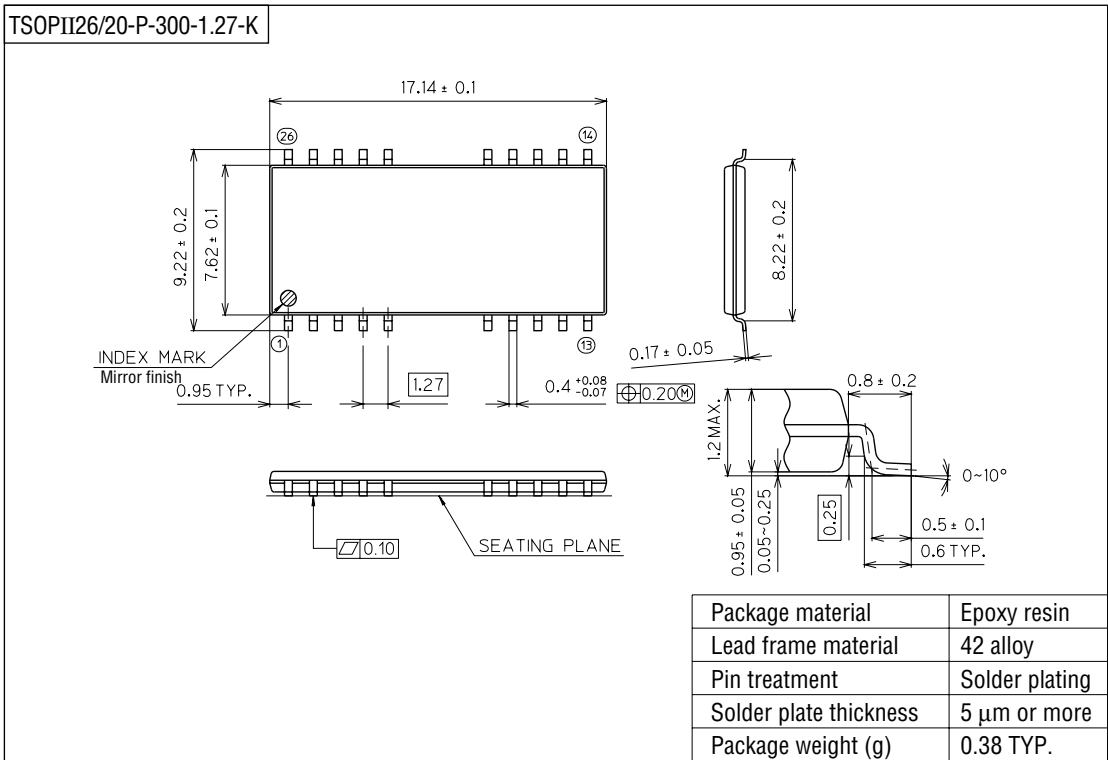
(Unit : mm)



Notes for Mounting the Surface Mount Type Package

The SOP, QFP, TSOP, SOJ, QFJ (PLCC), SHP and BGA are surface mount type packages, which are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact Oki's responsible sales person for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

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