Old Company Name in Catalogs and Other Documents

On April 1st, 2010, NEC Electronics Corporation merged with Renesas Technology Corporation, and Renesas Electronics Corporation took over all the business of both companies. Therefore, although the old company name remains in this document, it is a valid Renesas Electronics document. We appreciate your understanding.

Renesas Electronics website: http://www.renesas.com

April 1st, 2010 Renesas Electronics Corporation

Issued by: Renesas Electronics Corporation (http://www.renesas.com)
Send any inquiries to http://www.renesas.com/inquiry.



Notice

- 1. All information included in this document is current as of the date this document is issued. Such information, however, is subject to change without any prior notice. Before purchasing or using any Renesas Electronics products listed herein, please confirm the latest product information with a Renesas Electronics sales office. Also, please pay regular and careful attention to additional and different information to be disclosed by Renesas Electronics such as that disclosed through our website.
- Renesas Electronics does not assume any liability for infringement of patents, copyrights, or other intellectual property rights
 of third parties by or arising from the use of Renesas Electronics products or technical information described in this document.
 No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights
 of Renesas Electronics or others.
- 3. You should not alter, modify, copy, or otherwise misappropriate any Renesas Electronics product, whether in whole or in part.
- 4. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation of these circuits, software, and information in the design of your equipment. Renesas Electronics assumes no responsibility for any losses incurred by you or third parties arising from the use of these circuits, software, or information.
- 5. When exporting the products or technology described in this document, you should comply with the applicable export control laws and regulations and follow the procedures required by such laws and regulations. You should not use Renesas Electronics products or the technology described in this document for any purpose relating to military applications or use by the military, including but not limited to the development of weapons of mass destruction. Renesas Electronics products and technology may not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations.
- 6. Renesas Electronics has used reasonable care in preparing the information included in this document, but Renesas Electronics does not warrant that such information is error free. Renesas Electronics assumes no liability whatsoever for any damages incurred by you resulting from errors in or omissions from the information included herein.
- 7. Renesas Electronics products are classified according to the following three quality grades: "Standard", "High Quality", and "Specific". The recommended applications for each Renesas Electronics product depends on the product's quality grade, as indicated below. You must check the quality grade of each Renesas Electronics product before using it in a particular application. You may not use any Renesas Electronics product for any application categorized as "Specific" without the prior written consent of Renesas Electronics. Further, you may not use any Renesas Electronics product for any application for which it is not intended without the prior written consent of Renesas Electronics. Renesas Electronics shall not be in any way liable for any damages or losses incurred by you or third parties arising from the use of any Renesas Electronics product for an application categorized as "Specific" or for which the product is not intended where you have failed to obtain the prior written consent of Renesas Electronics. The quality grade of each Renesas Electronics product is "Standard" unless otherwise expressly specified in a Renesas Electronics data sheets or data books, etc.
 - "Standard": Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; and industrial robots.
 - "High Quality": Transportation equipment (automobiles, trains, ships, etc.); traffic control systems; anti-disaster systems; anti-crime systems; safety equipment; and medical equipment not specifically designed for life support.
 - "Specific": Aircraft; aerospace equipment; submersible repeaters; nuclear reactor control systems; medical equipment or systems for life support (e.g. artificial life support devices or systems), surgical implantations, or healthcare intervention (e.g. excision, etc.), and any other applications or purposes that pose a direct threat to human life.
- 8. You should use the Renesas Electronics products described in this document within the range specified by Renesas Electronics, especially with respect to the maximum rating, operating supply voltage range, movement power voltage range, heat radiation characteristics, installation and other product characteristics. Renesas Electronics shall have no liability for malfunctions or damages arising out of the use of Renesas Electronics products beyond such specified ranges.
- 9. Although Renesas Electronics endeavors to improve the quality and reliability of its products, semiconductor products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Further, Renesas Electronics products are not subject to radiation resistance design. Please be sure to implement safety measures to guard them against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a Renesas Electronics product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult, please evaluate the safety of the final products or system manufactured by you.
- 10. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. Please use Renesas Electronics products in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. Renesas Electronics assumes no liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
- 11. This document may not be reproduced or duplicated, in any form, in whole or in part, without prior written consent of Renesas Electronics
- 12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products, or if you have any other inquiries.
- (Note 1) "Renesas Electronics" as used in this document means Renesas Electronics Corporation and also includes its majority-owned subsidiaries.
- (Note 2) "Renesas Electronics product(s)" means any product developed or manufactured by or for Renesas Electronics.



MOS INTEGRATED CIRCUIT $\mu PD8862$

(2700 + 2700) PIXELS × 3 COLOR CCD LINEAR IMAGE SENSOR

DESCRIPTION

The μ PD8862 is a color CCD (Charge Coupled Device) linear image sensor which changes optical images to electrical signal and has the function of color separation.

The μ PD8862 has 3 rows of (2700 + 2700) staggered pixels, and each row has a dual-sided readout-type charge transfer register. And it has reset feed-through level clamp circuits and voltage amplifiers. Therefore, it is suitable for 600 dpi/A4 color image scanners, color facsimiles and so on.

FEATURES

• Valid photocell : (2700 + 2700) staggered pixels × 3

• Photocell pitch : 5.25 μm

Line spacing : 63 μm (12 lines) Red line - Green line, Green line - Blue line

10.5 μ m (2 lines) Odd line - Even line (for each color)

• Color filter : Primary colors (red, green and blue), pigment filter (with light resistance 10⁷ lx•hour)

• Resolution : 24 dot/mm A4 (210 × 297 mm) size (shorter side)

600 dpi US letter (8.5" × 11") size (shorter side)

• Drive clock level : CMOS output under 5 V operation

Data rate : 6 MHz Max.Power supply : +12 V

• On-chip circuits : Reset feed-through level clamp circuits

Voltage amplifiers

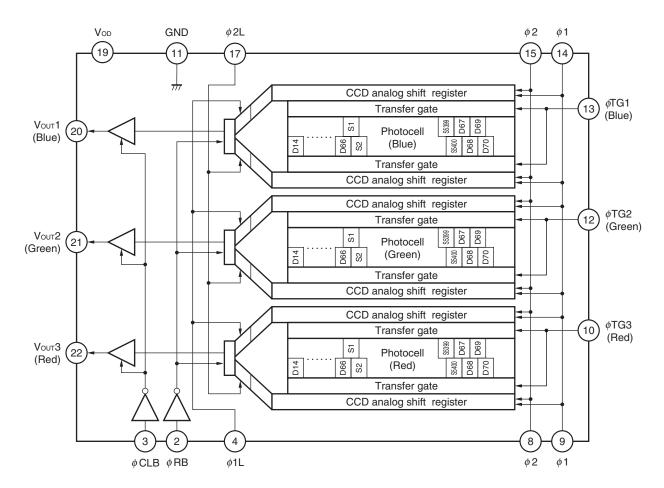
ORDERING INFORMATION

| Part Number | Package |
|-------------|---|
| μPD8862CY | CCD linear image sensor 22-pin plastic DIP (10.16 mm (400)) |

The information in this document is subject to change without notice. Before using this document, please confirm that this is the latest version. Not all products and/or types are available in every country. Please check with an NEC Electronics sales representative for availability and additional information.



BLOCK DIAGRAM

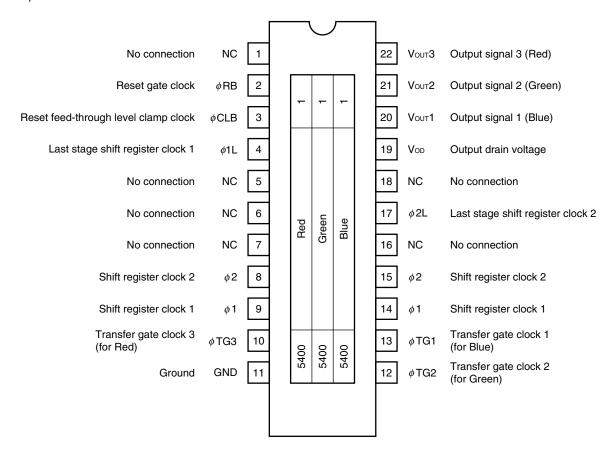




PIN CONFIGURATION (Top View)

CCD linear image sensor 22-pin plastic DIP (10.16 mm (400))

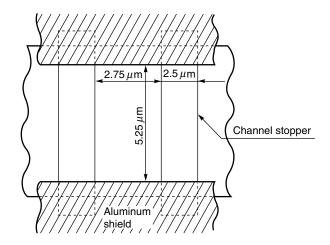
• μPD8862CY



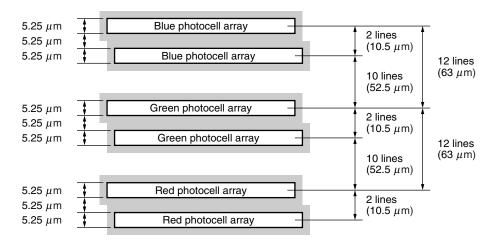
Caution Connect the No connection pins (NC) to GND.



PHOTOCELL STRUCTURE DIAGRAM



PHOTOCELL ARRAY STRUCTURE DIAGRAM (Line spacing)





ABSOLUTE MAXIMUM RATINGS ($T_A = +25$ °C)

| Parameter | Symbol | Ratings | Unit |
|--------------------------------------|--|-------------|------|
| Output drain voltage | Vod | −0.3 to +15 | V |
| Shift register clock voltage | $V_{\phi 1}, V_{\phi 2}, V_{\phi 1L}, V_{\phi 2L}$ | -0.3 to +8 | V |
| Reset gate clock voltage | V _Ø RB | -0.3 to +8 | V |
| Reset feed-through level clamp clock | V _Ø CLB | -0.3 to +8 | V |
| voltage | | | |
| Transfer gate clock voltage | V _φ τg1 to V _φ τg3 | -0.3 to +8 | V |
| Operating ambient temperature Note | Та | 0 to +60 | °C |
| Storage temperature | T _{stg} | -40 to +70 | °C |

Note Use at the condition without dew condensation.

Caution Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

RECOMMENDED OPERATING CONDITIONS ($T_A = +25$ °C)

| Parameter | Symbol | Min. | Тур. | Max. | Unit |
|--------------------------------------|--|------|--------------------|------------------------------------|------|
| Output drain voltage | Vod | 11.4 | 12.0 | 12.6 | ٧ |
| Shift register clock high level | V _φ 1_H, V _φ 2_H, V _φ 1LH, V _φ 2LH | 4.75 | 5.0 | 5.5 | V |
| Shift register clock low level | V _φ 1_L, V _φ 2_L, V _φ 1LL, V _φ 2LL | -0.3 | 0 | +0.25 | V |
| Reset gate clock high level | V _Ø RBH | 4.5 | 5.0 | 5.5 | V |
| Reset gate clock low level | V _Ø RBL | -0.3 | 0 | +0.5 | V |
| Reset feed-through level clamp clock | V _Ø CLBH | 4.5 | 5.0 | 5.5 | V |
| high level | | | | | |
| Reset feed-through level clamp clock | V _Ø CLBL | -0.3 | 0 | +0.5 | ٧ |
| low level | | | | | |
| Transfer gate clock high level | V _Ø тg1н to V _Ø тg3н | 4.75 | V _∅ 1_H | V _∅ 1_H ^{Note} | V |
| Transfer gate clock low level | VøTG1L to VøTG3L | -0.3 | 0 | +0.15 | ٧ |
| Data rate | føRB | - | 2.0 | 6.0 | MHz |

Note When Transfer gate clock high level ($V_{\phi TG1H}$ to $V_{\phi TG3H}$) is higher than Shift register clock high level ($V_{\phi 1_H}$), Image lag can increase.



ELECTRICAL CHARACTERISTICS

 $T_A = +25$ °C, $V_{OD} = 12$ V, data rate ($f_{\phi RB}$) = 2 MHz, storage time = 5.5 ms, input signal clock = 5 V_{p-p} , light source : 3200 K halogen lamp + C-500S (infrared cut filter, t = 1 mm) + HA-50 (heat absorbing filter, t = 3 mm)

| Parameter | | Symbol | Test Conditions | Min. | Тур. | Max. | Unit |
|-------------------------------|--------|--------------|---------------------------------|-------|-------|-------|--------|
| Saturation voltage | - | Vsat | | 2.0 | 2.5 | - | V |
| Saturation exposure | Red | SER | | _ | 0.421 | - | lx•s |
| | Green | SEG | | _ | 0.477 | _ | lx•s |
| | Blue | SEB | | _ | 0.740 | - | lx•s |
| Photo response non-unifor | mity | PRNU | Vout = 1.0 V | _ | 6 | 20 | % |
| Average dark signal | | ADS | Light shielding | _ | 0.2 | 2.0 | mV |
| Dark signal non-uniformity | | DSNU | Light shielding | _ | 1.5 | 5.0 | mV |
| Power consumption | | Pw | | _ | 360 | 540 | mW |
| Output impedance | | Zo | | _ | 0.35 | 1 | kΩ |
| Response | Red | RR | | 4.15 | 5.94 | 7.73 | V/lx•s |
| | Green | Rg | | 3.66 | 5.24 | 6.82 | V/lx•s |
| | Blue | Rв | | 2.36 | 3.38 | 4.39 | V/lx•s |
| Image lag | | IL | Vout = 1.0 V | _ | 3.0 | 7.0 | % |
| Offset level Note 1 | | Vos | | 4.5 | 6.0 | 7.5 | V |
| Output fall delay time Note 2 | | td | Vout = 1.0 V, t1', t2' = 5 ns | _ | 25 | - | ns |
| Total transfer efficiency | | TTE | Vout = 1.0 V, data rate = 6 MHz | 92 | 98 | _ | % |
| Register imbalance | - | RI | Vout = 1.0 V | _ | 1.0 | 4.0 | % |
| Response peak | Red | | | _ | 630 | _ | nm |
| | Green | | | _ | 540 | _ | nm |
| | Blue | | | _ | 460 | - | nm |
| Dynamic range | | DR1 | V _{sat} /DSNU | _ | 1666 | _ | times |
| | | DR2 | $V_{sat}/\sigma CDS$ | _ | 2500 | _ | times |
| Reset feed-through noise | lote 1 | RFTN | Light shielding | -2000 | +300 | +1000 | mV |
| Random noise (CDS) | | σ CDS | Light shielding | | 1.0 | - | mV |

Notes 1. Refer to TIMING CHART 2, 3.

2. When each fall time of ϕ 1L and ϕ 2L (t1', t2') is the Typ. value (refer to **TIMING CHART 2, 3**).



INPUT PIN CAPACITANCE (TA = +25°C, VoD = 12 V)

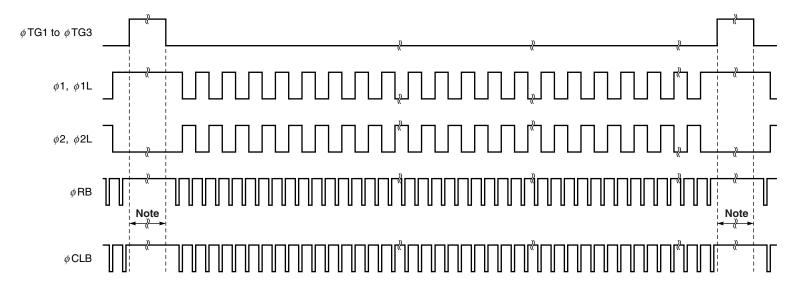
| | Parameter | Symbol | Pin name | Pin No. | Min. | Тур. | Max. | Unit |
|---|--|------------------|-----------|---------|------|------|------|------|
| | Shift register clock pin capacitance 1 | C _Ø 1 | φ1 | 9 | - | 250 | - | pF |
| | | | | 14 | - | 250 | _ | pF |
| * | | φ1 total ca | pacitance | | - | 500 | _ | pF |
| | Shift register clock pin capacitance 2 | C _{Ø2} | φ2 | 8 | - | 250 | _ | pF |
| | | | | 15 | - | 250 | 1 | pF |
| * | | φ2 total ca | pacitance | | - | 500 | 1 | pF |
| | Last stage shift register clock pin capacitance | CøL | φ1L | 4 | - | 10 | 1 | pF |
| | | | φ2L | 17 | - | 10 | _ | pF |
| | Reset gate clock pin capacitance | CøRB | φRB | 2 | - | 10 | _ | pF |
| | Reset feed-through level clamp clock pin capacitance | CøCLB | φ CLB | 3 | - | 10 | _ | pF |
| | Transfer gate clock pin capacitance | CøTG | φTG1 | 13 | - | 100 | _ | pF |
| | | | φTG2 | 12 | - | 100 | 1 | pF |
| | | | φTG3 | 10 | - | 100 | 1 | pF |

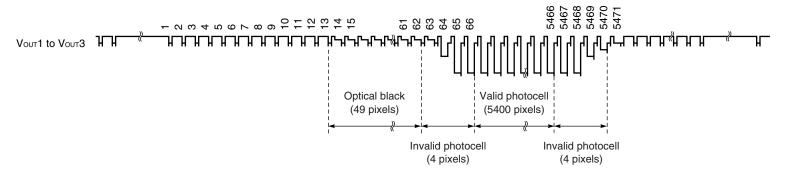
Remarks 1. Pins 9 and 14 (ϕ 1), 8 and 15 (ϕ 2) are each connected inside of the device.

2. $C_{\phi 1}$ and $C_{\phi 2}$ show the equivalent capacity of the real drive including the capacity of between $\phi 1$ and $\phi 2$.

 ∞

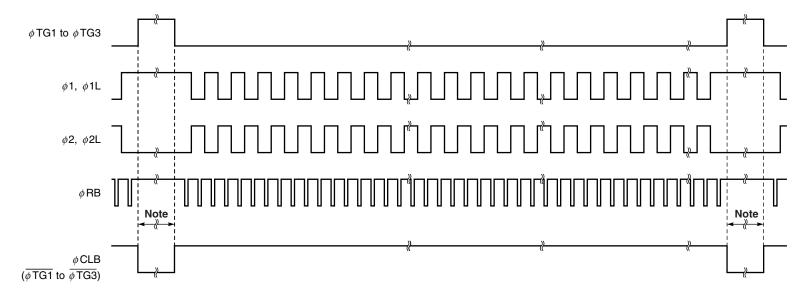
TIMING CHART 1-1 (Bit clamp mode, for each color)

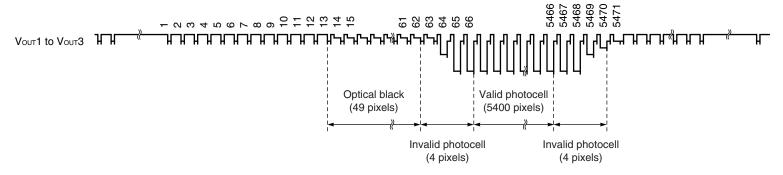




Note Set the ϕ RB and ϕ CLB to high level during this period.

TIMING CHART 1-2 (Line clamp mode, for each color)



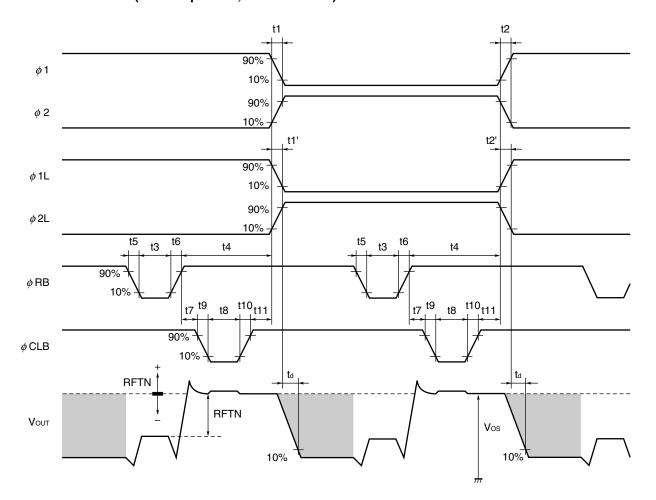


Note Set the ϕ RB to high level during this period.

Remark Inverse pulse of the ϕ TG1 to ϕ TG3 can be used as ϕ CLB.

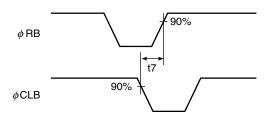


TIMING CHART 2 (Bit clamp mode, for each color)



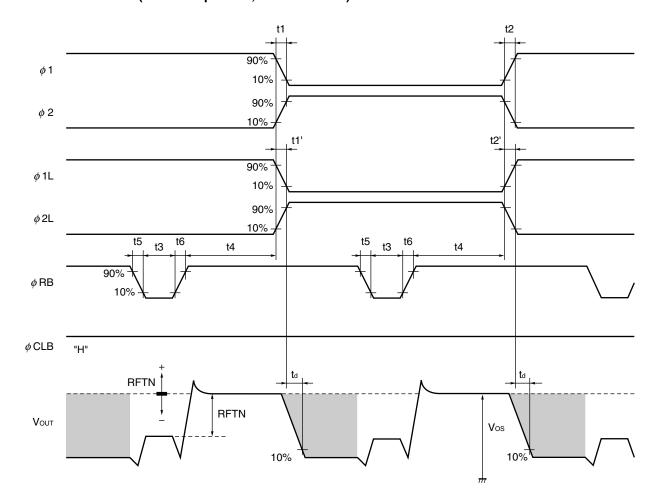
| Symbol | Min. | Тур. | Max. | Unit |
|----------|---------|------|------|------|
| t1, t2 | 0 | 25 | - | ns |
| t1', t2' | 0 | 5 | _ | ns |
| t3 | 20 | 100 | _ | ns |
| t4 | 30 | 150 | _ | ns |
| t5, t6 | 0 | 25 | _ | ns |
| t7 | −5 Note | 25 | _ | ns |
| t8 | 20 | 100 | _ | ns |
| t9, t10 | 0 | 25 | _ | ns |
| t11 | 5 | 25 | - | ns |

Note Min. of t7 shows that the ϕ RB and ϕ CLB overlap each other.





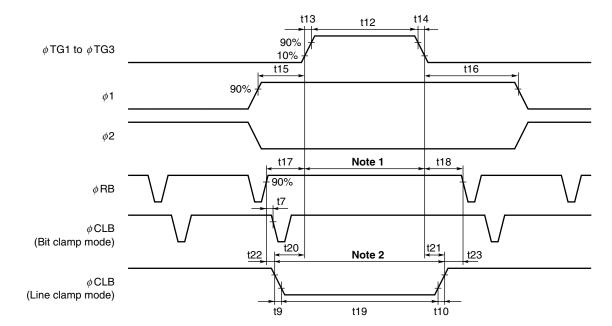
TIMING CHART 3 (Line clamp mode, for each color)



| Symbol | Min. | Тур. | Max. | Unit |
|----------|------|------|------|------|
| t1, t2 | 0 | 25 | ı | ns |
| t1', t2' | 0 | 5 | 1 | ns |
| t3 | 20 | 100 | - | ns |
| t4 | 30 | 150 | - | ns |
| t5, t6 | 0 | 25 | - | ns |



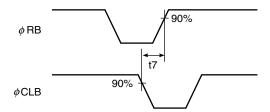
ϕ TG1 to ϕ TG3, ϕ 1, ϕ 2 TIMING CHART



| Symbol | Min. | Тур. | Max. | Unit |
|----------|-----------|-------|-------|------|
| t7 | −5 Note 3 | 25 | _ | ns |
| t9, t10 | 0 | 25 | = | ns |
| t12 | 5000 | 10000 | 50000 | ns |
| t13, t14 | 0 | 50 | _ | ns |
| t15, t16 | 900 | 1000 | = | ns |
| t17, t18 | 200 | 400 | - | ns |
| t19 | t12 | t12 | 50000 | ns |
| t20, t21 | 0 | 50 | = | ns |
| t22, t23 | 0 | 350 | - | ns |

Notes 1. Set the ϕ RB and ϕ CLB to high level during this period.

- **2.** Set the ϕ RB to high level during this period.
- 3. Min. of t7 shows that the ϕ RB and ϕ CLB overlap each other.



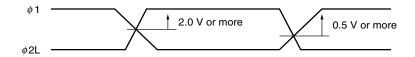
Remark Inverse pulse of the ϕ TG1 to ϕ TG3 can be used as ϕ CLB.



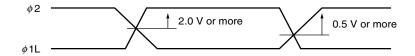
ϕ 1, ϕ 2 cross points



ϕ 1, ϕ 2L cross points



ϕ 2, ϕ 1L cross points



Remark Adjust cross points $(\phi 1, \phi 2)$, $(\phi 1, \phi 2L)$ and $(\phi 2, \phi 1L)$ with input resistance of each pin.

DEFINITIONS OF CHARACTERISTIC ITEMS

1. Saturation voltage: Vsat

Output signal voltage at which the response linearity is lost.

2. Saturation exposure : SE

Product of intensity of illumination (lx) and storage time (s) when saturation of output voltage occurs.

3. Photo response non-uniformity: PRNU

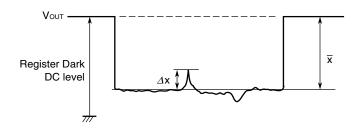
The output signal non-uniformity of all the valid pixels when the photosensitive surface is applied with the light of uniform illumination. This is calculated by the following formula.

PRNU (%) =
$$\frac{\Delta x}{\overline{x}} \times 100$$

 Δx : maximum of $|x_j - \overline{x}|$

$$\overline{x} = \frac{\sum_{j=1}^{5400} x_j}{5400}$$

x_j: Output voltage of valid pixel number j



4. Average dark signal: ADS

Average output signal voltage of all the valid pixels at light shielding. This is calculated by the following formula.

ADS (mV) =
$$\frac{\sum_{j=1}^{5400} d_j}{5400}$$

dj: Dark signal of valid pixel number j

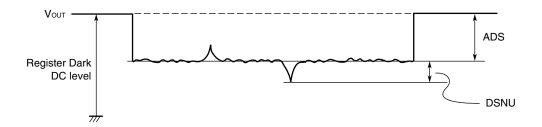


5. Dark signal non-uniformity: DSNU

Absolute maximum of the difference between ADS and voltage of the highest or lowest output pixel of all the valid pixels at light shielding. This is calculated by the following formula.

DSNU (mV): maximum of
$$|d_j - ADS|_{j=1 \text{ to } 5400}$$

dj : Dark signal of valid pixel number j



6. Output impedance : Zo

Impedance of the output pins viewed from outside.

7. Response: R

Output voltage divided by exposure (lx•s).

Note that the response varies with a light source (spectral characteristic).

8. Image lag: IL

The rate between the last output voltage and the next one after read out the data of a line.

$$\phi$$
TG Light ON OFF

Vout

Vout

Vout

Vout

Vout

Vout

9. Register imbalance: RI

The rate of the difference between the averages of the output voltage of Odd and Even pixels, against the average output voltage of all the valid pixels.

RI (%) =
$$\frac{\frac{2}{n} \left| \sum_{j=1}^{\frac{n}{2}} (V_{2j-1} - V_{2j}) \right|}{\frac{1}{n} \sum_{j=1}^{n} V_{j}} \times 100$$

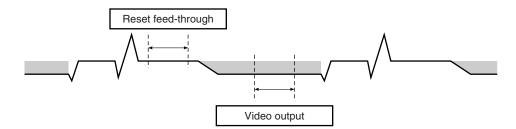
n : Number of valid pixelsV_j : Output voltage of each pixel

10. Random noise (CDS): σCDS

Random noise σ CDS is defined as the standard deviation of a valid pixel output signal with 100 times (=100 lines) data sampling at dark (light shielding). σ CDS is calculated by the following procedure.

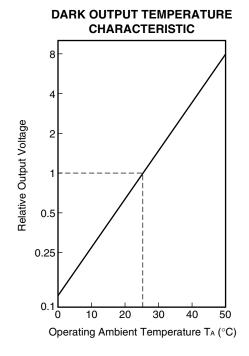
- 1. One valid photocell in one reading is fixed as measurement point.
- 2. The output level is measured during the reset feed-through period which is averaged over 100 ns to get "VDi".
- 3. The output level is measured during the video output time averaged over 100 ns to get "VOi".
- 4. The correlated double sampling output is defined by $VCDS_i = VD_i VO_i$
- 5. Repeat the above procedure (1 to 4) for 100 times (= 100 lines).
- 6. Calculate the standard deviation σ CDS using the following equation.

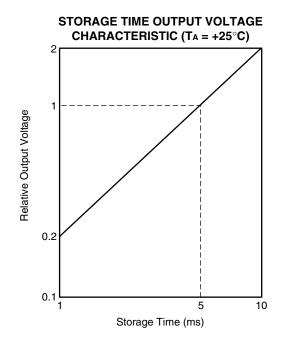
$$\sigma \text{CDS (mV)} = \sqrt{\frac{\sum_{i=1}^{100} (\text{VCDS}_i - \overline{\text{V}})^2}{100}} \quad , \ \overline{\text{V}} = \frac{1}{100} \sum_{i=1}^{100} \text{VCDS}_i$$

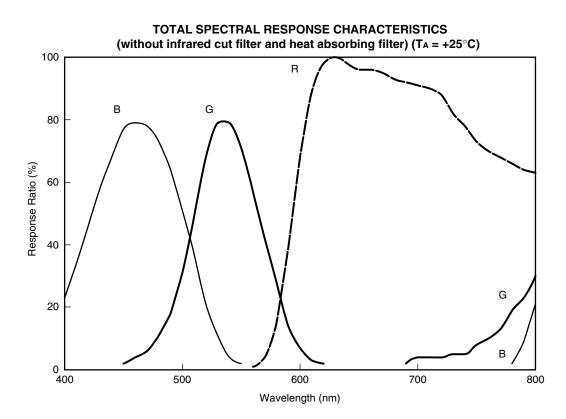




STANDARD CHARACTERISTIC CURVES (Reference Value)

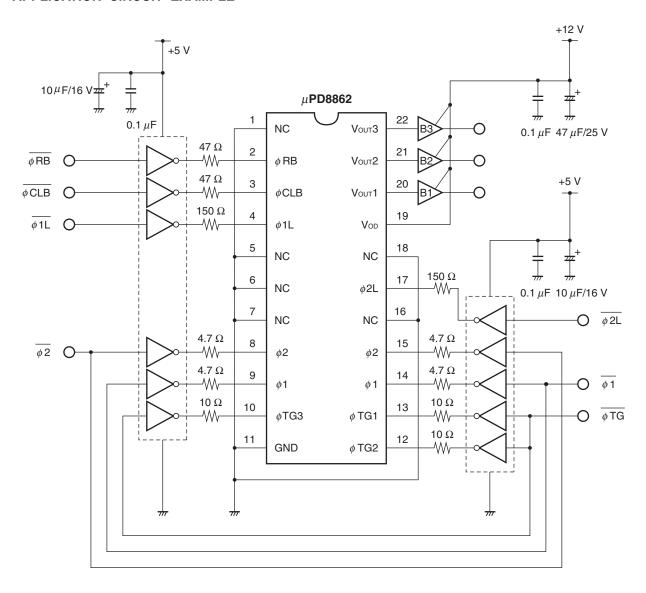






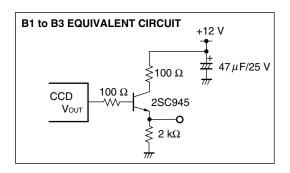


APPLICATION CIRCUIT EXAMPLE



Caution Connect the No connection pins (NC) to GND.

- **Remarks 1.** The inverters shown in the above application circuit example are the 74HC04 (data rate < 2 MHz) or the 74AC04 ($2 \le data rate < 6$ MHz).
 - 2. Inverters B1 to B3 in the above application circuit example are shown in the figure below.

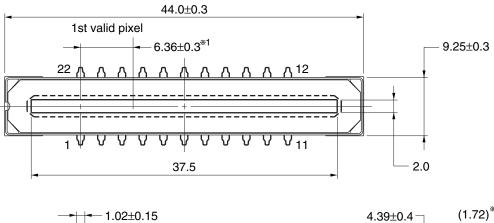


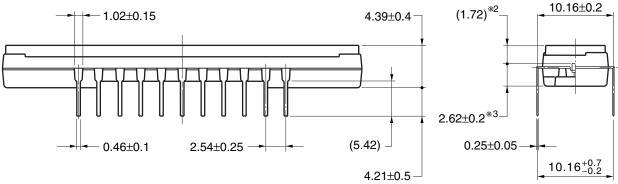


PACKAGE DRAWING

μPD8862CY CCD LINEAR IMAGE SENSOR 22-PIN PLASTIC DIP (10.16 mm (400))

(Unit: mm)





| Name | Dimensions | Refractive index |
|-------------|---------------|------------------|
| Plastic cap | 42.9×8.35×0.7 | 1.5 |

^{%1 1}st valid pixel → The center of the pin1

22C-1CCD-PKG12-2

^{※2} The surface of the CCD chip ← The top of the cap※3 The bottom of the package ← The surface of the CCD chip



RECOMMENDED SOLDERING CONDITIONS

When soldering this product, it is highly recommended to observe the conditions as shown below.

If other soldering processes are used, or if the soldering is performed under different conditions, please make sure to consult with our sales offices.

Type of Through-hole Device

μ PD8862CY : CCD linear image sensor 22-pin plastic DIP (10.16 mm (400))

| Process | Conditions | | |
|------------------------|--|--|--|
| Partial heating method | Pin temperature: 300 °C or below, Heat time: 3 seconds or less (per pin) | | |

- Cautions 1. During assembly care should be taken to prevent solder or flux from contacting the plastic cap. The optical characteristics could be degraded by such contact.
 - 2. Soldering by the solder flow method may have deleterious effects on prevention of plastic cap soiling and heat resistance. So the method cannot be guaranteed.



NOTES ON HANDLING THE PACKAGES -

1 DUST AND DIRT PROTECTING

The optical characteristics of the CCD will be degraded if the cap is scratched during cleaning. Don't either touch plastic cap surface by hand or have any object come in contact with plastic cap surface. Should dirt stick to a plastic cap surface, blow it off with an air blower. For dirt stuck through electricity ionized air is recommended. And if the plastic cap surface is grease stained, clean with our recommended solvents.

O CLEANING THE PLASTIC CAP

Care should be taken when cleaning the surface to prevent scratches.

We recommend cleaning the cap with a soft cloth moistened with one of the recommended solvents below. Excessive pressure should not be applied to the cap during cleaning. If the cap requires multiple cleanings it is recommended that a clean surface or cloth be used.

O RECOMMENDED SOLVENTS

The following are the recommended solvents for cleaning the CCD plastic cap.

Use of solvents other than these could result in optical or physical degradation in the plastic cap. Please consult your sales office when considering an alternative solvent.

| Solvents | Symbol |
|----------------------|--------|
| Ethyl Alcohol | EtOH |
| Methyl Alcohol | MeOH |
| Isopropyl Alcohol | IPA |
| N-methyl Pyrrolidone | NMP |

② MOUNTING OF THE PACKAGE

The application of an excessive load to the package may cause the package to warp or break, or cause chips to come off internally. Particular care should be taken when mounting the package on the circuit board. Don't have any object come in contact with plastic cap. You should not reform the lead frame. We recommended to use a IC-inserter when you assemble to PCB.

Also, be care that the any of the following can cause the package to crack or dust to be generated.

- 1. Applying heat to the external leads for an extended period of time with soldering iron.
- 2. Applying repetitive bending stress to the external leads.
- 3. Rapid cooling or heating

③ OPERATE AND STORAGE ENVIRONMENTS

Operate in clean environments. CCD image sensors are precise optical equipment that should not be subject to mechanical shocks. Exposure to high temperatures or humidity will affect the characteristics. So avoid storage or usage in such conditions.

Keep in a case to protect from dust and dirt. Dew condensation may occur on CCD image sensors when the devices are transported from a low-temperature environment to a high-temperature environment. Avoid such rapid temperature changes.

For more details, refer to our document "Review of Quality and Reliability Handbook" (C12769E)

4 ELECTROSTATIC BREAKDOWN

CCD image sensor is protected against static electricity, but destruction due to static electricity is sometimes detected. Before handling be sure to take the following protective measures.

- 1. Ground the tools such as soldering iron, radio cutting pliers of or pincer.
- 2. Install a conductive mat or on the floor or working table to prevent the generation of static electricity.
- 3. Either handle bare handed or use non-chargeable gloves, clothes or material.
- 4. Ionized air is recommended for discharge when handling CCD image sensor.
- 5. For the shipment of mounted substrates, use box treated for prevention of static charges.
- 6. Anyone who is handling CCD image sensors, mounting them on PCBs or testing or inspecting PCBs on which CCD image sensors have been mounted must wear anti-static bands such as wrist straps and ankle straps which are grounded via a series resistance connection of about 1 $M\Omega$.

[MEMO]



NOTES FOR CMOS DEVICES -

1 PRECAUTION AGAINST ESD FOR SEMICONDUCTORS

Note:

Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

② HANDLING OF UNUSED INPUT PINS FOR CMOS

Note:

No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

3 STATUS BEFORE INITIALIZATION OF MOS DEVICES

Note:

Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

- The information in this document is current as of July, 2003. The information is subject to change
 without notice. For actual design-in, refer to the latest publications of NEC Electronics data sheets or
 data books, etc., for the most up-to-date specifications of NEC Electronics products. Not all
 products and/or types are available in every country. Please check with an NEC Electronics sales
 representative for availability and additional information.
- No part of this document may be copied or reproduced in any form or by any means without the prior
 written consent of NEC Electronics. NEC Electronics assumes no responsibility for any errors that may
 appear in this document.
- NEC Electronics does not assume any liability for infringement of patents, copyrights or other intellectual property rights of third parties by or arising from the use of NEC Electronics products listed in this document or any other liability arising from the use of such products. No license, express, implied or otherwise, is granted under any patents, copyrights or other intellectual property rights of NEC Electronics or others.
- Descriptions of circuits, software and other related information in this document are provided for illustrative purposes in semiconductor product operation and application examples. The incorporation of these circuits, software and information in the design of a customer's equipment shall be done under the full responsibility of the customer. NEC Electronics assumes no responsibility for any losses incurred by customers or third parties arising from the use of these circuits, software and information.
- While NEC Electronics endeavors to enhance the quality, reliability and safety of NEC Electronics products, customers agree and acknowledge that the possibility of defects thereof cannot be eliminated entirely. To minimize risks of damage to property or injury (including death) to persons arising from defects in NEC Electronics products, customers must incorporate sufficient safety measures in their design, such as redundancy, fire-containment and anti-failure features.
- NEC Electronics products are classified into the following three quality grades: "Standard", "Special" and "Specific".

The "Specific" quality grade applies only to NEC Electronics products developed based on a customer-designated "quality assurance program" for a specific application. The recommended applications of an NEC Electronics product depend on its quality grade, as indicated below. Customers must check the quality grade of each NEC Electronics product before using it in a particular application.

- "Standard": Computers, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment and industrial robots.
- "Special": Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support).
- "Specific": Aircraft, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems and medical equipment for life support, etc.

The quality grade of NEC Electronics products is "Standard" unless otherwise expressly specified in NEC Electronics data sheets or data books, etc. If customers wish to use NEC Electronics products in applications not intended by NEC Electronics, they must contact an NEC Electronics sales representative in advance to determine NEC Electronics' willingness to support a given application.

(Note)

- (1) "NEC Electronics" as used in this statement means NEC Electronics Corporation and also includes its majority-owned subsidiaries.
- (2) "NEC Electronics products" means any product developed or manufactured by or for NEC Electronics (as defined above).