

LOW VOLTAGE DC MOTOR CONTROLLER

■ GENERAL DESCRIPTION

The **NJM2606/06A** are integrated circuits with wide operating supply voltage range for DC motor speed control. Especially, the **NJM2606A** is suited for the applications requiring low staturation output voltage.

■ PACKAGE OUTLINE





NJM2606D NJM2606AD

NJM2606M NJM2606AM

■ FEATURES

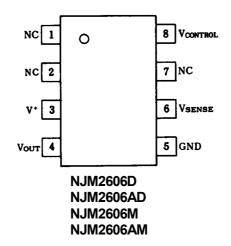
• Operating Voltage (1.8V to 8V)

• Internal Low Saturation Voltage Output Transistor

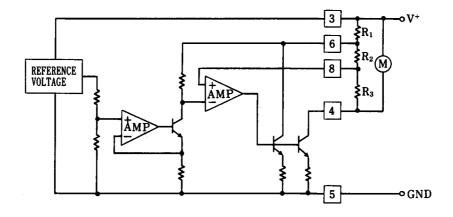
• Package Outline DIP8, DMP8

Bipolar Technology

■ PIN CONFIGURATION



■ BLOCK DIAGRAM



NJM2606 / 2606A

■ ABSOLUTE MAXIMUM RATINGS

(T_a=25°C)

PARAMETER	SYMBOL	RATINGS	UNIT	
Supply Voltage	V ⁺	10	V	
Peak-to-peak Output Current	I _{OP}	700	mA	
Power Dissipation	P _D	(DIP) 500	mW	
		(DMP8) 300	mW	
Operating Temperature Range	T _{opr}	-20 to 75	°C	
Storage Temperature Range	T _{stg}	-40 to 125	°C	

(note)At SW ON. (3 sec. at motor locked or 100msec at duty factor less than 0.1%)

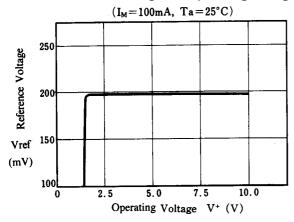
■ ELECTRICAL CHARACTERISTICS

 $(T_a=25^{\circ}C, V^{\dagger}=3V, I_M=100mA)$

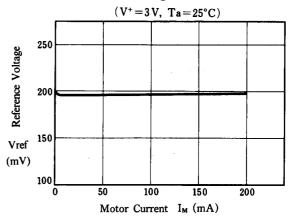
PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Operating Current	Icc		-	2.4	6.0	mA
Output Saturation Voltage						
NJM2606	Vosat		-	0.18	0.3	V
NJM2606A	V_{OSAT}		-	0.13	0.18	V
Reference Voltage	V_{REF}		0.18	0.20	0.22	V
vs. Operating Voltage	ΔV_{RSV}	V ⁺ =1.8V to 8.0V	-	0.7	8.0	mV
vs. Output Current	ΔV_{ROC}	I _M =20mA to 200mA	-	2.7	9.0	mV
vs. Ambient Temperature	ΔV_{RT}	T _a = -20°C to +75°C	-	0.04	-	mV / °C
Current Ratio	K	I _M =50mA to 150mA	45	50	55	
vs. Operating Voltage	ΔK_{SV}	V ⁺ =1.8V to 8.0V I _M =50mA to 150mA	-	0.6	3.0	
vs. Output Current	ΔK_{OC}	I _M =(20 to 50)mA to (170 to 200)mA	-	1.0	4.0	
vs. Ambient Temperature	ΔK _{TC}	T_a = -20°C to +75°C I_M =50mA to 150mA	-	1.0	-	1/°C

■ TYPICAL CHARACTERISTICS

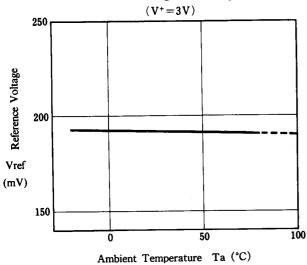
Reference Voltage vs. Operating Voltage



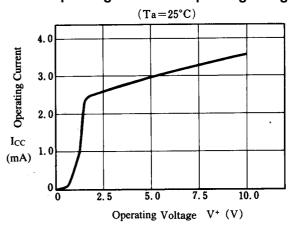
Reference Voltage vs. Motor Current



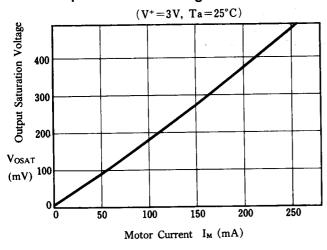
Reference Voltage vs. Temperature



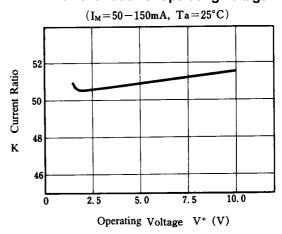
Operating Current vs. Operating Voltage



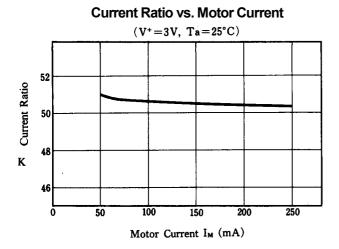
Output Staturation Voltage vs. Motor Current

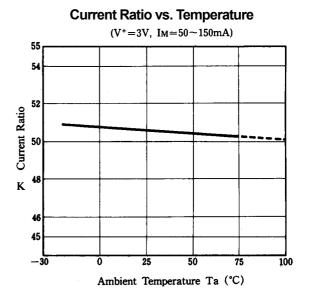


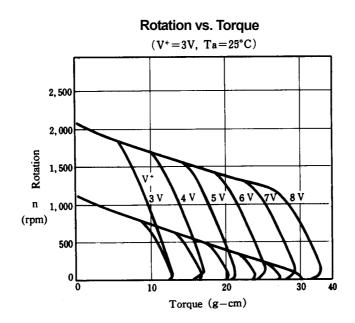
Current Ratio vs. Operating Voltage



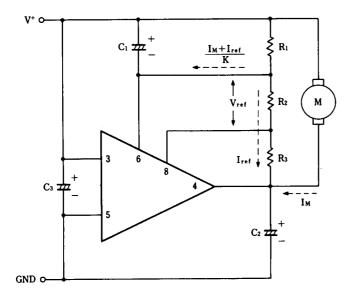
■ TYPICAL CHARACTERISTICS



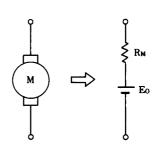




■ TYPICAL APPLICATION



Select C₁, C₂, C₃ for each motor type.



Vref: Reference Voltage
K: Current Ratio
IM: Motor Current

R_M: Internal Resistance of Motor E_O: Motor Counter Electromotive Voltage

The voltage applied at the motor is set as V_M, which brings the following formula.

$$V_{M} = (R_{1} + R_{2} + R_{3}) I_{ref} + R_{1} \cdot \frac{I_{M} + I_{ref}}{\kappa}$$

Now that, $I_{ref} = V_{ref} / R_2$ so that, $(I_{ref} \doteq 100 \mu A \text{ setting is appropriate})$

$$V_{M} = \frac{V_{ref}}{R_{2}} (R_{1} + \frac{R_{1}}{K} + R_{2} + R_{3}) + \frac{R_{1}}{K} I_{M} \Lambda \Lambda (1)$$

On the other hand, the voltage applied at the motor itself will be as in the following.

$$V_{M} = E_{O} + R_{M} \cdot I_{M} \Lambda \Lambda (2)$$

Through (1), (2), and then leading to stabilize the control system.

$$R_M \cdot I_M > \frac{R_1}{K} \cdot I_M$$

$$\therefore R_1 < K \cdot R_M \Lambda \Lambda (3)$$

Taking in consideration of deviations, $R_{1(MAX)} < K_{(MIN)} \cdot R_{M(MIN)}$ with the condition.

Items required checking in regard to the temperature coefficient

IC items

- 1. Reference voltage: Temperature coefficient of V_{ref}.
- 2. Current Ratio: Temperature coefficient of K
 - *1 External component items
- 3. Temperature coefficient of R_1 , R_2 and R_3

The relation among these 3 parts takes the very important roll.

- 4. Temperature coefficient of motor internal resistance
- 5. Temperature coefficient of motor generative voltage
- 6. Temperature coefficient ratio of R_1 and R_M Count up from 3.4.

[CAUTION]

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