

CMOS quad tri-state differential line driver

General features

■ TTL input compatible

■ Typical propagation delay: 6ns

■ Typical output skew: 0.5ns

■ Output will not load line when V_{CC} = 0V

Meets the requirements of EIA standard RS-422

Operation from single 5V supply

3-state outputs for connection to system buses

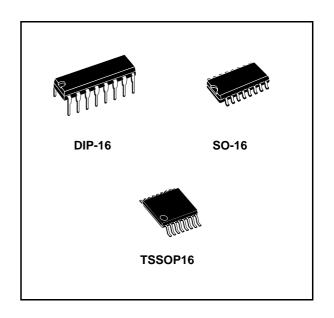
■ Low quiescent current

Available in surface mount

Description

The ST26C31 is a quad differential line driver designed for digital data transmission over balanced lines and meets all the requirements of EIA standard RS-422 while retaining the low power characteristics of CMOS.

The ST26C31 accepts TTL or CMOS input levels and translates these to RS-422 output levels. This part uses special outputs circuitry common to all four drivers. All outputs are protected against damage due to electrostatic discharge by diode to V_{CC} and ground.



Order code

Part number	Temperature range	Package	Packaging
ST26C31BN	-40 to 85 °C	DIP-16	25 parts per tube / 40 tube per box
ST26C31BDR	-40 to 85 °C	SO-16 (Tape & Reel)	2500 parts per reel
ST26C31BTR	-40 to 85 °C	TSSOP16 (Tape & Reel)	2500 parts per reel

Contents ST26C31

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ST26C31 Pin configuration

1 Pin configuration

Figure 1. Pin connections

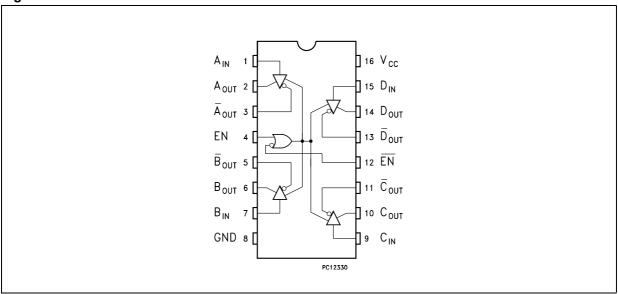


Table 1. Pin description

Pin n°	Symbol	Name and function
1	A _{IN}	INPUT A
2	A _{OUT}	Channel A Output
3	A _{OUT}	Channel A Output
4	EN	ENABLE
5	B _{OUT}	Channel B Output
6	B _{OUT}	Channel B Output
7	B _{IN}	INPUT B
8	GND	Ground
9	C _{IN}	INPUT C
10	C _{OUT}	Channel C Output
11	C _{OUT}	Channel C Output
12	EN	ENABLE
13	D _{OUT}	Channel D Output
14	D _{OUT}	Channel D Output
15	D _{IN}	INPUT D
16	V _{CC}	Supply Voltage

Pin configuration ST26C31

Table 2. Truth table

Enable	Enable	Input	Output	Output
L	Н	Х	Z	Z
All other combination	one of enable inputs	L	L	Н
All other combinations of enable inputs		Н	Н	L

Note: $L = Low \ Voltage \ State$

H = High Logic State
X = Don't Care
Z = High Impedance

ST26C31 Maximum ratings

2 Maximum ratings

Table 3. Absolute maximum ratings (*Note 1*, *Note 2*)

Symbol	Parameter	Value	Unit
V_{CC}	Supply voltage	-0.5 to 7	V
V _{IN}	DC Input voltage	-0.5 to (V _{CC} + 0.5)	V
V _{OUT}	DC Output voltage (high or low state)	-0.5 to 7	V
I _{IK}	Clamp diode current	± 20	mA
I _{OUT}	DC Output current per pin	± 150	mA
I _{CC}	DC V _{CC} or gnd current	± 150	mA
T _{STG}	Storage temperature range	-65 to +150	°C

Note:

- Absolute Maximum Ratings are those values beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the device should be operated at these limits. The table of electrical characteristics provide conditions for actual device operation.
- 2 Unless otherwise specified, all voltage are referenced to ground. All currents into the device pins are positive; all currents out of the device pins are negative.

Table 4. Recommended operating conditions

Symbol	Parameter	Value	Unit
V _{CC}	Supply voltage	4.5 to 5.5	V
V _{IN}	DC Input voltage	0 to V _{CC}	V
V _{OUT}	DC Output voltage (high or low state)	0 to V _{CC}	V
V _{OUT}	DC Output voltage (V _{CC} = 0V or high impedance)	0 to 5	V
T _A	Operating temperature range	-40 to +85	°C
t _r , t _f	Maximum enable input rise or fall times	500	ns

Electrical characteristics ST26C31

3 Electrical characteristics

Table 5. Electrical characteristics ($V_{CC} = 5V \pm 10\%$, unless otherwise specified, See *Note 1*)

Symbol	Parameter	Te:		Value			
Symbol	Farameter	ie:	Min.	Тур.	Max.	Unit	
V _{IH}	High level input voltage			2			V
V _{IL}	Low level input voltage					0.8	V
V _{OH}	High level output voltage	$V_{IN} = V_{IH} \text{ or } V_{I}$	_L , I _{OUT} = -20mA	2.5	3.4		V
V _{OL}	Low level output voltage	$V_{IN} = V_{IH}$ or V_{I}	L, I _{OUT} = +20mA		0.3	0.5	V
V _T	Differential output voltage	$R_L = 100 \Omega (N)$	ote 2)	2	3.1		V
$V_T - \overline{V}_T$	Difference in differential output voltage	R _L = 100 Ω (<i>Note 2</i>)				0.4	V
V _{OS}	Common mode output voltage	R _L = 100 Ω (<i>Note 2</i>)			1.8	3	V
V _{OS} - V _{OS}	Difference in common mode output voltage	R _L = 100 Ω (<i>Note 2</i>)				0.4	V
I _{IN}	Input current	$V_{IN} = V_{CC}, GN$	ID, V _{IH} or V _{IL}			±1	μΑ
	Quiescent supply current		$V_{IN} = V_{CC}$ or GND		200	500	μΑ
I _{CC}	(Note 2)	I _{OUT} = 0 μA	V _{IN} = 2.4 or 0.5 V (<i>Note 3</i>)		0.8	2	mA
I _{OZ}	3-STATE output leakage current	$V_{OUT} = V_{CC}$ or GND ENABLE = V_{IL} ENABLE = V_{IH}			±0.5	±5	μА
I _{SC}	Output short circuit current	V _{IN} = V _{CC} or GND (<i>Note 2, Note 4</i>)		-30		-150	mA
1	Power off output leakage	V _{CC} = 0 V	V _{OUT} = 6 V			100	μΑ
lOFF	current (Note 2)	ACC = 0 A	V _{OUT} = -0.25 V			-100	μΑ

Note: 1 Unless otherwise specified, min/max limits apply across the recommended operating temperature range. All typical are given for $V_{CC} = 5V$ and $T_a = 25^{\circ}C$

- 2 See EIA Specification RS422 for exact test conditions.
- 3 Measured per pin input. All other input at V_{CC} or GND.
- 4 This is the current sourced when a high output is shorted to ground. Only one output at time should be shorted.

Table 6. Switching characteristics ($V_{CC} = 5V \pm 10\%$, $t_r = t_f \le 6$ ns, See *Note 1*)

Symbol	Doromotor	Test Conditions	Value			Unit	
Symbol	Parameter	rest Conditions	Min.	Тур.	Max.	Oill	
t _{PLH} t _{PHL}	Propagation delay input to output	S1 Open	2	6	11	ns	
Skew	(Note 2)	S1 Open		0.5	2	ns	
t _{TLH} t _{THL}	Differential output rise and fall times	S1 Open		6	10	ns	
t _{PZH}	Output enable time	S1 Closed		11	19	ns	
t _{PZL}	Output enable time	S1 Closed		13	21	ns	
t _{PHZ}	Output disable time (Note 3)	S1 Closed		5	9	ns	
t _{PLZ}	Output disable time (Note 3)	S1 Closed		7	11	ns	
C _{PD}	Power dissipation capacitance (Note 4)			50		pF	
C _{IN}	Input capacitance			6		pF	

Note:

- 1 Unless otherwise specified, min/max limits apply across the recommended operating temperature range. All typical are given for V_{CC} =5V and T_a = 25°C
- 2 Skewis defined as the difference in propagation delays between complementary outputs at the 50% point.
- 3 Output disable time is the delay from the control input being switched to the output transistors tuning off. The actual disable times are less than indicated due to the delay added by RC time constant of the load.
- 4 CPD determines the no load dynamic power consumption, $P_D = C_{PD} V_{CC}^2$, $f = I_{CC} V_{CC}$, and the no load dynamic current consumption, $P_D = C_{PD} V_{CC} f + I_{CC}$.

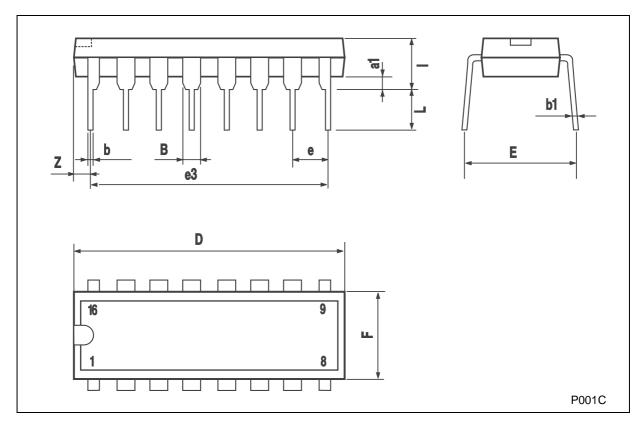
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4 Package mechanical data

In order to meet environmental requirements, ST offers these devices in ECOPACK® packages. These packages have a Lead-free second level interconnect. The category of second level interconnect is marked on the package and on the inner box label, in compliance with JEDEC Standard JESD97. The maximum ratings related to soldering conditions are also marked on the inner box label. ECOPACK is an ST trademark. ECOPACK specifications are available at: www.st.com

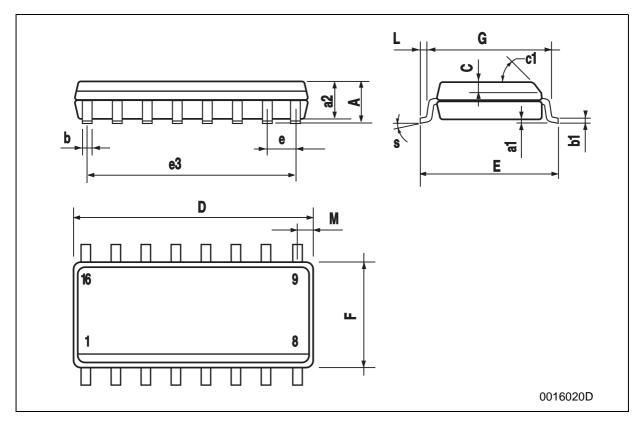
Plastic DIP-16 (0.25) MECHANICAL DATA

DIM	mm.			inch		
DIM.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
a1	0.51			0.020		
В	0.77		1.65	0.030		0.065
b		0.5			0.020	
b1		0.25			0.010	
D			20			0.787
E		8.5			0.335	
е		2.54			0.100	
e3		17.78			0.700	
F			7.1			0.280
1			5.1			0.201
L		3.3			0.130	
Z			1.27			0.050



SO-16 MECHANICAL DATA

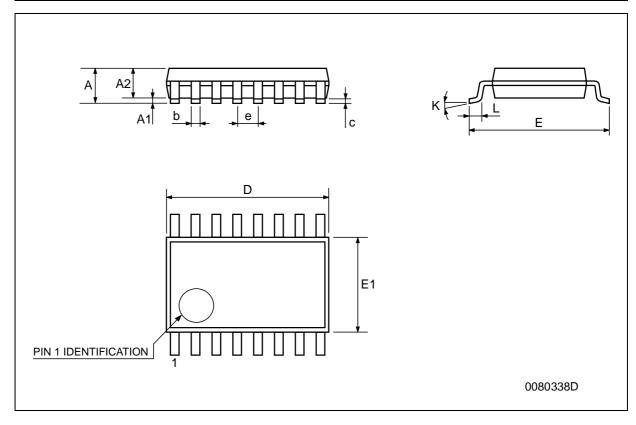
DIM		mm.			inch		
DIM.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.	
А			1.75			0.068	
a1	0.1		0.25	0.004		0.010	
a2			1.64			0.063	
b	0.35		0.46	0.013		0.018	
b1	0.19		0.25	0.007		0.010	
С		0.5			0.019		
c1			45°	(typ.)			
D	9.8		10	0.385		0.393	
Е	5.8		6.2	0.228		0.244	
е		1.27			0.050		
e3		8.89			0.350		
F	3.8		4.0	0.149		0.157	
G	4.6		5.3	0.181		0.208	
L	0.5		1.27	0.019		0.050	
М			0.62			0.024	
S			8° (ı	max.)		1	



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TSSOP16 MECHANICAL DATA

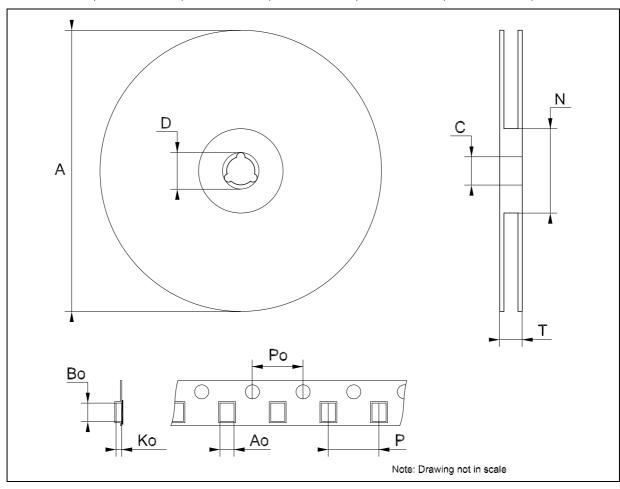
DIM	mm.			inch		
DIM.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
А			1.2			0.047
A1	0.05		0.15	0.002	0.004	0.006
A2	0.8	1	1.05	0.031	0.039	0.041
b	0.19		0.30	0.007		0.012
С	0.09		0.20	0.004		0.0079
D	4.9	5	5.1	0.193	0.197	0.201
E	6.2	6.4	6.6	0.244	0.252	0.260
E1	4.3	4.4	4.48	0.169	0.173	0.176
е		0.65 BSC			0.0256 BSC	
К	0°		8°	0°		8°
L	0.45	0.60	0.75	0.018	0.024	0.030



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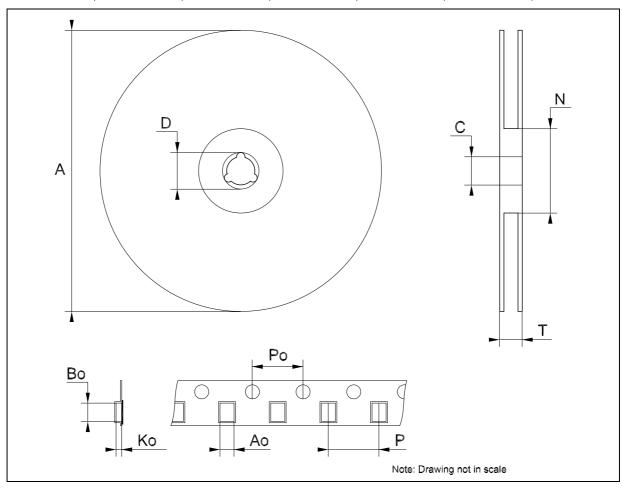
Tape & Reel SO-16 MECHANICAL DATA

DIM		mm.			inch		
DIM.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.	
А			330			12.992	
С	12.8		13.2	0.504		0.519	
D	20.2			0.795			
N	60			2.362			
Т			22.4			0.882	
Ao	6.45		6.65	0.254		0.262	
Во	10.3		10.5	0.406		0.414	
Ко	2.1		2.3	0.082		0.090	
Po	3.9		4.1	0.153		0.161	
Р	7.9		8.1	0.311		0.319	



Tape 8	& Reel	TSSOP16 MECHANICAL DATA
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DIM.	mm.			inch		
	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
А			330			12.992
С	12.8		13.2	0.504		0.519
D	20.2			0.795		
N	60			2.362		
Т			22.4			0.882
Ao	6.7		6.9	0.264		0.272
Во	5.3		5.5	0.209		0.217
Ко	1.6		1.8	0.063		0.071
Po	3.9		4.1	0.153		0.161
Р	7.9		8.1	0.311		0.319



Revision history ST26C31

5 Revision history

Table 7. Revision history

Date	Revision	Changes
02-May-2006	7	Order codes has been updated and new template.

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