Radiator Fan Controlled Timer

Description

The bipolar integrated circuit, U6049B, is designed as a radiator fan controlled timer. After the ignition is switched off, the thermal switch of the engine can activate

Features

- Delay time range: 3.7 s to 20 h
- Cooling time starts when thermal switch is closed
- RC-oscillator determines switching characteristics
- Relay driver with Z-diode
- Debounced input for coolant temperature switch

Ordering Information

the radiator fan via relay for a preset period to support the cooling process.

- Not debounced input for ignition key (Terminal 15)
- Load-dump protection
- RF interference protected
- Protection according to ISO/TR 7637-1 (VDE 0839)

| Extended Type Number | Package | Remarks |
|----------------------|---------|---------|
| U6049B | DIP8 | |
| U6049B-FP | SO8 | |

Block Diagram

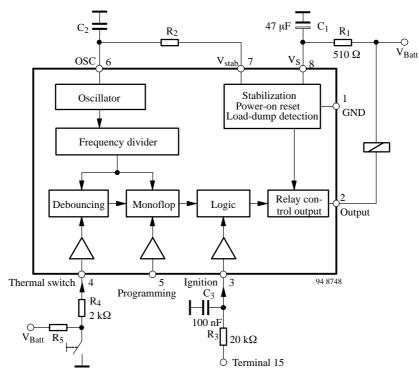


Figure 1. Block diagram with external circuit

Pin Configuration

| Pin | Symbol | Function |
|-----|-------------------|-------------------------|
| 1 | GND | Reference point, ground |
| 2 | Output | Relay control output |
| 3 | Ignition | Signal input, ignition |
| 4 | S _{th} | Thermal switch, input |
| 5 | Program | Programming input |
| 6 | OSC | RC oscillator input |
| 7 | V _{stab} | Stabilized voltage |
| 8 | VS | Supply voltage |

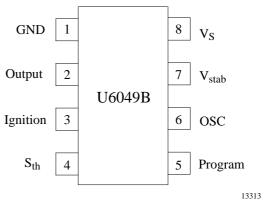


Figure 2. Pinning

Functional Description

Power Supply, Pin 8

For reasons of interference protection and surge immunity, the supply voltage (Pin 8) must be provided with an RC circuit as shown in figure 2a. Dropper resistor, R_1 , limits the current in case of overvoltage, whereas C_1 smoothes the supply voltage at Pin 8.

Recommended values are: $R_1 = 510 \Omega$, $C_1 = 47 \mu F$.

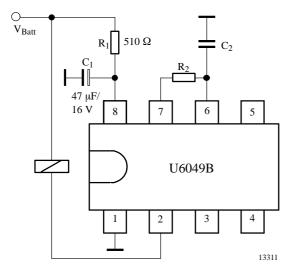


Figure 3. Basic circuit for 12 V voltage supply and oscillator

The integrated Z-diode (14 V) protects the supply voltage, V_S . Therefore, the operation of the IC is possible between 6 V and 16 V supplied by V_{Batt} .

However it is possible to operate the integrated circuit with a 5 V supply, but it should be free of interference voltages. In this case, Pin 7 is connected to Pin 8 as shown in figure 4, and the R_1C_1 circuit is omitted.

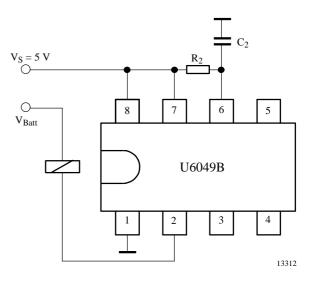


Figure 4. Basic circuit for $V_S = 5 V$

Oscillator, Pin 6

Oscillator frequency, f, is determined mainly by R_2C_2 -circuit. Resistance R_2 determines the charge time, whereas the integrated resistance (2 k Ω) is responsible for discharge time. For the stability of the oscillator frequency, it is recommended to select R_2 much greater than internal resistance (2 k Ω), because the temperature response and the tolerances of the integrated resistance are considerably greater than the external resistance value.

Oscillator frequency, f, is calculated as follows:

$$\mathbf{f} = \frac{1}{\mathbf{t}_1 + \mathbf{t}_2}$$

where

 $\begin{array}{l} t_1 = charge \ time = \alpha_1 \times & R_2 \times & C_2 \\ t_2 = discharge \ time = \alpha_2 \cdot 2 \ k\Omega \cdot C_2 \end{array}$

 α_1 and α_2 are constants and has $\alpha_1 = 0.833$ and $\alpha_2 = 1.551$ when $C_2 = 470$ pF to 10 nF $\alpha_1 = 0.746$ and $\alpha_2 = 1.284$ when $C_2 = 10$ nF to 4700 nF

Debounce time, t_3 , and the delay time, t_d , depend on the oscillator frequency, f, as follows:

$$t_{3} = 6 \times \frac{1}{f}$$
$$t_{d} = 73728 \times \frac{1}{f}$$

Table 1 shows relationships between t_3 , t_d , C_2 , R_2 and frequencies from 1 Hz to 20 kHz.

Output, Pin 2

Output Pin 2 is an open-collector Darlington circuit with integrated 23-V Z-diode for limitation of the inductive cut–off pulse of the relay coil. The maximum static collector current must not exceed 300 mA and the saturation voltage is typically 1.1 V @ 200 mA.

Interference Voltages and Load-Dump

The IC supply is protected by R_1 , C_1 , and an integrated Z-diode, while the inputs are protected by a series resistor, integrated Z-diode and RF-capacitor.

The relay control output is protected via the integrated 23-V Z-diode in the case of short interference peaks. It is switched to conductive condition for a battery voltage of greater than approx. 40 V in the case of load-dump. The output transistor is dimensioned so that it can withstand the current produced.

Power-on Reset

When the operating voltage is switched on, an internal power-on reset pulse (POR) is generated which sets the logic of the circuits to a defined initial condition. The relay control output is disabled.

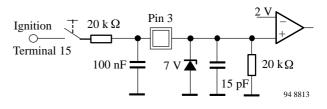


Figure 5. Input circuit for ignition (Pin 3)

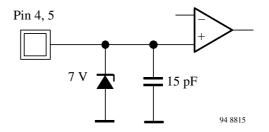


Figure 6. Input circuit Pin 4 and Pin 5

Relay Control Output behavior, Pin 2

The U6049B controls the cooling fan motor in an automobile by means of a relay.

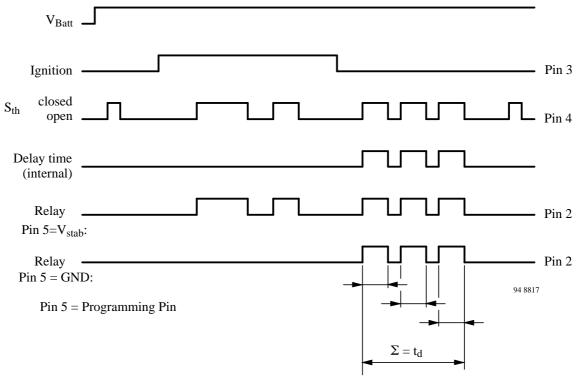
Figure 5 shows the internal input circuit of ignition (Pin 3). It has an integrated pull-down resistor (20 k Ω), RF-capacitor (15 pF) and 7-V Z-diode. It reacts to voltages greater than 2 V.

For the programming input, Pin 5, and thermal switch input, Pin 4, there is neither a pull-up nor pull-down resistor integrated internally (see figure 6).

One can reduce the standby current through the internal Z-diode by selecting a higher value for resistance R_4 (see figure 8, R_4 up to 200 k Ω). Resistance R_5 determines the contact current through the thermal control switch, S_{th} .

Ignition input (terminal 15) is not debounced. Debouncing can be achieved by an external circuit (R_3,C_3) connected to Pin 3 (see figures 1 and 7).

U6049B



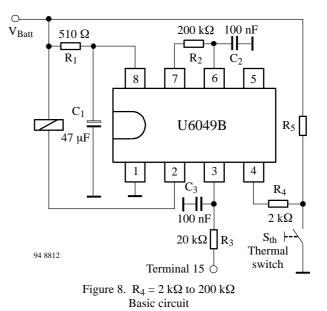
 t_d is stopped, if S_{th} is open

Figure 7. Timing waveform

The programming input (Pin 5) is high-ohmic and should therefore be connected to Pin 7 (V_{stab}) or GND. The relay control output is shown according to Pin 5 connection.

Thermal switch input, Pin 4, is debounced (see figure 1). Relay control output, Pin 2, is disabled when the battery voltage, V_{Batt} , is applied. Relay control output follows the conditions of the switch, S_{th} , only when the ignition is switched-ON. This is possible only after the debounce time, t_3 . In this case Pin 5 is connected to Pin 7.

Timing waveforms are shown in figure 4. Total delay time, t_d , is the sum of all ON-pulses caused by the thermostatic switching. This can run down at once or in parts. If S_{th} (Pin 4) is open, the oscillator is stopped (switched-off) internally, but when it starts (S_{th} closed), the delay time, t_d , starts running again. In case of renewed switching of ignition, the counter of the delay time is reset.



Absolute Maximum Ratings

| Parameters | Symbol | Value | Unit |
|----------------------------------|-------------------|-------------|------|
| Operating voltage, static, 5 min | V _{Batt} | 24 | V |
| Ambient temperature range | T _{amb} | -40 to +125 | °C |
| Storage temperature range | T _{stg} | -55 to +125 | °C |
| Junction temperature | Тj | 150 | °C |

Thermal Resistance

| Parameters | | Symbol | Maximum | Unit |
|-----------------------|--|-------------------|---------|------|
| Junction ambient DIP8 | | R _{thJA} | 110 | K/W |
| SO8 | | R _{thJA} | 160 | K/W |

Electrical Characteristics

 $V_{Batt} = 13.5 \text{ V}, T_{amb} = 25^{\circ}\text{C}$, reference point ground, figure 2, unless otherwise specified

| Parameters | Test Conditions | / Pin | Symbol | Min | Тур | Max | Unit |
|--|---|------------|---------------------------------|-------|-----|-------|--------|
| Operating voltage | $R_1 \ge 510 \Omega$ | | V _{Batt} | 6 | | 16 | |
| | t < 5 min | | | | | 24 | V |
| | t < 60 min | | | | | 18 | |
| 5 V supply | Without R_1 , C_1 | | V ₈ , V ₇ | 4.3 | | 6.0 | V |
| | figure 2b Pins | 7 and 8 | | | | | |
| Stabilized voltage | | Pin 7 | V ₇ | 5.0 | 5.2 | 5.4 | V |
| Undervoltage threshold | Power-on reset | | Vs | 3.0 | | 4.2 | V |
| Supply current | Push buttons open | Pin 8 | IS | | 1.3 | 2.0 | mA |
| Internal Z-diode | $I_8 = 10 \text{ mA}$ | Pin 8 | VZ | 13.5 | 14 | 16 | V |
| Relay output | | Pin 2 | | | | | |
| Saturation voltage | $I_2 = 200 \text{ mA}$ | | V2 | | 1.2 | | V |
| | $I_2 = 300 \text{ mA}$ | | | | | 1.5 | |
| Leakage current | $V_2 = 14 V$ | | I _{lkg} | | 2 | 100 | μA |
| Output current | | | I ₂ | | | 300 | mA |
| Output pulse current | | | | | | | |
| Load dump pulse | | | I ₂ | | | 1.5 | A |
| Internal Z-diode $I_2 = 10 \text{ mA}$ | | | V ₂ | 20 | 22 | 24 | V |
| Oscillator input | f = 0.001 to 40 kHz, se | e table 1 | Pin 6 | | | | |
| Internal discharge resistance | e | | R ₆ | 1.6 | 2.0 | 2.4 | kΩ |
| Switching voltage | Lower | | V _{6L} | 0.9 | 1.1 | 1.4 | V |
| | Upper | | V_{6H} | 2.8 | 3.1 | 3.5 | |
| Input current | $V_6 = 0 V$ | | -I ₆ | | | 1 | μA |
| Switching times | | | | | | | |
| Debounce time | | | t3 | 5 | | 7 | cycles |
| Delay time | | | t _d | 72704 | | 74752 | cycles |
| Inputs | Pi | in 3, 4, 5 | | | | | |
| Switching threshold | | | V _{3,4,5} | 1.6 | 2.0 | 2.4 | V |
| Internal Z-diode | $I_{3, 4, 5} = 10 \text{ mA}$ | | V _{3,4,5} | 6.5 | 7.1 | 8.0 | V |
| Ignition input | , , - | Pin 3 | | | | • | • |
| Pull-down resistance | Switched to V _{Batt} (| 15) | R ₃ | 13 | 20 | 50 | kΩ |
| Thermal switch | Pin 4 | | | | • | | |
| Input current | | | - I4 | | | 2 | μA |
| Programming input | | | | | | | |
| Input current | $\frac{\text{Pin 5}}{\text{V}_5 = 0 \text{ V}}$ | | - I5 | | | 2 | μA |
| L | 5 | | 5 | 1 | | 1 | 1 1 |

| Table 1. | Oscillator | frequency, | debounce tir | me, delay | time. | dimensioning |
|----------|------------|------------|--------------|-----------|-------|--------------|
|----------|------------|------------|--------------|-----------|-------|--------------|

| Fre- quency f | De- bounce time t ₃ | Delay t | | C ₂ | R ₂ | Fique |
|---------------------|---|------------|-----|----------------|----------------|-------|
| Hz | ms | min | s | nF | kΩ | H |
| 1 | 6000 | 1229 | | 4700 | 280 | 6 |
| 2 | 3000 | 614 | | 1000 | 650 | 7 |
| 3 | 2000 | 410 | | 1000 | 440 | 8 |
| 4 | 1500 | 307 | | 1000 | 330 | 9 |
| 5 | 1200 | 246 | | 1000 | 260 | 10 |
| 6 | 1000 | 205 | | 1000 | 220 | 20 |
| 7 | 857 | 176 | | 1000 | 190 | 30 |
| 8 | 750 | 154 | | 1000 | 160 | 40 |
| 9 | 667 | 137 | | 1000 | 140 | 50 |
| 10 | 600 | 123 | | 1000 | 130 | 60 |
| 20 | 300 | 61 | | 100 | 650 | 70 |
| 30 | 200 | 41 | | 100 | 440 | 80 |
| 40 | 150 | 31 | | 100 | 330 | 90 |
| 50 | 120 | 25 | | 100 | 260 | 10 |
| 60 | 100 | 20 | | 100 | 220 | 110 |
| 70 | 86 | 18 | | 100 | 190 | 12 |
| 80 | 75 | 15 | | 100 | 160 | 13 |
| 90 | 67 | 14 | | 100 | 140 | 14 |
| 100 | 60 | 12 | | 100 | 130 | 15 |
| 200 | 30 | | 369 | 10 | 600 | 16 |
| 300 | 20 | | 246 | 10 | 400 | 17 |
| 400 | 15 | | 184 | 10 | 300 | 18 |
| 500 | 12 | | 147 | 10 | 240 | 19 |
| <u> </u> | 1 | 1 | I | 1 | 1 | 20 |

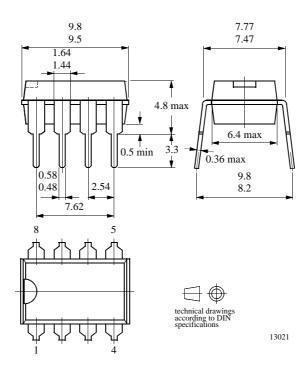
| Fre- quency f | De- bounce time t ₃ | Delay time t _d | | C ₂ | R ₂ |
|---------------------|---|------------------------------|-----|----------------|----------------|
| Hz | ms | min | s | nF | kΩ |
| 600 | 10.00 | | 123 | 10 | 200 |
| 700 | 9.00 | | 105 | 10 | 170 |
| 800 | 8.00 | | 92 | 10 | 150 |
| 900 | 7.00 | | 82 | 10 | 130 |
| 1000 | 6.00 | | 74 | 10 | 120 |
| 2000 | 3.00 | | 37 | 1 | 600 |
| 3000 | 2.00 | | 25 | 1 | 400 |
| 4000 | 1.50 | | 18 | 1 | 300 |
| 5000 | 1.20 | | 15 | 1 | 240 |
| 6000 | 1.00 | | 12 | 1 | 200 |
| 7000 | 0.86 | | 11 | 1 | 170 |
| 8000 | 0.75 | | 9 | 1 | 150 |
| 9000 | 0.67 | | 8 | 1 | 130 |
| 10000 | 0.60 | | 7 | 1 | 120 |
| 11000 | 0.55 | | 6.7 | 1 | 110 |
| 12000 | 0.50 | | 6.1 | 1 | 99 |
| 13000 | 0.46 | | 5.7 | 1 | 91 |
| 14000 | 0.43 | | 5.3 | 1 | 85 |
| 15000 | 0.40 | | 4.9 | 1 | 79 |
| 16000 | 0.38 | | 4.6 | 1 | 74 |
| 17000 | 0.35 | | 4.3 | 1 | 70 |
| 18000 | 0.33 | | 4.1 | 1 | 66 |
| 19000 | 0.32 | | 3.9 | 1 | 62 |
| 20000 | 0.30 | | 3.7 | 1 | 59 |



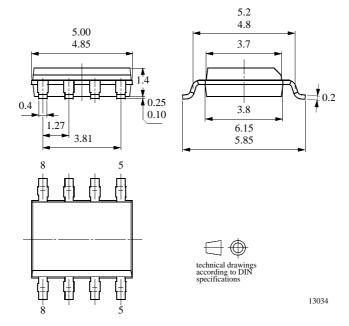
Package Information

Package DIP8

Dimensions in mm



Package SO8 Dimensions in mm



Ozone Depleting Substances Policy Statement

It is the policy of TEMIC TELEFUNKEN microelectronic GmbH to

- 1. Meet all present and future national and international statutory requirements.
- 2. Regularly and continuously improve the performance of our products, processes, distribution and operating systems with respect to their impact on the health and safety of our employees and the public, as well as their impact on the environment.

It is particular concern to control or eliminate releases of those substances into the atmosphere which are known as ozone depleting substances (ODSs).

The Montreal Protocol (1987) and its London Amendments (1990) intend to severely restrict the use of ODSs and forbid their use within the next ten years. Various national and international initiatives are pressing for an earlier ban on these substances.

TEMIC TELEFUNKEN microelectronic GmbH semiconductor division has been able to use its policy of continuous improvements to eliminate the use of ODSs listed in the following documents.

- 1. Annex A, B and list of transitional substances of the Montreal Protocol and the London Amendments respectively
- 2. Class I and II ozone depleting substances in the Clean Air Act Amendments of 1990 by the Environmental Protection Agency (EPA) in the USA
- 3. Council Decision 88/540/EEC and 91/690/EEC Annex A, B and C (transitional substances) respectively.

TEMIC can certify that our semiconductors are not manufactured with ozone depleting substances and do not contain such substances.

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