

# **1-3GHz Bidirectional I<sup>2</sup>C Bus Controlled Synthesiser**

Advance Information

Supersedes February 1997 version, DS3758-4.1

DS3758 - 5.0 June 1998

SP5611

The SP5611 is a single chip frequency synthesiser designed for TV tuning systems. Control data is entered in the standard I<sup>2</sup>C BUS format. The device contains 4 addressable bidirectional open collector ports, one of which is a 3-bit ADC. The information on these ports can be read via the I<sup>2</sup>C BUS. the device has 4 programmable addresses, programmed by applying a specific input voltage to the P3 address select input. This enables two or more synthesisers to be used in a system.

## **FEATURES**

- Complete 1.3GHz Single Chip System
- High Sensitivity RF Inputs
- Programmable via I<sup>2</sup>C BUS
- Low Power Consumption (5V, 20mA)
- Low Radiation
- Phase Lock Detector
- Varactor Drive Amp Disable
- 4 Bi-directional Controllable Outputs
- 5-Level ADC
- Variable I<sup>2</sup>C BUS Address for Multi-tuner Applications
- ESD Protection: 4kV, Mil-Std-883C, Method 3015<sup>(1)</sup>
- Switchable ÷512/1024 Reference Divider
- Pin and Function Compatible with SP5511S<sup>(2)</sup>
  - (1) Normal ESD handling precautions should be observed.
  - (2) The SP5511S does not have a switchable reference division ratio.

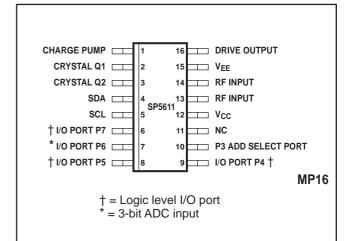


Fig. 1 Pin connections - top view

### **APPLICATIONS**



Cable Tuning Systems

VCRs

#### THERMAL DATA

 $\begin{array}{l} \theta_{JC} = 41^{\circ}C/W \\ \theta_{JA} = 111^{\circ}C/W \end{array}$ 

## **ORDERING INFORMATION**

SP5611 KG/MPAS (Tubes) SP5611S KG/MPAD (Tape and reel)

# **ELECTRICAL CHARACTERISTICS**

 $T_{AMB} = -40^{\circ}C$  to  $+85^{\circ}C$ ,  $V_{CC} = +4.5V$  to +5.5V, reference frequency = 4MHz. These Characteristics are guaranteed by either production test or design. They apply within the specified ambient temperature and supply voltage ranges unless otherwise stated.

Characteristic	Pin		Value		Units	Conditions	
Characteristic	Pin	Min.	Тур.	Typ. Max.		Conditions	
Supply current Prescaler input voltage	12 13,14	12·5	20	27 300	mA mVrms	V <sub>CC</sub> = 4·5V to 5·5V (note 1) 50MHz to 1·3GHz sinewave, see Fig. 5	
Prescaler input impedance	13,14		50		Ω		
Prescaler input capacitance	13, 14		2		pF		
SDA, SCL Input high voltage Input low voltage Input high current Input low current Leakage current	4,5 4,5 4,5 4,5 4,5 4,5	3 0		5·5 1·5 10 –10 10	V V μΑ μΑ	Input voltage = $V_{CC}$ Input voltage = 0V When $V_{CC}$ = 0V	
SDA	4,5			10	μΛ		
Output voltage	4			0.4	v	Sink current = 3mA	
Charge pump current low Charge pump current high Charge pump output leakage current Charge pump drive output current Charge pump amplifier gain Recommended crystal series resistance Crystal oscillator drive level Crystal oscillator negative resistance External reference input frequency External reference input amplitude	1 1 16 2 2 2 2 2	500 10 750 2 70	$\pm 50 \\ \pm 170$ 6400 80 1000	±5 200 8 200	μΑ μΑ nA μΑ mV p-p Ω MHz mVrms	Byte 4, bit 2 = 0, pin 1 = 2V Byte 4, bit 2 = 1, pin 1 = 2V Byte 4, bit 4 = 1, pin 1 = 2V V pin 16 = $0.7V$ Parallel resonant crystal (note 2) AC coupled sinewave	
Output Ports P4-P7 sink current P4-P7 leakage current	9-6 9-6	10		10	mA μA	$V_{OUT} = 0.7V$ $V_{OUT} = 13.2V$	
Input Ports P3 input current high P3 input current low P4, P5, P7 input voltage low P4, P5, P7 input voltage high P6 input current high P6 input current low	10 10 9,8,6 9,8,6 7 7	2.7		1 -0.5 0.8 +10 -10	mA mA V V μA μA	V pin 10 = V <sub>CC</sub> V pin 10 = 0V See Table 3 for ADC levels	

NOTES

1. Maximum power consumption is 150mW with  $V_{CC} = 5.5V$  and all ports off. 2. Resistance specified is maximum under all conditions.

# ABSOLUTE MAXIMUM RATINGS

All voltages are referred to  $V_{EE}$  and pin 3 at 0V

Parameter	Pin	Va	lue	Units	Conditions
		Min.	Max.	onito	Conditions
Supply voltage	12	-0.3	7	v	
RF input voltage	13,14		2.5	V р-р	
Port voltage	6-9	-0.3	14	V	Port in off state
	6-9	-0.3	6	V	Port in on state
Total port output current	6-9		50	mA	
Address select voltage	10	-0.3	V <sub>CC</sub> +0·3	V	
RF input DC offset	13-14	-0.3	V <sub>CC</sub> +0·3	V	
Charge pump DC offset	1	-0.3	V <sub>CC</sub> +0·3	V	
Drive output DC offset	16	-0.3	V <sub>CC</sub> +0·3	V	
Crystal oscillator DC offset	2	-0.3	V <sub>CC</sub> +0·3	V	
SDA, SCL input voltage	4,5	-0.3	V <sub>CC</sub> +0·3	V	
		-0.3	6	V	
Storage temperature		-55	+150	°C	
Junction temperature			+150	°C	

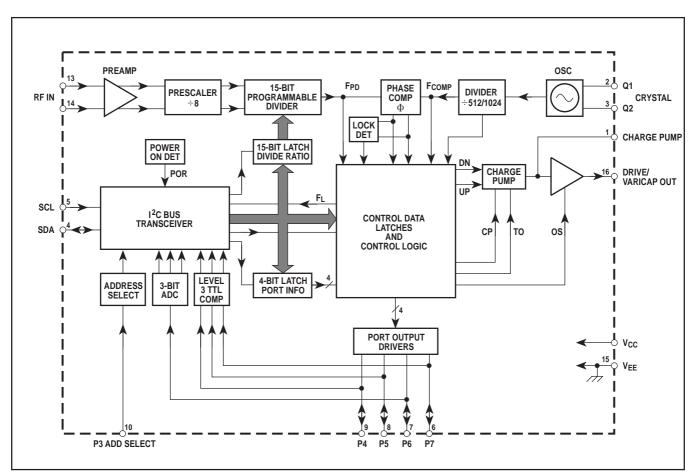


Fig. 2 Block diagram

# SP5611

#### **FUNCTIONAL DESCRIPTION**

The SP5611 is programmed from an  $I^2C$  Bus. Data and Clock are fed in on the SDA and SCL lines respectively, as defined by the  $I^2C$  Bus format. The synthesiser can either accept new data (write mode) or send data (read mode). The LSB of the address byte (R/W) sets the device into write mode if it is low and read mode if it is high. The Tables in Fig. 3 illustrate the format of the data. The device can be programmed to respond to several addresses, which enables the use of more than one synthesiser in an  $I^2C$  Bus system. Table 4 shows how the address is selected by applying a voltage to P3.

When the device receives a correct address byte, it pulls the SDA line low during the acknowledge period, and during following acknowledge periods after further data bytes are programmed. When the device is programmed into the read mode, the controller accepting the data must pull the SDA line low during all status byte acknowledge periods to read another status byte. If the controller fails to pull the SDA line low during this period, the device generates an internal STOP condition, which inhibits further reading.

#### WRITE Mode (Frequency Synthesis)

When the device is in write mode bytes 2 and 3 select the synthesised frequency, while bytes 4 and 5 control the output port states, charge pump, reference divider ratio and various test modes.

Once the correct address is received and acknowledged, the first bit of the next byte determines whether that byte is interpreted as byte 2 or 4; a logic 0 for frequency information and a logic 1 for control and output port information. When byte 2 is received the device always expects byte 3 next. Similarly, when byte 4 is received the device expects byte 5 next. Additional data bytes can be entered without the need to re-address the device until an  $I^2C$  stop condition is recognised. This allows a smooth frequency sweep for fine tuning or AFC purposes.

If the transmission of data is stopped mid-byte (for example, by another device on the bus) then the previously programmed byte is maintained.

Frequency data from bytes 2 and 3 are stored in a 15-bit register and used to control the division ratio of the 15-bit programmable divider. This is preceded by a divide-by-8 prescaler and amplifier to give excellent sensitivity at the local oscillator input, see Fig. 5. The input impedance is shown in Fig. 7.

The programmed frequency can be calculated by multiplying the programmed division ratio by 8 times the comparison frequency  $F_{COMP}$ . When frequency data is entered, the phase comparator, via a charge pump and varicap drive amplifier, adjusts the local oscillator control voltage until the output of the programmable divider is frequency and phased locked to the comparison frequency.

The reference frequency may be generated by an external source capacitively coupled into pin 2, or provided by an onchip crystal controlled oscillator. The comparison frequency  $F_{COMP}$  is derived from the reference frequency via the reference divider. The reference divider division ratio is switchable from 512 to 1024, and is controlled by bit 7 of byte 4 (TS0); a logic 1 to 512, a logic 0 for 1024. The SP5611 differs from the SP5511 in this respect, only 512 being available on the SP5511. Note that the comparison frequency is  $7\cdot8125$ kHz when a 4MHz reference is used, and divide by 512 is selected.

Bit 2 of byte 4 of the programming data (CP) controls the current in the charge pump circuit, a logic 1 for  $\pm 170\mu$ A and a logic 0 for  $\pm 50\mu$ A, allowing compensation for the variable tuning slope of the tuner and also to enable fast channel changes over the full band. When the device is frequency locked, the charge pump current is internally set to  $\pm 50\mu$ A regardless of CP.

Bit 4 of byte 4 (T0) disables the charge pump when it is set to a logic 1.

Bit 8 of byte 4 (OS) switches the charge pump drive amplifier's output off when it is set to a logic 1.

Bit 3 of byte 4 (T1) enables various test modes when set high. These modes are selected by bits 5, 6 and 7 of byte 4 (TS2, and TS1, TS0) as detailed in Table 5. When T1 is set low, TS2 and TS1 are assigned a 'don't care' condition, and TS0 selects the reference divider ratio as previously described.

Byte 5 programs the output ports P4 to P7; a logic 0 for a high impedance output and a logic 1 for low impedance (on).

#### **READ Mode**

When the device is in read mode the status byte read from the device on the SDA line takes the form shown in Table 2.

Bit 1 (POR) is the power-on reset indicator and is set to a logic 1 if the  $V_{CC}$  supply to the device has dropped below 3V (at 25°C), for example, when the device is initially turned on. The POR is reset to 0 when the read sequence is terminated by a stop command. When POR is set high (at low  $V_{CC}$ ), the programmed information is lost and the output ports are all set to high impedance.

Bit 2 (FL) indicates whether the device is phase locked, a logic 1 is present if the device is locked, and a logic 0 if the device is unlocked.

Bits 3, 4 and 5 (I2, I1, I0) show the status of the I/O Ports P7, P5 and P4 respectively. A logic 0 indicates a low level and a logic 1 a high level. If the ports are to be used as inputs they should be programmed to a high impedance state (logic 1). These inputs will then respond to data complying with TTL type voltage levels.

Bits 6,  $\overline{7}$  and 8 (A2, A1, A0) combine to give the output of the 5-level ADC. The ADC can be used to feed AFC information to the microprocessor from the IF section of the receiver, as illustrated in the typical application circuit.

#### APPLICATION

A typical application is shown in Fig. 4. All input/output interface circuits are shown in Fig. 6. The SP5611 is function and pin equivalent to the SP5511 device apart from the switchable reference divider, and has much lower power dissipation, improved RF sensitivity and better ESD performance.

	MSB							LSB		
Address	1	1	0	0	0	MA1	MA0	0	Α	Byte 1
Programmable divider	0	2 <sup>14</sup>	2 <sup>13</sup>	2 <sup>12</sup>	2 <sup>11</sup>	2 <sup>10</sup>	2 <sup>9</sup>	2 <sup>8</sup>	A	Byte 2
Programmable divider	2 <sup>7</sup>	2 <sup>6</sup>	2 <sup>5</sup>	24	2 <sup>3</sup>	2 <sup>2</sup>	2 <sup>1</sup>	2 <sup>0</sup>	Α	Byte 3
Charge pump and test bits	1	CP	T1	T0	TS2	TS1	TS0	OS	Α	Byte 4
I/O port control bits	Ρ7	P6	P5	P4	Х	Х	Х	Х	Α	Byte 5

Table 1 Write data format (MSB transmitted first)

Address	1	1	0	0	0	MA1	MA0	1	Α	Byte 1
Status byte	POR	FL	12	11	10	A2	A1	A0	А	Byte 2

Table 2 Read data format

A2	<b>A</b> 1	<b>A</b> 0	Voltage input to P6
1	0	0	0.6V <sub>CC</sub> to 13.2V
0	1	1	0·45V <sub>CC</sub> to 0·6V <sub>CC</sub>
0	1	0	$0.3V_{CC}$ to $0.45V_{CC}$
0	0	1	0·15V <sub>CC</sub> to 0·3V <sub>CC</sub>
0	0	0	0V to 0·15V <sub>CC</sub>

MA1	MA0	Address select input voltage
0	0	0V to 0.1V <sub>CC</sub>
0	1	Open circuit
1	0	$0.4V_{CC}$ to $0.6V_{CC}$
1	1	$0.9V_{CC}$ to $V_{CC}$

Table 3 ADC levels

Table 4 Address selection

T1	TS2	TS1	TS0	Operation mode description
0	Х	Х	0	Normal operation, test modes disabled, reference divider ratio = 1024
0	Х	Х	1	Normal operation, test modes disabled, reference divider ratio = 512
1	0	0	Х	Charge pump source (down). Status bit FL set to 0
1	0	1	Х	Charge pump sink (up). Status bit FL set to 1
1	1	0	0	Ports P4, P5, P6, P7set to state X
1	1	0	1	Port P7 = $F_{PD}/2$ ; P4, P5, P6 set to state X
1	1	1	Х	Port P7 = $F_{PD}$ ; P6 = $F_{COMP}$ ; P4, P5 set to state X

Table 5 Operation modes

NOTES X = don't care

For further details of test modes, see Table 6

A MA1, MA0 CP T1 T0 TS2, TS1, TS0 OS P7, P6, P5, P4, POR FL I2, I1, I0 A2, A1, A0	<ul> <li>Acknowledge bit</li> <li>Variable address bits (see Table 4)</li> <li>Charge Pump current select</li> <li>Test mode selection</li> <li>Charge pump disable</li> <li>Operation mode control bits (see Table 5)</li> <li>Varactor drive Output disable Switch</li> <li>Control output port states</li> <li>Power On Reset indicator</li> <li>Phase lock detect flag</li> <li>Digital information from ports P7, P5 and P4 respectively</li> <li>5-level ADC data from P6 (see Table 3)</li> </ul>
A2, A1, A0 X	<ul> <li>5-level ADC data from P6 (see Table 3)</li> <li>Don't care</li> </ul>

# SP5611

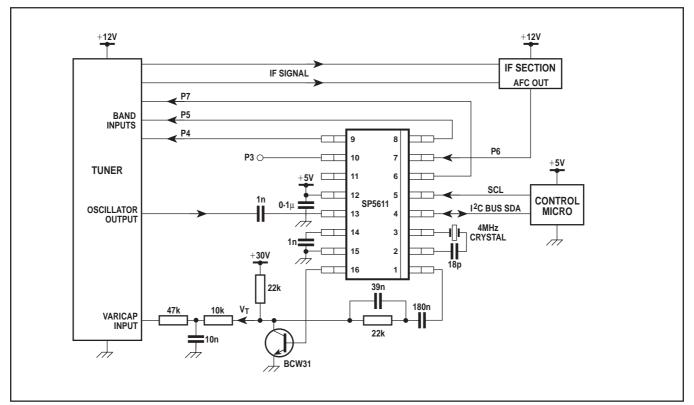


Fig. 4 Typical application

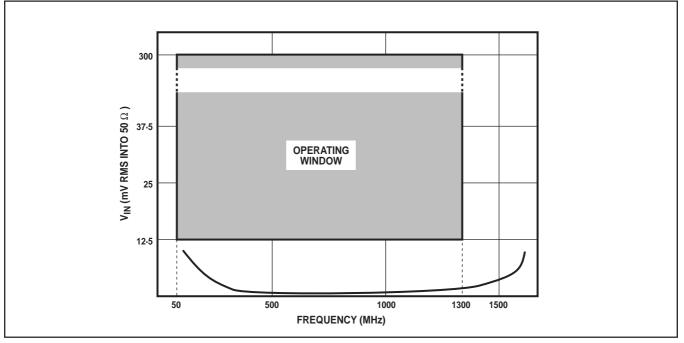


Fig. 5 Typical input sensitivity

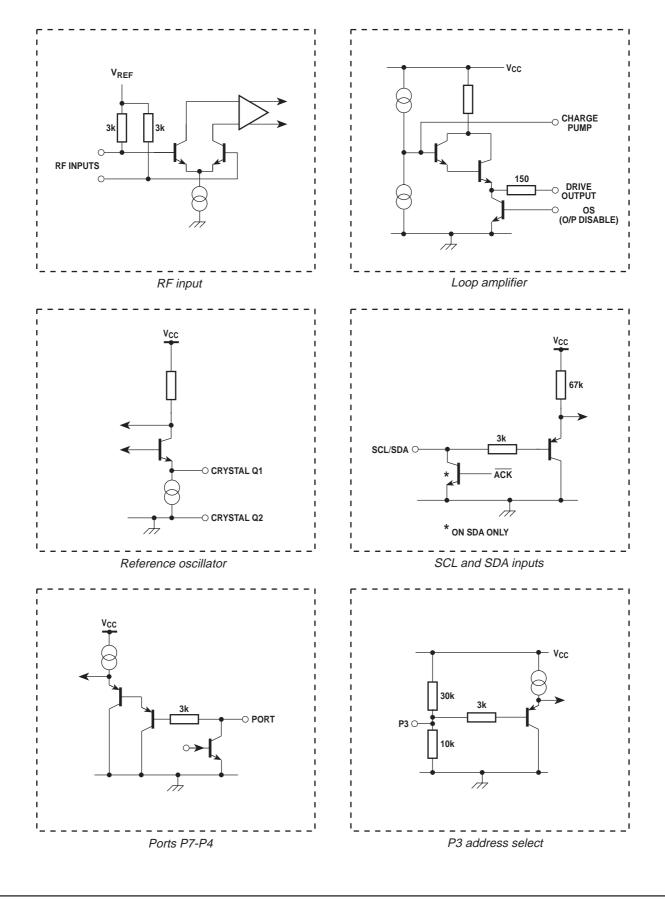


Fig. 6 SP5611 input/output interface circuits

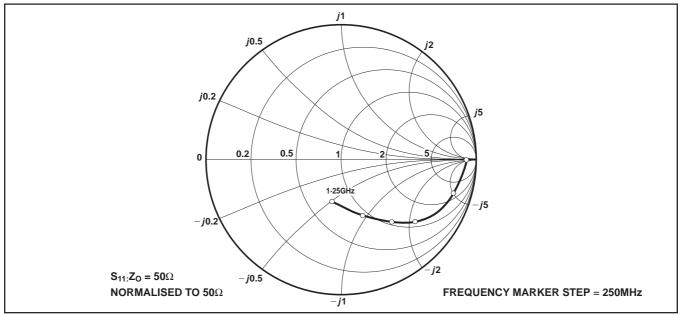


Fig. 7 Typical input impedance,

# **APPLICATION NOTES**

An application note, AN168, is available for designing with synthesisers such as the SP5611. It covers aspects such as loop filter design, decoupling and  $I^2C$  bus radiation problems.

The application note is published in the Mitel Semiconductor Media IC Handbook. A generic test/demonstration board has been produced, which can be used for the SP5611. A circuit diagram and layout for the board are shown in Figs. 8 and 9.

- The board can be used for the following purposes: (A) Measuring RF sensitivity perfomance
  - (B) Indicating port function
  - (C) Synthesising a voltage controlled oscillator
- (D)Testing external reference sources

The programming codes relevant to these tests are given in Table 6.

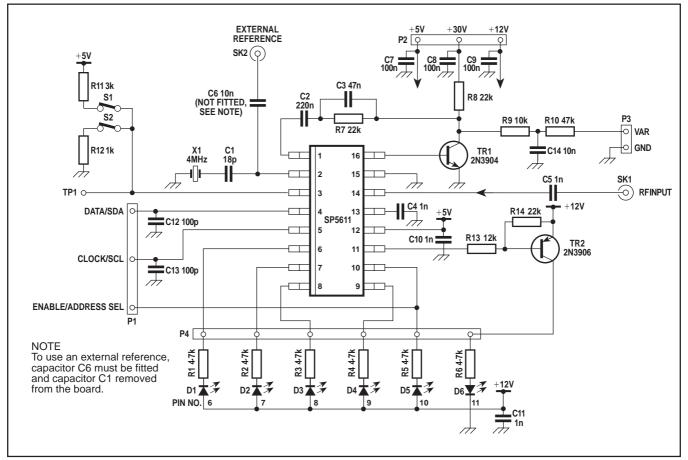


Fig. 8 Test board circuit

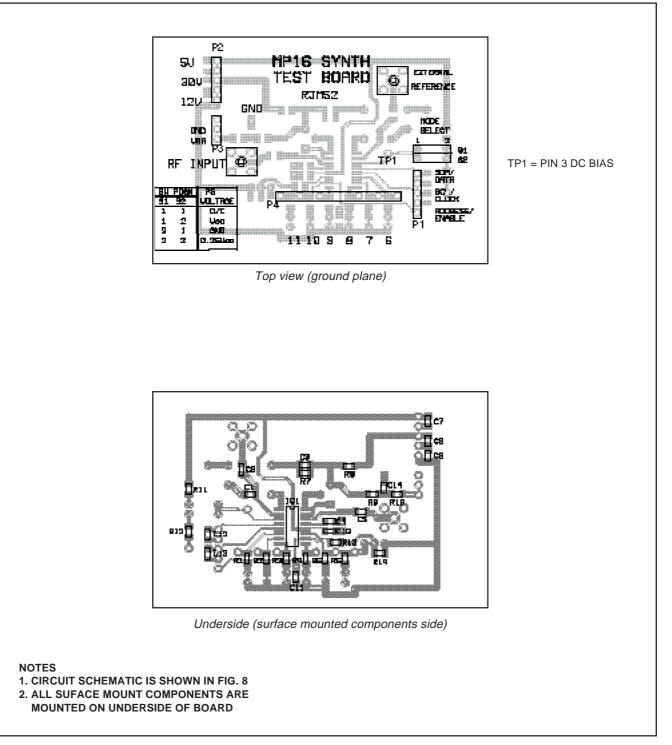


Fig. 9 Test board layout

# SP5611

### **TEST MODES**

As explained in the functional description, The SP5611 can be programmed into a numb er of test modes. These are invoked by programming Hex codes into byte 4, those most commonly used being shown in Table 6.

Other codes will also apply due to don't care conditions, which are assumed to be 1 in the Table.

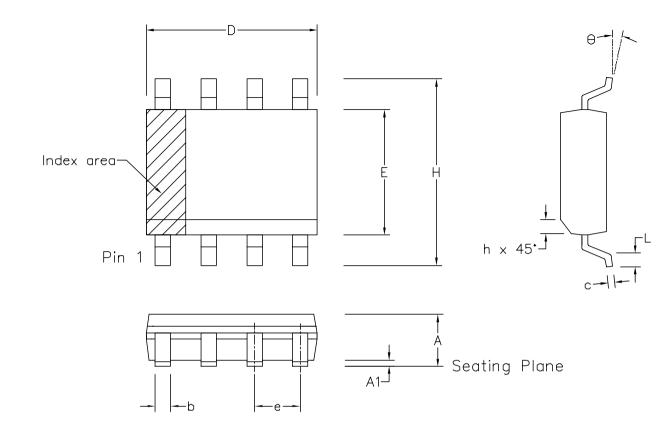
NOTE:

When looking at  $F_{PD}$  or  $F_{COMP}$  signals from ports P7 and P6. byte should be sent twice, first to set the desired reference division ratio then to switch on the chosen test mode.

The pulses can then be measured by simply connecting an oscilloscope or counter to the relevant output pin on the test board.

Or exertion mode description	Hex code (byte 4)				
Operation mode description	CP high mode	CP low mode			
Normal operation, reference divider ratio = 1024	CC	8C			
Normal operation, reference divider ratio = 512	CE	8E			
Charge pump source (down), FL set to 0	E2	A2			
Charge pump sink (up), FL set to 1	E6	A6			
Port P7 = $F_{PD}/2$	EA	AA			
Port P7 = $F_{PD}$ , P6 = $F_{COMP}$	EE	AE			
Charge pump disable, reference divider ratio = 512	DE	9E			
Varactor line disable, reference divider ratio = 512	CF	8F			
Charge pump and varactor linedisable, reference divider ratio = 512	DF	9F			

Table 5 Operation modes



	Min	Max	Min	Max			
	mm	mm	inch	inch			
A	1.35	1.75	0.053	0.069			
A1	0.10	0.25	0.004	0.010			
D	9.80	10.00	0.386	0.394			
Н	5.80	6.20	0.228	0.244			
E	3.80	4.00	0.150	0.157			
L	0.40	1.27	0.016	0.050			
e	1.27	BSC	0.050 BSC				
b	0.33	0.51	0.013	0.020			
С	0.19	0.25	0.008	0.010			
0	O°	8"	Û°	8°			
h	0.25	0.50	0.010	0.020			
	Pin Features						
N	1	6	16				
Conforms to JEDEC MS-012AC lss. C							

# Notes:

- 1. The chamfer on the body is optional. If it not present, a visual index feature, e.g. a dot, must be located within the cross-hatched area.
- 2. Controlling dimension are in inches.
- Dimension D do not include mould flash, protusion or gate burrs. These shall not exceed 0.006" per side.
   Dimension E1 do not include inter-lead flash or protusion. These shall not exceed 0.010" per side.
   Dimension b does not include dambar protusion/intrusion. Allowable dambar protusion shall be 0.004"
- total in excess of b dimension.

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