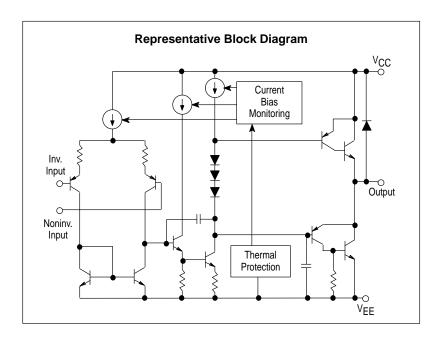


Advance Information

Dual Power Operational Amplifier

The TCA0372 is a monolithic circuit intended for use as a power operational amplifier in a wide range of applications, including servo amplifiers and power supplies. No deadband crossover distortion provides better performance for driving coils.

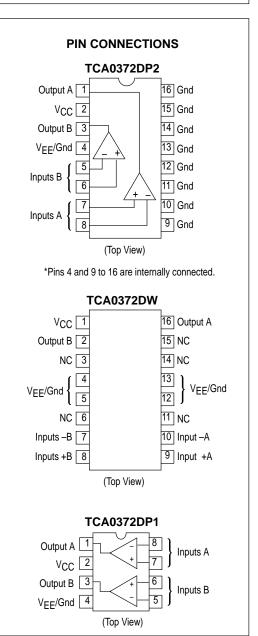
- Output Current to 1.0 A
- Slew Rate of 1.3 V/μs
- Wide Bandwidth of 1.1 MHz
- Internal Thermal Shutdown
- Single or Split Supply Operation
- Excellent Gain and Phase Margins
- Common Mode Input Includes Ground
- Zero Deadband Crossover Distortion



ORDERING INFORMATION

| Device | Operating Temperature Range | Package |
|------------|--|----------------|
| TCA0372DW | | SOP (12+2+2) L |
| TCA0372DP1 | $T_J = -40^{\circ} \text{ to } +150^{\circ}\text{C}$ | Plastic DIP |
| TCA0372DP2 | | Plastic DIP |

DW SUFFIX PLASTIC PACKAGE CASE 751G SOP (12+2+2)L DP2 SUFFIX PLASTIC PACKAGE CASE 648 DP1 SUFFIX PLASTIC PACKAGE CASE 626 B 1



MAXIMUM RATINGS

| Rating | Symbol | Value | Unit |
|---|--------------------|-------------|------|
| Supply Voltage (from V _{CC} to V _{EE}) | ٧s | 40 | V |
| Input Differential Voltage Range | VIDR | (Note 1) | V |
| Input Voltage Range | VIR | (Note 1) | V |
| Junction Temperature (Note 2) | TJ | +150 | °C |
| Storage Temperature Range | T _{stg} | -55 to +150 | °C |
| DC Output Current | Io | 1.0 | А |
| Peak Output Current (Nonrepetitive) | I _(max) | 1.5 | Α |

DC ELECTRICAL CHARACTERISTICS ($V_{CC} = +15 \text{ V}$, $V_{FF} = -15 \text{ V}$, R_I connected to ground, $T_{IJ} = -40^{\circ}$ to $+125^{\circ}$ C.)

| Characteristics | Symbol | Min | Тур | Max | Unit |
|--|----------------------|------|-----------------------|----------------|-------|
| Input Offset Voltage (V _{CM} = 0) | VIO | | | | mV |
| $T_J = +25^{\circ}C$ | | _ | 1.0 | 15 | |
| T _J , T _{low} to T _{high} | | _ | _ | 20 | |
| Average Temperature Coefficient of Offset Voltage | ΔV _{IO} /ΔΤ | _ | 20 | _ | μV/°C |
| Input Bias Current (V _{CM} = 0) | I _{IB} | _ | 100 | 500 | nA |
| Input Offset Current (V _{CM} = 0) | IIO | _ | 10 | 50 | nA |
| Large Signal Voltage Gain | A _{VOL} | 30 | 100 | _ | V/mV |
| $V_{O} = \pm 10 \text{ V}, R_{L} = 2.0 \text{ k}$ | | | | | |
| Output Voltage Swing (I _L = 100 mA) | VOH | | | | V |
| T _J = +25°C | | 14.0 | 14.2 | - | |
| $T_J = T_{low}$ to T_{high} $T_{.l} = +25^{\circ}C$ | Voi | 13.9 | | | |
| $T_J = +23 \text{ C}$ $T_J = T_{low} \text{ to } T_{high}$ | VOL | | — 14.Z — | -14.0 -13.9 | |
| Output Voltage Swing (I _L = 1.0 A) | Vari | | | 10.0 | V |
| $V_{CC} = +24 \text{ V. VFF} = 0 \text{ V. T.}_{1} = +25^{\circ}\text{C}$ | VOH | 22.5 | 22.7 | l _ | V |
| $V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_J = T_{low} \text{ to } T_{high}$ | | 22.5 | | l _ | |
| V _{CC} = +24 V, V _{FF} = 0 V, T _{.I} = +25°C | VOL | _ | 1.3 | 1.5 | |
| $V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_J = T_{low} \text{ to } T_{high}$ | "- | _ | _ | 1.5 | |
| Input Common Mode Voltage Range | VICR | | | | V |
| $T_J = +25^{\circ}C$ | | | to (V _{CC} - | | |
| $T_{J} = T_{low}$ to T_{high} | | VEE | to (VCC - | -1.3) | |
| Common Mode Rejection Ratio (R _S = 10 k) | CMRR | 70 | 90 | _ | dB |
| Power Supply Rejection Ratio (R _S = 100 Ω) | PSRR | 70 | 90 | _ | dB |
| Power Supply Current | ID | | | | mA |
| $T_J = +25^{\circ}C$ | | - | 5.0 | 10 | |
| $T_J = T_{low}$ to T_{high} | | | | 14 | |

AC ELECTRICAL CHARACTERISTICS (V_{CC} = +15 V, V_{EE} = -15 V, R_L connected to ground, T_J = +25°C, unless otherwise noted.)

| Characteristics | Symbol | Min | Тур | Max | Unit |
|---|----------------|------------|------|-----|---------|
| Slew Rate ($V_{in} = -10 \text{ V to } +10 \text{ V}, R_L = 2.0 \text{ k}, C_L = 100 \text{ pF}$) $A_V = -1.0, T_J = T_{low} \text{ to } T_{high}$ | SR | 1.0 | 1.4 | _ | V/µs |
| Gain Bandwidth Product (f = 100 kHz, C_L = 100 pF, R_L = 2.0 k) T_J = 25°C T_J = T_{low} to T_{high} | GBW | 0.9 0.7 | 1.4 | _ | MHz |
| Phase Margin $T_J = T_{low}$ to T_{high} $R_L = 2.0 \text{ k}$, $C_L = 100 \text{ pF}$ | φm | _ | 65 | _ | Degrees |
| Gain Margin $R_L = 2.0 \text{ k}, C_L = 100 \text{ pF}$ | Am | _ | 15 | _ | dB |
| Equivalent Input Noise Voltage $R_S = 100 \Omega$, $f = 1.0$ to 100 kHz | e _n | _ | 22 | _ | nV/√Hz |
| Total Harmonic Distortion $A_V = -1.0$, $R_L = 50 \Omega$, $V_O = 0.5 VRMS$, $f = 1.0 kHz$ | THD | _ | 0.02 | _ | % |

 $\textbf{NOTE:} \ \ \text{In case V}_{\text{EE}} \ \text{is disconnected before V}_{\text{CC}}, \text{a diode between V}_{\text{EE}} \ \text{and Ground is recommended to avoid damaging the device.}$

NOTES: 1. Either or both input voltages should not exceed the magnitude of V_{CC} or V_{EE}.

2. Power dissipation must be considered to ensure maximum junction temperature (T_J) is not exceeded.

Figure 1. Supply Current versus Suppy Voltage with No Load

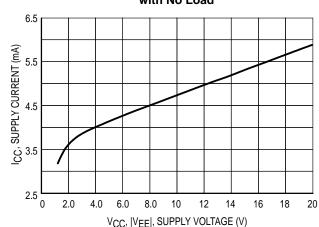


Figure 2. Output Saturation Voltage versus Load Current

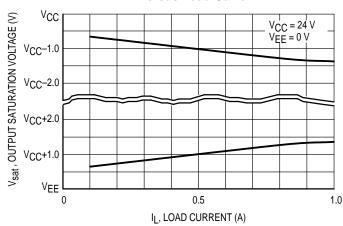


Figure 3. Voltage Gain and Phase versus Frequency

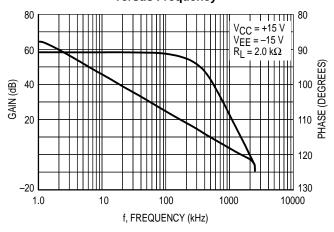


Figure 4. Phase Margin versus Output Load Capacitance

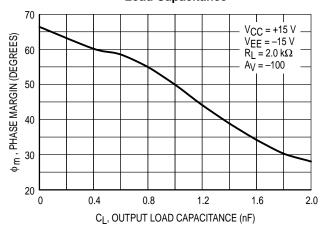


Figure 5. Small Signal Transient Response

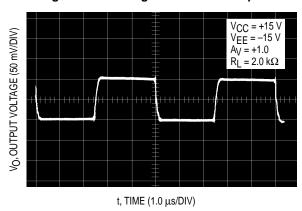


Figure 6. Large Signal Transient Response

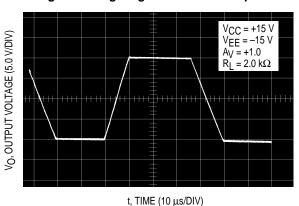


Figure 7. Sine Wave Reponse

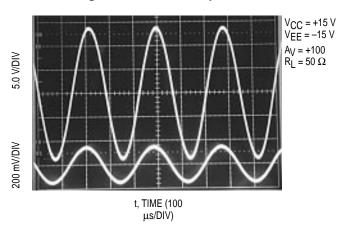


Figure 8. Bidirectional DC Motor Control with Microprocessor–Compatible Inputs

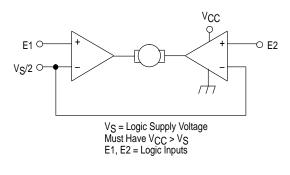
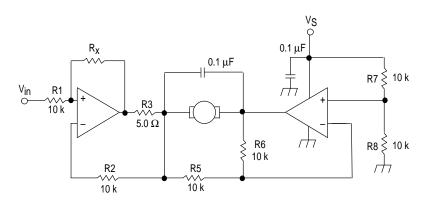


Figure 9. Bidirectional Speed Control of DC Motors



For circuit stability, ensure that $R_X > \frac{2R3 \cdot R1}{R_M}$ where, R_M = internal resistance of motor. The voltage available at the terminals of the motor is: $V_M = 2 \ (V_1 - \frac{VS}{2}) + |R_0| \cdot I_M$ where, $|R_0| = \frac{2R3 \cdot R1}{R_X}$ and I_M is the motor current.

THERMAL INFORMATION

The maximum power consumption an integrated circuit can tolerate at a given operating ambient temperature can be found from the equation:

$$P_{D(TA)} = \frac{T_{J(max)} - T_{A}}{R_{\theta JA} (typ)}$$

where, $P_{D(TA)}$ = power dissipation allowable at a given operating ambient temperature.

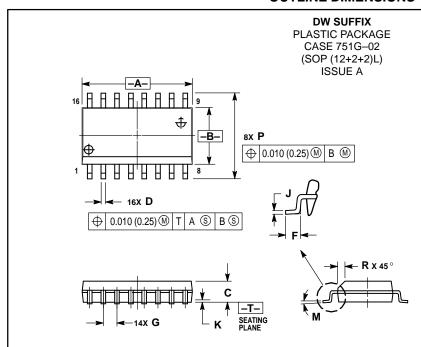
This must be greater than the sum of the products of the supply voltages and supply currents at the worst case operating condition.

T_{J(max)} = Maximum operating junction temperature as listed in the maximum ratings section.

T_A = Maximum desired operating ambient temperature.

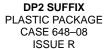
 $R_{\theta JA(typ)} = Typical thermal resistance junction–to–ambient.$

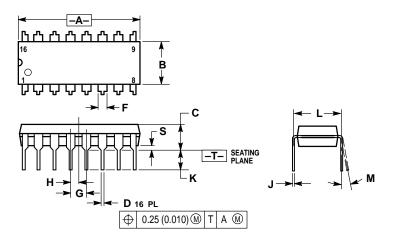
OUTLINE DIMENSIONS



- NOTES:
 1. DIMENSIONING AND TOLERANCING PER ANSI
- Y14.5M, 1982.
 2. CONTROLLING DIMENSION: MILLIMETER.
- DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
- MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER
- MAXIMUM MULLI PROTRUSION 0.13 (0.006) PER SIDE. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.13 (0.005) TOTAL IN EXCESS OF D DIMENSION AT MAXIMUM MATERIAL CONDITION.

| | MILLIN | IETERS | INC | HES |
|-----|----------|--------|-----------|-------|
| DIM | MIN | MAX | MIN | MAX |
| Α | 10.15 | 10.45 | 0.400 | 0.411 |
| В | 7.40 | 7.60 | 0.292 | 0.299 |
| С | 2.35 | 2.65 | 0.093 | 0.104 |
| D | 0.35 | 0.49 | 0.014 | 0.019 |
| F | 0.50 | 0.90 | 0.020 | 0.035 |
| G | 1.27 BSC | | 0.050 BSC | |
| J | 0.25 | 0.32 | 0.010 | 0.012 |
| K | 0.10 | 0.25 | 0.004 | 0.009 |
| M | 0 ° | 7 ° | 0 ° | 7 ° |
| Р | 10.05 | 10.55 | 0.395 | 0.415 |
| R | 0.25 | 0.75 | 0.010 | 0.029 |



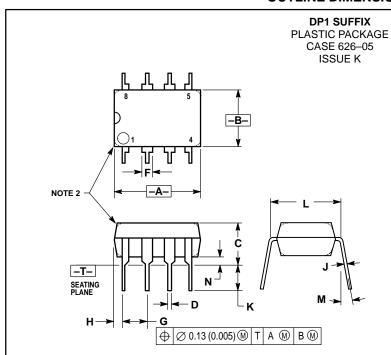


NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI
- DIMENSIONING PER AINSI Y14.5M, 1982. CONTROLLING DIMENSION: INCH. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL. DIMENSION B DOES NOT INCLUDE MOLD FLASH. ROUNDED CORNERS OPTIONAL.

| | INC | HES | MILLIN | IETERS |
|-----|-------|-------------|----------|--------|
| DIM | MIN | MAX | MIN | MAX |
| Α | 0.740 | 0.770 | 18.80 | 19.55 |
| В | 0.250 | 0.270 | 6.35 | 6.85 |
| С | 0.145 | 0.175 | 3.69 | 4.44 |
| D | 0.015 | 0.021 | 0.39 | 0.53 |
| F | 0.040 | 0.70 | 1.02 | 1.77 |
| G | 0.100 | BSC | 2.54 BSC | |
| Н | 0.050 | 0.050 BSC 1 | | BSC |
| J | 0.008 | 0.015 | 0.21 | 0.38 |
| K | 0.110 | 0.130 | 2.80 | 3.30 |
| L | 0.295 | 0.305 | 7.50 | 7.74 |
| M | 0° | 10 ° | 0° | 10 ° |
| S | 0.020 | 0.040 | 0.51 | 1.01 |

OUTLINE DIMENSIONS



- NOTES:

 1. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.

 2. PACKAGE CONTOUR OPTIONAL (ROUND OR SQUARE CORNERS).

 3. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

| | MILLIMETERS | | INC | HES | |
|-----|-------------|----------|-------|-----------|--|
| DIM | MIN | MAX | MIN | MAX | |
| Α | 9.40 | 10.16 | 0.370 | 0.400 | |
| В | 6.10 | 6.60 | 0.240 | 0.260 | |
| С | 3.94 | 4.45 | 0.155 | 0.175 | |
| D | 0.38 | 0.51 | 0.015 | 0.020 | |
| F | 1.02 | 1.78 | 0.040 | 0.070 | |
| G | 2.54 | 2.54 BSC | | 0.100 BSC | |
| Н | 0.76 | 1.27 | 0.030 | 0.050 | |
| J | 0.20 | 0.30 | 0.008 | 0.012 | |
| K | 2.92 | 3.43 | 0.115 | 0.135 | |
| L | 7.62 BSC | | 0.300 | BSC | |
| M | | 10° | | 10° | |
| N | 0.76 | 1.01 | 0.030 | 0.040 | |

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