



DC COUPLING HIGH VOLTAGE VIDEO AMPLIFIER

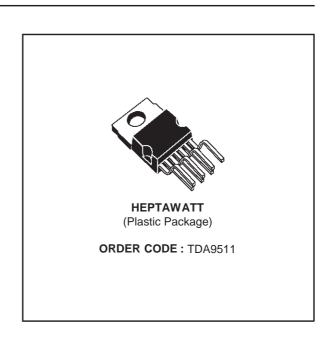
■ BANDWIDTH: 40MHzTYPICAL ■ RISE AND FALLTIME: 9ns TYPICAL

■ SUPPLY VOLTAGE: 110V ■ POWER DISSIPATION: 3.0W

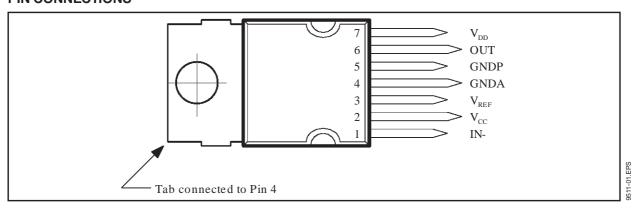
■ ESD PROTECTED



The TDA9511 is a video amplifier designed with a high voltage Bipolar/CMOS/DMOS technology (BCD). It drives in DC coupling mode one cathode of a monitor and is protected against flashovers. It is available in Heptawatt package.



PIN CONNECTIONS

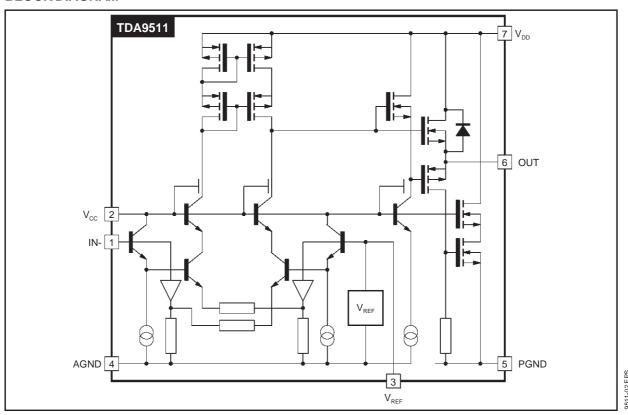


PIN CONFIGURATION

Pin N	Symbol	Function				
1	IN-	Input of the amplifier	7			
2	V _{CC}	Low Voltage Power Supply (12V Typ.)]			
3	V_{REF}	ernal Voltage Reference (3.3V)				
4	GNDA	nalog Ground				
5	GNDP	Power Ground	7			
6	OUT	Output driving the cathode				
7	V _{DD}	High Voltage Power Supply (110V Max.)				

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BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
V_{DD}	Supply High Voltage (Pin 7)	120	V
V _{CC}	Supply Low Voltage (Pin 2)	20	V
VESD	ESD Susceptibility Human Body Model, 100pF Discharge through 1.5k Ω EIAJ Norm, 200pF Discharge through 0Ω	2 300	kV V
I _{OD} I _{OG}	Output Current to V _{DD} (Pin 6) Output Current to Ground (Pin 6) (see Note 1)	protected 80	mA
lj	Input Current (Pin 1)	50	mA
Tj	Junction Temperature	150	°C
T _{oper}	Operating Ambient Temperature	0, +70	°C
T _{stg}	Storage Temperature	-20, +150	°C

Note 1 : Pulsed current $t \leq 50 \mu s$

THERMAL DATA

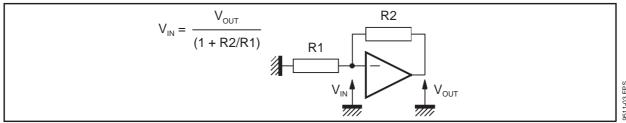
Symbol	Parameter	Value	Unit
R _{th (j-c)}	Junction-Case Thermal Resistance Max.	3	°C/W
R _{th (j-a)}	Junction-Ambient Thermal Resistance Typ.	70	°C/W

$\textbf{ELECTRICAL CHARACTERISTICS} \ (V_{CC} = 12 V, V_{DD} = 110 V, T_{amb} = 25 ^{o}C, \ unless \ otherwise \ specified)$

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
V_{DD}	High Supply Voltage (Pin 7)		20		110	V
Vcc	Low Supply Voltage (Pin 2)		10	12	15	V
I _{DD}	DC Current of High Voltage Supply (without feedback current)	V _{OUT} = 60V		9		mA
Icc	Low Voltage Supply Internal DC Current			15		mA
V _{REF}	Internal Reference (Pin 3)			3.2		V
V _{IN}	Input Voltage	V _{OUT} = 60V		3.25		V
dV_{IN}/dV_{CC}	Drift of Input Voltage versus V _{CC}	Measured on Pin 1		0.12		%
dV _{IN} /dT	Drift of Input Voltage versus Temperature			0.5		mV/°C
V _{SATH}	High Output Saturation Voltage (Pin 6)	I _O = -60mA		V _{DD} - 8.5		V
VSATL	Low Output Saturation Voltage (Pin 6)	Io = 60mA		12		V
ELin	Linearity Error	17V < V _{OUT} < V _{DD} - 15V			5	%
OS	Overshoot			5		%
BW	Bandwidth at -3dB	$\begin{array}{l} \text{Measured on CRT cathodes.} \\ \text{C}_{\text{LOAD}} = 10 \text{pF, Rprotect} = 220 \Omega, \\ \text{V}_{\text{OUT}} = 60 \text{V, } \Delta \text{V}_{\text{OUT}} = 20 \text{V}_{\text{PP,}} \\ \text{Feedback gain} = 20 \end{array}$		40		MHz
t _R , t _F	Rise and Fall Time	Measured between 10% & 90% of output pulse, $C_{LOAD} = 10 pF$, $Rprotect = 220 \Omega$, $V_{OUT} = 60 V$, $\Delta V_{OUT} = 40 V_{PP}$		9		ns
Go	Open Loop Gain	V _{OUT} = 60V		60		dB
	Open Loop Gain Temperature Coefficient			0.03		dB/°C
I _{IB}	Input Bias Current (Pin 1)	V _{OUT} = 60V		20	30	μΑ
	Input Bias Temperature Coefficient			90		nA/°C
R _{IN}	Input Resistance	See Note 2		200		kΩ

Note 2: Characterized and not tested.

Figure 1: Measurement of Input Voltage



TYPICAL APPLICATION

The TDA9511 consists of:

- A differential amplifier with active load,
- A DMOS output buffer,
- Abandgap voltage reference (Pin 3 for filtering only).

PC board lay-out

The best performances are obtained with a carefully designed HF PC-Board, especially for the output and input capacitors.

The feedback resistor R_F must have a low parasitic capacitor ($C_F < 0.3pF$).

This parasitic capacitor C_F must be compensated by a capacitor R3 (roughly 20 · C_F) connected in parallel with the input resistor R1.

The full bandwidth of the device is only obtained with well matched compensation otherwise the application will have either an integrator response with a low bandwidth or a differentiator response with too much ringing.

A diode D_P (see Figure 2) has to be connected for flashover protection.

Power dissipation

The power dissipation consists of a static part and a dynamic part. The static dissipation varies with the output voltage and the feedback resistor. The dynamic power dissipation increases with the pixel frequency.

For a signal frequency of 40MHz and $40V_{PP}$ output signal, the typical power dissipation is about 3.0W, for $V_{DD} = 110V$.

In first approximation, the dynamic dissipation is:

$$P_D = V_{DD} * C_{LOAD} * \Delta V_{OUT} * f$$

and the total dissipation is:

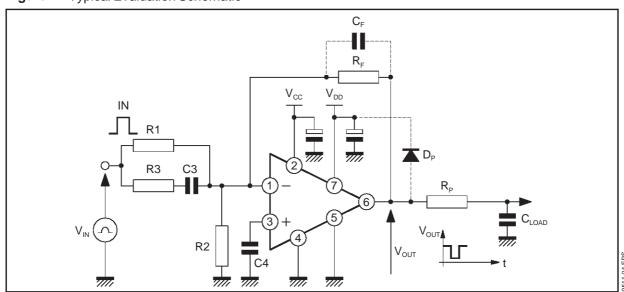
$$P = V_{DD} * C_{LOAD} * \Delta V_{OUT} * f + V_{DD} * I_{DD}$$

+
$$V_{CC}$$
 * I_{CC} - $(V_{DD}$ - $V_{OUT})$ $\frac{V_{OUT}}{R_{FEEDBACK}}$

with f = pixel frequency

P = 110V x 10pF x 40V x 40MHz + 110V x 7mA +12 x 20mA - 60^2 V/20kΩ = 2.95W

Figure 2: Typical Evaluation Schematic



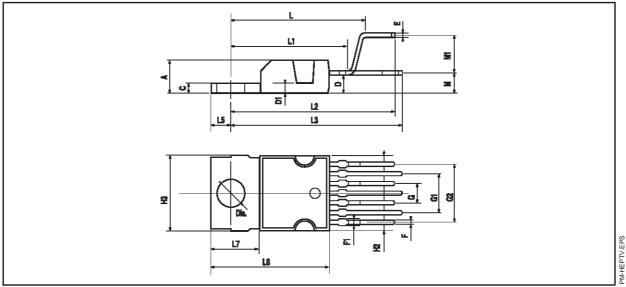
Recommended values:

 $R1 = 1k\Omega$, $R2 = 1.8k\Omega$, $R_F = 20k\Omega$, $R_P = 200\Omega$,

C4 > 10nF, C3 = 10 to 12pF for $C_F # 0.5pF$.

R3 # 150 Ω .

PACKAGE MECHANICAL DATA: 7 PINS - PLASTIC HEPTAWATT



Dimensions	Millimeters			Inches		
Dimensions	Min.	Тур.	Max.	Min.	Тур.	Max.
А			4.8			0.189
С			1.37			0.054
D	2.4		2.8	0.094		0.110
D1	1.2		1.35	0.047		0.053
E	0.35		0.55	0.014		0.022
F	0.6		08	0.024		0.031
F1			0.9			0.035
G	2.41	2.54	2.67	0.095	0.100	0.105
G1	4.91	5.08	5.21	0.193	0.200	0.205
G2	7.49	7.62	7.8	0.295	0.300	0.307
H2			10.4			0.409
H3	10.05		10.4	0.396		0.409
L		16.97			0.668	
L1		14.92			0.587	
L2		21.54			0.848	
L3		22.62			0.891	
L5	2.6		3	0.102		0.118
L6	15.1		15.8	0.594		0.622
L7	6		6.6	0.236		0.260
M		2.8			0.110	
M1		5.08			0.200	
Dia.	3.65		3.85	0.144		0.152

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